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Standard

Division

Roll

Subject

DSA & Placement

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C++ STL

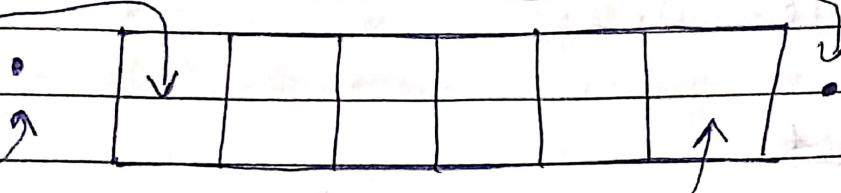
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[take u forward if u like]

`begin()` → start on the array

• `end()` → end of the array after the point



• `rbegin()` → end of the array the point

• `rend()` → start of the array the point

`end` : right after the last element

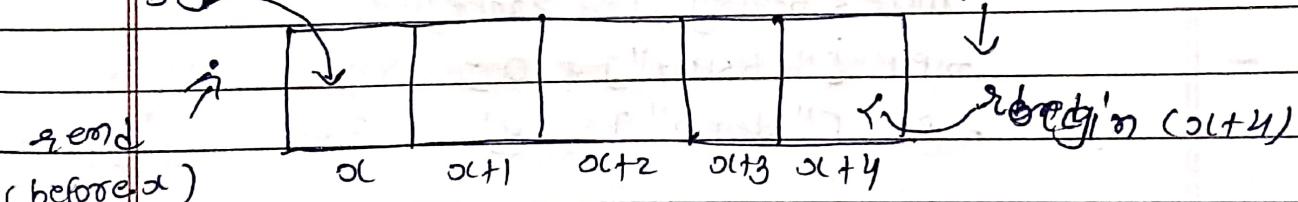
`rend` : right before the start element

`rbegin` : Array of the last element

`begin` : Array of the start element

`begin(x)`

`end(after x+4)`



`size` : size of the array

`front` : Point first element

`back` : Point last element

• Set

→ set store unique element on A ccreding order
 $O(\log N)$

* unordered set

- element stored in front order
- every time random order stored
- unique O(1).

* multiset

- you can add all type element in sorted order. NOT unique O(log N)

* map (Container)

- map only stores unique (key maintains a linearly increasing order)

```
map<string, int> mpp;  
mpp["Akash"] = 10;  
mpp["demo"] = 20;
```

```
for (auto it : mpp) {
```

```
cout << it.first << " " << it.second << "
```

```
}
```

* unordered map

- does not stores in any order
- O(1) in almost all cases & O(N) worst case
- unordered-map NOT define a pair

* Stack & queue

- stack means LIFO (last in first out)
- queue means FIFO (first in first out)
- queue all operation O(1) but only pop is
to time taken O(n)

* Priority queue

- store all in sorted order & does all operation
perform in $O(\log N)$
- duplicated values are allow

* List

- list are used to get element on side like
front, back, top... etc...
- It make doubly linked list

Time & Space Complexity

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- In here three type of complexity available
- 1) Big O notation
 - 2) Theta O
 - 3) Omega O

• Constant time - $O(1)$	$O(N!)$
• Linear time - $O(n)$	$O(2^n)$
• Logarithmic time - $O(\log n)$	$O(n^3)$
• Quadratic time - $O(n^2)$	$O(n^2)$
• Cubic time - $O(n^3)$	$O(n \log n)$
	$O(n)$
	$O(\log n)$
	$O(1)$

★ PF stuck in TLE at last 30 min.

→ 10^8 operation rule → most of the modern machine perform 10^8 operations

$\leq [10 \dots 12]$	-	$O(n^1)$
$\leq [15 \dots 18]$	-	$O(2^n \alpha n^2)$
≤ 100	-	$O(n^4)$
≤ 400	-	$O(n^3)$
≤ 2000	-	$O(n^2 \alpha \log n)$
$\leq 10^4$	-	$O(n^2)$
$\leq 10^6$	-	$O(n \log n)$
$\leq 10^8$	-	$O(n^2), O(\log n)$

~~Algo~~ Arrays

[Arrays - LB sheet]
string - LB sheet

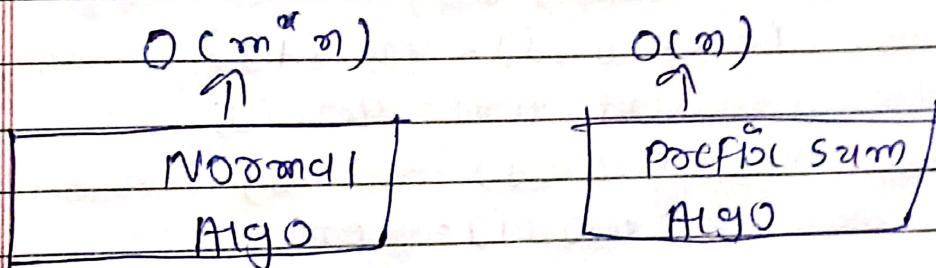
→ Some important Algorithms in Arrays

1. Prefix sum Algo

→ when ever you can sum whole Arrays then you can use prefix sum Algo.

→ A normal Algorithms take $O(m^2n)$ time to perform m number of queries to find range sum on n size array

→ Prefix sum Algorithm take $O(n)$ time

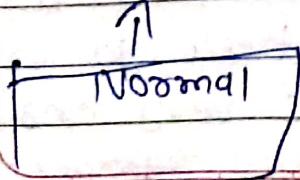


For `for (int i=1; i<n; i++)
A[i] = A[i] + A[i-1];`

② Kadane's Algorithm (maximum sum subarray)

$O(n^2) \rightarrow O(n)$

$O(1)$



Sorting

[GFG Article]

Sorting Algorithms

- 1. Selection Sort
2. Insertion Sort
3. Bubble Sort
4. merge sort
5. Quick Sort
6. counting sort

selection Sort

```
FOR (int i=0; i<n-1; i++)  
    FOR (int j=i+1; j<n; j++)  
        IF (arr[j] < arr[i])  
            int temp = arr[i];  
            arr[j] = arr[i];  
            arr[i] = temp;
```

Time: $O(N^2)$

Space: $O(1)$

why we use selection sort ?

selection sort can be good at checking if everything is already sorted. it is also good to use when memory space is limited.

This is because unlike other sorting algorithms, selection sort doesn't go around swapping things until the very end, resulting in less temporary storage space.

② Insertion Sort

```
void insertion (int arr[], int n) {
    int key;
```

```
for (int i=1; i<n; i++) {
    key = arr[i];
    j = i-1;
```

```
while (j >= 0 && arr[j] > key) {
```

```
    arr[j+1] = arr[j];
    j = j-1;
```

g

$arr[j+1] = key$

time: $O(N^2)$

space: $O(1)$

→ Insertion sort is used when number of elements is small. It can also be useful when input array is almost sorted, only few elements are misplaced or complete big Array.

③ Bubble Sort

```
void bubble (int arr[], int n) {
```

```
    for (int i=0; i<n-1; i++)
```

```
        for (int j=0; j<n-i-1; j++)
```

```
            if (arr[j] > arr[j+1])
```

```
                swap (arr[j], arr[j+1]);
```

g

Time: $O(N^2)$

Space: $O(1)$

Best case: $O(N)$, $O(1)$

- Due to its simplicity, bubble sort is often used to introduce the concept of a sorting algorithm.
- In computer graphics, it is popular for its capability to detect a very small error (like a swap of just two elements) in almost-sorted arrays and fix it with just linear complexity.

④

merge sort

```
void merge(int arr[], int start, int end)
{
    if (start < end) {
        int mid = (start + end) / 2;
        mergesort(arr, start, mid);
        mergesort(arr, mid + 1, end);
        merge(arr, start, mid, end);
    }
}
```

3
3

Time: $O(n \log n)$

Space: $O(n)$

- It is based on the divide and conquer strategy. Merge sort continuously cuts down a list into multiple sublists until each has only one item, then merges those sublists into sorted lists.

(5)

Quick Sort

```
void quick( int arr[], int low, int high ) {  
    if (low < high) {
```

```
        int pi = partition( arr, low, high );
```

```
        quicksort( arr, low, pi - 1 );
```

```
        quicksort( arr, pi + 1, high );
```

Best	average	worst
Time: $n \log n$	$n \log n$	$O(n^2)$

(6)

Counting Sort

Time: $O(n+k)$

Space: $O(n+k)$

★ Searching

① Linear Search

```
int Linear (int arr[], int n, int key)
```

{

```
for (int i=0; i<n; i++) {
```

```
    if (arr[i] == key)
```

```
        return i;
```

```
    }
```

}

Time: O(n)
Space: O(1)

→ Linear search is usually very simple to implement.
It is practical when the list has only a few elements or when performing a single search in an unordered list.

→ When many values have to be searched in the same list, it often pays to pre-process the list in order to use a faster method.

② Binary Search

[Additional reading]

```
int Binary (int arr[], int n, int key) {
```

```
    int start = 0;
```

```
    int end = n;
```

```
    while (start < end) {
```

```
        int mid = (start + end) / 2;
```

```
        if (arr[mid] == key)
```

```
            return mid;
```

```
else if (arr[mid] > key)
```

```
end = mid - 1;
```

```
else
```

```
start = mid + 1
```

```
return -1;
```

Best: $O(1)$

Ave: $O(\log n)$

Worst: $O(\log n)$

Space: $O(1)$

* Some questions on Binary Search

① Binary search on reverse sorted array

arr[]:	0	1	2	3	4	5	6
	20	17	15	14	13	12	8

Search = 13

```
if (arr[mid] == key)
```

```
return mid;
```

```
else if (arr[mid] < key)
```

```
end = mid - 1;
```

```
else
```

```
start = mid + 1;
```

②

Order not known search

→ You can check array are sorted ascending or descending order

$\text{if } (\text{arr}[i] < \text{arr}[i+1])$

ascending

else

③ First/last occurrence of an element

	0	1	2	3	4	5	6
arr[]:	2	4	10	10	10	18	20

Search = 10 First Last

First -

ans = mid;
end = mid - 1;

Last -

ans = mid;
start = mid + 1;

④ Count of an element in a sorted array

	0	1	2	3	4	5	6
arr[]:	2	4	10	10	10	18	20

Search = 10 start end

return (end - start) + 1

$$(4 - 2) + 1 = 2 + 1 = 3$$

⑤ Number of times a sorted array is rotated

	0	1	2	3	4	5	6	7
arr[]:	11	12	15	18	2	5	6	8

→ Number of times array rotated by depends on index of minimum elements.

11 12 15
sorted

18 2 5 6 8
unsorted

1. find mid
2. Rotate & move

$\text{int Paev} = (\text{mid} + n - 1) \% n;$

$\text{int next} = (\text{mid} + 1) \% n;$

if ($\text{nums}[\text{mid}] \leq \text{nums}[\text{Paev}] \&\& \text{nums}[\text{mid}] \leq \text{nums}[\text{next}]$)
return $\text{nums}[\text{mid}]$;

else if ($\text{nums}[\text{mid}] > \text{nums}[\text{end}]$)

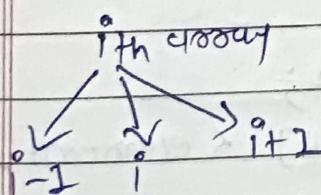
start = $\text{mid} + 1$;

else

end = $\text{mid} - 1$;

⑥ nearest sorted Array

arr [] :	5	10	30	20	40
----------	---	----	----	----	----



if ($\text{element} == \text{arr}[\text{mid}] \&\& \text{element} == \text{arr}[\text{mid}-1]$
 $\&\& \text{element} == \text{arr}[\text{mid}+1]$)
return mid;

$$\begin{array}{r} \text{ceil } 8 \\ 7+8 \\ \hline 1000 \end{array}$$

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(7)

Find Floor of an element in a sorted array

arr[] =	[1	2	3	4	8	10	10	10	12]
arr[] = 5											

Floor = greatest element smaller than 5

Output: ~~4~~ 4

int res = -1;

if (arr[mid] < element)

res = mid / arr[mid];

start = mid + 1;

else if (arr[mid] > element)

end = mid - 1;

(8)

Find ceil of an element in a sorted array

Output: 8

int res = -1;

if (arr[mid] > element)

res = mid;

end = mid - 1;

else if (arr[mid] < element)

start = mid + 1;

return res;

(9)

Neat Alphabetical element

I/P.	arr [] :	a	c	F	h		key = F
------	-----------	---	---	---	---	--	---------

O/P :- h

char res = arr [start]

if (arr [mid] == key)

start = mid + 1;

else if (arr [mid] > key)

res = key [mid];

end = mid - 1;

else

start = mid + 1;

return res;

(10)

Find position of an element in an infinite
[Sorted array]

I/P	arr [] :	0	1	2	3	4	...	5
		1	2	3	4	5	...	5

key = 7

start end

int start = 0;

int end = 1;



while (key > arr [mid]) {

low = high;

high = high * 2;

3 2 after

B/S (low, current end)

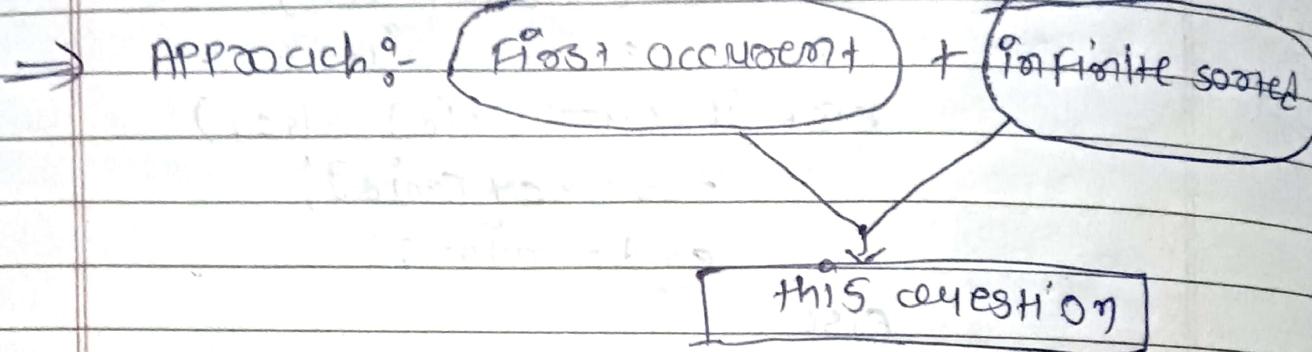
low = start
high = end

- (11) index of first 1 in a Binary sorted infinite array

I/P arr[]: 0 0 0 1 1 1 1 ... ∞

0	1	2	3	4	5	
↑	↑					start end

O/P:- 3



while ($\text{key} > \text{arr}[\text{end}]$) {

$\text{end} = \text{mid} + 1;$

y

$\text{ans} = \text{mid};$

$\text{end} = \text{mid} - 1;$

- (12) minimum difference element in sorted array

I/P arr[]: 4 6 10

Key = 7	4	6	10	6
				Output: $4 - 7 = 3$

$$6 - 7 = 1$$
$$10 - 7 = 3$$

→ If key present then return key otherwise go to (Floor Approach)

→ Other Approach:-

`while (start <= end) {`

$\rightarrow \text{int mid} = \text{start} + (\text{end} - \text{start}) / 2;$

~~because & for this
type to stop
integer overflow~~

`if (key == arr[mid])`

`return key;`

`else if`

`abs (arr [start - key]);`

`abs (arr [end - key]);`

(13) Binary search on Answer concept

If sorted array \rightarrow BS

If Unsorted array \rightarrow BS

How ?

↓
see all neat
explanation,

(14) Peak element

0	1	2	3
I/P arr[] : 5	10	20	15

$10 \div 2$

\rightarrow peak means both of side element are smaller than current element

10 \swarrow \searrow 20 15
this is peak element

`int start = 0;`

`int end = size - 1;`

while ($start \leq end$) {

 int mid = start + (end - start) / 2;

 if ($mid > 0 \ \& \ mid \neq n$) {

 if ($cross[mid] > cross[mid - 1] \ \& \ cross[mid] > cross[mid + 1]$)

 return mid;

 } else if ($cross[mid - 1] > cross[mid]$)

 end = mid - 1;

 } else

 start = mid + 1;

}

 else if ($mid == 0$) { (- first element)

 if ($cross[0] > cross[1]$)

 return cross[0];

 } else

 return cross[1];

 } else if ($mid == size - 1$) {

 if ($cross[size - 1] > cross[size - 2]$)

 return size - 1;

 check last

 element else

 return size - 2;

3

(15) find maximum element in Bitonic Array

	0	1	2	3	4	5
I/P arr[] :	1	3	8	12	4	2

O/P :- 12

P 5 10 15 20

→ Bitonic Array means : monotonically increasing & decreasing

→ Approach:- same like previous question
(peak element)

(16) search An element in Bitonic Array

	0	1	2	3	4	5
I/P arr[] :	1	3	8	12	4	2

key = 4

O/P :- 4

index of 4

1 3 8

↑ increasing order

12 4 2

↑ Decreasing order

→ Approach:- First find peak element such like prev. question [max = 12]

→ after BS (arr, 0, index-1, desc);
BS (arr, index, size-1, des);

→ one BS return -1

→ one BS return Pindex & return it

→ if not found index then return -1

★ Heap (Priority Queue)

[Priority queue]

• How to identify heap question?

- 1) In here two keyword find in heap question,
 [$k + \text{smallest/largest/greater}$]

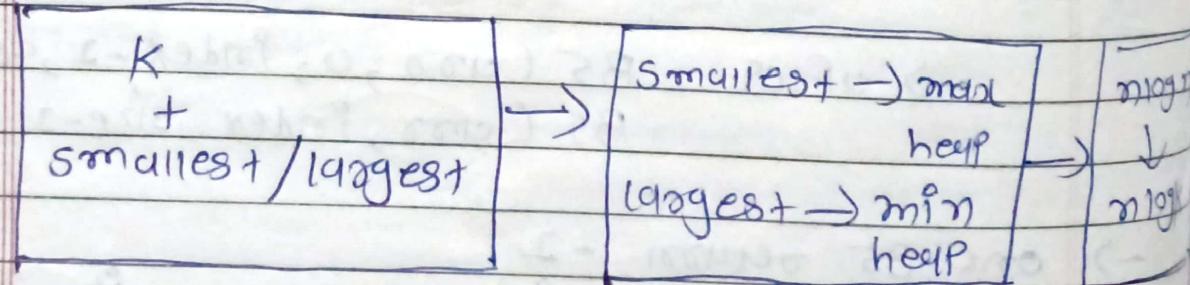
- Or we need to heap data structure?
→ Because in this question given array after you can use merge sort ($\log n$) complexity
But we reduce by using heap sort ($\log k$)

★ Two types of heap

- 1) max heap $\rightarrow (k + \text{smallest})$
2) min heap $\rightarrow (k + \text{largest})$

→ First think about sorting $(\log k)$. But in here question k are given so you can try to heap with $(\log k)$ complexity

★ Observation



(1) min heap

(K + smallest / closest / lowest)

Priority queue $\langle \text{int} \rangle \rightarrow \text{pq};$

while ($\text{pq}.\text{empty}() == \text{false}$)

g

cout << pq.top() << " ";

pq.pop();

g

(2)

min heap

(largest / greatest / top + K)

Priority queue $\langle \text{int}, \text{vector} \langle \text{int} \rangle \rangle, \text{greater} \langle \text{int} \rangle \gg \text{pq};$

while ($\text{pq}.\text{empty}() == \text{false}$)

g

cout << pq.top() << " ";

pq.pop();

g

(3)

Kth smallest element

I/P arr[] : [7 | 10 | 4 | 3 | 20 | 15]

K = 3

O/P : 7

1st approach:

sorting

(n log n)

sort [3 | 4 | 7 | 10 | 15 | 20]

return arr[K-1];

2nd Approach :- max heap $O(n \log k)$

int findKth (vector<int> &int> nums, int k)

{

int val;

priority_queue<int> pq;

int n = nums.size();

for (int i = 0; i < n; i++)

{

pq.push(nums[i]);

if (pq.size() > k)

pq.pop();

}

return pq.top();

3

(1) Kth largest elements in array

I/P arr[] : [7 | 10 | 4 | 3 | 20 | 15]

K = 3

O/P :- 10 | 20 | 15

1st Approach :- sorting $O(n \log n)$

.sort (arr, arr+n);

return arr[n-k];

2nd Approach:- min heap $O(n \log k)$

int FindKth (vector<int>&nums, int k)
{

Priority - queue <int>, vector<int>, greater<int> > mp;
int n = nums.size();

for (int i=0; i<n; i++)

{

mp.push(nums[i]);

if (mp.size() > k)

mp.pop();

}

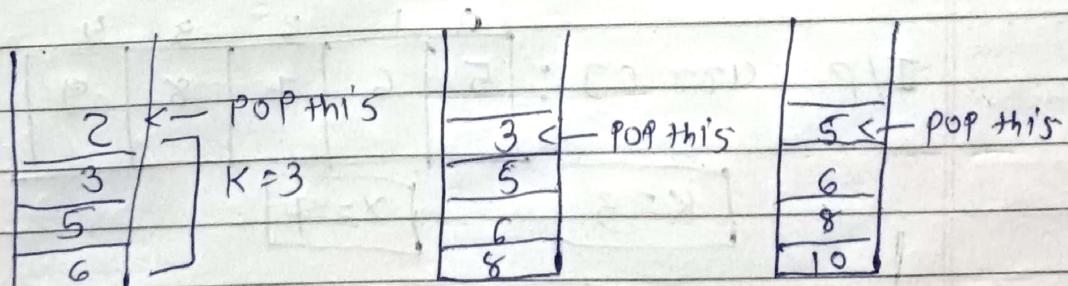
return mp.top();

}

(5) Sort a k sorted array || sort nearly sorted array

I/P :	6	5	3	2	8	10	9
K = 3							

→ index zero value move & sort under Kth elements
means 6 are move to up to 3rd index



min
heap

Output:- 2 | 3 | 5 | 6 | 8 | 9 | 10

void sortKth (vector<int>& nums, int k) {

Priority queue <int, vector<int>, greater<int>> pq;

For (int i=0; i<=k; i++) {

pq.push(nums[i]);

}

int index = 0;

techie
code

For (int i=k+1; i<nums.size(); i++) {

{

nums[index++] = pq.top();

pq.pop();

pq.push(nums[i]);

}

while (!pq.empty())

{

nums[index++] = pq.top();

pq.pop();

}

g

Time: $O(n \log k)$
Space: $O(k)$

⑤

k^{th} closest numbers

I/P arr[]: [5 | 6 | 7 | 8 | 9]

[K=3]

[X=7]

O/P: [6 | 7 | 8]

- we need to have pair because pair stores not only key stored with. key & absolute different store
- we use min-heap because closest elements need

~~two points code~~

void KthClosest (int arr[], int n, int x, int k)

{

Priority-queue <pair<int, int>> pq;

for (int i=0; i<k; i++)

pq.push ({abs(arr[i]-x), i});

for this

↓

2/9
2/5
1/8
2/6
0/7

for (int i=k; i<n; i++) {

int diff = abs (arr[i]-x);

if (diff > pq.top().first)

continue;

pq.pop();

pq.push ({diff, i});

}

while (pq.empty() == false)

{

cout << arr[pq.top().second] << " ";

pq.pop();

}

3

(E)

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TOP Kth Frequent Numbers (min heap)

I/P arr[] :

0	1	2	3	4	5	6
1	1	1	3	2	2	4

K=2

1 → 3 time present in array

3 → 2 time present in array

2, 2 → 2 time present in array

4 → 1 time present in array

for arr[]

→ we need to top 2 max frequent Number

O/P : [1, 2]

1. Hashing (unordered_map)

2. after min heap

(8)

Frequency Sort

0	1	2	3	4	5	6
1	1	1	3	2	2	4

O/P : [1 1 1 2 2 3 4]

3, 1

1st Approach: compare function in STL C++

2, 2

2nd Approach: Heap (max heap)

1, 3

while (maxheap.size() > 0)

1, 4

§

int fore = maxheap.top().first;

int ele = maxheap.top().second;

for arr[]



For (Pnt i=1; Pk = Foe; i++)
cout << ele <<;

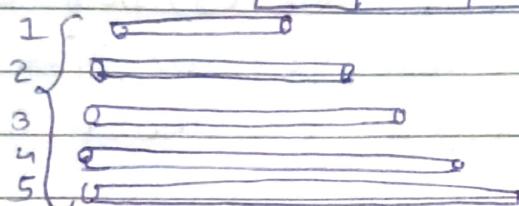
· map(heap, pop());

g

(9) k^{th} closest point To origin

(10) connect ropes

I/P :- arr [] : [1 | 2 | 3 | 4 | 5]



O/P :-

(11) sum of element between k_1 smallest & k_2 smallest numbers

I/P arr [] : [1 | 3 | 12 | 5 | 15 | 11]
 $\boxed{k_1 = 3}, \boxed{k_2 = 6}$

\rightarrow [1 | 3 | 5 | 11 | 12 | 15]
 ↓ ↓ ↓
 3rd + 6th
 $11 + 12 = 23$ return

★ Stack

① How to identify stack question

→ if you have implemented Brute Force $O(n^2)$
and after you not decide ki how to optimize
this them check this observation $(O(n^2))$

$j \rightarrow 0$ to i	$j++$
$j \rightarrow i$ to 0	$j--$
$j \rightarrow i$ to n	$j++$
$j \rightarrow n$ to i	$j--$

→ when in Brute force 2nd (J) loop depends
on i (first loop) then you can think about
Stack and in optimize under $O(n)$ time

★ Some stack question

① Nearest greater to right || Nearest (largest) ele.
NGR

I/P arr[]:	0	1	2	3
	1	3	2	4

O/P	3	4	4	-1

1st approach: Brute force $O(n^2)$

for (int i=0; i<n-1; i++)

 for (int j=i+1; j<n; j++)

→ In here 2nd loop (j) depend on 1st loop (i) so we think about stack data structure

2nd Approach :- Stack

Time: O(m), Space: O(m)

vector<int> v; // creating vector for store result
stack<int> s;

```

for (int i = 0; i <
left → for (int i = n - 1; i >= 0; i--) {
    if (s.size() == 0)
        v.push_back(-1);
    else if (s.size() > 0 && s.top() > arr[i])
        v.push_back(s.top());
    else if (s.size() > 0 && s.top() <= arr[i])
        s.pop();
    if (s.size() == 0)
        v.push_back(-1);
    else
        v.push_back(s.top());
}
s.push(arr[i]);
}
reverse(v.begin(), v.end());
return v;

```

(2) Nearest greater to left (NGL)

	0	1	2	3
I/P:	1	3	2	4

O/P:	-1	-1	3	-1

st Approach :- $O(m^2)$

FOR (int i=0; i<n; i++)

FOR (int j=i-1; j>=0; j--)

→ we clearly see 2nd loop depend on 1st
 so we think about optimize stack form

2nd Approach:

→ left to right

→ NO reverse required

{ same like pre. cos}

(3) Nearest smaller to left (NSL)

	0	1	2	3	4
I/P : arr C/J :	4	5	2	10	8

O/P :	-1	4	-1	2	2
-------	----	---	----	---	---

Ist Route Form: $O(m^2)$

FOR (int i=0; i<m; i++)

FOR (int j=i-1; j>=0; j--)

2nd Approach: $O(n)$ stacks

1. left to right
2. no reverse required
3. greater than sign to less than & less to greater

(4) Nearest smaller to right (NSR)

0	1	2	3	4
I/P : arr CJ : [4 5 2 10 8]				

O/P : [2 2 -1 8 -1]

• 1st Brute Force Approach = $O(n^2)$

for (int i=0; i<n; i++)

 for (int j=i+1; j<n; j++)

• 2nd Approach: stack ($O(n)$, $O(n)$)

1. Right to left

2. smaller

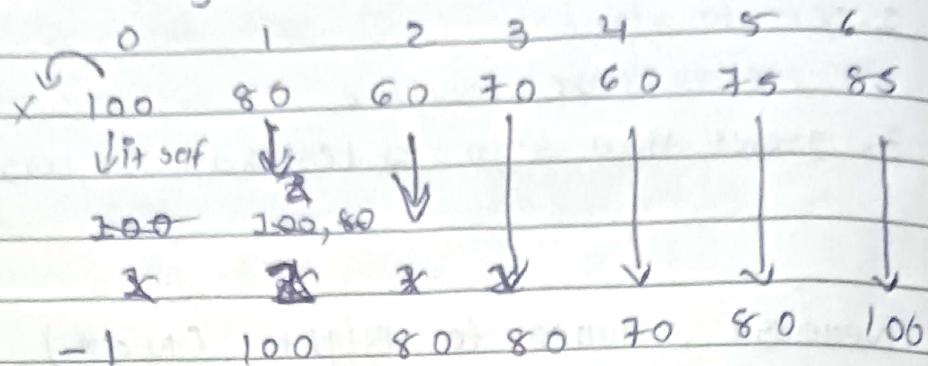
3. vector reverse

(5) Stock Span Problem

I/P arr CJ : [100 80 60 70 60 75 85]
--

O/P : [1 1 1 2 1 4 6]

Approach: you can think about nearest greater element to left



`arr[i]` index - nearest greater element index

$$\boxed{1} \quad \boxed{1-0=1} \quad \boxed{2-1=1} \quad \boxed{3-1=2} \quad \boxed{4-3=1} \quad \boxed{5-1=4} \quad \boxed{6-0=6}$$

actual output: { 1, 1, 1, 2, 1, 4, 6 }

structs <pair<int, int>> S;

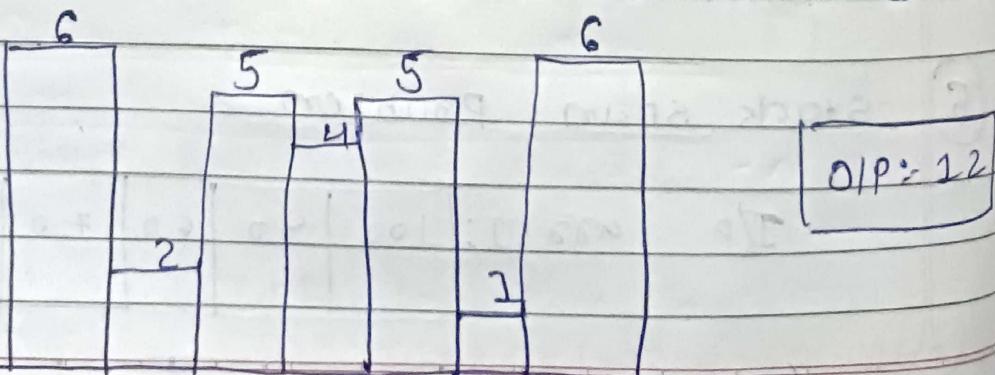
[store] [store]
[NGL] [index]

Other code same like NEGL

⑥ maximum Area Histogram || (mAH)

I/P arr[]:	0	1	2	3	4	5	6
	6	2	5	4	5	2	6

O/P:- 1 5 1 3 1 7 1



Approach:-

0	1	2	3	4	5	6
6	2	5	4	5	1	6

NSR index 1 5 3 5 5 7 7

NSL Pindex -1 -1 1 1 3 -1 5

$$\text{width} = (\text{NSR} - \text{NSL}) - 1$$

arr	6	2	5	4	5	1	6
width	1	5	1	3	1	7	1

Area of : 6 10 5 12 5 7 6

Vector

max Area

(7) max Area Rectangle in Binary matrix

(8) Rain water trapping

(9) minimum element in stack with extra space
(min stack)
 $O(n), O(n)$ (10) minimum element in stack with extra space
(min stack) optimize spaceTime: $O(n)$ Space: $O(1)$

★ Hashing

(Hello world YT)

- hashing is a technique that is used to uniquely identify a specific object from a group of similar objects
 - in hashing, large key are converted into small keys by using hash functions
- Ex:- WD53AFK32 → #32
- the value are then stored in a data structure it's called hash table
 - the idea of hashing is to distribute entries (key/values pairs) uniformly across an array
 - By using that key you can access the element in O(1) time.

★ How to handle negative numbers in hashtable

→ The idea is to use a 2D array of size

hashTable[m+1][z]

	0	mid	mid	
0	0 0 0 0	0 0 0	0 0 0	+ve
1	0 0 0 0	0 0 0	0 0 0	-ve

- in general try to first think about Brute force (O(n^2)) After think about O(1) using hashing

★ Code of Hashing Implementation

```
#define MAX 1000  
bool hashTable[MAX+2][2];
```

```
bool search (int x) {  
    if (x >= 0) {  
        if (hashTable[x][0] == 1) {  
            return true;  
        } else  
            return false;  
    } else {  
        return false;  
    }
```

```
    x = abs(x);  
    if (hashTable[x][1] == 1) {  
        return true;  
    } else  
        return false;  
}
```

```
void insert (int arr[], int n) {  
    for (int i=0; i<n; i++) {  
        if (arr[i] >= 0)  
            hashTable[abs(arr[i])][0] = 1;  
        else  
            hashTable[abs(arr[i])][1] = 1;  
    }
```

g
g

* what is unordered-set

- set → keys are stored in order fashion
- unordered-set → keys are stored in unordered fashion
- set → is implemented in Red Black tree
- unordered-set → is implemented in hashing
- Set → operation $O(\log n)$
- unordered-set → $O(1)$ (insert, search, delete)

* what is unordered-map

- they store $\langle \text{key}, \text{value} \rangle$ pair other all are same
- unordered-set

* some observation

① Non Repeating Element

I/P arr[]:	[-1 2 -1 3 2]
O/P :	3

- we stored here $\langle \text{key}, \text{name} \rangle$ pair Because in key we store arr[i] & in value store count of arr[i]

int first (int arr[], int n) {

unordered_map<int, int> umap;

for (int i=0; i<n; i++)

umap[arr[i]]++;

for (int i=0; i<n; i++) {

int key = arr[i];

auto temp = umap.find(key);

if (temp->second == 1)

return key;

}

② First Repeating Element

if (temp->second > 1)
return it;

③ Intersection of two arrays (unordered_set)

④ Key pair hashing problems (unordered_map)

⑤ Subarray with sum 0

⑥ Winner of an election

⑦ Pairs with positive negative values

⑧ Relative sort array. | sort an array according to the other

⑨ group Anagrams | point Anagrams together

⑩ sort array by increasing frequency

⑪ custom sort string

★ Recursion & Backtracking

[striver]

- Recursion :- when a function call it self until specify condition is met.

Basic example of Recursion

```
int count = 0;
```

```
void Total() {
```

$\text{if } (\text{count} == 3)$	← base condition to stop program
action;	

```
cout << count << " ";
```

```
count++;

```

```
Total();
```

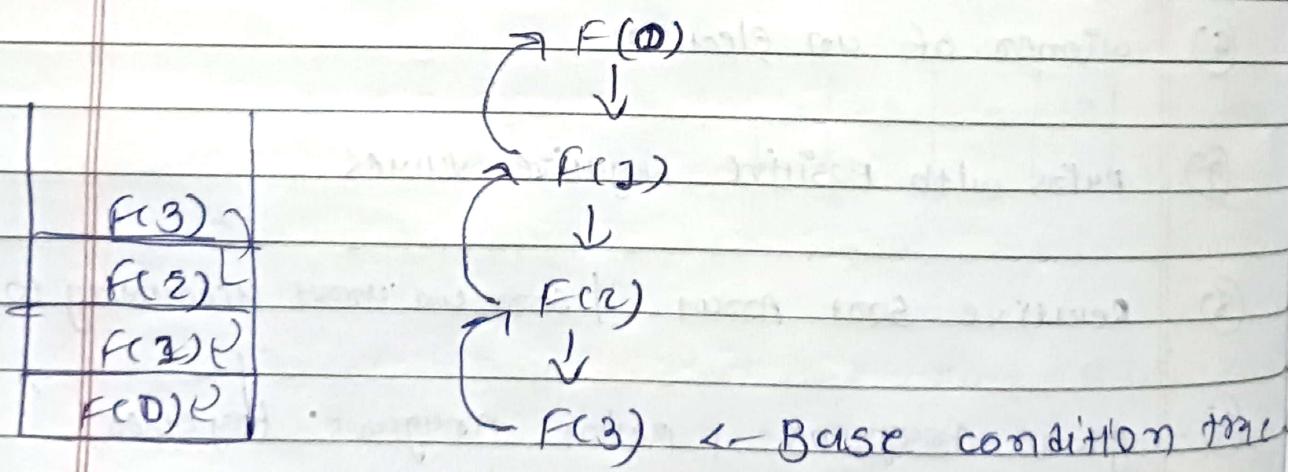
O/P : 0 1 2

3

Time: O(N)

Space: O(N)

- Recursion Tree



* Some Basic Question [try yourself] on Recursion

- 1) Paint Name 5 times
- 2) paint linearly from 1 to N
- 3) paint linearly from N to 1
- 4) paint linearly from 1 to N (using Backtrack)
- 5) paint linearly from N to 1 (using Backtrack)
- 6) sum of first N number using
 - 1) parameterize way
 - 2) Functional way
- 7) factorial of first N number
- 8) Fibonacci of first N number
- 9) Reverse array using recursion
 - 1) using two variable
 - 2) using single variable
- 10) check if a string is palindrome or not

★ Backtracking

① Subsets of Array

I/P :- arr [3] = {1, 2, 3}

O/P :- {{}, {1}, {2}, {3}, {1, 2}, {1, 3}, {2, 3}, {1, 2, 3}}

$$2^n = 2^3 = 8$$

Approach:

class Solution :

private :

```
void solve (vector<int> nums, vector<vector<int>>
           &output, int index, vector<vector<int>>
```

{

if (index >= nums.size())

base case

 output.push_back (output);

 return;

}

 solve (nums, output, index + 1, output);

 int element = nums [index];

 output.push_back (element);

 solve (nums, output, index + 1, output);

}

public : vector<vector<int>> subsets (vector<int> &nums)

 vector<vector<int>> output;

 int index = 0;

 solve (nums, output, index, output);

 return output;

(2) Phone Keypad Problem using Bucketising [Electroce]

class Solution {

private:

void solve(string digit, string output, int index, vector

<string> &ans, string mapping)

2

if (index >= digit.length()) {

ans.push_back(output);

return;

3

int number = digit[index] - '0';

string value = mapping[number];

for (int i = 0; i < value.length(); i++) {

output.push_back(value[i]);

solve(digit, output, index + 1, ans, mapping);

Backtrack → output.pop_back();

public: vector<string> letterCombinations(string digits) {

vector<string> ans;

if (digits.length() == 0)

return ans;

string output, int index = 0;

string mapping[10] = { " ", " ", "abc", "def", "ghi", "jkl", "mno", "pqrs", "tuv", "wxyz" };

solve(digits, output, index, ans, mapping);

return ans;

3

• Some Standard Leetcode Backtracking review

- 1) letter combinations of a phone no.
- 2) generate parentheses
- 3) permutations
- 4) permutations (using next permutation)
- 5) combinations - 88 combination sum & combinations sum II
- 6) subsets
- 7) subsets II
- 8) N-queens [IMP]
- 9) Sudoku solver
- 10) word search
- 11) palindrome partitioning

★ LinkedList

→ Linked list is a linear data structure.

- Some Practical Application of LinkedList

- 1) image viewer
- 2) web browser
- 3) music players

- How to create a linked list

→ You need to data, & next then you can make linked list;

① How to create & add Node in linked list

linked-list * add (int data, linked-list * head)

{

 if (head == NULL) {

 head = temp;

 temp = temp->next;

 } else {

 temp = head;

 while (temp->next != NULL)

 temp = temp->next;

 temp->next = new linked-list (data);

}

 return head;

}

(2) Print linked-list

```
void LinkedListPrint(LinkedList *head)
{
    auto temp = head;
    while (temp != NULL)
    {
        cout << temp->data << " -> ";
        temp = temp->next;
    }
    cout << endl;
}
```

(3) Find middle element in linkedlist

```
int middleElement(LinkedList *head)
{
    auto sp = head, fp = head;
    while (fp->next->next != NULL)
    {
        sp = sp->next;
        fp = fp->next->next;
    }
    return sp->data;
}
```

(4) Delete middle element in linkedlist

```
LinkedList *DeleteLink(LinkedList *head),
{
    auto sp = head, fp = head;
    auto pre = sp;
```

while ($FP \neq \text{NULL}$ & $FP \rightarrow \text{next} \neq \text{NULL}$) {
 $Pde = SP;$ $SP = SP \rightarrow \text{next};$
 $FP = FP \rightarrow \text{next} \rightarrow \text{next}$

$Pde \rightarrow \text{next} = SP \rightarrow \text{next};$
 delete $SP;$
 return head;

(3) delete linked list

linked-list * delete_linked_list (auto head)

{

 auto $pde = \text{head};$
 $\text{head} = \text{head} \rightarrow \text{next};$

 if ($\text{head} == \text{NULL}$)
 delete $pde;$

 while ($\text{head} \neq \text{NULL}$) {
 delete $pde;$
 $pde = \text{head};$
 $\text{head} = \text{head} \rightarrow \text{next};$

 return head;

}

A) Some Imp question on linked list

- 1) Recursively Print Reverse of linked list
- 2) Reverse linked list
- 3) Palindrome linked list
- 4) Delete Duplicate from linked list
(sorted & unsorted)
- 5) Detect loop in linked list
- 6) Remove loop
- 7) Intersection point in a linked list
- 8) Odd Even linked list
- 9) merge sort on linked list