Lecture 5 - Linear transformations and determinants A matrix transformation satisfies (1) & (2) Question: Are all transformations satisfying (1) & (2) coming from multiplication by a matrix that is, are they always matrix transformations? Ans. Yes Take ZER, that is, Z=(2), say, & let

T:R -R satisfy (1) & (2).

Since  $\vec{x} = x_1\vec{e_1} + x_2\vec{e_2} + \cdots + x_n\vec{e_n}$ ,  $T(\vec{x}) = T(x_1\vec{e_1}) + \cdots + T(x_n\vec{e_n})$  (from (1))  $= x_1T(\vec{e_1}) + \cdots + x_nT(\vec{e_n})$  (from (2))

Thus it is enough to determine  $T(\vec{e_1}), \dots, T(\vec{e_n})$  to get T(x) for any  $x \in R$ .

We want A such that  $T = I_A : R \to IR$ .

A is  $m \times n$ .

Each of  $T(e_1), \dots, T(e_n)$  is  $m \times I$ .

Consider A = (Tei) .... T(en)

Then is Ta=T&

= T(x). (by ) & this is true + xel?.

SOT indeed comes from a matrix

A = [T(ei) | T(ez) | ... | T(en)]

columns

 $T_A(\mathbf{x}) = T_B(\mathbf{x})$  for every vector  $\mathbf{x}$  in  $\mathbb{R}^n$ , then A = B.

$$B\vec{e}_{i} = \begin{pmatrix} b_{i1} \\ \dot{b}_{m_{i}} \end{pmatrix}$$
  
Since  $T_{A}(\vec{e}_{i}) = T_{B}(\vec{e}_{i})$ , we have  $a_{i1} = b_{i1}$  for all  $1 \le i \le m$ .  
Similarly,  $a_{ij} = b_{ij}$  for all  $2 \le j \le n$  &  $1 \le i \le m$   
 $= A = B$ .

Find the standard matrix A for the linear transformation 
$$T: \mathbb{R}^2 \to \mathbb{R}^3$$
.

$$T\left(\begin{bmatrix} \chi_1 \\ \chi_2 \end{bmatrix}\right) = \begin{bmatrix} 2\chi_1 + \chi_2 \\ \chi_1 - 3\chi_2 \end{bmatrix}$$

$$e_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} e_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$e_{1} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, e_{2} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$T/\Gamma 17 = [2(1) + 0] = [2]$$

$$T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 2(1) + 0 \\ 1 - 3(0) \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

$$T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 2(0) + 1 \\ 0 - 3(1) \\ -0 + 1 \end{bmatrix} = \begin{bmatrix} 1 \\ -3 \\ 1 \end{bmatrix}$$

$$= A - \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$= A = \begin{bmatrix} 2 & 1 \\ 1 & -3 \\ -1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 2 & 1 \\ 1 & -3 \\ 1 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2x_1 + x_2 \\ x_1 - 3x_2 \\ -x_1 + x_2 \end{bmatrix}$$

## Chapter 2 - Determinants

So an application of determinants is in computing inverses.

Determinant of an nxn matrix

Defined in terms of det. of (n-1)x(n-1)
matrices

Defined in terms of det. of (n-2)x(n-2)

Defined in terms of detrof (n-2)x(n-. matrices

Defn. det (a,1) = a11, defined

Let  $A = \begin{pmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & a_{ij} & \vdots \\ a_{n1} & \cdots & a_{nn} \end{pmatrix}$ 

Defn. Minor of a::

- Denoted by Mi determinant of the - Defined to be the Submatrix of A that remains after deleting ith row and it column from A.

 $M_{ij} = \det \begin{pmatrix} a_{i1} & \cdots & a_{in} \\ \vdots & \vdots & \ddots \\ a_{n1} & \cdots & a_{nn} \end{pmatrix}$ 

Defn. Cofactor of az:

$$C_{ij} = (-1)^{i+j} M_{ij}$$

$$\begin{vmatrix}
+ & - & + & - & + & \cdots \\
- & + & - & + & - & \cdots \\
+ & - & + & - & + & \cdots \\
- & + & - & + & - & \cdots \\
\vdots & \vdots & \vdots & \vdots & \vdots
\end{vmatrix}$$

 $C_{11} = M_{11}, \quad C_{21} = -M_{21}, \quad C_{22} = M_{22}$ 

 $\det(A) = a_{1i}C_{1i} + a_{2i}C_{2i} + \dots + a_{ni}C_{ni}$ [cofactor expansion along the jth column] OR

$$\det(A) = a_{i1}C_{i1} + a_{i2}C_{i2} + \dots + a_{in}C_{in}$$
[cofactor expansion along the *i*th row]

Find the determinant of the matrix

$$A = \begin{bmatrix} 1 & -2 & 3 \\ 6 & 7 & -1 \\ -3 & 1 & 4 \end{bmatrix}$$

co-factor expansion along 1st row;

$$= (28+1)+2(24-3)+3(6+21)$$

$$= 29+42+81$$

co-factor expansion along 3rd column:

$$= 3(6+21)+1(1-6)+4(7+12)$$

$$= 81 - 5 + 76$$

Ex.2 find the determinant of the matrix

$$\begin{bmatrix}
1 & 0 & 0 & -1 \\
3 & 2 & 2 \\
1 & 0 & -2 & 1 \\
2 & 0 & 0 & 1
\end{bmatrix}$$

$$\begin{array}{c}
\text{Co-factor expansion along 2} \\
\text{Column} \\$$

Ex. 2 Find det · of 
$$a_{11}$$
 0 0 0  $a_{21}$   $a_{22}$  0 0  $a_{31}$   $a_{32}$   $a_{33}$  0  $a_{41}$   $a_{42}$   $a_{43}$   $a_{44}$  det (A) =  $a_{11}$   $a_{22}$  0  $a_{32}$   $a_{33}$  0  $a_{32}$   $a_{33}$  0  $a_{32}$   $a_{33}$  0  $a_{33}$   $a_{44}$ 

Note: The same can be done for any upper/ lower triangular matrix.

## Sect. 2.2 Another way to find determinant by EROS

R, -> KR1	
$R_i \leftrightarrow R_i$	

Relationship	Operation		
$\begin{vmatrix} ka_{11} & ka_{12} & ka_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = k \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix}$ $\det(B) = k \det(A)$	In the matrix $B$ the first row of $A$ was multiplied by $k$ .		
$\begin{vmatrix} a_{21} & a_{22} & a_{23} \\ a_{11} & a_{12} & a_{13} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = - \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix}$ $\det(B) = -\det(A)$	In the matrix $B$ the first and second rows of $A$ were interchanged.		
$\begin{vmatrix} a_{11} + ka_{21} & a_{12} + ka_{22} & a_{13} + ka_{23} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix}$ $\det(B) = \det(A)$	In the matrix <i>B</i> a multiple of the second row of <i>A</i> was added to the first row.		

## **THEOREM 2.2.4** Let E be an $n \times n$ elementary matrix.

- (a) If E results from multiplying a row of  $I_n$  by a nonzero number k, then det(E) = k.
- (b) If E results from interchanging two rows of  $I_n$ , then det(E) = -1.
- (c) If E results from adding a multiple of one row of  $I_n$  to another, then det(E) = 1.

Ex. 4 Find det(A) using EROs:

$$A = \begin{bmatrix} 0 & 1 & 5 \\ 3 & -6 & 9 \\ 2 & 6 & 1 \end{bmatrix}$$

$$R_{1} \Rightarrow R_{2}$$

$$\begin{bmatrix} 3 & -6 & 9 \\ 0 & 1 & 5 \\ 2 & 6 & 1 \end{bmatrix}$$

$$\begin{bmatrix} R_{1} \Rightarrow R_{1/3} \\ -2 & 3 \\ 2 & 6 & 1 \end{bmatrix}$$

$$R_{3} \Rightarrow R_{3} = 2R_{1}$$

$$\begin{bmatrix} 1 & -2 & 3 \\ 0 & 1 & 5 \\ 2 & 6 & 1 \end{bmatrix}$$

$$R_{3} \Rightarrow R_{3} = 2R_{1}$$

$$\begin{bmatrix} 1 & -2 & 3 \\ 0 & 1 & 5 \\ 0 & 1 & 5 \\ 0 & 1 & 5 \\ 0 & 1 & 5 \end{bmatrix}$$

$$R_{3} \Rightarrow R_{3} = 10R_{2}$$

$$R_{3} \Rightarrow R_{3} = 10R_{3}$$

$$=(-3)(1)(1)(-55) = 165$$