CS 559: Machine Learning Fundamentals & Applications

Lecture 5: Linear Classification



Outline



- 5.0. Lecture 4 Review
- 5.1. Introduction
- 5.2. Discriminant Functions
 - 5.2.1. Linear Discriminant Analysis (LDA)
 - 5.2.2. Perceptron
- 5.3. Probabilistic Generative Models MLE
- 5.4. Probabilistic Discriminative Models Logistic Regression

5.0 Lecture 4 Review



Linear Regression

- One of simplest linear models in ML.
- Overcoming the conditions and assumptions may be challenge.

Model Selection

- Overfit vs. Underfit
- Regularization
- Bias-Variance Trade-off



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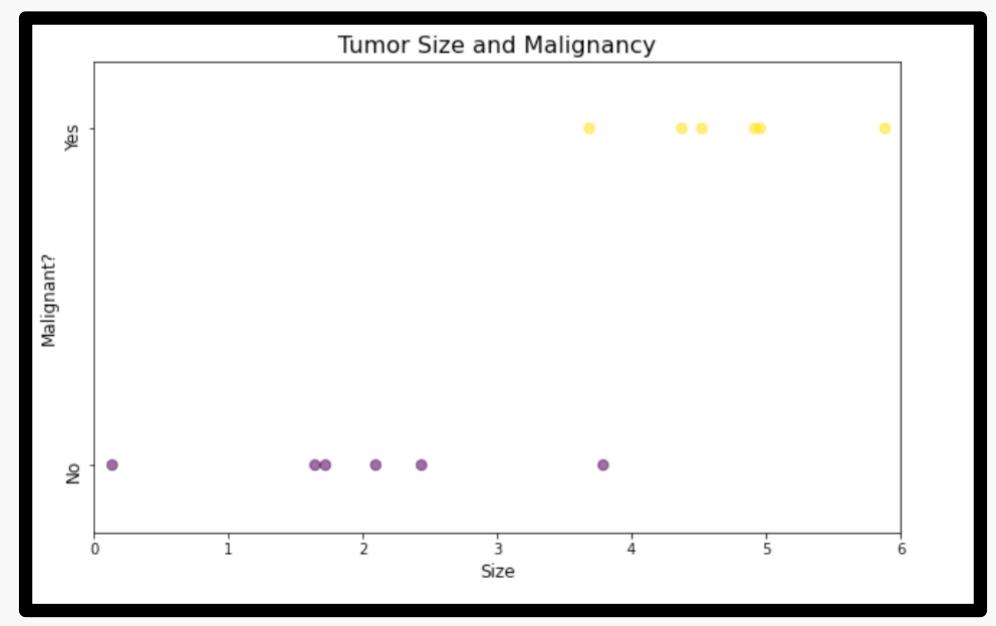
Goal: to take an input vector \mathbf{x} and to assign it to one of K discrete classes C_k where k = 1, ..., K.

- Data Condition: The classes are disjoint, and the target is discrete.
- The input space is divided into *decision regions* linear decision surfaces called *hyperplanes* in *D*-1 dimensions if the input space is in D-dimensions.
- For binary problem, target $t \in \{0,1\}$ or $\{-1,1\}$.

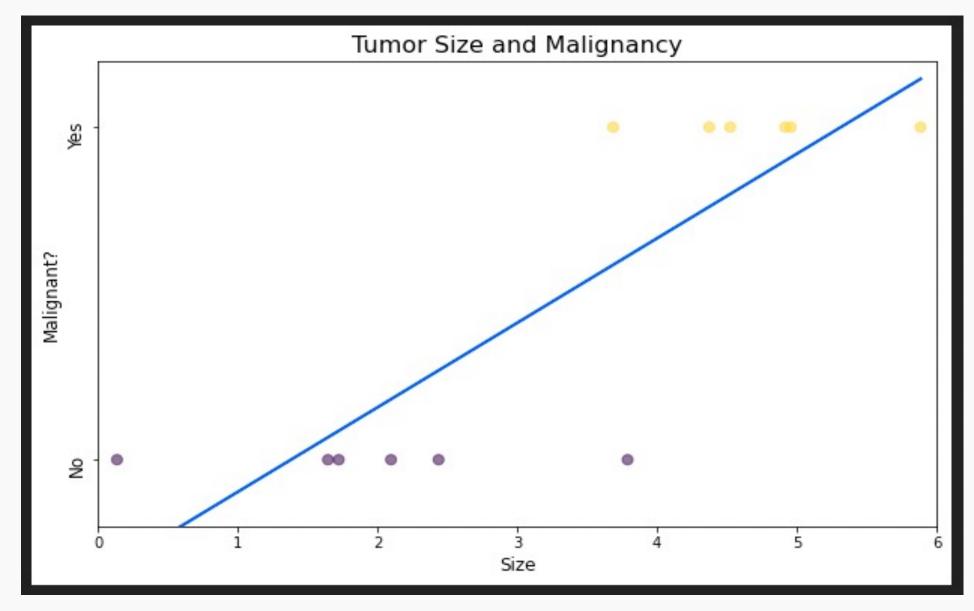
We approach in three different approaches:

- 1. A *discriminant modeling*: directly assigns each vector **x** to a specific class (LDA, Perceptron).
- 2. A *probabilistic modeling*: determines the conditional probability distribution $p(C_k|x)$ and represent them as a parametric model.
 - 1. Probabilistic generative modeling: a classification modeling using Bayes' theorem (MLE).
 - **2. Probabilistic discriminative modeling**: a classification modeling using MLE in a form of discriminative modeling (logistic regression).

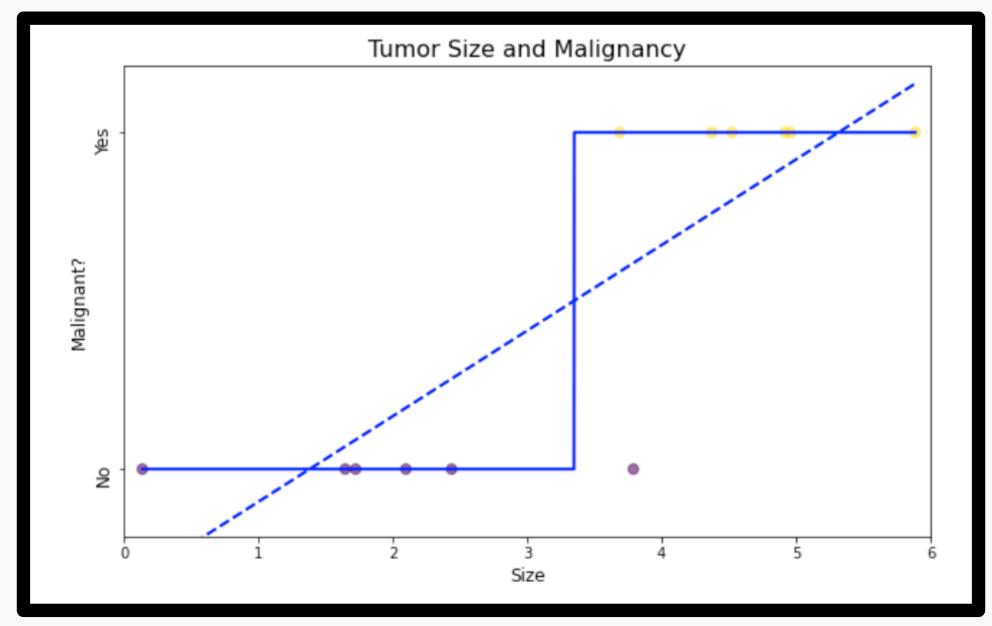














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(5-1)

Consider a simple linear discriminant function of the input vector \mathbf{x} ,

$$y(x) = w^T x + w_0$$

where w is called a *weight vector*, and w_0 is a bias.

- If $w_0 < 0$, sometimes we call it a *threshold*.
- If $y(x) \ge 0$, then x is assigned to class C_1 . Otherwise, C_2 .
- The corresponding hyperplane is when y(x) = 0.

- If two points x_A and x_B both lying on the decision surface, $y(x_A) = y(x_B) = 0$.
- The normal distance from the origin to the decision surface is

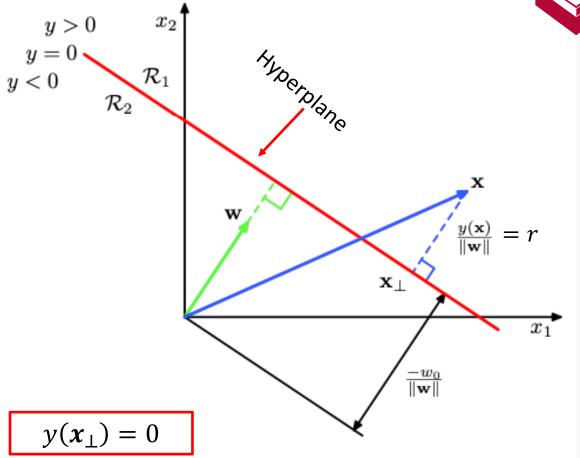
$$\frac{\boldsymbol{w}^T\boldsymbol{x}}{|\boldsymbol{w}|} = -\frac{w_0}{|\boldsymbol{w}|}.$$

• The perpendicular distance r of the point \mathbf{x} from the hyperplane can be expressed as

$$x = x_{\perp} + r\left(\frac{w}{|w|}\right)$$

where x_{\perp} is the orthogonal projection onto the hyperplane. It also can be expressed in terms of y:

$$y(x) = y(x_{\perp}) + r\left(\frac{\mathbf{w}^T \mathbf{w}}{|\mathbf{w}|}\right) \rightarrow r = \frac{y(x)}{|\mathbf{w}|}.$$

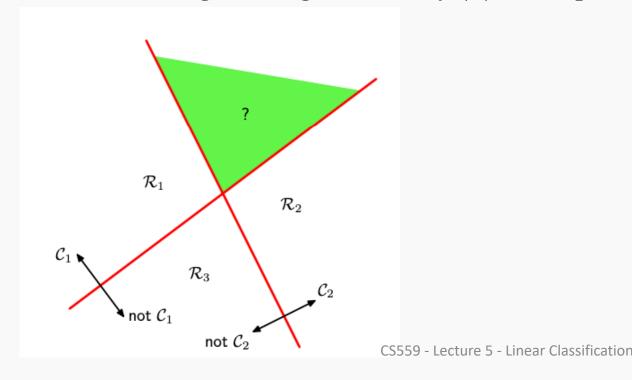


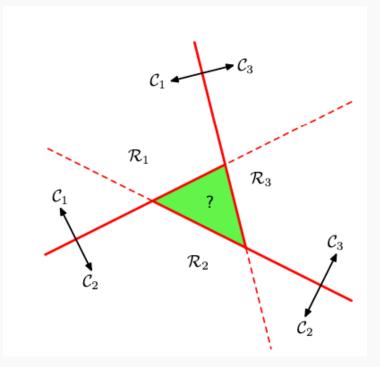
$$|w| = \sqrt{w^T w} \to \frac{|w|}{w^T w} = \frac{1}{|w|}$$
 (5-2)

What happens when the target has more than two classes?

If we approach as binary classification problem, there are two possible approaches.

- One-verse-rest classifier: the K-1 classifier that solves as a two-class problem of separating points in a particular class C_k from points not in that class.
- *One-verse-one* classifier: each point is classified according to a majority vote amongst the discriminant functions.
- Either holds an ambiguous region where y(x) is not possible for some x.







• Instead, we consider a single *K*-class linear discriminant function comprising *K* many functions in the form of

$$y_k(\mathbf{x}) = \mathbf{w}_k^T \mathbf{x} + w_{k0}$$

to assign a class C_k for a point **x** if $y_k(x) > y_j(x)$ for all $j \neq k$.

• The class boundary between C_k and C_j is when $y_k = y_j$ defined by

$$(\mathbf{w}_k - \mathbf{w}_j)^T x + (\mathbf{w}_{ko} - \mathbf{w}_{j0}) = 0.$$
 (5-3)

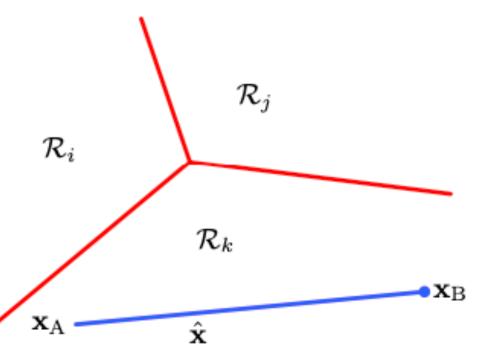
- In this way, we can connect the decision regions into a single point and be convex.
- Consider any point \hat{x} lies on the line between two points x_A and x_B in R_k ,

$$\widehat{x} = \lambda x_A + (1 - \lambda) x_B$$

where $0 \le \lambda \le 1$. From the linearity of the discriminant functions, it follows that

$$y_k(\widehat{\mathbf{x}}) = \lambda y_k(\mathbf{x}_A) + (1 - \lambda)y_k(\mathbf{x}_B).$$







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- Consider a binary linear classifier in terms of *dimensionality reduction* for *D*-dimensional input vector \mathbf{x} having an output $\{C_1, C_2\}$.
- Let y be C_1 if $y \ge -w_0$ and otherwise C_2 .
- Suppose we projectile down to 1-dimension using $y = \mathbf{w}^T \mathbf{x}$.
- We can control **w** to project by maximizing the class separation to avoid the considerable loss information that may occur in projection D-dimensional space to 1-dimentional space.

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If there are N_1 points in C_1 and N_2 in C_2 , the mean vector of the two classes is

$$m_1 = \frac{1}{N_1} \sum_{n \in C_1} x_n$$
, $m_2 = \frac{1}{N_2} \sum_{n \in C_2} x_n$.

The separation mean of the projected means can measure the separation of the classes to maximize

$$m_2 - m_1 = \boldsymbol{w}^T (\boldsymbol{m_2} - \boldsymbol{m_1}).$$

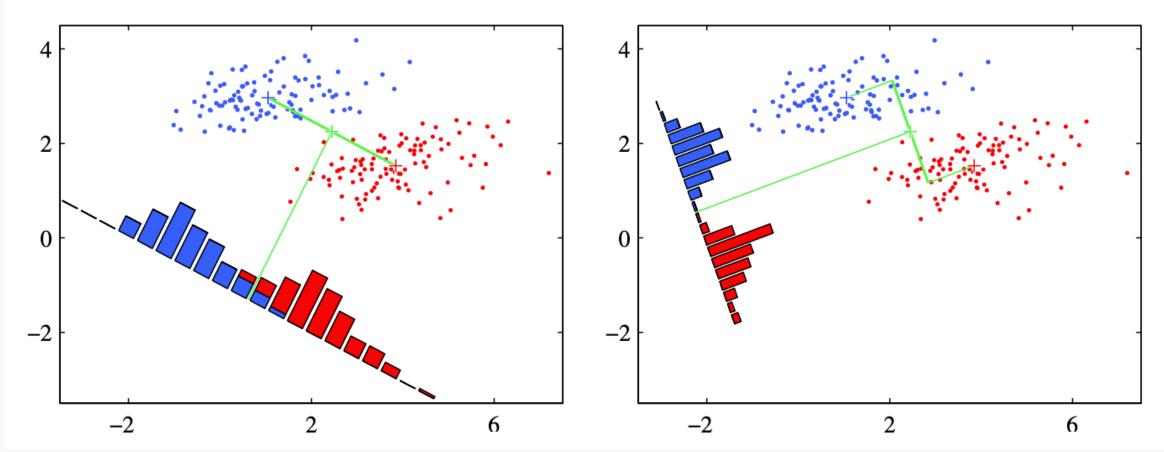
However, the separation becomes arbitrary large when the magnitude of w is large.

To avoid this, **w** will be forced to be a unit length $\sum_i w_i^2 = 1$.

- However, the strong nondiagonal **covariances** of the class distributions still may have **overlap** when projected onto the line joining their means.
- To minimize the overlap, the function must give the **largest separation** between the projected class means while the **smallest variance** within each class, also known as the within-class variance.

(5-13)







The within-class variance of the transformed data from class C_k is

$$s_k^2 = \sum_{n \in C_k} (y - m_k)^2$$
 where $y_n = \mathbf{w}^T \mathbf{x}_n$ (5-4)

and the total within-class variance is

$$s^2 = \sum_{k=1}^K s_k^2 \,. \tag{5-5}$$

The **Fisher criterion**, J(w), is the ratio of the between-class variance to the within-class variance (Eq. 5-5) and is defined as

$$J(\mathbf{w}) = \frac{(m_2 - m_1)^2}{s_1^2 + s_2^2}.$$
 (5-6)



It can be rewritten as the dependence on \boldsymbol{w} as

$$J(w) = \frac{w^T S_B w}{w^T S_w w}$$

where S_B is the *between-class* covariance matrix

$$S_B = (m_2 - m_1)(m_2 - m_1)^T$$

and S_w is the **total** within-class covariance matrix is given by

$$S_w = \sum_{n \in C_1} (x_n - m_1)(x_n - m_1)^T + (x_n - m_2)(x_n - m_2)^T.$$

J(w) is maximized when $\nabla_{\mathbf{w}}J(w) = 0$:

$$(w^T S_B w) S_w w = (w^T S_w w) S_B w.$$

(5-7)

To obtain \mathbf{w} , we can consider the following two properties.

- The between-class shows that $S_B w$ is always in the direction of $(m_2 m_1)$.
- Considering the direction only (not the magnitude), the scalar factors $(w^T S_B w)$ and $(w^T S_w w)$ can be dropped in Eq. (5-7).

Then multiplying S_w^{-1} on both sides, then w can be obtained as $w \propto S_w^{-1}(m_2 - m_1)$.

(5-8)

Alternatively, we can find w that maximizes the criterion using Linear Algebra via generalized eigenvalue problem:

 \circ The eigenvalue, λ , can be computed as

$$S_B w = \lambda S_w w \to (S_w^{-1} S_B - \lambda I) = 0$$
$$\det(S_w^{-1} S_B - \lambda I) = 0$$

The eigenvector for λ_{max} is then solution.

(5-9)

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We can relate to the least squares.

Suppose we can model the class-conditional densities $p(y|C_k)$ using Gaussian distribution. The solution of w can be approached via MLE.

Consider a binary classification and let the target $t_1 = \frac{N}{N_1}$ for class C_1 where N is the total number and N_1 is the number in C_1 . Similarly, let $t_2 = -\frac{N}{N_2}$.

Start from the sum-of-squares error function,

$$E = \frac{1}{2} \sum_{n=1}^{N} (\mathbf{w}^{T} \mathbf{x}_{n} + \mathbf{w}_{0} - t_{n})^{2}.$$

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Set the derivative of the sum-of-squares error function w.r.t. w equals to 0,

$$\sum_{n=1}^{N} (\mathbf{w}^{T} \mathbf{x}_{n} + w_{0} - t_{n}) \mathbf{x}_{n} = 0.$$

The use of

$$\sum_{n=1}^{N} t_n = \frac{N_1 N}{N_1} - \frac{N_2 N}{N_2} = 0$$

$$m = \frac{1}{N} \sum_{n=1}^{N} x_n = \frac{1}{N} (N_1 m_1 + N_2 m_2)$$

and

$$w_0 = -\boldsymbol{w}^T \boldsymbol{m},$$

the derivative of the sum-of-squares error function (using S_w and S_B from slide #19) becomes

$$\left(S_w + \frac{N_1 N_2}{N} S_B\right) w = N(m_1 - m_2).$$

(5-9)



For K > 2 classes, assume D > K.

Suppose there are D' > 1 linear new features $y_k = \mathbf{w}_k^T \mathbf{x}$ for k = 1, ..., D' where \mathbf{y} is the vector for y_k : $\mathbf{y} = \mathbf{W}^T \mathbf{x}$

where the bias parameter w_0 is excluded.

The within-class covariance matrix is

$$S_w = \sum_{k=1}^K S_k$$

where \boldsymbol{S}_k is

$$S_k = \sum_{n \in C_k} (x_n - m_k)(x_n - m_k)^T = \sum_{n \in C_k} \left(x_n - \frac{1}{N_k} \sum_{n \in C_k} x_n \right) \left(x_n - \frac{1}{N_k} \sum_{n \in C_k} x_n \right)^T.$$



The total covariance matrix

$$S_T = \sum_{n=1}^{N} (\boldsymbol{x}_n - \boldsymbol{m}) (\boldsymbol{x}_n - \boldsymbol{m})^T$$

where *m* is the mean of total set

$$m = \frac{1}{N} \sum_{n=1}^{N} x_n = \frac{1}{N} \sum_{k=1}^{K} N_k m_k.$$

The total covariance is the sum of within-class variance and the between-class covariance

$$S_B = \sum_{k=1}^K N_k (m_k - m)(m_k - m)^T$$
,
 $S_T = S_W + S_B$.



In the projected D'-dimensional y-space

$$s_w = \sum_{k=1}^K \sum_{n \in C_k} (y_n - \mu_k)(y_n - \mu_k)^T$$

and

$$\mathbf{s}_B = \sum_{k=1}^K N_k (\boldsymbol{\mu_k} - \boldsymbol{\mu}) (\boldsymbol{\mu_k} - \boldsymbol{\mu})^T$$

where

$$\mu_k = \frac{1}{N_k} \sum_{n \in C_k} y_n$$
, $\mu = \frac{1}{N} \sum_{k=1}^K N_k \mu_k$.

Then, the criterion can be expressed as

$$J(\mathbf{W}) = Tr\{\mathbf{s}_{\mathbf{w}}^{-1}\mathbf{s}_{\mathbf{B}}\} \rightarrow J(\mathbf{w}) = Tr\{(\mathbf{W}\mathbf{S}_{\mathbf{W}}\mathbf{W}^{T})^{-1}(\mathbf{W}\mathbf{S}_{\mathbf{B}}\mathbf{W})\}.$$

The weight values to maximize the criterion can be determined by the eigenvectors of $S_w^{-1}S_B$ that correspond to the D' largest eigenvalues.

Class	(x_1, x_2)	m	
C_1	(1,2), (2,3), (3,4.9)	(2, 3.3)	
C_2	(2,1), (3,2), (4, 3.9)	(3,2.3)	



The total within-class variance is

$$S_w = \begin{bmatrix} 4 & 5.8 \\ 5.8 & 8.68 \end{bmatrix}$$

and its inverse is

$$S_w^{-1} = \begin{bmatrix} 8.04 & -5.37 \\ -5.37 & 3.70 \end{bmatrix}.$$

Since w is proportional to $S_w^{-1}(m_2 - m1)$,

$$w \propto S_w^{-1}(m_2 - m_1) = \begin{bmatrix} -13.41 \\ 9.07 \end{bmatrix}$$

and its unit vector is

$$\widehat{\boldsymbol{w}} = \frac{\boldsymbol{w}}{|\boldsymbol{w}|} = \begin{bmatrix} -0.83\\ 0.56 \end{bmatrix}$$

and therefore, the model is

$$y = -0.83x_1 + 0.56x_2.$$



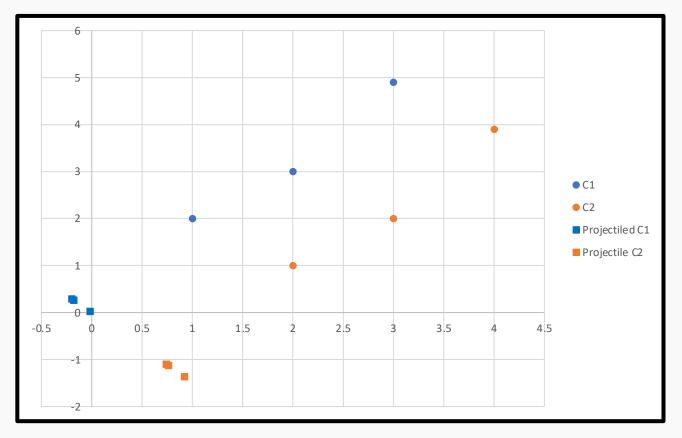
Substituting data into the model reveals

$$y = [0.29 \quad 0.025 \quad 0.26 \quad -1.10 \quad -1.36 \quad -1.13].$$

For the complete orthogonal projection, set y=0 and find the

model

$$x_2 = \frac{0.83}{0.56} x_1$$





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Consider a binary class model of the form

$$y(\mathbf{x}) = f(\mathbf{w}^T \phi(\mathbf{x}))$$

where the nonlinear activation function $f(\cdot)$ is a step function of the form

$$f(a) = \begin{cases} 1, & a \ge 0 \\ -1, & a < 0 \end{cases}$$

The target values are

$$t = \begin{cases} 1, & for C_1 \\ -1, & for C_2 \end{cases}.$$

The learning is motivated from the error function minimization.

- But the change of w can cause the change of decision boundary and lead to misclassification.
- Therefore, the approaching in gradient descent way is not possible. We need a different error function.
- Instead, we use the *perceptron criterion* to ensure the misclassification is minimized. The perceptron criterion is given by

$$E_p(\mathbf{w}) = -\sum_{n \in \mathcal{M}} \mathbf{w}^T \phi_n t_n$$

where \mathcal{M} is the set of all misclassified patterns.

(5-10)

- Suppose we seek for a linear pattern s.t. $\mathbf{w}^T \phi(\mathbf{x}_n) > 0$ for C_1 .
- The patterns with $\mathbf{w}^T \phi(\mathbf{x}_n) t_n > 0$ will also be followed. For \mathbf{x}_n in C_2 will also follow the same pattern since $\mathbf{w}^T \phi(\mathbf{x}_n) < 0$ and $t_n = -1$ for all correct classification.
- In other words, misclassified x_n , that is $n \in \mathcal{M}$, will have pattern of $\mathbf{w}^T \phi(x_n) t_n < 0$ for any classes.
- We need to therefore minimize the quantity $-\mathbf{w}^T \phi(\mathbf{x}_n) t_n$ by applying the stochastic gradient descent algorithm,

$$\mathbf{w}^{(\tau+1)} = \mathbf{w}^{(\tau)} - \eta \nabla E_p(\mathbf{x_n}).$$

- For each iteration, y(x, w) is evaluated.
- If the pattern is correctly classified, the weight does not change.

$$\boldsymbol{w}^{(\tau+1)} = \boldsymbol{w}^{(\tau)}$$

(5-11a)

- If the classification is incorrect,
 - For C_1 , we add the vector $\phi(x_n)$ to w.

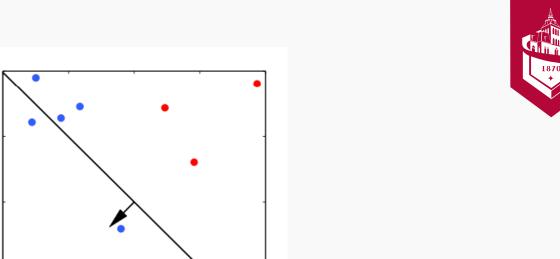
$$\mathbf{w}^{(\tau+1)} = \mathbf{w}^{\tau} + \mathbf{x}_n$$

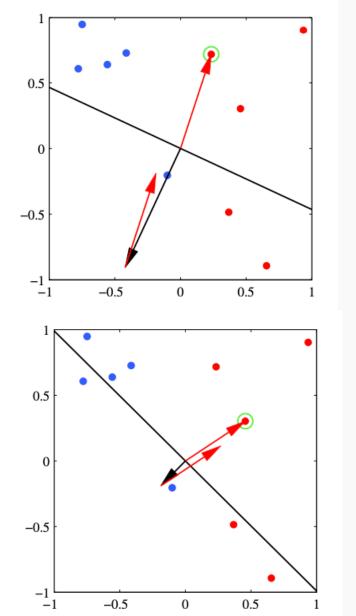
• For C_2 , we subtract vector $\phi(x_n)$ from w.

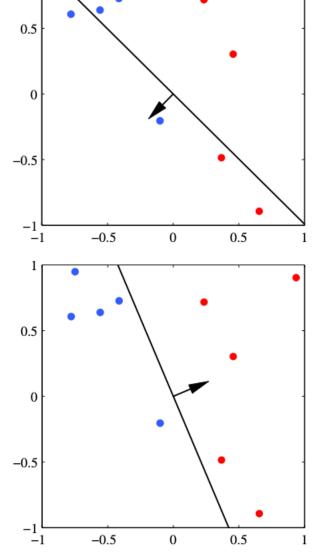
$$\boldsymbol{w}^{(\tau+1)} = \boldsymbol{w}^{\tau} - \boldsymbol{x}_n$$

(5-11c)

(5-11b)







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Consider $\eta = 1$ and $||\phi_n t_n||^2 > 0$, the single update will reduce the error from the misclassification:

$$-\mathbf{w}^{(\tau+1)T}\phi_n t_n = -\mathbf{w}^{(\tau)T}\phi_n t_n - (\phi_n t_n)^T \phi_n t_n < -\mathbf{w}^{(\tau)T}\phi_n t_n.$$

- It will not impact the error from another misclassified pattern.
- It may change the result on previously corrected patterns.
- It does not guarantee the reduction of the total error function at each stage.
- However, if the training data is linearly separable, the perceptron guarantees the exact solution after the finite iteration the *perceptron convergence theorem*.
- The perceptron may have many solutions depends on the parameter initialization.
- The learning algorithm will never converge if the training data is not linearly separable.

Class	(x_1, x_2)
1	(1,2), (2,3), (3,4.9)
-1	(2,1), (3,2), (4, 3.9)

Initial
$$\mathbf{w} = [\mathbf{5}, -\mathbf{6}, \mathbf{1}], y = w_0 + w_1 x_1 + w_2 x_2$$
.

	w_0	w_1	W_2
Initialization	5	-6	1
1st Iteration	6	-4	4
2nd Iteration	5	-6	3

$$\hat{w} = [0.598, -0.717, 0.585]$$

	1	2	3	4	5	6
Initialization	1	-1	-1	-1	-1	-1
1st Iteration	1	1	1	1	1	1
2nd Iteration	1	1	1	-1	-1	-1







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5.3. Probabilistic Generative Models

Consider a binary class classification, C_1 and C_2 .

The posterior probability for C_1 ,

$$p(C_1|\mathbf{x}) = \frac{p(\mathbf{x}|C_1)p(C_1)}{p(\mathbf{x}|C_1)p(C_1) + p(\mathbf{x}|C_2)p(C_2)} = \frac{1}{1 + \exp(-a)} = \sigma(a)$$

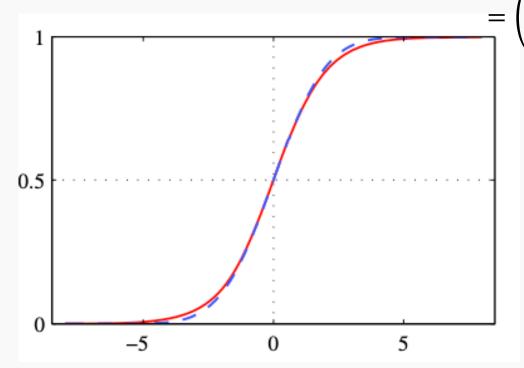
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(5-12)

where

$$a = \ln \frac{p(x|C_1)p(C_1)}{p(x|C_2)p(C_2)}.$$
 Note: $\exp(-a) = \exp\left(-\ln \frac{p(x|C_1)p(C_1)}{p(x|C_2)p(C_2)}\right)$
$$= \left(\frac{p(x|C_1)p(C_1)}{p(x|C_2)p(C_2)}\right)^{-1}$$

 $\sigma(a)$ is called the *logistic sigmoid*.



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It follows the symmetry property

$$\sigma(-a) = 1 - \sigma(a).$$



The inverse of the logistic sigmoid is known as the *logit* function in the form of

$$a = \ln\left(\frac{\sigma}{1 - \sigma}\right)$$

and represents to log of the ratio of $\ln[p(C_1|x)/p(C_2|x)]$ for the two classes, also known as the log odds.



For the case of K > 2 classes, the posterior probability of C_k is in the form

$$p(C_k|\mathbf{x}) = \frac{p(\mathbf{x}|C_k)p(C_k)}{\sum_j p(\mathbf{x}|C_j)p(C_j)} = \frac{\exp a_k}{\sum_j \exp(a_j)}$$

which is known as the *normalized exponential* and can be regarded as a multiclass generalization of the logistic sigmoid and the quantities a_k are defined by

$$a_k = \ln p(\mathbf{x}|C_k)p(C_k).$$

This is also known as the *softmax function* that smooths the max function:

$$p(C_k|\mathbf{x}) \approx 1$$
$$p(C_i|\mathbf{x}) \approx 0$$

for all $j \neq k$.



Assume the class-conditional densities are Gaussian and all classes share the same covariance matrix. The density for class C_k is

$$p(x|C_k) = \frac{1}{(2\pi)^{\frac{D}{2}}} \frac{1}{|\mathbf{\Sigma}|^{\frac{1}{2}}} \exp\left\{-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu_k})^T \mathbf{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu_k})\right\}.$$

Consider for binary classes,

$$p(C_1|\mathbf{x}) = \sigma(\mathbf{w}^T\mathbf{x} + w_0)$$

Derivation:

Let the prior probability be $p(C_1) = \pi_1$ and $p(C_2) = \pi_2$.



$$p(C_1|\mathbf{x}) = \frac{p(\mathbf{x}|C_1)p(C_1)}{p(\mathbf{x}|C_1)p(C_1) + p(\mathbf{x}|C_2)p(C_2)}$$

$$= \frac{\pi_1 \exp\left\{-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu_1})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu_1})\right\}}{\pi_1 \exp\left\{-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu_1})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu_1})\right\} + \pi_2 \exp\left\{-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu_2})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu_2})\right\}}$$

The exponential term can be simplified as

$$-\frac{1}{2}(x-\mu_1)^T \Sigma^{-1}(x-\mu_1) = -\frac{1}{2}(x\Sigma^{-1}x - 2\mu_1^T \Sigma^{-1}x + \mu_1^T \Sigma^{-1}\mu_1).$$

The first term in the right side is not associate with C_1 and it can be vanished. The equation above can be expressed as

$$\mu_1^T \Sigma^{-1} x - \frac{1}{2} \mu_1^T \Sigma^{-1} \mu_1.$$

The posterior probability then becomes

$$= \frac{\pi_{1} \exp \left\{ \mu_{1}^{T} \Sigma^{-1} x - \frac{1}{2} \mu_{1}^{T} \Sigma^{-1} \mu_{1} \right\}}{\pi_{1} \exp \left\{ \mu_{1}^{T} \Sigma^{-1} x - \frac{1}{2} \mu_{1}^{T} \Sigma^{-1} \mu_{1} \right\} + \pi_{2} \exp \left\{ \mu_{2}^{T} \Sigma^{-1} x - \frac{1}{2} \mu_{2}^{T} \Sigma^{-1} \mu_{2} \right\}}$$

$$= \frac{1}{1 + \frac{\pi_{2}}{\pi_{1}} \exp \left\{ \mu_{2}^{T} \Sigma^{-1} x - \frac{1}{2} \mu_{2}^{T} \Sigma^{-1} \mu_{2} - \mu_{1}^{T} \Sigma^{-1} x + \frac{1}{2} \mu_{1}^{T} \Sigma^{-1} \mu_{1} \right\}}$$

$$= \frac{1}{1 + \exp \left\{ \mu_{2}^{T} \Sigma^{-1} x - \frac{1}{2} \mu_{2}^{T} \Sigma^{-1} \mu_{2} - \mu_{1}^{T} \Sigma^{-1} x + \frac{1}{2} \mu_{1}^{T} \Sigma^{-1} \mu_{1} + \ln \frac{\pi_{2}}{\pi_{1}} \right\}}$$

$$= \frac{1}{1 + \exp \left\{ - \left[(\mu_{1}^{T} - \mu_{2}^{T}) \Sigma^{-1} x + \frac{1}{2} (\mu_{1}^{T} \Sigma^{-1} \mu_{1} - \mu_{2}^{T} \Sigma^{-1} \mu_{2}) + \ln \frac{\pi_{1}}{\pi_{2}} \right] \right\}}$$

$$= \frac{1}{1 + \exp \left\{ - \left[(\mu_{1}^{T} - \mu_{2}^{T}) \Sigma^{-1} x + \frac{1}{2} (\mu_{1}^{T} \Sigma^{-1} \mu_{1} - \mu_{2}^{T} \Sigma^{-1} \mu_{2}) + \ln \frac{\pi_{1}}{\pi_{2}} \right] \right\}}$$

where

$$w^{T} = (\mu_{1}^{T} - \mu_{2}^{T}) \Sigma^{-1},$$

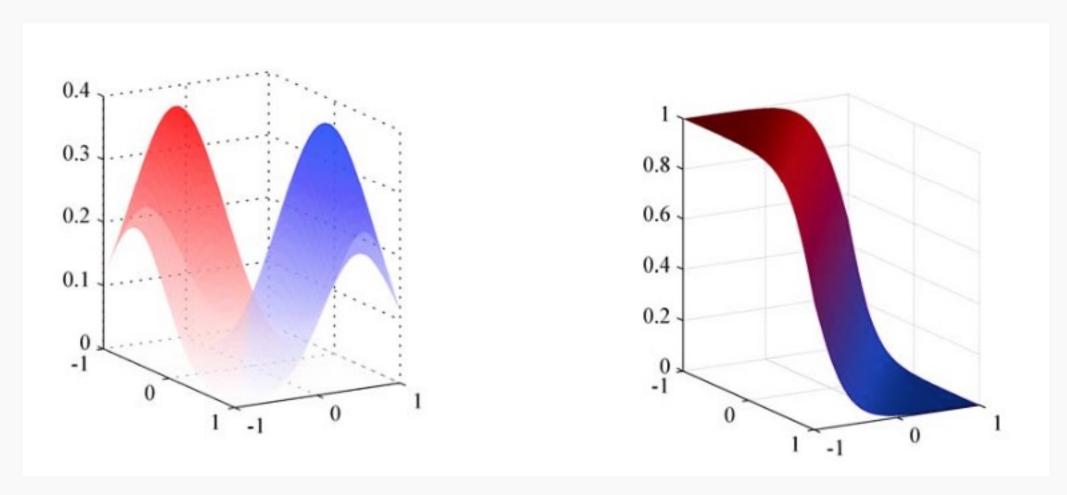
$$w_{0} = \frac{1}{2} (\mu_{1}^{T} \Sigma^{-1} \mu_{1} - \mu_{2}^{T} \Sigma^{-1} \mu_{2}) + \ln \frac{\pi_{1}}{\pi_{2}},$$

and

$$a = \mathbf{w}^T \mathbf{x} + \mathbf{w}_0$$
.

(5-13)



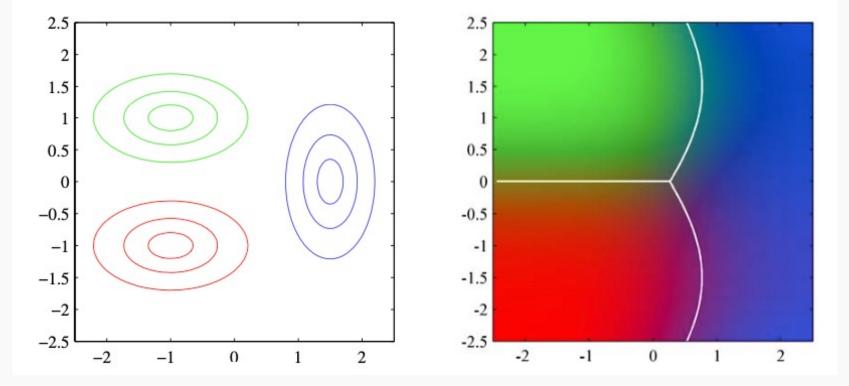


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For the case of K > 2 classes,

$$a_k(x) = \mathbf{w}_k^T x + w_{k0}$$
 where $\mathbf{w}_k = \mathbf{\Sigma}^{-1} \boldsymbol{\mu}_k$ and $w_{k0} = -\frac{1}{2} \boldsymbol{\mu}_k^T \mathbf{\Sigma}^{-1} \boldsymbol{\mu}_k + \ln p(C_k)$.

If each class has its own covariance matrix Σ_k , then $x\Sigma_k^{-1}x$ term will not be vanished.



The parameters can be estimated using MLE if the data set comprises observes of x along with their corresponding class labels.

Consider a binary class dataset, $\{x_n, t_n\}$ where $n = 1, \dots, N$.

- Each class having a Gaussian class-conditional density with a shared Σ .
- $t_n = \{1,0\}$ for C_1 and C_2 , respectively.
- Let the prior class probability be $p(C_1) = \pi$ and $p(C_2) = 1 \pi$.

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For a data point x_n from class C_1 , $t_n = 1$ and hence

$$p(\mathbf{x}_n, C_1) = p(C_1)p(\mathbf{x}_n|C_1) = \pi \mathcal{N}(\mathbf{x}_n|\boldsymbol{\mu_1}, \boldsymbol{\Sigma}).$$

Similarly,

$$p(\mathbf{x}_n, C_2) = p(C_2)p(\mathbf{x}_n|C_2) = (1-\pi)\mathcal{N}(\mathbf{x}_n|\boldsymbol{\mu}_2, \boldsymbol{\Sigma}).$$

Then the likelihood function is given by

$$p(\boldsymbol{t}|\boldsymbol{\pi},\boldsymbol{\mu_1},\boldsymbol{\mu_2},\boldsymbol{\Sigma}) = \prod_{n=1}^{N} [\boldsymbol{\pi} \mathcal{N}(\boldsymbol{x}_n|\boldsymbol{\mu_1},\boldsymbol{\Sigma})]^{t_n} [(1-\boldsymbol{\pi}) \mathcal{N}(\boldsymbol{x}_n|\boldsymbol{\mu_2},\boldsymbol{\Sigma})]^{1-t_n}$$

$$\propto \left(\pi exp\left[-\frac{1}{2}(\boldsymbol{x}_n-\boldsymbol{\mu}_1)^T\boldsymbol{\Sigma}^{-1}(\boldsymbol{x}_n-\boldsymbol{\mu}_1)\right]\right)^{t_n} \left((1-\pi) \exp\left[-\frac{1}{2}(\boldsymbol{x}_n-\boldsymbol{\mu}_2)^T\boldsymbol{\Sigma}^{-1}(\boldsymbol{x}_n-\boldsymbol{\mu}_2)\right]\right)^{1-t_n},$$

where log-likelihood terms that depend on π are

$$\sum_{n=1}^{N} \{t_n \ln \pi + (1 - t_n) \ln (1 - \pi)\}.$$

(5-14)

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Setting the derivative w.r.t. $\pi = 0$,

$$\pi = \frac{1}{N} \sum_{n=1}^{N} t_n = \frac{N_1}{N}$$

where N_1 is the number of data points in class C_1 .

Consider the log-likelihood function terms that depend on μ_1 ,

$$\sum_{n=1}^{N} t_n \ln \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_1, \boldsymbol{\Sigma}) = -\frac{1}{2} \sum_{n=1}^{N} t_n (\mathbf{x}_n - \boldsymbol{\mu}_1)^T \boldsymbol{\Sigma}^{-1} (\mathbf{x}_n - \boldsymbol{\mu}_1) + Const.$$

The derivative w.r.t. μ_1 will have

$$\mu_1 = \frac{1}{N_1} \sum_{n=1}^{N} t_n x_n \,,$$

the mean of all the input vectors \mathbf{x}_n assigned to C_1 . Similarly,

$$\mu_2 = \frac{1}{N_2} \sum_{n=1}^{N} (1 - t_n) x_n.$$



The covariance then can be estimated from the derivative of log-likelihood w.r.t. Σ ,

$$\mathbf{\Sigma} = \frac{N_1}{N} \mathbf{S}_1 + \frac{N_2}{N} \mathbf{S}_2$$

where

$$\mathbf{S}_{1} = \frac{1}{N_{1}} \sum_{n \in C_{1}} (\mathbf{x}_{n} - \boldsymbol{\mu}_{1}) (\mathbf{x}_{n} - \boldsymbol{\mu}_{1})^{T}$$

and

$$S_2 = \frac{1}{N_2} \sum_{n \in C_2} (x_n - \mu_2) (x_n - \mu_2)^T.$$

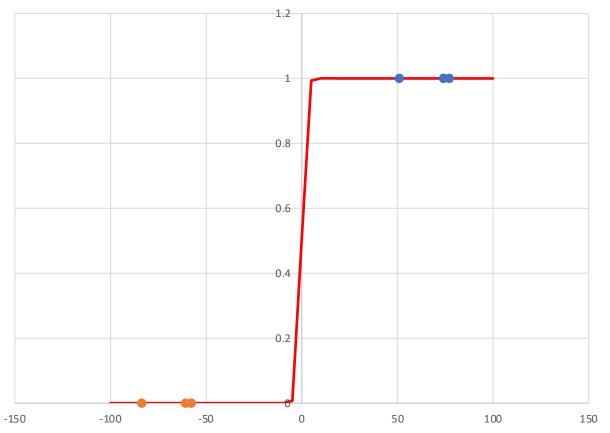


Class	(x_1, x_2)		
1	(1,2), (2,3), (3,4.9)		
-1	(2,1), (3,2), (4, 3.9)		

$$\mathbf{\Sigma} = \begin{bmatrix} 0.667 & 0.967 \\ 0.967 & 1.467 \end{bmatrix}$$

$$\mathbf{\Sigma}^{-1} = \begin{bmatrix} 48.22 & -32.22 \\ -32.22 & 22.22 \end{bmatrix}$$

$$w = (\mu_1 - \mu_2)\Sigma^{-1} = [48.667, -80.444, 54.444]$$
$$\widehat{w} = \frac{w}{|w|} = [0.448, -0.828, 0.560]$$



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- Consider a case of discrete feature values x_i .
- For the simplicity, let $x_i \in \{0,1\}$ and there are D many inputs.
- Assume the naïve Bayes, the feature values are independent.
- The class-conditional distribution is

$$p(\mathbf{x}|C_k) = \prod_{i=1}^{D} \mu_{ki}^{x_i} (1 - \mu_{ki})^{1 - x_i}.$$

• Substituting into the quantities a_k ,

$$a_k(\mathbf{x}) = \sum_{n=1}^{D} \{x_i \ln \mu_{ki} + (1 - x_i) \ln(1 - \mu_{ki})\} + \ln p(C_k)$$

• which is the linear function of the input values x_i .



Each class C_k is described by its own linear model

$$y_k(\mathbf{x}) = \mathbf{w}_k^T \mathbf{x} + \mathbf{w}_{k0} = \widetilde{\mathbf{w}}_k^T \widetilde{\mathbf{x}}$$

where k = 1, ..., K, $\widetilde{\boldsymbol{w}}_k = \left(w_{k0}, \boldsymbol{w}_k^T\right)^T$, and $\widetilde{\boldsymbol{x}}$ is the corresponding augmented input vector $(1, \boldsymbol{x}^T)^T$. In the matrix formation, the expression becomes much simpler as below $\boldsymbol{y}(\boldsymbol{x}) = \widetilde{\boldsymbol{W}}^T \widetilde{\boldsymbol{x}}$.

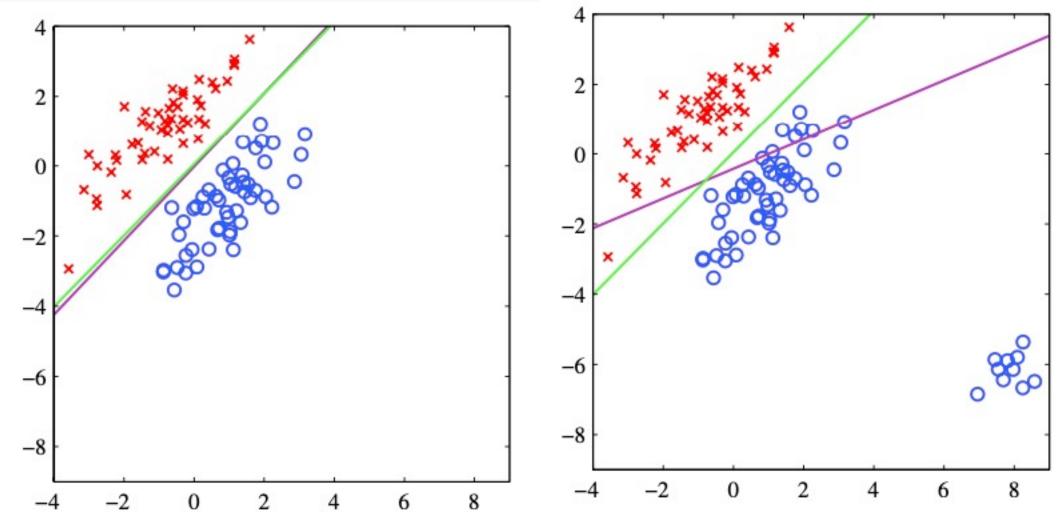
Consider a training data set $\{x_n, t_n\}$ where n = 1, ..., N, the sum-of-squares error function

$$E_D(\widetilde{\boldsymbol{W}}) = \frac{1}{2}\operatorname{Tr}\left\{\left(\widetilde{\mathbf{X}}\widetilde{\boldsymbol{W}} - \boldsymbol{T}\right)^T\left(\widetilde{\mathbf{X}}\widetilde{\boldsymbol{W}} - \boldsymbol{T}\right)\right\}$$

can set the derivative w.r.t. $\widetilde{\boldsymbol{W}}$ to zero to have

$$\widetilde{\boldsymbol{W}} = \left(\widetilde{\boldsymbol{X}}^T \widetilde{\boldsymbol{X}}\right)^{-1} \widetilde{\boldsymbol{X}} \boldsymbol{T}.$$







- 5.0. Lecture 4 Review
- 5.1. Introduction
- 5.2. Discriminant Functions
 - 5.2.1. Linear Discriminant Analysis (LDA)
 - 5.2.2. Perceptron
- 5.3. Probabilistic Generative Models MLE
- 5.4. Probabilistic Discriminative Models Logistic Regression

Consider a binary class problem.

Assume the posterior probability of class C_1 can be written as a logistic sigmoid acting on a linear function of the feature vector ϕ ,

$$p(C_1|\phi) = y(\phi) = \sigma(\mathbf{w}^T\phi)$$

with $p(C_2|\phi) = 1 - p(C_1|\phi)$. This model is known as *logistic regression*.

The parameters of the logistic regression model can be determined using maximum likelihood,

$$\frac{d\sigma}{da} = \sigma(1 - \sigma).$$



For a data set $\{\phi_n, t_n\}$, where

- $t_n \in \{0,1\}$
- $\phi_n = \phi(x_n)$ with n = 1, ..., N.

The likelihood function can be written

$$p(t|w) = \prod_{n=1}^{N} y_n^{t_n} \{1 - y_n\}^{1 - t_n}$$

where $t = (t_1, ..., t_N)^T$ and $y_n = p(C_1 | \phi_n)$.

The *cross-entropy* error function is the negative log-likelihood in the form

$$E(\mathbf{w}) = -\ln p(\mathbf{t}|\mathbf{w}) = -\sum_{n=1}^{N} \{t_n \ln y_n + (1 - t_n) \ln(1 - y_n)\}$$

where $y_n = \sigma(\mathbf{w}^T \phi_n)$ and the gradient of the error function w.r.t. w is

$$\nabla E(\mathbf{w}) = \sum_{n=1}^{N} (y_n - t_n) \phi_n.$$

The maximum likelihood solution occurs when the hyperplane corresponding to $\sigma = 0.5$, equivalent to $\mathbf{w}^T \phi = 0$.



For the precise measurement, the error function can be minimized by an efficient iterative technique based on the *Newton-Raphson* iterative optimization, which uses a local quadratic approximation to the log-likelihood function in the form of

$$\mathbf{w}^{(new)} = \mathbf{w}^{(old)} - \mathbf{H}^{-1} \nabla E(\mathbf{w})$$

where **H** is the Hessian matrix whose elements are the second derivatives of E(w) w.r.t. w:

$$H = \nabla \nabla E(\mathbf{w}) = \nabla \left(\sum_{n=1}^{N} (\mathbf{w}^{T} \phi_{n} - t_{n}) \phi_{n} \right)$$

$$= \nabla (\boldsymbol{\phi}^T \boldsymbol{\phi} \boldsymbol{w} - \boldsymbol{\phi}^T \boldsymbol{t}) = \boldsymbol{\phi}^T \boldsymbol{\phi}.$$

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Alternatively, we can update the cross-entropy error function as

$$\boldsymbol{H} = \nabla \left(\boldsymbol{\phi}^{T} (\boldsymbol{y} - \boldsymbol{t}) \right) = \sum_{n=1}^{N} y_{n} (1 - y_{n}) \phi_{n} \phi_{n}^{T} = \boldsymbol{\phi}^{T} \boldsymbol{R} \boldsymbol{\phi}$$

where **R** is the $N \times N$ weight matrix with elements $R_{nn} = y_n(1 - y_n)$. The error function is not quadratic longer but is not constant.

The Newton-Raphson update formula for the logistic regression model then becomes

$$w^{new} = w^{old} - (\phi^T R \phi)^{-1} \phi^T (y - t)$$

$$= (\phi^T R \phi)^{-1} \{ \phi^T R \phi w^{(old)} - \phi^T (y - t) \}$$

$$= (\phi^T R \phi)^{-1} \phi^T R z$$

where **z** is an *N*-dimensional vector with elements

$$z = \phi w^{(old)} - R^{-1}(y - t).$$



w0	1	-1	1	0.577350269	-0.57735027	0.577350269	
likelihood	-2.93486703						
Z	2	2	2.9	0	0	0.9	
sigmoid	0.880797078	0.880797078	0.947846437	0.5	0.5	0.710949503	
У	1	1	1	0	0	1	
grad	-1.4203901	-4.82972856	-3.42113599				
Н	0.964921047	2.535282692	2.318643613	H_inv	9.296241883	-2.81430131	-0.36016317
	2.535282692	7.507874965	6.772426941		-2.81430131	1.979349879	-0.9930948
	2.318643613	6.772426941	6.927476275		-0.36016317	-0.9930948	1.235767788
Delta	1.620188714	-2.16480455	1.080220871				
w_update	2.620188714	-3.16480455	2.080220871	0.568951952	-0.6872107	0.451702475	

After 6 iterations:

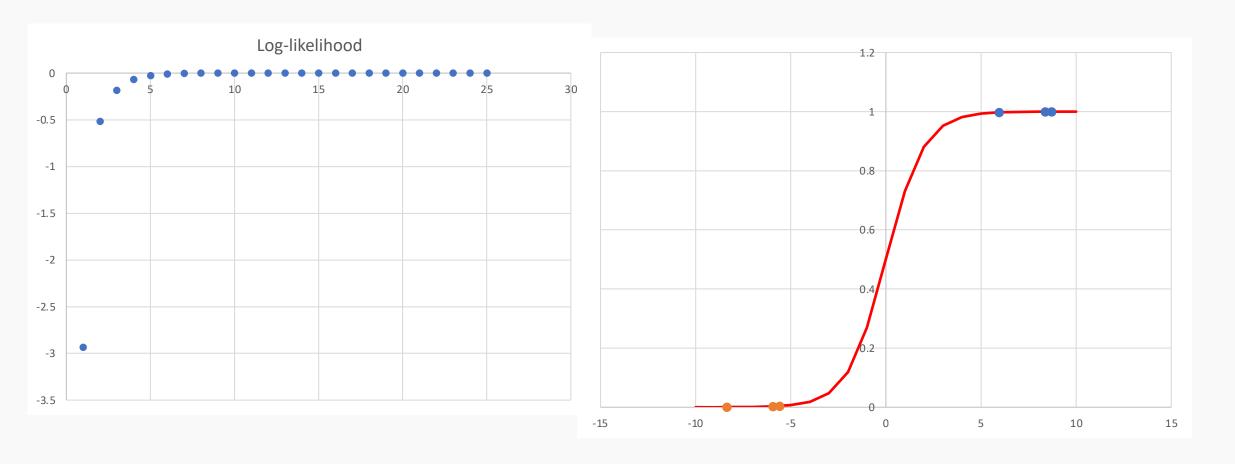
w_update	5.713665154	-8.53726067	5.768785273	0.484958884	-0.72461726	0.489637316	
likelihood	-0.00960079						
Z	8.713975027	5.945499627	8.368930973	-5.59207092	-8.36054632	-5.93711497	
sigmoid	0.999835753	0.99738924	0.99976809	0.00371346	0.000233862	0.002632685	
У	1	1	1	0	0	0	
grad	-0.00357309	-0.01257775	-0.00515152				
Н	0.009559251	0.024671452	0.02368409	H_inv	949.3811091	-344.421922	17.81857682
	0.024671452	0.071581703	0.069124327		-344.421922	263.5807941	-135.555362
	0.02368409	0.069124327	0.074231849		17.81857682	-135.555362	134.0146649
Delta	0.848035592	-1.38628593	0.950934258				

$$\nabla E = (t - \sigma(\mathbf{w}^T \mathbf{x}))\mathbf{x}$$

$$\boldsymbol{H} = \begin{bmatrix} \frac{\partial^2 \nabla E}{\partial x_0^2} & \frac{\partial^2 \nabla E}{\partial x_0 \partial x_1} & \frac{\partial^2 \nabla E}{\partial x_0 \partial x_2} \\ \frac{\partial^2 \nabla E}{\partial x_1 \partial x_0} & \frac{\partial^2 \nabla E}{\partial x_1^2} & \frac{\partial^2 \nabla E}{\partial x_1 \partial x_2} \\ \frac{\partial^2 \nabla E}{\partial x_2 \partial x_0} & \frac{\partial^2 \nabla E}{\partial x_2 \partial x_1} & \frac{\partial^2 \nabla E}{\partial x_2^2} \end{bmatrix}$$

$$\mathbf{\Delta} = \mathbf{H}^{-1} \mathbf{\nabla} E$$

$$w^{(new)} = w^{(old)} + \Delta$$



The posterior probabilities are given by a softmax transformation of linear functions of the feature variables

$$p(C_k|\phi) = y_k(\phi) = \frac{\exp(\mathbf{w}_k^T \phi)}{\sum_j \exp(\mathbf{w}_k^T \phi)}.$$

The derivative of y_k w.r.t. the activation function $a_k = \mathbf{w}_k^T \phi$ is

$$\frac{\partial y_k}{\partial a_i} = y_k \big(I_{kj} - y_j \big)$$

where I_{kj} are the elements of the identity matrix.



The target variables t_{nk} form a $N \times K$ matrix T, can express the likelihood function as

$$p(T|\mathbf{w_1}, ..., \mathbf{w}_k) = \prod_{n=1}^{N} \prod_{k=1}^{K} p(C_k|\phi_n)^{t_{nk}} = \prod_{n=1}^{N} \prod_{k=1}^{K} y_{nk}^{t_{nk}}$$

where $y_{nk} = y_k(\phi_n)$.

The negative logarithm gives the error function as

$$E(\mathbf{w_1}, ..., \mathbf{w}_K) = -\ln p(\mathbf{T}|\mathbf{w_1}, ..., \mathbf{w}_K) = -\sum_{n=1}^{N} \sum_{k=1}^{K} t_{nk} \ln y_{nk}$$

which is known as the *cross-entropy* error function for the multiclass classification problem.

The gradient of the error function w.r.t. one of the parameter vectors \mathbf{w}_j result the derivative of the softmax function,

$$\nabla_{\mathbf{w}_j} E(\mathbf{w}_1, \dots, \mathbf{w}_K) = \sum_{n=1}^N (y_{nj} - t_{nj}) \phi_n$$

and the parameter vectors can be found using via the iterative least square following Newton-Raphson method where the Hessian matrix is

$$\nabla_{\mathbf{w}_k} \nabla_{\mathbf{w}_j} = E(\mathbf{w}_1, \dots, \mathbf{w}_K) = -\sum_{n=1}^N y_{nk} (I_{kj} - y_{nj}) \phi_n \phi_n^T.$$