

# Numerical Analysis : [ MA214 ]

## Lecture 4

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# Recall:- Osculatory interpolation

Simplest and often occurring case

$$x_0, x_1, \dots, x_k$$

$$f(x_0), f(x_1), f(x_2), \dots, f(x_k)$$

$$f'(x_0), f'(x_1), f'(x_2), \dots, f'(x_k)$$

**Algorithm:-**  $z_{2i} = x_i$ , and  $z_{2i+1} = x_i$  for  $i = 0, 1, \dots, k$

$$\text{Set } f[z_i, z_{i+1}] = \begin{cases} f'(z_i) & \text{if } z_i = z_{i+1} \\ \frac{f(z_{i+1}) - f(z_i)}{z_{i+1} - z_i} & \text{if } z_i \neq z_{i+1} \end{cases}$$

$$s \geq 2$$

$$f[z_i, z_{i+1}, \dots, z_{i+s}] = \frac{f[z_{i+1}, \dots, z_{i+s}] - f[z_i, \dots, z_{i+s-1}]}{z_{i+s} - z_i}$$

$$P_{2k+1}(x) = f[z_0] + f[z_0, z_1](x - z_0) + f[z_0, z_1, z_2](x - z_0)(x - z_1)$$

$$+ \dots + f[z_0, \dots, z_{2k+1}] \prod_{i=1}^{2k} (x - z_i)$$

For interpolation problems it is good idea to create the Newton divided-difference table.

We then did the general Osculatory interpolating formula

Let  $x_0, x_1, \dots, x_m$  be not necessarily distinct points.

We say two function  $f(x)$  and  $g(x)$  agree at the points  $x_0, x_1, \dots, x_m$  if

$$f^{(j)}(z) = g^{(j)}(z) , \text{ for } j = 0, 1, \dots, k - 1$$

for every points  $z$  which occurs  $k$  times in the sequence  $x_0, x_1, \dots, x_m$ .

Last time we proved that

if  $f(x)$  has  $r$  continuous derivatives and no point in the  $x_0, x_1, \dots, x_m$  occurs more than  $r$  times then there exists exactly one polynomial  $P_m(x)$  of degree  $\leq m$  which agree with  $f(x)$  at  $x_0, x_1, \dots, x_m$ .

Uniqueness was an exercise, I hope you have done it.

# Disadvantage of interpolation

Usually the number of data points  $x_0, x_1, \dots, x_m$  is very large.

Large degree polynomial oscillate a lot. It also create lot of round off errors.

To avoid this problem we study piecewise-polynomial interpolation

We did

- ① piecewise linear interpolation
- ② piecewise cubic interpolation
  - ① piecewise-cubic Hermite
  - ② piecewise-cubic Spline ( we will do this today)

# Piecewise cubic Hermite

$$a = x_1 < x_2 < x_3 < \cdots < x_{N+1} = b$$

in  $[x_i, x_{i+1}]$ ,  $g_i(x)$  is given by polynomial  $P_i(x)$  which interpolate  $f(x)$  at  $x_i, x_i, x_{i+1}, x_{i+1}$ , i.e.

$$P_i(x_i) = f(x_i) \text{ and } P_i(x_{i+1}) = f(x_{i+1})$$

$$P'_i(x_i) = f'(x_i) \text{ and } P'_i(x_{i+1}) = f'(x_{i+1})$$

$$\begin{aligned} P_i(x) &= f(x_i) + f[x_i, x_i](x - x_i) \\ &+ f[x_i, x_i, x_{i+1}](x - x_i)^2 + f[x_i, x_i, x_{i+1}, x_{i+1}](x - x_i)^2(x - x_{i+1}) \\ x &\in [x_i, x_{i+1}] \end{aligned}$$

The piecewise Hermite polynomial  $g(x)$  is continuously differentiable in  $[a, b]$

## Disadvantage of piecewise Hermite polynomial

$f'(x)$  might not be available.

# Cubic Spline Interpolation I

## Definition

Given a function  $f$  defined on  $[a, b]$  and a set of nodes

$$a = x_0 < x_1 < x_2 < x_3 < \cdots < x_n = b$$

A cubic spline interpolation  $S$  for  $f$  is a function that satisfies the following conditions.

- ①  $S(x)$  is a cubic polynomial denoted by  $S_j(x)$  on the sub-interval  $[x_j, x_{j+1}]$ , for each  $j = 0, 1, \dots, n-1$
- ②  $S_j(x_j) = f(x_j)$ ,  $S_j(x_{j+1}) = f(x_{j+1})$ , for each  $j = 0, 1, \dots, n-1$
- ③ for each  $j = 0, 1, \dots, n-2$ 
  - ①  $S_{j+1}(x_{j+1}) = S_j(x_{j+1})$
  - ②  $S'_{j+1}(x_{j+1}) = S'_j(x_{j+1})$
  - ③  $S''_{j+1}(x_{j+1}) = S''_j(x_{j+1})$
- ④ One of the following set of boundary condition is satisfied

# Cubic Spline Interpolation II

- ①  $S''(x_1) = S''(x_n) = 0$ , ( free boundary )
- ②  $S'(x_0) = f'(x_0)$ ,  $S'(x_n) = f'(x_n)$  ( clamped boundary )

## Construction of cubic spline interpolant on $[x_j, x_{j+1}]$

$$S_j(x) = a_j + b_j(x - x_j) + c_j(x - x_j)^2 + d_j(x - x_j)^3$$

$$S_j(x_j) = f(x_j). \text{ So } a_j = f(x_j)$$

Set  $h_j = x_{j+1} - x_j$

$$a_{j+1} = S_j(x_{j+1}) = a_j + b_j h_j + c_j h_j^2 + d_j h_j^3 \quad (1)$$

$$S'_j(x) = b_j + 2c_j(x - x_j) + 3d_j(x - x_j)^2$$

$$S'_j(x_j) = b_j$$

$$b_{j+1} = S'_{j+1}(x_{j+1}) = S'_j(x_{j+1})$$



$$b_{j+1} = b_j + 2c_j h_j + 3d_j h_j^2 \quad (2)$$

Define  $b_n = S'(x_n)$

$$S_j''(x) = 2c_j + 6d_j(x - x_j)$$

$$c_j = \frac{S_j''(x_j)}{2}$$

$$c_{j+1} = \frac{S_{j+1}''(x_{j+1})}{2} = \frac{S_j''(x_{j+1})}{2}$$

$$c_{j+1} = c_j + 3d_j h_j \quad (3)$$

Define  $c_n = \frac{S''(x_n)}{2}$

By equation (3),  $d_j = \frac{1}{3h_j}(c_{j+1} - c_j)$

by equation (1)

$$\begin{aligned}a_{j+1} &= a_j + b_j h_j + c_j h_j^2 + d_j h_j^3 \\&= a_j + b_j h_j + c_j h_j^2 + \frac{1}{3}(c_{j+1} - c_j)h_j^3\end{aligned}$$

$$a_{j+1} = a_j + b_j h_j + \frac{1}{3}(c_{j+1} + 2c_j)h_j^2 \quad (4)$$

Plugging values of  $d_j$  in equation (2) we get

$$\begin{aligned}b_{j+1} &= b_j + 2c_j h_j + h_j(c_{j+1} - c_j) \\b_{j+1} &= b_j + h_j(c_{j+1} + c_j)\end{aligned} \quad (5)$$

By equation (4) we get

$$b_j = \frac{1}{h_j}(a_{j+1} - a_j) - \frac{h_j}{3}(c_{j+1} + 2c_j) \quad (6)$$

$$b_{j-1} = \frac{1}{h_{j-1}}(a_j - a_{j-1}) - \frac{h_{j-1}}{3}(c_j + 2c_{j-1})$$

plugging these values of  $b_j$  and  $b_{j-1}$  in equation (5)

$$\begin{aligned} \frac{1}{h_j}(a_{j+1} - a_j) - \frac{h_j}{3}(c_{j+1} + 2c_j) &= \frac{1}{h_{j-1}}(a_j - a_{j-1}) - \frac{h_{j-1}}{3}(c_j + 2c_{j-1}) \\ &+ h_{j-1}(c_j + c_{j-1}) \end{aligned}$$

Collecting terms of  $c_j$ ,  $c_{j+1}$ ,  $c_{j-1}$  we get

$$\begin{aligned} h_{j-1}c_{j-1} + 2(h_{j-1} + h_j)c_j + h_jc_{j+1} &= \frac{3}{h_j}(a_{j+1} - a_j) - \frac{3}{h_{j-1}}(a_{j-1} - a_j) \\ j &= 1, 2, \dots, n-1 \end{aligned}$$

$n-1$  equations and  $n+1$  unknowns  $c_0, c_1, \dots, c_n$

**Case 1 :** free boundary  $S''(x_1) = S''(x_n) = 0$

$$S_j''(x) = 2c_j + 6d_j(x - x_j)$$

$$0 = S_j''(x_0) = 2c_0 + 6d_j(0)$$

So  $c_0 = 0$  and  $c_n = \frac{S''(x_n)}{2} = 0$ .

So we have a system  $Ax = b$ , where  $A$  is  $(n+1) \times (n+1)$  matrix

$$\begin{bmatrix} 1 & 0 & 0 & \cdots & 0 & 0 \\ h_0 & 2(h_0 + h_1) & h_1 & \cdots & 0 & 0 \\ 0 & h_1 & 2(h_1 + h_2) & h_2 \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \cdots & \vdots & \vdots \\ & & & h_{n-2} & 2(h_{n-2} + h_{n-1}) & h_{n-1} \\ 0 & 0 & \cdots & 0 & 0 & 1 \end{bmatrix}$$

$$x = \begin{bmatrix} c_0 \\ c_1 \\ \vdots \\ c_n \end{bmatrix}$$

$$b = \begin{bmatrix} 0 \\ \frac{3}{h_1}(a_2 - a_1) - \frac{3}{h_0}(a_1 - a_0) \\ \vdots \\ \frac{3}{h_{n-1}}(a_n - a_{n-1}) - \frac{3}{h_{n-2}}(a_{n-1} - a_{n-2}) \\ 0 \end{bmatrix}$$

**Question 1.** Does  $Ax = b$  have a solution?

**Question 2.** Any comments on the structure of  $A$ ?

## Definition

A matrix  $T = (t_{ij})_{n \times n}$  is called strictly diagonally dominated if

$$|t_{ii}| > \sum_{j=1, j \neq i}^n |t_{ij}|$$

We will see later that strictly diagonally dominated matrix  $T$  is invertible.

Our matrix  $A$  is strictly diagonally dominated.

So we can solve  $Ax = b$  to get  $c_0, c_1, \dots, c_n$ .

Then we obtain  $d_0, d_1, \dots, d_n$  and  $b_0, b_1, \dots, b_n$

# Example

Approximate  $f(x) = e^x$  in the interval  $[0, 3]$ .

$$x_0 = 0, x_1 = 1, x_2 = 2, x_3 = 3$$

$$f(x_0) = 1, f(x_1) = e, f(x_2) = e^2, f(x_3) = e^3$$

Find cubic spline with free boundary.

**Ans.**

$$n = 3, h_0 = h_1 = h_2 = 1$$

$$a_0 = 1, a_1 = e, a_2 = e^2, a_3 = e^3$$

$$A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 4 & 1 & 0 \\ 0 & 1 & 4 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$b = \begin{bmatrix} 0 \\ 3(e^2 - 2e + 1) \\ 3(e^3 - 2e^2 + e) \\ 0 \end{bmatrix}$$

$$x = \begin{bmatrix} c_0 \\ c_1 \\ c_2 \\ c_3 \end{bmatrix}$$

free boundary. So  $c_0 = c_3 = 0$

$$4c_1 + c_2 = 3(e^2 - 2e + 1)$$

$$c_1 + 4c_2 = 3(e^3 - 2e^2 + e)$$

$$c_1 = 0.7569 \quad c_2 = 5.83$$



$$d_1 = \frac{1}{3h_0}(c_1 - c_0) = \frac{1}{3}c_1 = 0.2523$$

$$d_2 = \frac{1}{3h_1}(c_2 - c_1) = 1.691$$

$$d_3 = \frac{1}{3h_2}(c_3 - c_2) = -1.943$$

$$\begin{aligned} b_0 &= \frac{1}{h_0}(a_1 - a_0) - \frac{h_0}{3}(2c_0 + c_1) \\ &= a_1 - a_0 - \frac{1}{3}c_1 = 1.466 \end{aligned}$$

$$\begin{aligned} b_1 &= \frac{1}{h_1}(a_2 - a_1) - \frac{h_1}{3}(2c_1 + c_2) \\ &= 2.223 \end{aligned}$$

$$\begin{aligned} b_2 &= \frac{1}{h_2}(a_3 - a_2) - \frac{h_2}{3}(2c_2 + c_3) \\ &= 8.81 \end{aligned}$$

$$S(x) = \begin{cases} 1 + 1.466x + 0x^2 + 0.2523x^3, & 0 \leq x \leq 1 \\ 2.718 + 2.223(x-1) + 0.7569(x-1)^2 + 1.691(x-1)^3, & 1 \leq x \leq 2 \\ 7.389 + 8.81(x-2) + 5.83(x-2)^2 - 1.943(x-2)^3, & 2 \leq x \leq 3 \end{cases}$$

## Case 2 : Clamped boundary

$$S'(x_0) = f'(x_0) \text{ and } S'(x_n) = f'(x_n), S'(x_0) = f'(a) = b_0$$

$$f'(a) = \frac{1}{h_0}(a_1 - a_0) - \frac{h_0}{3}(2c_0 + c_1)$$

$$2h_0c_0 + h_0c_1 = \frac{3}{h_0}(a_1 - a_0) - 3f'(a)$$

$$f'(b) = b_n = b_{n-1} + h_{n-1}(c_{n-1} + c_n)$$

So equation 6 with  $j = n - 1$  gives

$$f'(b) = \frac{1}{h_{n-1}}(a_n - a_{n-1}) - \frac{h_{n-1}}{3}(c_n + 2c_{n-1}) + h_{n-1}(c_{n-1} + c_n)$$

Simplify to get,

$$h_{n-1}c_{n-1} + 2h_{n-1}c_n = 3f'(b) - \frac{3}{h_{n-1}}(a_n - a_{n-1})$$

Thus we obtain  $Ax = b$  where

$$A = \begin{bmatrix} 2h_0 & h_0 & 0 & \cdots & 0 & 0 \\ h_0 & 2(h_0 + h_1) & h_1 & \cdots & 0 & 0 \\ 0 & h_1 & 2(h_1 + h_2) & h_2 \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \cdots & \vdots & \vdots \\ & & & h_{n-2} & 2(h_{n-2} + h_{n-1}) & h_{n-1} \\ 0 & 0 & \cdots & 0 & h_{n-1} & 2h_n \end{bmatrix}$$

$$x = \begin{bmatrix} c_0 \\ c_1 \\ \vdots \\ c_n \end{bmatrix}$$

$$b = \begin{bmatrix} \frac{3}{h_0}(a_1 - a_0) - 3f'(a) \\ \frac{3}{h_1}(a_2 - a_1) - \frac{3}{h_0}(a_1 - a_0) \\ \vdots \\ \frac{3}{h_{n-1}}(a_n - a_{n-1}) - \frac{3}{h_{n-2}}(a_{n-1} - a_{n-2}) \\ 3f'(b) - \frac{3}{h_{n-1}}(a_n - a_{n-1}) \end{bmatrix}$$

The matrix  $A$  is again strictly diagonally dominated. So  $A$  is invertible.

Thus we can solve  $Ax = b$  to get  $c_0, \dots, c_n$ .

Then we find  $d$  and  $b$  to get the final answer.

# Numerical Integration

## Reasons for Numerical Integration

- ① We can not solve  $\int_a^b f(x)dx$  exactly.

**Examples:-**

①  $\int_0^1 \sin(x^2)dx$

②  $\int_0^1 e^{-x^2} dx$

③  $\int_0^1 \sqrt{1 + \cos^4 x} dx$

- ② And is not known explicitly. Only values of  $f$  at some points are known

**Example:-**

$$\frac{dy}{dx} = \sin(x^2 + y^2) , y(0) = 1$$

find  $\int_0^1 y(t)dt$

Note that we do not know  $y$  exactly.

By Numerical Solution to ODE's we can approximate

$$y(0.1), y(0.2), \dots, y(1)$$

# Derivation of Numerical Integration formulae

Let  $P_k(x)$  be the polynomial which interpolates  $f(x)$  at points  $x_1, x_2, \dots, x_k$ .

We approximate  $I(f) = \int_a^b f(x)dx$  by  $I(P_k) = \int_a^b P_k(x)dx$

$$f(x) = P_k(x) + f[x_0, x_1, \dots, x_k, x]\Psi_k(x)$$

$$\Psi_k(x) = \prod_{j=0}^k (x - x_j)$$

Error in computing integral =  $E(f) = I(f) - I(P_k)$

$$E(f) = \int_a^b f[x_0, x_1, \dots, x_k, x]\Psi_k(x)dx$$

# Simplification of error terms

**Case 1**  $\psi_k(x)$  is of one sign on  $(a, b)$ .

Then by MVT for integral

$$\begin{aligned} E(f) &= \int_a^b f[x_0, x_1, \dots, x_k, x] \psi_k(x) dx \\ &= f[x_0, x_1, \dots, x_k, \xi] \int_a^b \psi_k(x) dx \end{aligned}$$

If in addition  $f(x)$  is  $k + 1$  times differentiable then

$$\begin{aligned} E(f) &= \frac{f^{(k+1)}(\eta)}{(k+1)!} \int_a^b \psi_k(x) dx \\ &\quad \text{for some } \eta \in (a, b) \end{aligned}$$



**Case 2**  $\int_a^b \Psi_k(x) dx = 0$ . We use the identity

$$f[x_0, x_1, \dots, x_k, x] = f[x_0, x_1, \dots, x_k, x_{k+1}] + f[x_0, x_1, \dots, x_{k+1}, x](x - x_{k+1})$$

$$\begin{aligned} E(f) &= \int_a^b f[x_0, x_1, \dots, x_k, x] \Psi_k(x) dx \\ &= \int_a^b f[x_0, x_1, \dots, x_k, x_{k+1}] \Psi_k(x) dx \\ &\quad + \int_a^b f[x_0, x_1, \dots, x_{k+1}, x] (x - x_{k+1}) \Psi_k(x) dx \\ &= \int_a^b f[x_0, x_1, \dots, x_{k+1}, x] \Psi_{k+1}(x) dx \end{aligned}$$

$$\Psi_{k+1}(x) = (x - x_{k+1}) \Psi_k(x) = \prod_{j=0}^{k+1} (x - x_j)$$

$$E(f) = \int_a^b f[x_0, x_1, \dots, x_{k+1}, x] \Psi_{k+1}(x) dx$$

If we can choose  $x_{k+1}$  such that  $\psi_{k+1}(x)$  is of one sign on  $(a, b)$ , then by MVT of integrals

$$E(f) = f[x_0, x_1, \dots, x_{k+1}, \xi] \int_a^b \psi_{k+1}(x) dx$$

If  $f(x)$  is  $k+2$  times continuously differentiable then

$$E(f) = \frac{f^{(k+2)}(\eta)}{(k+2)!} \int_a^b \psi_{k+1}(x) dx$$

for some  $\eta \in (a, b)$

# Examples

Let  $k = 0$

$$P_0 = f(x_0)$$

$$f(x) = f(x_0) + f[x_0, x](x - x_0)$$

$$I = \int_a^b f(x) dx = \int_a^b f(x_0) dx + \int_a^b f[x_0, x](x - x_0) dx$$

$$I(P_0(x)) = (b - a)f(x_0)$$

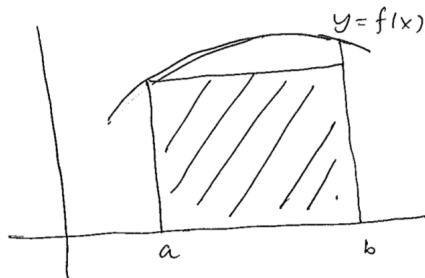
**Case 1**  $x_0 = a$

$$I(f) \approx R = (b - a)f(a)$$

$\Psi_0(x) = x - a$  has one sign in  $[a, b]$ .

$$E^R = f'(\eta) \int_a^b (x - a) dx = f'(\eta) \frac{(b - a)^2}{2}$$

$R \leftarrow$  Rectangle rule



**Case 2**  $x_0 = \frac{a+b}{2}$

$\psi_0(x) = x - x_0$ , not of one sign

However  $\int_a^b (x - \frac{a+b}{2}) dx = 0$

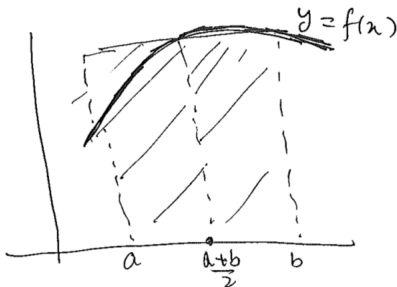
Choose  $x_1 = x_0$

$\psi_1(x) = (x - x_0)^2$ , is of one sign

$$I(f) \approx M = (b-a)f\left(\frac{a+b}{2}\right), \text{ Midpoint rule}$$

$$\begin{aligned} E^M &= \frac{f''(\eta)}{2} \int_a^b \left(x - \frac{a+b}{2}\right)^2 dx \\ &= \frac{f''(\eta)}{2} \frac{(b-a)^3}{24}, \text{ for some } \eta \in [a, b] \end{aligned}$$

**Midpoint rule is better than rectangle rule**



Now let  $k = 1$

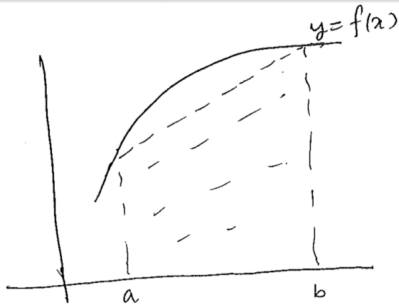
$$f(x) = f(x_0) + f[x_0, x_1](x - x_0) + f[x_0, x_1, x]\Psi_1(x)$$

Where  $\Psi_1(x) = (x - x_0)(x - x_1)$ ,  $x_0 = a$ ,  $x_1 = b$

$$\Psi_1(x) = (x - a)(x - b) \leq 0 \text{ on } [a, b]$$

$$\begin{aligned} I(f) &= \int_a^b [f(x_0) + f[a, b](x - a)]dx \\ &+ \frac{1}{2}f''(\eta) \int_a^b (x - a)(x - b)dx \\ I(f) &\approx T = \frac{1}{2}(b - a)[f(a) + f(b)] , \text{ Trapezoidal rule} \end{aligned}$$

$$E^T = -\frac{f''(\eta)(b - a)^3}{12}, \text{ for some } \eta \in [a, b]$$



Now let  $k = 2$

$$f(x) = P_2(x) + f[x_0, x_1, x_2, x]\psi_2(x)$$

For distinct points  $x_0, x_1, x_2$

$$\psi_2(x) = (x - x_0)(x - x_1)(x - x_2) \text{ is not of } \mathbf{one} \text{ sign on } [a, b]$$

However for  $x_0 = a, x_1 = \frac{a+b}{2}, x_2 = b$

$$\begin{aligned}
 \int_a^b \psi_2(x) dx &= \int_a^b (x-a) \left( x - \frac{a+b}{2} \right) (x-b) dx \\
 &\quad \text{By using } u = x - \frac{a+b}{2} \\
 &= \int_{-\frac{a+b}{2}}^{\frac{a+b}{2}} \left( u + \frac{b-a}{2} \right) u \left( u - \frac{b-a}{2} \right) du \\
 &= 0
 \end{aligned}$$

Put  $x_3 = x_1 = \frac{a+b}{2}$

$$\psi_3(x) = (x-a) \left( x - \frac{a+b}{2} \right)^2 (x-b) \leq 0 \text{ on } [a, b]$$



$$I(f) = I(P_2) + \frac{1}{4!} f^{(4)}(\eta) \int_a^b \psi_3(x) dx$$

One calculate

$$\begin{aligned} \int_a^b \psi_3(x) dx &= \int_a^b (x-a) \left( x - \frac{a+b}{2} \right)^2 (x-b) dx \\ &= \frac{-4}{15} \left( \frac{b-a}{2} \right)^5 \end{aligned}$$

$$E^S(f) = -\frac{1}{90} f^{(4)}(\eta) \left( \frac{b-a}{2} \right)^5, \quad \eta \in [a, b]$$

$$I(f) \approx I(P_2)$$

$$P_2(x) = f(a) + f[a, b](x-a) + f \left[ a, b, \frac{a+b}{2} \right] (x-a)(x-b)$$

$$\begin{aligned}
 \int_a^b P_2(x) dx &= f(a)(b-a) + f\left[a, b\right] \frac{(b-a)^2}{2} \\
 &+ f\left[a, b, \frac{a+b}{2}\right] \int_a^b (x-a)(x-b) dx \\
 \int_a^b (x-a)(x-b) dx &= -\frac{(b-a)^3}{6}
 \end{aligned}$$

**Note:-**

$$f\left[a, b, \frac{a+b}{2}\right] = f\left[a, \frac{a+b}{2}, b\right], \text{ ( why ? )}$$

$$\begin{aligned}
 f\left[a, \frac{a+b}{2}, b\right] (b-a)^2 &= \left( f\left[\frac{a+b}{2}, b\right] - f\left[a, \frac{a+b}{2}\right] \right) (b-a) \\
 &= \left\{ \frac{f(b) - f\left(\frac{a+b}{2}\right)}{\frac{b-a}{2}} - \frac{f\left(\frac{a+b}{2}\right) - f(a)}{\frac{b-a}{2}} \right\} (b-a) \\
 &= 2(f(b) - 2f\left(\frac{a+b}{2}\right) + f(a))
 \end{aligned}$$

$$\begin{aligned}
 I(P_2) &= \int_a^b P_2(x) dx \\
 &= f(a)(b-a) + (f(b) - f(a)) \left( \frac{b-a}{2} \right) \\
 &\quad - 2 \left( f(b) - 2f \left( \frac{a+b}{2} \right) + f(a) \right) \frac{b-a}{6} \\
 &= \frac{b-a}{6} \left\{ f(a) + 4f \left( \frac{a+b}{2} \right) + f(b) \right\}, \text{ ( Simpson's Rule )}
 \end{aligned}$$

$$\begin{aligned}
 \int_a^b f(x) dx &\approx \frac{b-a}{6} \left\{ f(a) + 4f \left( \frac{a+b}{2} \right) + f(b) \right\} \\
 E^S &= -\frac{1}{90} f^{(4)}(\eta) \left( \frac{b-a}{2} \right)^5
 \end{aligned}$$

## k=3 "Corrected Trapezoidal rule"

$$f(x) = P_3(x) + f[x_0, x_1, x_2, x_3, x]\Psi_3(x)$$

$$x_0 = x_1 = a, x_2 = x_3 = b$$

$$\Psi_3(x) = (x-a)^2(x-b)^2 \text{ is of one sign in } [a, b]$$

$$E(f) = \frac{1}{4!} f^{(4)}(\eta) \int_a^b (x-a)^2(x-b)^2 dx = \frac{f^{(4)}(\eta)(b-a)^5}{720}$$

$$\begin{aligned} P_3(x) &= f(a) + f[a, a](x-a) + f[a, a, b](x-a)^2 \\ &= f[a, a, b, b](x-a)^2(x-b) \end{aligned}$$

$$\begin{aligned} \int_a^b P_3(x) dx &= f(a)(b-a) + f'(a) \frac{(b-a)^2}{2} \\ &+ f[a, a, b] \frac{(b-a)^3}{3} + f[a, a, b, b] \left\{ \frac{(b-a)^4}{4} - \frac{(b-a)^4}{3} \right\} \\ f[a, a, b] &= \frac{f[a, b] - f'(a)}{b-a} \end{aligned}$$

$$f[a, a, b, b] = \frac{f'(b) - 2f[a, b] + f'(a)}{(b - a)^2}$$

$$\begin{aligned} \int_a^b P_3(x) dx &= f(a)(b - a) + f'(a) \frac{(b - a)^2}{2} \\ &+ \{f[a, b] - f'(a)\} \frac{(b - a)^2}{3} \\ &- \{f'(b) - 2f[a, b] + f'(a)\} \frac{(b - a)^2}{12} \end{aligned}$$

replace  $f[a, b]$  by  $\frac{f(b) - f(a)}{b - a}$ . So we get

$$I(f) \approx CT = \frac{b - a}{2} (f(a) + f(b)) + \frac{(b - a)^2}{12} (f'(a) - f'(b))$$

Corrected Trapezoidal rule

$$E^{CT} = \frac{f^{(4)}(\eta)(b - a)^5}{720}$$

# Rules for Numerical Integration

$$\text{Rectangle rule } I \approx (b - a)f(a)$$

$$\text{Midpoint rule } I \approx (b - a)f\left(\frac{a + b}{2}\right)$$

$$\text{Trapezoidal rule } I \approx \frac{1}{2}(b - a)[f(a) + f(b)]$$

$$\text{Simpson's rule } I \approx \frac{b - a}{6} \left\{ f(a) + 4f\left(\frac{a + b}{2}\right) + f(b) \right\}$$

Corrected Trapezoidal rule

$$I \approx \frac{b - a}{2}(f(a) + f(b)) + \frac{(b - a)^2}{12}(f'(a) - f'(b))$$