

Lecture 16: Tracking Feature tracking

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CS131 Computer Vision: Foundations and Applications

- What will we learn today?
- Feature Tracking
 - Problem statement
 - Overview

Reading: [Szeliski] Chapters: 8.4, 8.5

[Fleet & Weiss, 2005]

http://www.cs.toronto.edu/pub/jepson/teaching/vision/2503/opticalFlow.pdf

Problem statement

Image sequence



Slide credit: Yonsei Univ.

Problem statement

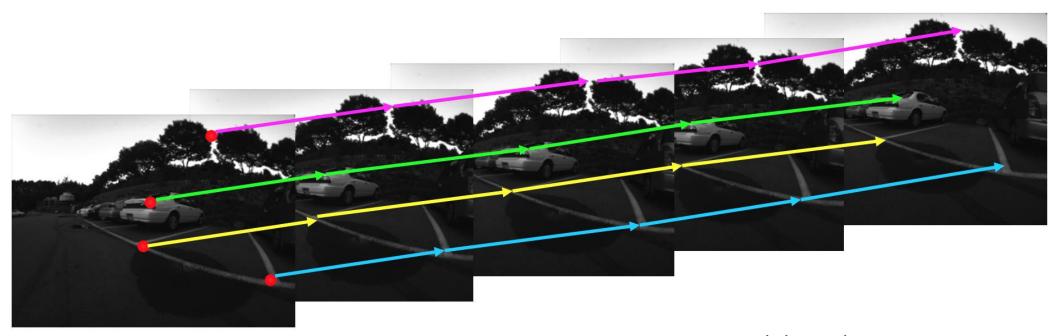
Feature point detection



Slide credit: Yonsei Univ.

Problem statement

Feature point tracking



Slide credit: Yonsei Univ.

Single object tracking





Multiple object tracking

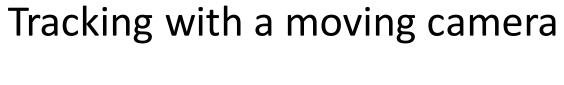


Tracking with a fixed camera







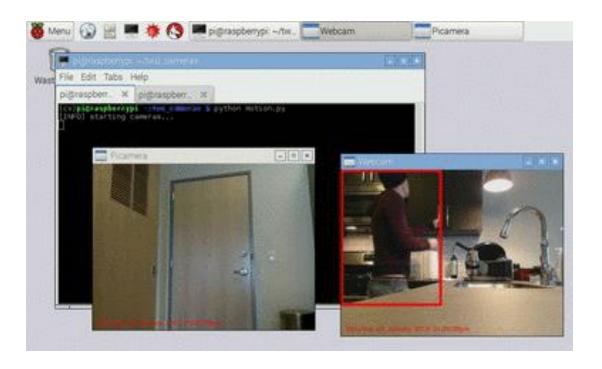








Tracking with multiple cameras



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Challenges in Feature tracking

- Figure out which features can be tracked
 - Efficiently track across frames
- Some points may change appearance over time
 - e.g., due to rotation, moving into shadows, etc.
- Drift: small errors can accumulate as appearance model is updated
- Points may appear or disappear.
 - need to be able to add/delete tracked points.

What are good features to track?

- Intuitively, we want to avoid smooth regions and edges. But is there a more is principled way to define good features?
- What kinds of image regions can we detect easily and consistently? Think about what you learnt earlier in the class.

What are good features to track?

- Can measure "quality" of features from just a single image.
- Hence: tracking Harris corners (or equivalent) guarantees small error sensitivity!

Motion estimation techniques

Optical flow

Recover image motion at each pixel from spatio-temporal image brightness
 variations (optical flow)

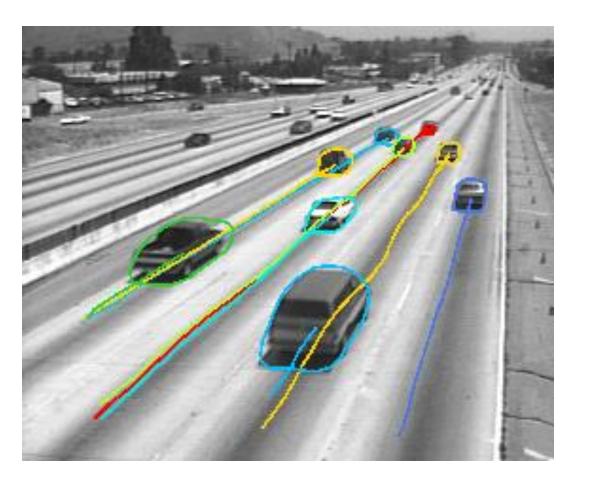
Feature-tracking

 Extract visual features (corners, textured areas) and "track" them over multiple frames



Optical flow can help track features

Once we have the features we want to track, Lucas-Kanade or other optical flow algorithms can help track those features



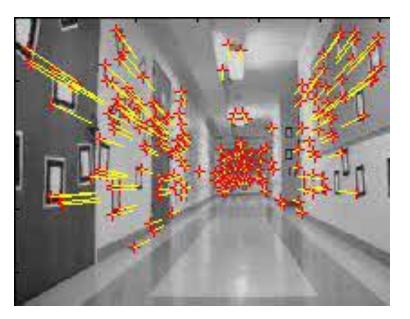
Feature-tracking

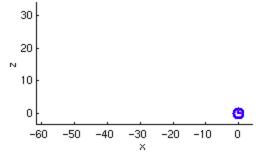




Feature-tracking







Courtesy of Jean-Yves Bouguet – Vision Lab, California Institute of Technology

Summary

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