

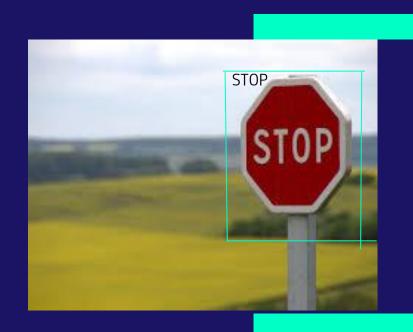
### TRAFFIC SIGNS CLASSIFICATION

GUIDE - PROF. SWATI HIRA

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### INTRODUCTION

- Trending Technology.
- Basic building block of self driving cars.
- Safety and Accident prevention.
- Area of research.



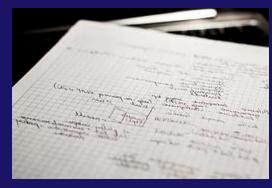


"Self-Driving cars are the natural extension of active safety and obviously something we should do."

-ELON MUSK

## Literature Survey and Data Collection

### **Datasets**





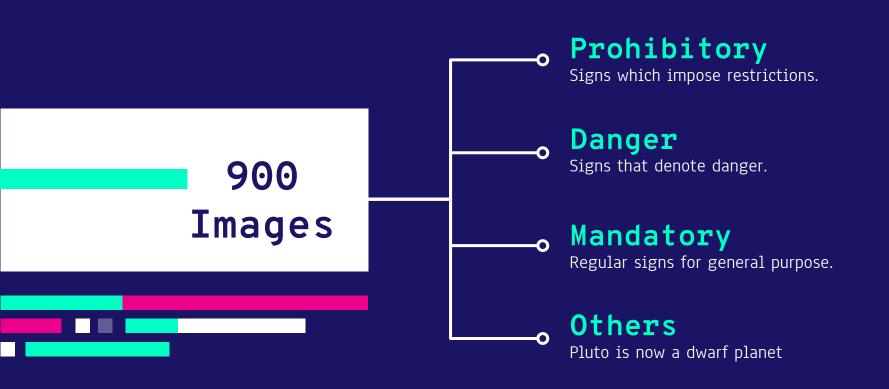








### **DATASET**



# 02

Planning and Methodology

### TIMELINE

### Step 1

Literature Survey and data collection

### Step 4

Learning R-CNN and object detection

### Step 2

Planning of project structure

### Step 5

Training our custom data and building a model

### Step 3

Understanding Yolo-V3 and Darknet Architecture

### Step 6

Integrating it with a GUI

### TECH-STACK



### Python

Base language for coding purpose.



### YOLO-V3 and Darknet

For implementing Real time Object Detection.

### PyQt5

Designing of Graphical User Interface.



### penCV

For interacting with images, videos and webcam.



# **O3**Yolo-V3 and Darknet Architecture

### YOLO-V3

	Type	Filters	Size	Output
	Convolutional	32	$3 \times 3$	$256 \times 256$
	Convolutional	64	$3 \times 3/2$	128 × 128
	Convolutional	32	1 x 1	
1×	Convolutional	64	$3 \times 3$	
	Residual			$128 \times 128$
	Convolutional	128	$3 \times 3/2$	$64 \times 64$
	Convolutional	64	1 × 1	
2×	Convolutional	128	$3 \times 3$	
	Residual			$64 \times 64$
ı	Convolutional	256	$3 \times 3/2$	$32 \times 32$
	Convolutional	128	1 x 1	
8×	Convolutional	256	$3 \times 3$	
	Residual			$32 \times 32$
	Convolutional	512	$3 \times 3/2$	16 × 16
	Convolutional	256	1 × 1	
8×	Convolutional	512	$3 \times 3$	
	Residual			16 × 16
Ī	Convolutional	1024	$3 \times 3/2$	8 × 8
	Convolutional	512	1 x 1	
4×	Convolutional	1024	$3 \times 3$	
	Residual			8 × 8
	Avgpool		Global	
	Connected		1000	
	Softmax			

Figure 1. Architecture of YOLO-3

- YOLO stands for "You Only Look Once" and uses convolutional neural networks (CNN) for object detection.
- When YOLO works it predicts classes' labels and detects locations of objects at the same time. That is why, YOLO can detect multiple objects in one image.
- YOLO divides image into regions, predicts bounding boxes and probabilities for every such region.
- YOLO also predicts confidence for every bounding box showing information that this particular bounding box actually includes object, and probability of included object in bounding box being a particular class.

### WHAT IS DARKNET?

- Darknet is an open source neural network framework.
- It is a fast and highly accurate framework for real time object detection.
- Accuracy for custom trained model depends on training data, epochs, batch size and some other factors.
- Also can be used for images



# 04

Preprocessing Dataset

### Task at Hand

- Convert Images from .ppm to .jpg
- Convert annotation file to YOLO
- Create .txt file with annotations next to every image that will have the same names as images files.

# 04

Training Model on custom data

#### DATA FILE

#### **EVERY DATA FILE CONTAINS:**

- Number of classes
- Full path to train.txt file
- Full path to test.txt file
- Full path to classes.names file.
- Full path to location where trained weights are to stored.

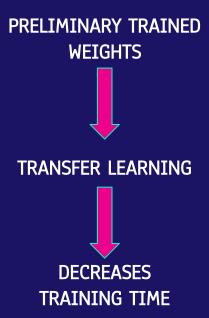
### **CONFIGURATION FILE**

- Parameters for Training file
  - Learning Rate
  - Angle and Saturation
  - Exposure and Hue
- Structure of CNN Layers
  - Filters
  - Activation
  - Size and stride
- Last 3 YOLO layers

#### SOME ADDITIONAL CONFIGURATIONS

- FILTERS = (classes + coordinates + 1)\*masks, = (4 + 4 + 1)\*3 = 27
- MAX\_BATCHES → (Total number of iterations for training.)
  - = classes\*2000 (but not less than 4000)
  - = 4\*2000 = 8000
- STEPS → (Number of iterations after which learning rate will be multiplied by scale factor.)
  - = 80% of MAX\_BATCHES, 90% of MAX\_BATCHES
  - = 6400, 7200
- BATCH → (Number of images that will be processed during One iteration.)

=64



#### READING RGB IMAGE



### COMPLETE IDEA



LOADING YOLO V3 NETWORK







NON-MAXIMUM SUPRESSION

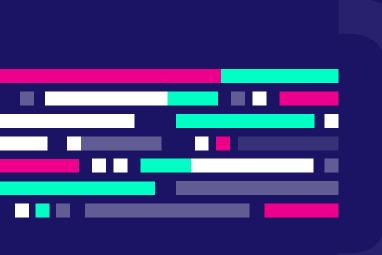


GETTING BOUNDING BOXES

### SAMPLES







### **TO-DO**

- Integrating the Trained Model with a GUI.
- Increase the number of classes for prediction.
- Train and test the model on Google Colab for Real-time classification.

