

# Akshay Agrawal

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## EDUCATION

<b>Christian Albrechts Universität, Kiel, DE</b> Master of Science (M.Sc.)   Major: Computer Science	<b>2019-2023</b>
<b>Xavier Institute of Engineering, Mumbai, India</b> Bachelor of Engineering (B.E.)   Major: Computer Science	<b>2015-2019</b>
<b>Udemy</b> Web Development Bootcamp   Major: MERN Stack	<b>2024-Present</b>

## SKILLS & INTERESTS

- **Languages:** English (Native), German (Intermediate)
- **Programming Languages:** Python, JavaScript, HTML5, CSS3
- **Frameworks and Libraries:** TensorFlow, Keras, NumPy, Pandas, Flask, React, Node.js, SQLAlchemy
- **Database:** SQLAlchemy, MongoDB, MySQL
- **Technologies and Tools:** Docker, Git, AWS, CI/CD, Linux, Jupyter Notebook, RESTful API
- **Interest:** Photography, swimming, cooking and volleyball

## WORK EXPERIENCE

<b>Christian Albrechts Universität, Kiel DE</b> <i>Research Assistant (Information Systems)</i>	<b>Apr 2023 – Sept 2022</b>
<ul style="list-style-type: none"><li>• In collaboration with the supervisor, Conducted <b>data analysis</b> for over <b>100 computer science course offerings</b> at CAU, Kiel, collaborating with the supervisor to find insights, patterns, and correlations to enhance the curriculum.</li><li>• Utilized Neo4j to create and manage <b>graph databases</b>, for better <b>data visualization</b> and <b>interpretation</b> of course relationship, providing a comprehensive understanding of the curriculum.</li><li>• Designed a <b>web-based structure</b> using Flask to highlight complex data relationships, for effective data exploration.</li></ul> <p><b>Skills Learnt:</b> Insight's analysis, Collaboration, Data Visualization</p>	
<b>ZeroBS GmbH, Kiel DE</b> <i>FullStack Developer</i>	<b>Oct 2021 – July 2022</b>
<ul style="list-style-type: none"><li>• Developed a CMS infrastructure that improved efficiency, leading to <b>3x productivity</b>, involving <b>backend development</b> using Flask and <b>frontend development</b> with JavaScript and Jinja2 templates.</li><li>• Implemented <b>Agile methodologies</b> and <b>automated</b> of manual processes, reducing operational overhead by <b>90%</b>.</li><li>• Crafted one-click deployments, providing the client with complete autonomy and authority.</li><li>• Deployed and managed up to <b>5,000 processes</b> of different cloud providers (AWS, Digital Ocean) on the Python module <b>Terraform</b>.</li><li>• Maintained <b>asynchronous job queues</b> for application stability using Celery, and RabbitMQ.</li><li>• Collaborated with core team members <b>conveying problems, solutions, updates</b>, and <b>project</b> status to management, along with <b>program</b> and <b>user documentation</b>.</li></ul> <p><b>Skills Learnt:</b> Web development, Infrastructure management, Communication</p>	

## PERSONAL PROJECTS

<b>Non-Neural Twin for Simple Autoencoders</b> Master Thesis - <a href="#">Github</a>
<ul style="list-style-type: none"><li>• Researched and compared various non-neural machine learning methods giving a potential replacement for an <b>unsupervised neural network</b>.</li></ul>

- Identified and experimented **VQPCA** as a superior data reduction technique for linear relationships, surpassing the MSE results for **Autoencoders** by  $10^{-1}$  % resulting in enhanced interpretability.
- Managed and processed synthetic and real-world datasets with dimensions up to 30, along with refining **data reduction algorithms** using Python libraries including **NumPy**, and **Pandas**.
- Data visualization of up to 500x500 using **Matlab** and **Seaborn**, for decision-making by comparison of different heatmaps.

**Skills Learnt:** Machine Learning, Deep Learning, Neural Networks(Keras, TensorFlow)

### **Autonomous Driving Car in ROS for Formula Student**

Master Project - Visual Modelling

- Engineered an algorithm for **centerline estimation**, optimizing the car's path on the race track and enhancing speed performance.
- Spearheaded supervised **machine learning(SVM)**, for detailed track analysis and trajectory optimization.
- Performed **interpolation** of track data improving accuracy in trajectory calculation using **scipy.bspline**.
- Operated ROS for simulating the car's behavior and collaborated in weekly multi-team meetings for updates and idea discussions.
- Visualized track data and the centerline using **Matplotlib** and **Wandb**, evaluating performance on multiple datasets.

**Skills Learnt:** Computer Vision, Simulation, C++, Cmake, numerical analysis