AUP Assignment 7

111703013 Akshay Rajesh Deodhar

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Q1 Create a child process. Let the parent sleeps of 5 seconds and exits. Can the child send SIGINT to its parent if exists and kill it? Verify with a sample program.

Code

```
#include <sys/types.h>
    #include <unistd.h>
    #include <signal.h>
    #include <stdlib.h>
    #include <stdio.h>
    #include <errno.h>
    int main(void) {
            int child_pid;
            if ((child_pid = fork()) == -1) {
13
                     /* fork failed */
                    perror("fork");
15
                     return errno;
            }
            else if (child_pid) {
                     /* parent */
19
                     sleep(5);
20
                     printf("Parent is Alive\n");
21
            }
22
            else {
23
                     /* child */
24
                     if (kill(getppid(), SIGINT) == -1) {
                             perror("SIGINT to parent");
26
                             return errno;
27
28
                     printf("Child sent kill signal\n");
29
                     sleep(5);
                     printf("Child slept for time equal to parent\n");
            }
32
33
            return 0;
34
35
```

Output

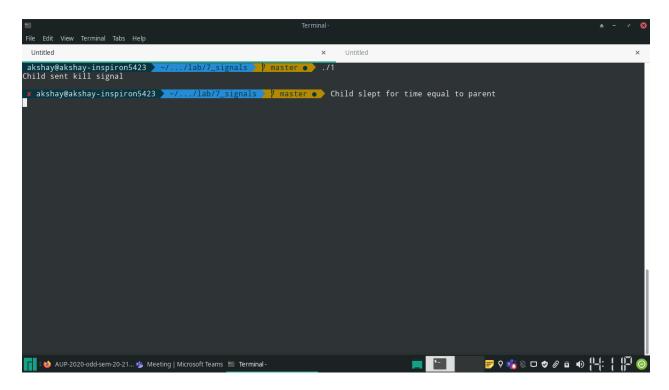


Figure 1: Parent is alive not printed, parent killed by SIGINT sent by child

Q2:

Create a signal disposition to catch SIGCHLD and in the handler function display some message. Create a child process and let the child sleeps for some time and exits. The parent calls a wait() for the child. Display the return value of wait() to check success or failure. If failure, display the error number. Run the program:

- a. Normal way executing in the foreground
- b. Run as a back ground process and send SIGCHLD to it from the shell

Code

```
#include <sys/types.h>
#include <sys/wait.h>
#include <unistd.h>
#include <signal.h>
#include <errno.h>
#include <stdio.h>

void print_sigchld_msg(int sig_number) {
    printf("SIGCHLD hits parent (msg)\n");
}

int main(void) {
    pid_t child_id;
```

```
int dead_child;
17
             int status;
18
19
             /* set handler for SIGCHLD */
20
             signal(SIGCHLD, print_sigchld_msg);
21
22
             if ((child_id = fork()) == -1) {
23
                     perror("fork");
24
                     return errno;
25
             }
26
             else if (child_id) {
27
                     /* parent */
28
29
                     if ((dead_child = wait(&status)) == -1) {
30
                              perror("wait failed");
31
                              return errno;
32
                     }
33
                     else {
34
                              printf("Wait returned, child %d exited\n", dead_child);
35
                     }
36
             }
37
             else {
38
                     /* Child */
39
                     printf("Child sleeping\n");
40
                     sleep(10);
41
             }
^{42}
43
44
             return 0;
45
46
```

Output

Figure 2: Normal way of executing the program, SIGCHLD hits once



Figure 3: Run as a back ground process and send SIGCHLD to it from the shell, SIGCHLD hits twice

Q3 You have to create a process tree as shown below. Then you let the parent process create a process group of (3, 4, 5) so that it sends a signal to this group. Print appropriate messages.

- 1 and 2 are children of 0
- 5 is child of 1
- 3 is child of 2
- 4 is child of 3

Code

```
#include <sys/types.h>
   #include <sys/mman.h>
4 #include <sys/stat.h>
5 #include <sys/wait.h>
6 #include <unistd.h>
7 #include <fcntl.h>
   #include <semaphore.h>
   #include <signal.h>
   #include <stdio.h>
   #include <stdlib.h>
   #include <errno.h>
   #define SHARED_ARR "shared_array"
14
   #define SEMAPHORE_FORKING "fork_semaphore"
15
   #define N 6
16
17
   /* to ensure that fp can be used by all processes */
   static int fp;
20
   void print_message(int signo) {
            printf("%d got hit by signal %d\n", getpid(), signo);
22
23
24
    void examine_child(int pid) {
        int status;
27
        if (waitpid(pid, &status, 0) == -1) {
28
                perror("wait");
29
                exit(errno);
30
        }
31
        if (WIFEXITED(status)) {
                printf("%d exited with %d\n", pid, WEXITSTATUS(status));
34
        }
35
        else if (WIFSIGNALED(status)) {
36
                printf("%d killed by signal %d\n", pid, WTERMSIG(status));
37
        }
        else {
                printf("%d died in some other way\n", pid);
40
41
42
43
   void *get_shared_arr() {
44
            void *buf;
45
            /* asssert: fp is a file descriptor which points to the shared memory,
             * and is inherited by all processes */
47
```

```
if ((buf = mmap(NULL, sizeof(int) * N, PROT_READ | PROT_WRITE, MAP_SHARED, fp, 0)) == MAP_FAILED) {
48
                      perror("shared memory mmap() failed");
49
                      exit(errno);
50
51
             return buf;
52
    }
53
54
     int main(void) {
56
57
             /* process 0 */
58
             /* can see the pids of {1, 2} */
59
             sem_t *fork_sem, *pgid_sem, *exit_sem;
60
             int *child_pid;
61
             int ret;
62
63
             if (signal(SIGUSR1, print_message) == SIG_ERR) {
64
                      perror("SIGUSR1");
65
                      return errno;
66
             }
67
             /* link shared memory address to process- this will be visible in
69
              * children */
70
             if ((child_pid= mmap(NULL, sizeof(int) * N,
71
                                               PROT_READ | PROT_WRITE,
72
                                               MAP_SHARED | MAP_ANONYMOUS,
73
                                               -1, 0)) == MAP_FAILED) {
75
                      perror("mmap");
76
                      return errno;
77
             }
78
79
             /* create a shared memory map for semaphore */
 80
             if ((fork_sem = mmap(NULL, sizeof(sem_t),
                                               PROT_READ | PROT_WRITE,
 82
                                               MAP_SHARED | MAP_ANONYMOUS,
 83
                                               -1, 0)) == MAP_FAILED) {
 85
                      perror("semaphore");
 86
                      return errno;
 87
             }
             /* initialize semaphore with initial value 0- when 5 and 3 get
89
              * created, this is incremented by 1 each. O will synchronize by calling
90
                down() on this twice */
91
             if (sem_init(fork_sem, 1, 0) == -1) {
92
                      perror("semaphore initialization");
93
                      return errno;
94
             }
96
             /* create a shared memory map for semaphore */
97
             if ((exit_sem = mmap(NULL, sizeof(sem_t),
98
                                               PROT_READ | PROT_WRITE,
99
                                               MAP_SHARED | MAP_ANONYMOUS,
100
                                               -1, 0)) == MAP_FAILED) {
102
                      perror("semaphore");
103
                      return errno;
104
             }
105
```

106

```
/* initialize semaphore with initial value 0- when signals have been
107
               * sent, this will be incremented 5 times, wherin all processes will
108
               * exit */
109
             if (sem_init(exit_sem, 1, 0) == -1) {
110
                      perror("semaphore initialization");
111
                      return errno;
112
             }
113
114
             /* create a shared memory map for semaphore */
115
             if ((pgid_sem = mmap(NULL, sizeof(sem_t),
116
                                                PROT_READ | PROT_WRITE,
117
                                                MAP_SHARED | MAP_ANONYMOUS,
118
                                                -1, 0)) == MAP_FAILED) {
119
120
                      perror("semaphore");
121
                      return errno;
122
123
124
             \slash * initialize semaphore with initial value 0- when all processes have
125
              * called setpgid, the parent can send signals */
126
             if (sem_init(pgid_sem, 1, 0) == -1) {
127
                      perror("semaphore initialization");
128
                      return errno;
129
             }
130
131
             /* assert: now each child will have access to the semaphore, unless the
132
              * memory region is purposely unliked */
133
134
135
             if ((ret = fork()) == -1) {
136
                      perror("fork 1");
137
                      return errno;
138
             }
139
             else if (!ret) {
                      /* child 1 */
141
                      /* can see pids of {5} */
142
                      /* child_pid = (int *)get_shared_arr(); */
143
144
                      if ((ret = fork()) == -1) {
145
                              perror("fork 5");
146
147
                              return errno;
148
                      else if (!ret) {
149
                               /* chlid 5 */
150
                               /* can see pids of {} */
151
                               /* child_pid = (int *)get_shared_arr(); */
152
153
                               /* wait for the PID of 3 to be available */
154
                               if (sem_wait(fork_sem) == -1) {
155
                                       perror("P operation in 5");
156
                               }
157
158
                               /* set own process group to 3 */
159
                               if (setpgid(0, child_pid[3]) == -1) {
160
                                       perror("setpgid(5, 3)");
161
                                       return errno;
162
                               }
163
164
                               if (sem_post(pgid_sem) == -1) {
165
```

```
perror("setpgid(5, 3) done synchronization");
166
                                        return errno;
167
                               }
168
169
170
                               /* wait for 0 to allow exiting */
171
                               if (sem_wait(exit_sem) == -1) {
^{172}
                                        perror("V operation in 4");
                                        return errno;
174
                               }
175
176
                               printf("%d is child of %d\n", getpid(), getppid());
177
178
                               return 0;
179
                      }
180
                      child_pid[5] = ret;
181
182
183
184
                      /* wait for 0 to allow exiting */
185
                      if (sem_wait(exit_sem) == -1) {
                               perror("V operation in 2");
187
                               return errno;
188
                      }
189
190
                      printf("%d is child of %d\n", getpid(), getppid());
191
                      examine_child(child_pid[5]);
193
194
                      return 0;
195
196
              child_pid[1] = ret;
197
198
             if ((ret = fork()) == -1) {
                      perror("fork 2");
200
                      return errno;
201
             }
202
             else if (!ret) {
203
                      /* child 2 */
204
                      /* can see pids of {3} */
205
                      /* child_pid = (int *)get_shared_arr(); */
207
                      if ((ret = fork()) == -1) {
208
                               perror("fork 3");
209
                               return errno;
210
                      }
211
                      else if (!ret) {
212
                               /* child 3*/
213
                               /* can see pids of {4} */
214
215
                               child_pid[3] = getpid();
216
217
                               if (setpgid(child_pid[3], child_pid[3]) == -1) {
218
                                        perror("setpgid(3, 3");
220
                                        return errno;
                               }
221
222
                               if (sem_post(pgid_sem) == -1) {
223
                                        perror("setpgid(3, 3) done synchronization");
224
```

```
225
                                        return errno;
                               }
226
227
                               /* tell 5 that pid of 3 is available in shared memory,
228
                                * and it can call setpgid safely*/
229
                               if (sem_post(fork_sem) == -1) {
230
                                       perror("P operation in 3");
231
                                        return errno;
                               }
233
234
235
                               if ((ret = fork()) == -1) {
236
                                        perror("fork 4");
237
                                        return errno;
238
                               }
239
                               else if (!ret) {
240
                                        /* child 4*/
241
                                        /* can see pids of {} */
242
                                        /* child_pid = (int *)get_shared_arr(); */
243
244
                                        if (setpgid(0, child_pid[3]) == -1) {
245
                                                perror("setpgid(4, 3)");
246
                                                return errno;
247
                                        }
248
249
                                        /* tell 0 that 4 has moved to new process group
250
                                         * */
251
                                        if (sem_post(pgid_sem) == -1) {
^{252}
                                                perror("setpgid(4, 3) done synchronization");
253
                                                return errno;
254
                                        }
255
256
257
                                        /* wait for 0 to allow exiting */
                                        if (sem_wait(exit_sem) == -1) {
259
                                                perror("V operation in 4");
260
                                                return errno;
261
                                        }
262
263
                                        printf("%d is child of %d\n", getpid(), getppid());
264
265
                                        return 0;
266
267
                               }
268
269
                               child_pid[4] = ret;
270
271
272
                               if (sem_wait(exit_sem) == -1) {
273
                                       perror("V operation in 3");
274
                                       return errno;
275
                               }
276
277
                               printf("%d is child of %d\n", getpid(), getppid());
279
                               examine_child(child_pid[4]);
280
281
                               return 0;
282
                      }
283
```

```
child_pid[3] = ret;
285
286
                       /* wait for 0 to allow exiting */
287
                      if (sem_wait(exit_sem) == -1) {
288
                               perror("V operation in 2");
289
                               return errno;
290
                      }
291
292
                      printf("%d is child of %d\n", getpid(), getppid());
293
294
                      examine_child(child_pid[3]);
295
                      return 0;
              }
298
              child_pid[2] = ret;
299
300
              /* wait till all processes created, and the 3 setpgid calls finish */
301
              int i;
302
              for (i = 0; i < 3; i++) {
303
                      if (sem_wait(pgid_sem) == -1) {
304
                               perror("V operation in 0");
305
                               return errno;
306
                      }
307
              }
308
              child_pid[0] = getpid();
311
              if (kill(-child_pid[3], SIGUSR1) == -1) {
312
                      perror("kill");
313
                      return errno;
314
              }
315
316
              for (i = 0; i <= 5; i++) {
                      printf("Process %d = %d\n", i, child_pid[i]);
318
              }
319
320
321
              for (i = 0; i < 5; i++) {
322
                      if (sem_post(exit_sem) == -1) {
323
                               perror("P by 0");
                               return errno;
325
                      }
326
              }
327
328
              examine_child(child_pid[1]);
329
              examine_child(child_pid[2]);
330
331
              return 0;
332
333
     }
334
```

Explanation

- Shared memory is created for sharing pids and semaphores
- 3 semaphores are used
- fork_sem is used by process 3 to tell process 5 that it's pid is available in shared memory, and that it's process group has been created
- pgid_sem is used for telling 0 that all 3 setpgid calls are done

• exit_sem is used for telling 1-5 that it has called kill, and they are free to exit now

Output

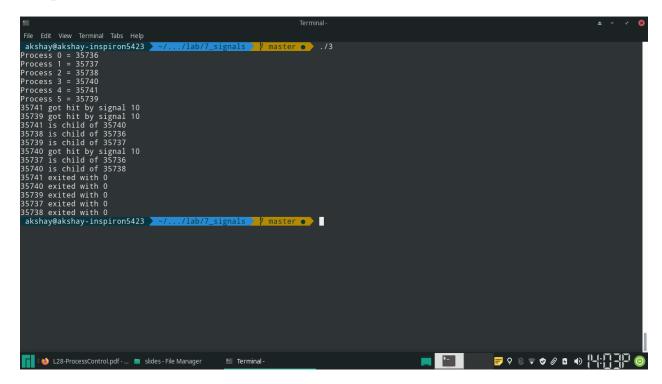


Figure 4: Execution of 3, SIGUSR hits 3, 4, 5 $\,$