

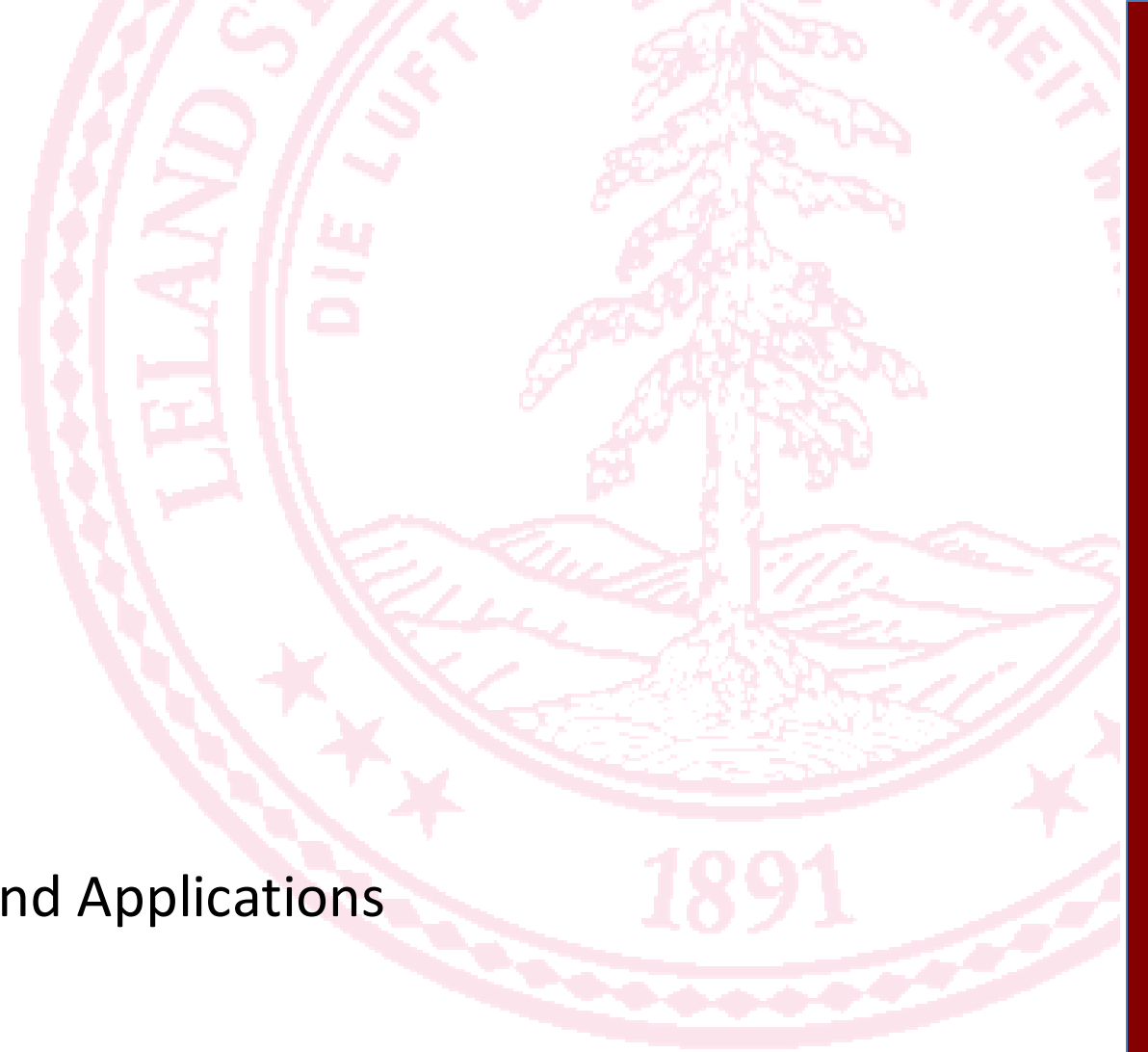


## Lecture 13: Visual Bag of Words

# Spatial pyramid matching

Juan Carlos Niebles and Jiajun Wu

CS131 Computer Vision: Foundations and Applications

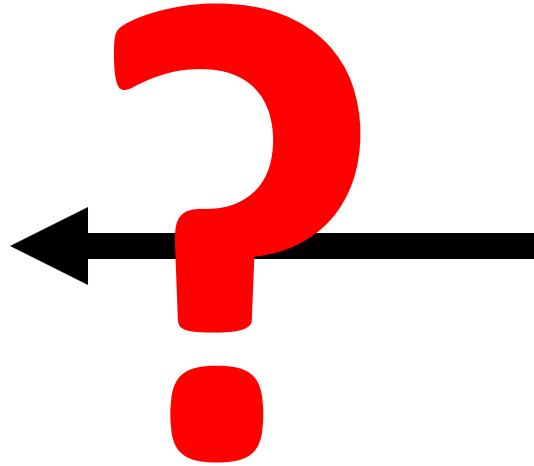


# What will we learn today?

- Spatial pyramid matching



# What about spatial info?



# Pyramids

- Very useful for representing images.
- Pyramid is built by using copies of an image at multiple resolutions.
- Each level in the pyramid is  $1/2$  of the size of previous level.
- The lowest level is of the highest resolution.
- The highest level is of the lowest resolution.

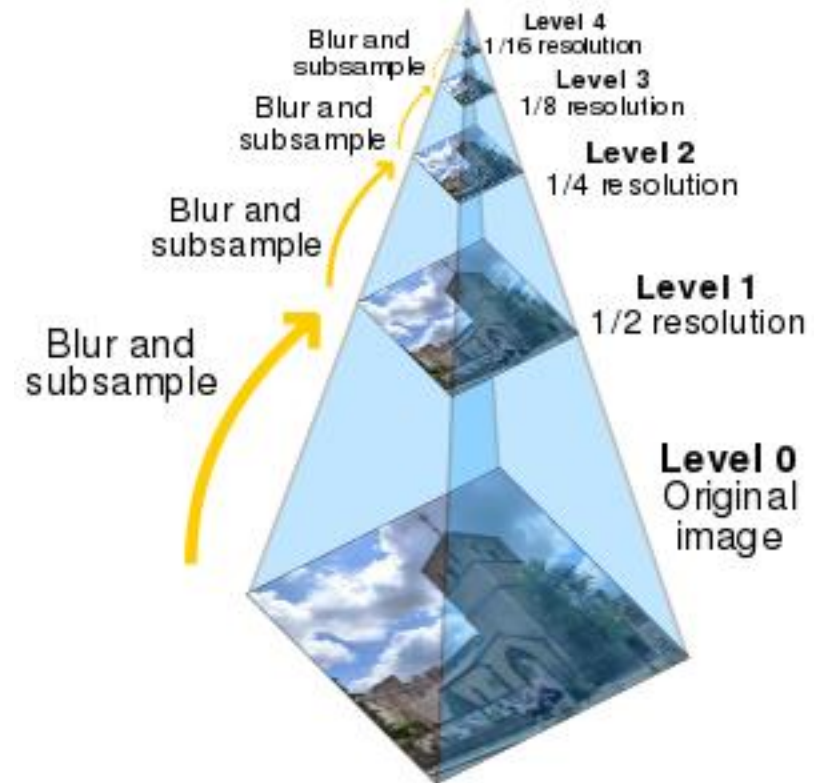
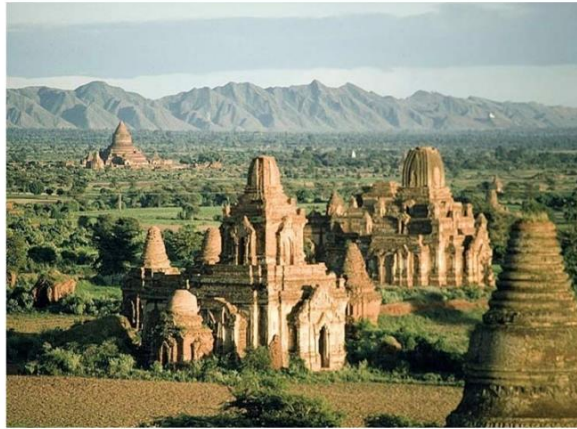
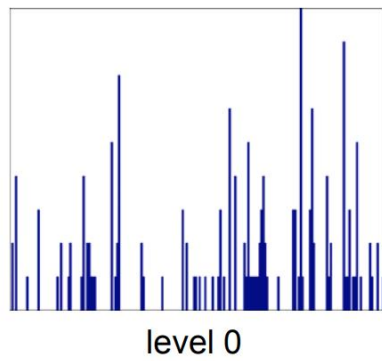


Image source: cmglee at commons.wikimedia.org

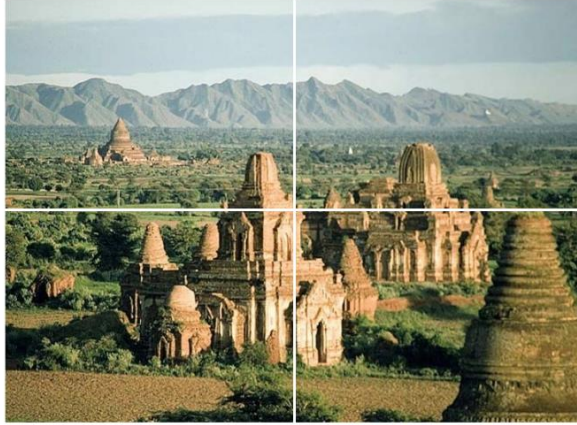
# Bag of words + pyramids



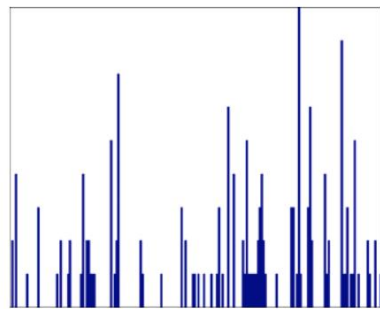
Locally orderless  
representation at  
several levels of  
spatial resolution



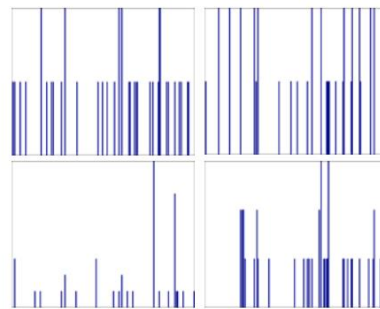
# Bag of words + pyramids



Locally orderless  
representation at  
several levels of  
spatial resolution



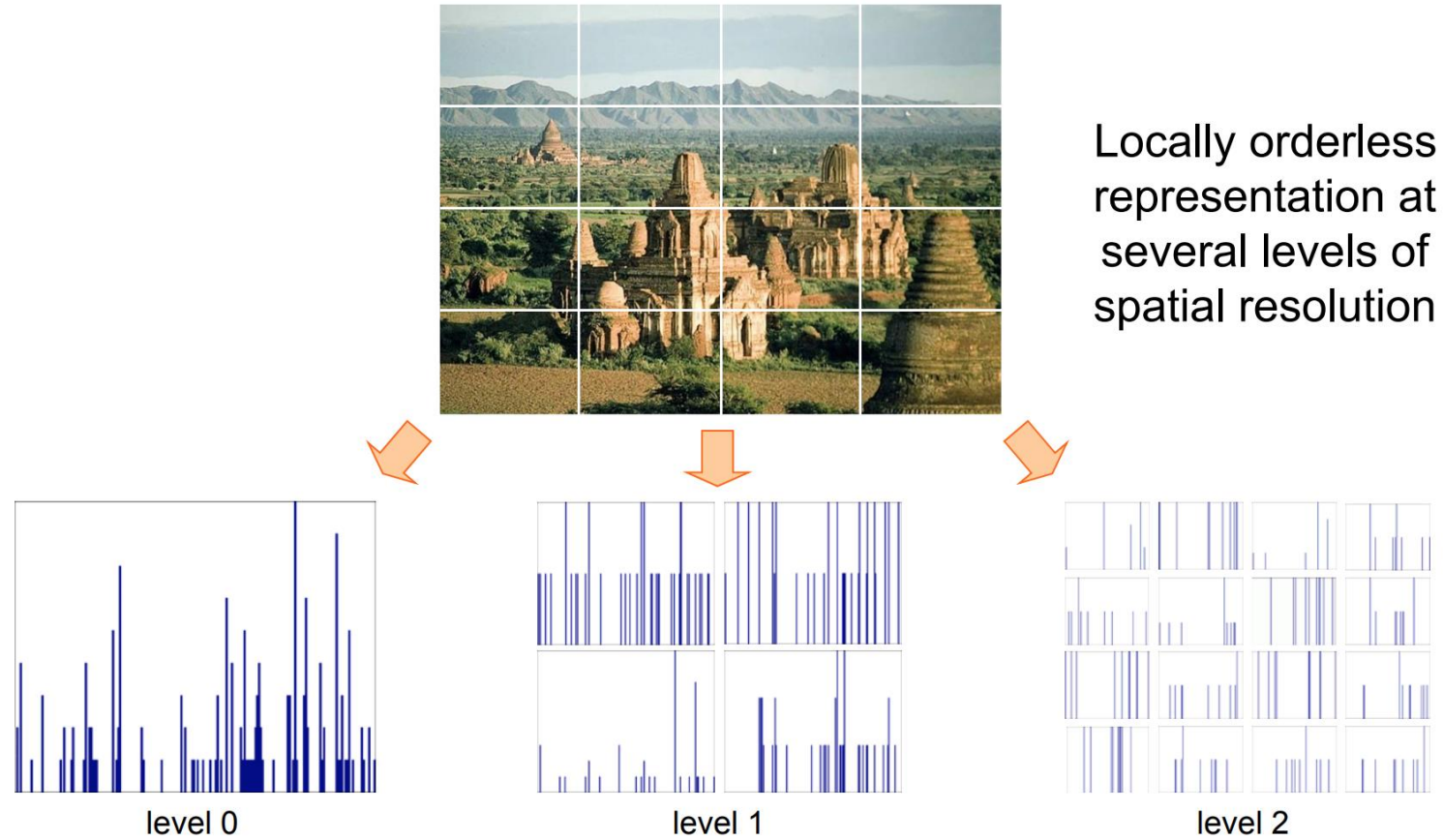
level 0



level 1

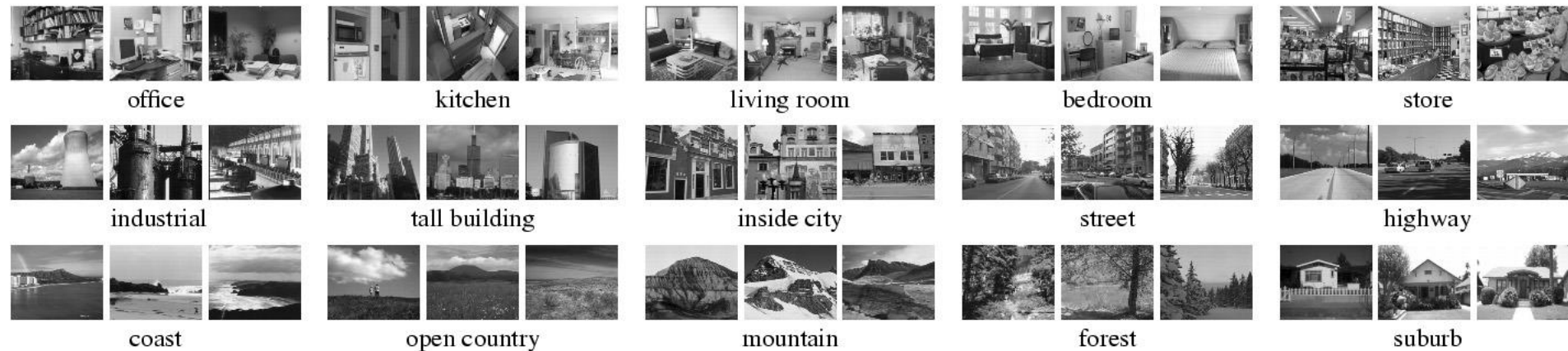


# Bag of words + pyramids





# Scene category dataset



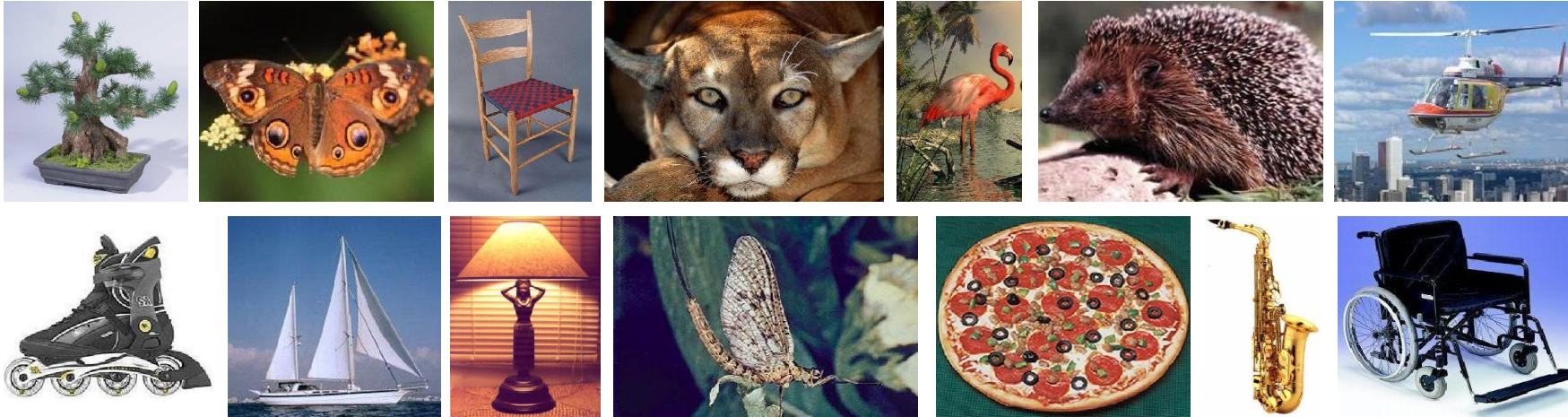
Multi-class classification results  
(100 training images per class)

	Weak features (vocabulary size: 16)		Strong features (vocabulary size: 200)	
Level	Single-level	Pyramid	Single-level	Pyramid
0 ( $1 \times 1$ )	45.3 $\pm$ 0.5		72.2 $\pm$ 0.6	
1 ( $2 \times 2$ )	53.6 $\pm$ 0.3	56.2 $\pm$ 0.6	77.9 $\pm$ 0.6	79.0 $\pm$ 0.5
2 ( $4 \times 4$ )	61.7 $\pm$ 0.6	64.7 $\pm$ 0.7	79.4 $\pm$ 0.3	<b>81.1</b> $\pm$ 0.3
3 ( $8 \times 8$ )	63.3 $\pm$ 0.8	<b>66.8</b> $\pm$ 0.6	77.2 $\pm$ 0.4	80.7 $\pm$ 0.3



# Caltech101 dataset

[http://www.vision.caltech.edu/Image\\_Datasets/Caltech101/Caltech101.html](http://www.vision.caltech.edu/Image_Datasets/Caltech101/Caltech101.html)



Multi-class classification results (30 training images per class)

	Weak features (16)		Strong features (200)	
Level	Single-level	Pyramid	Single-level	Pyramid
0	15.5 $\pm$ 0.9		41.2 $\pm$ 1.2	
1	31.4 $\pm$ 1.2	32.8 $\pm$ 1.3	55.9 $\pm$ 0.9	57.0 $\pm$ 0.8
2	47.2 $\pm$ 1.1	49.3 $\pm$ 1.4	63.6 $\pm$ 0.9	<b>64.6</b> $\pm$ 0.8
3	52.2 $\pm$ 0.8	<b>54.0</b> $\pm$ 1.1	60.3 $\pm$ 0.9	64.6 $\pm$ 0.7

Slide credit: Svetlana Lazebnik



# Summary

- Spatial pyramid matching
  - Motivation
  - Method
  - Results on scene classification

