

STATIC EQUILIBRIUM AND STRESSES PART II

Lecture 3 ,4 and 5

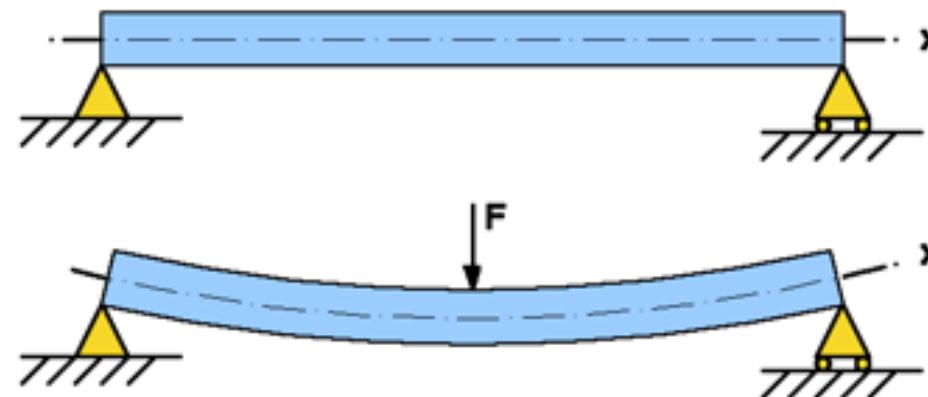
MM203

Mechanics of Materials

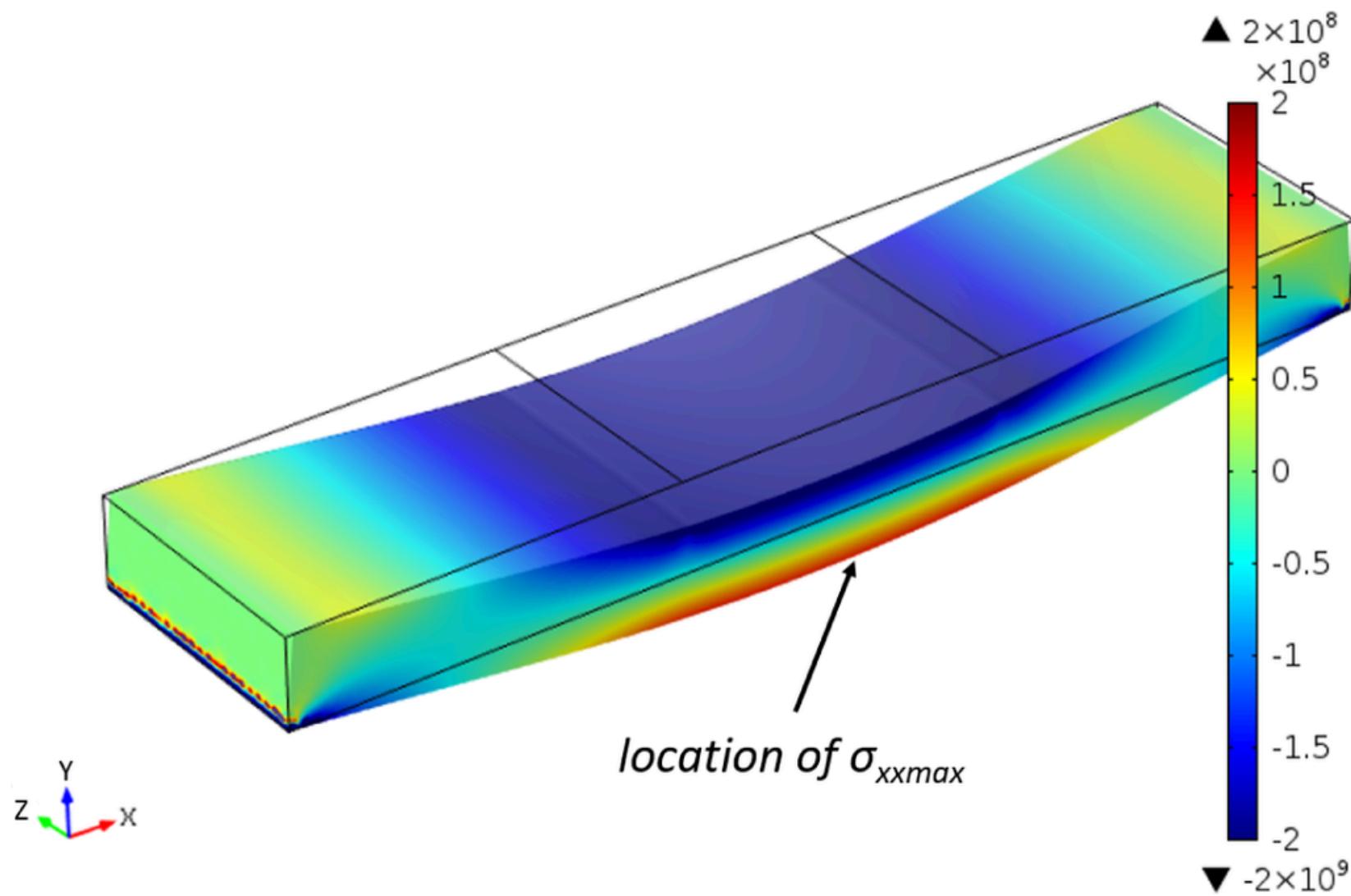
Recap

- Different kind of structures.
- Free body diagram and forces and moments applied by surroundings.
- Development of theory of elasticity and concepts of stresses and strains.
- Requirements to define stress: Force and Area.
- Shear stress and normal stress.
- Constitutive equations.

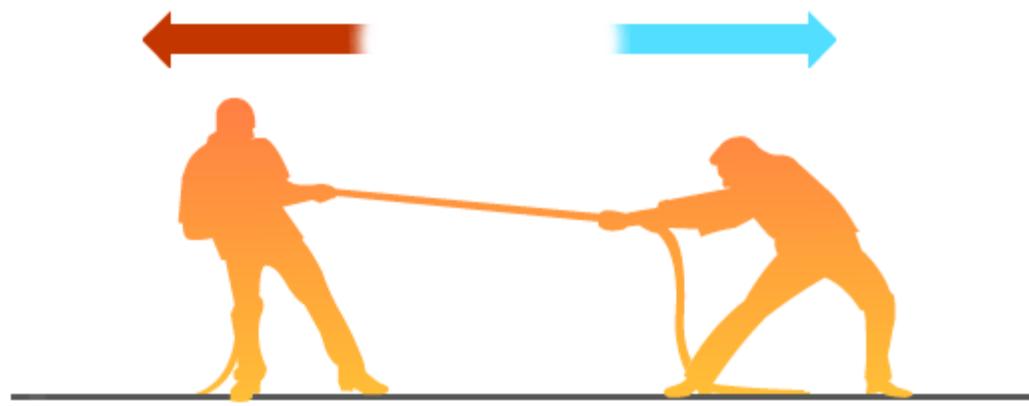
Examples



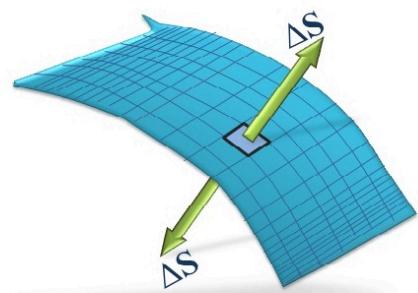
Stresses



How to represent a general state of stress.

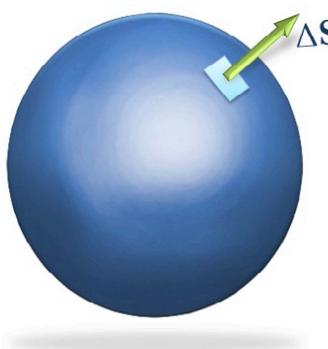


Area Vectors



Open Surface

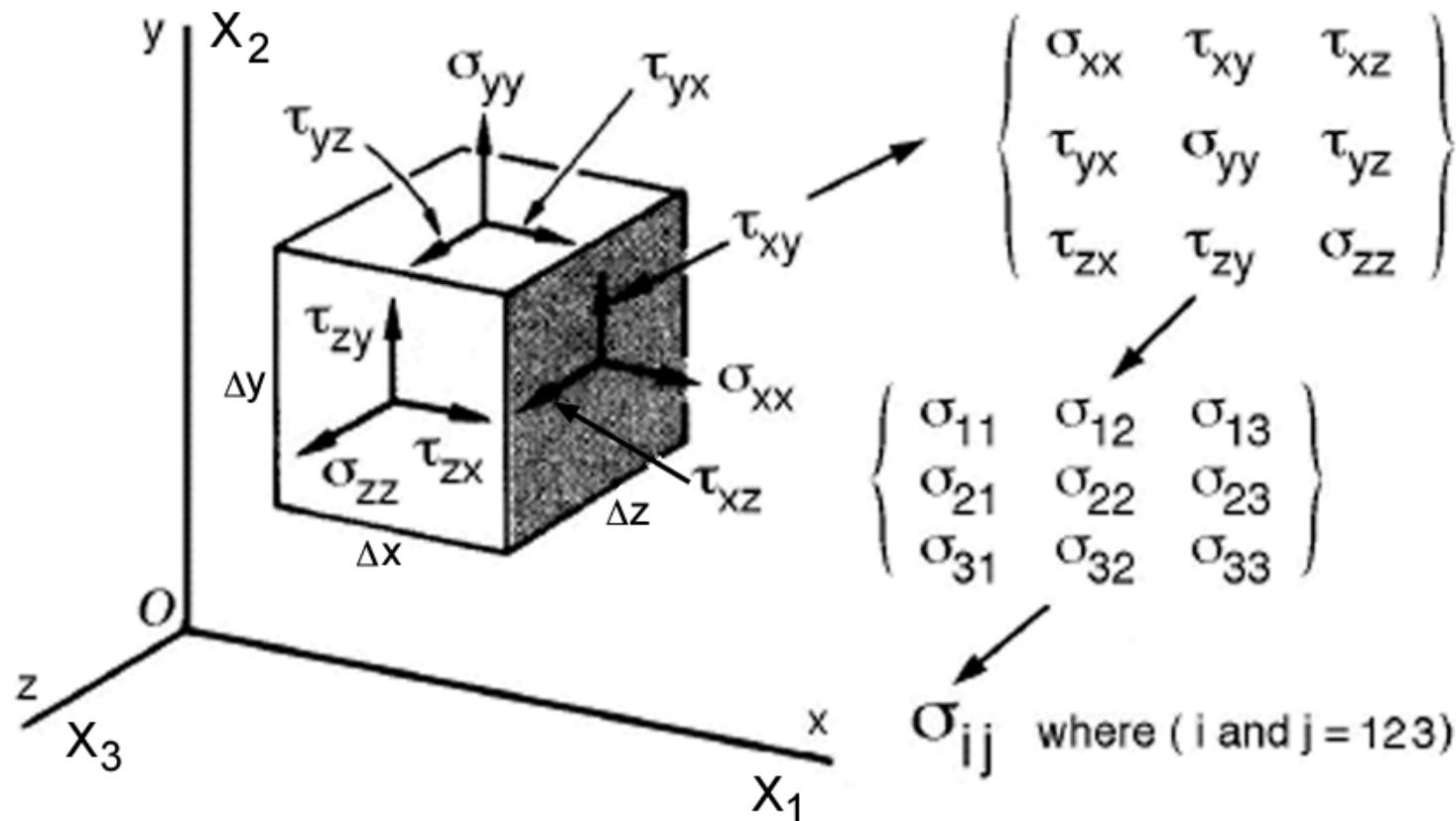
(Any one of the two *normals* can be taken as the *outward normal*)



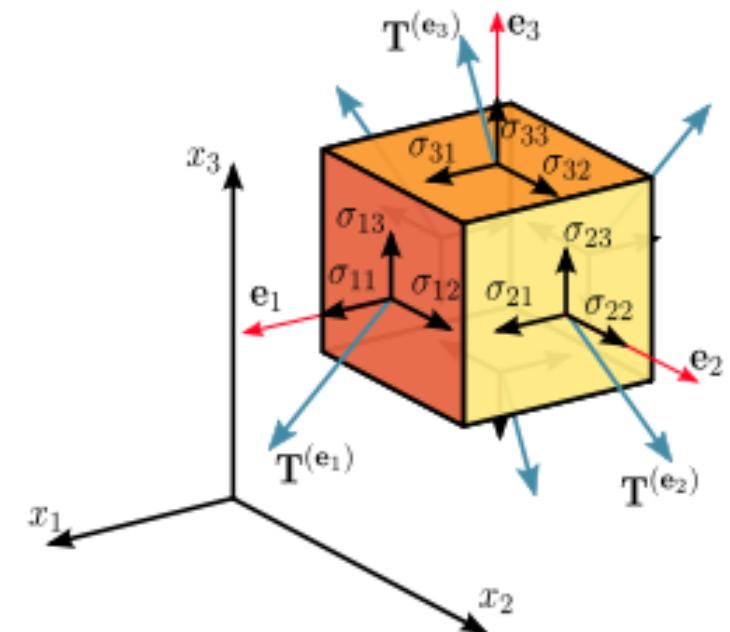
Closed Surface

(Only one possible *outward normal*)

Tensor Representation



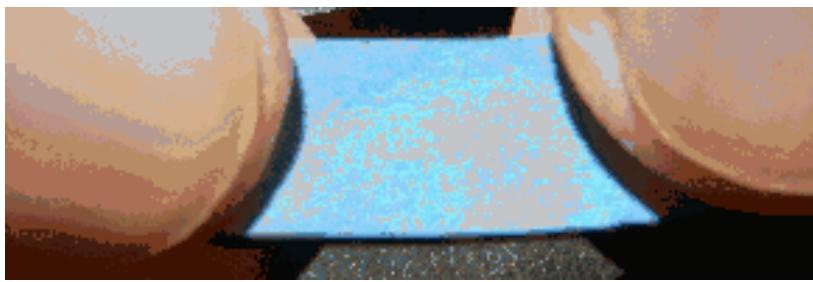
How to calculate the stresses in the bridge



Strain Tensor

- Write the strain tensor for a general state of stress.

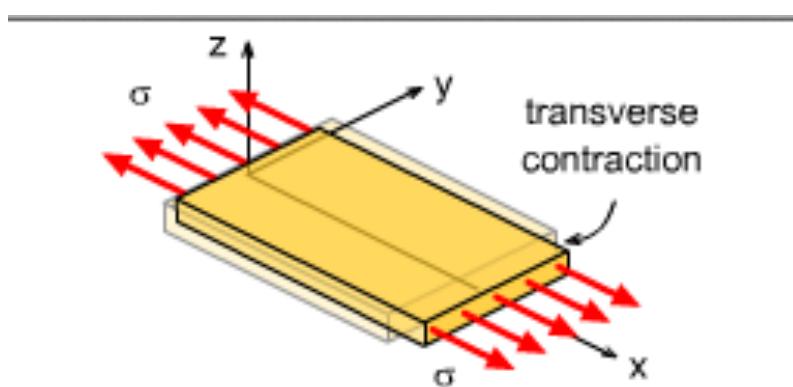
$$\begin{pmatrix} \varepsilon_{xx} & \varepsilon_{xy} & \varepsilon_{xz} \\ \varepsilon_{yx} & \varepsilon_{yy} & \varepsilon_{yz} \\ \varepsilon_{zx} & \varepsilon_{zy} & \varepsilon_{zz} \end{pmatrix}$$



Poisson's Ratio

- When loaded axially, what happens in lateral direction.

$$\nu = -\frac{d\varepsilon_{\text{trans}}}{d\varepsilon_{\text{axial}}} = -\frac{d\varepsilon_y}{d\varepsilon_x} = -\frac{d\varepsilon_z}{d\varepsilon_x}$$

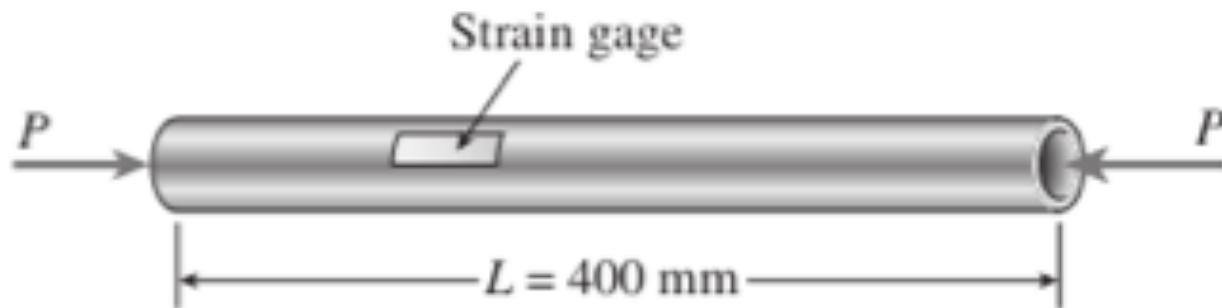


Generate State of Strain for Uniaxial Loading

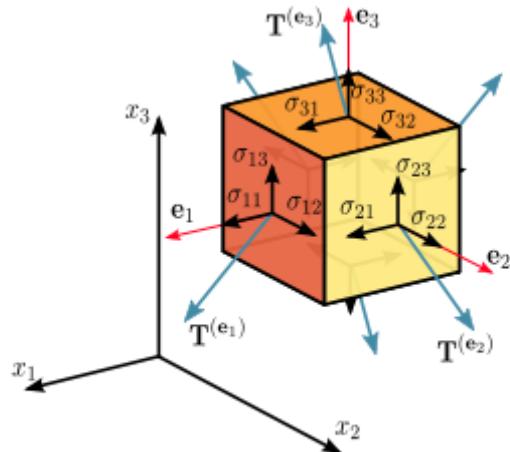
- Write the general state of strain for uniaxial loading.

Problem 1 A circular aluminum tube of length $L = 400$ mm is loaded in compression by forces P (see figure). The outside and inside diameters are 60 mm and 50 mm, respectively. A strain gage is placed on the outside of the bar to measure normal strains in the longitudinal direction.

- If the measured strain is $\epsilon = 550 \times 10^{-6}$, what is the shortening δ of the bar?
- If the compressive stress in the bar is intended to be 40 MPa, what should be the load P ?



What is the strain in terms of stresses



$$\varepsilon_x = \frac{\sigma_x}{E} - \nu \frac{\sigma_y}{E} - \nu \frac{\sigma_z}{E}$$

$$\varepsilon_y = -\nu \frac{\sigma_x}{E} + \frac{\sigma_y}{E} - \nu \frac{\sigma_z}{E}$$

$$\varepsilon_z = -\nu \frac{\sigma_x}{E} - \nu \frac{\sigma_y}{E} + \frac{\sigma_z}{E}$$

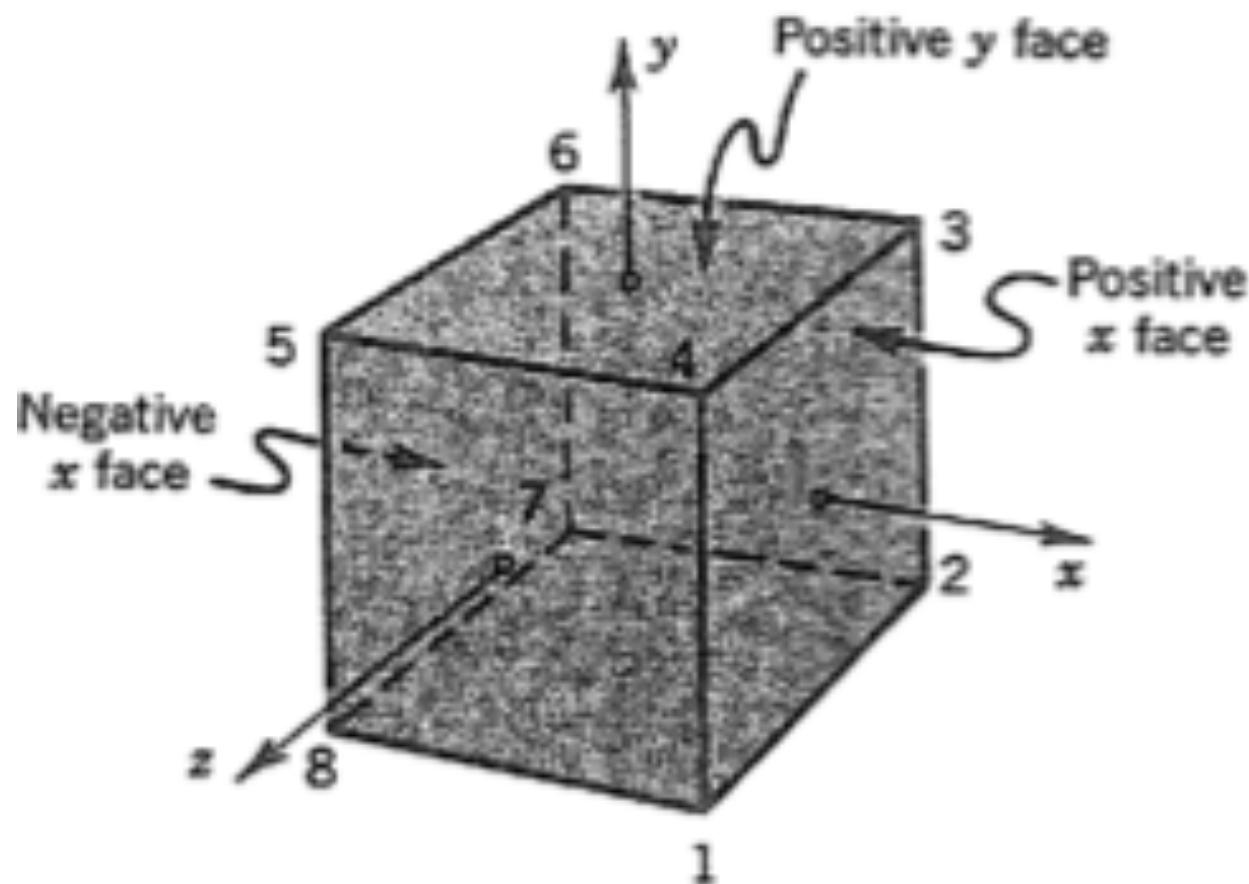
$$\gamma_{xy} = \frac{\tau_{xy}}{G} \quad \gamma_{yz} = \frac{\tau_{yz}}{G} \quad \gamma_{zx} = \frac{\tau_{zx}}{G}$$

Volume change

Isotropic Material

$$G = \frac{E}{2(1+\nu)}$$

Sign convention



Three aspects of problem-solving

- Principles of equilibrium.
- Geometrical compatibility.
- Relations between force and deformation.

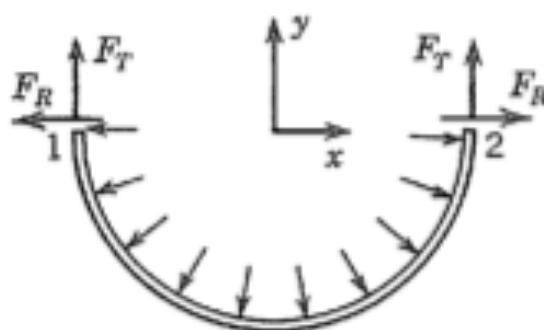
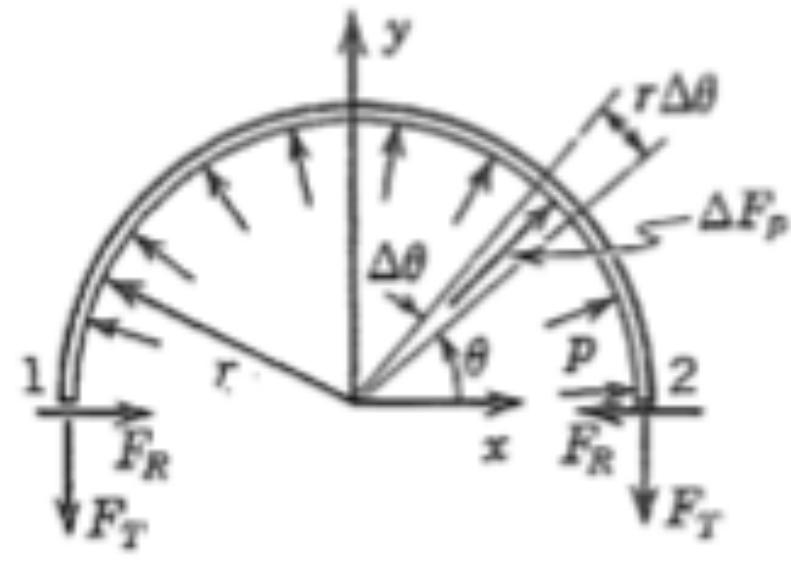
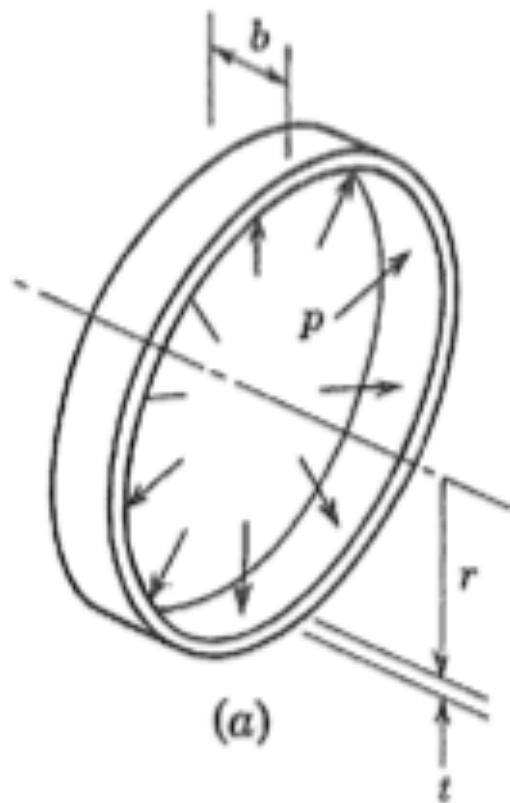
Plane fuselage



Aloha Airlines

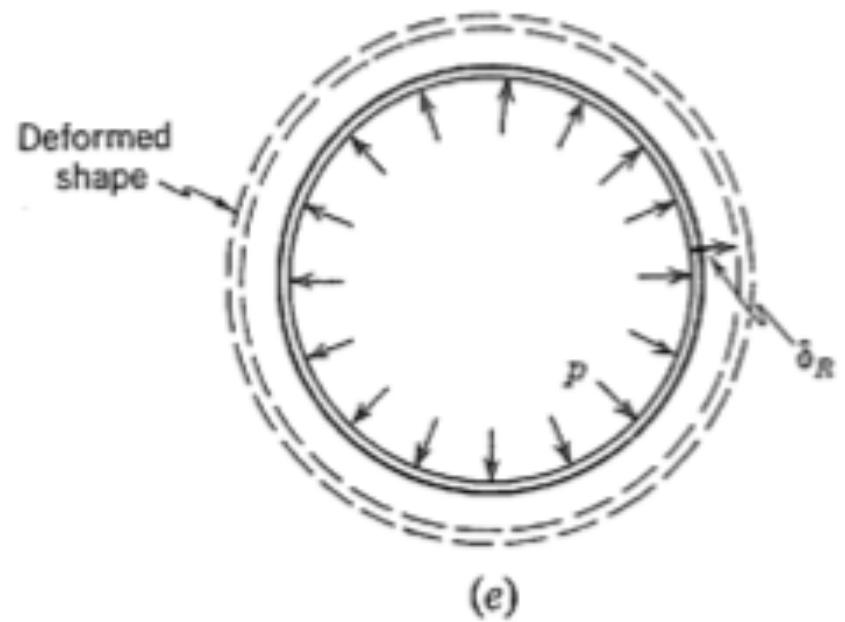


Hoop Stress



Three aspects of problem-solving

- Principles of equilibrium.
- Geometrical compatibility.
- Relations between force and deformation.

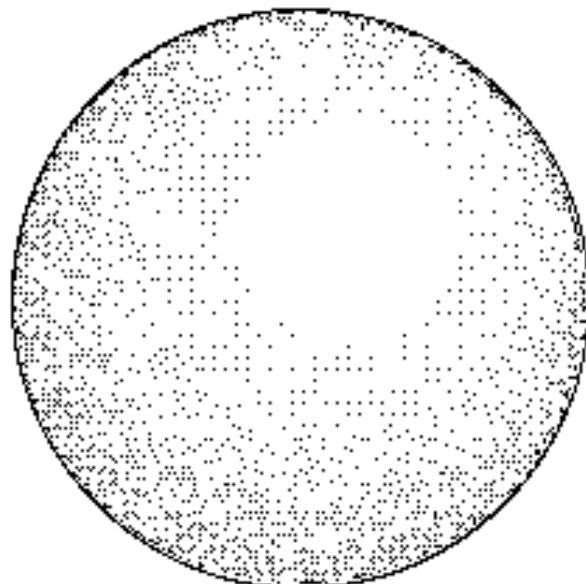


Three aspects of problem-solving

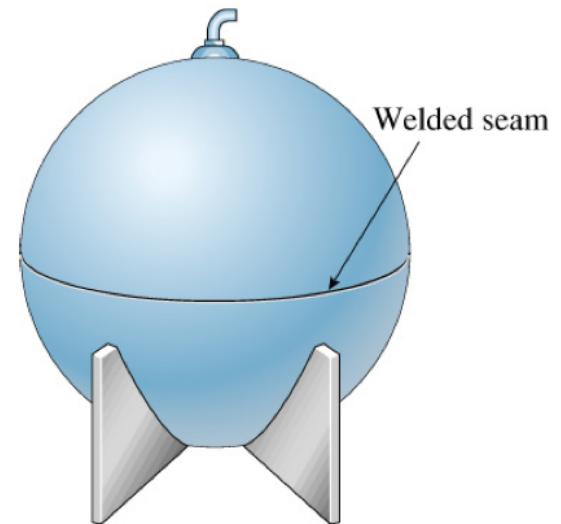
- Principles of equilibrium.
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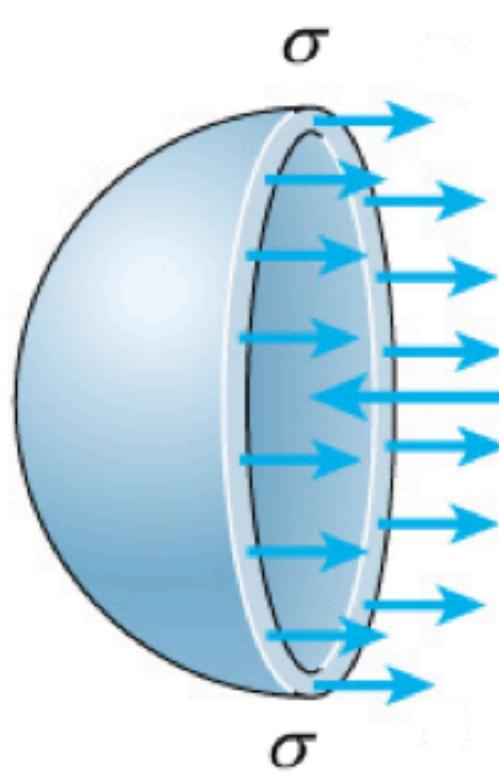
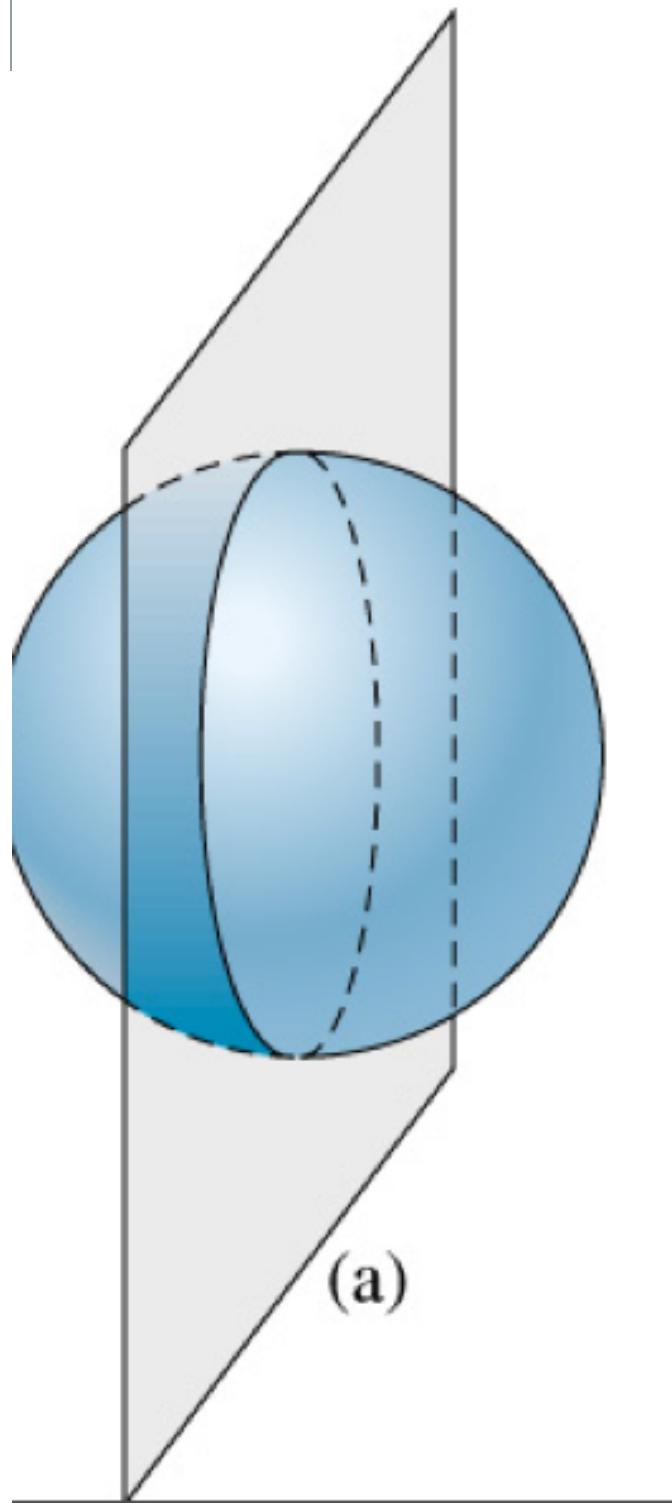
Problem

- What are the stresses in a sphere if the pressure is p ?



Another common pressure vessel shape is the sphere. Storage containers for high pressure gasses are often spherical. Also, when we blow-up balloons they often take the shape of a





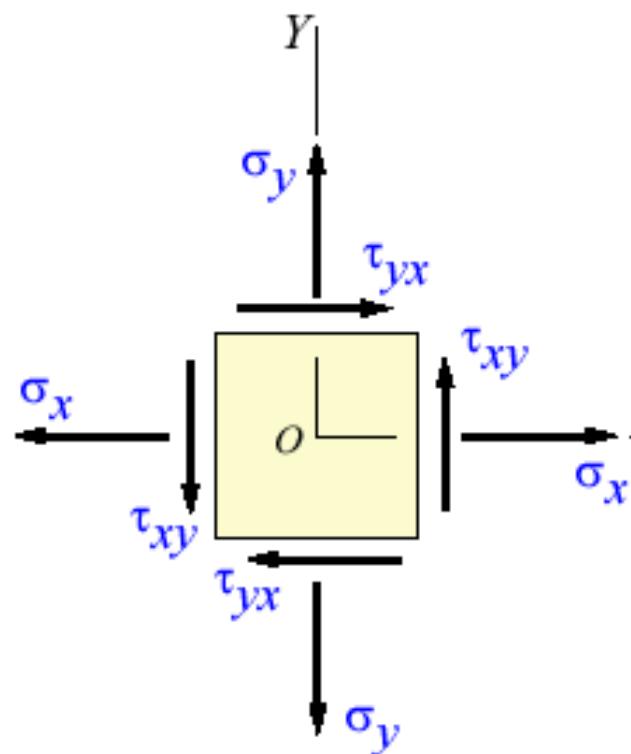
$$\sigma = \frac{pr}{2t}$$

(c)

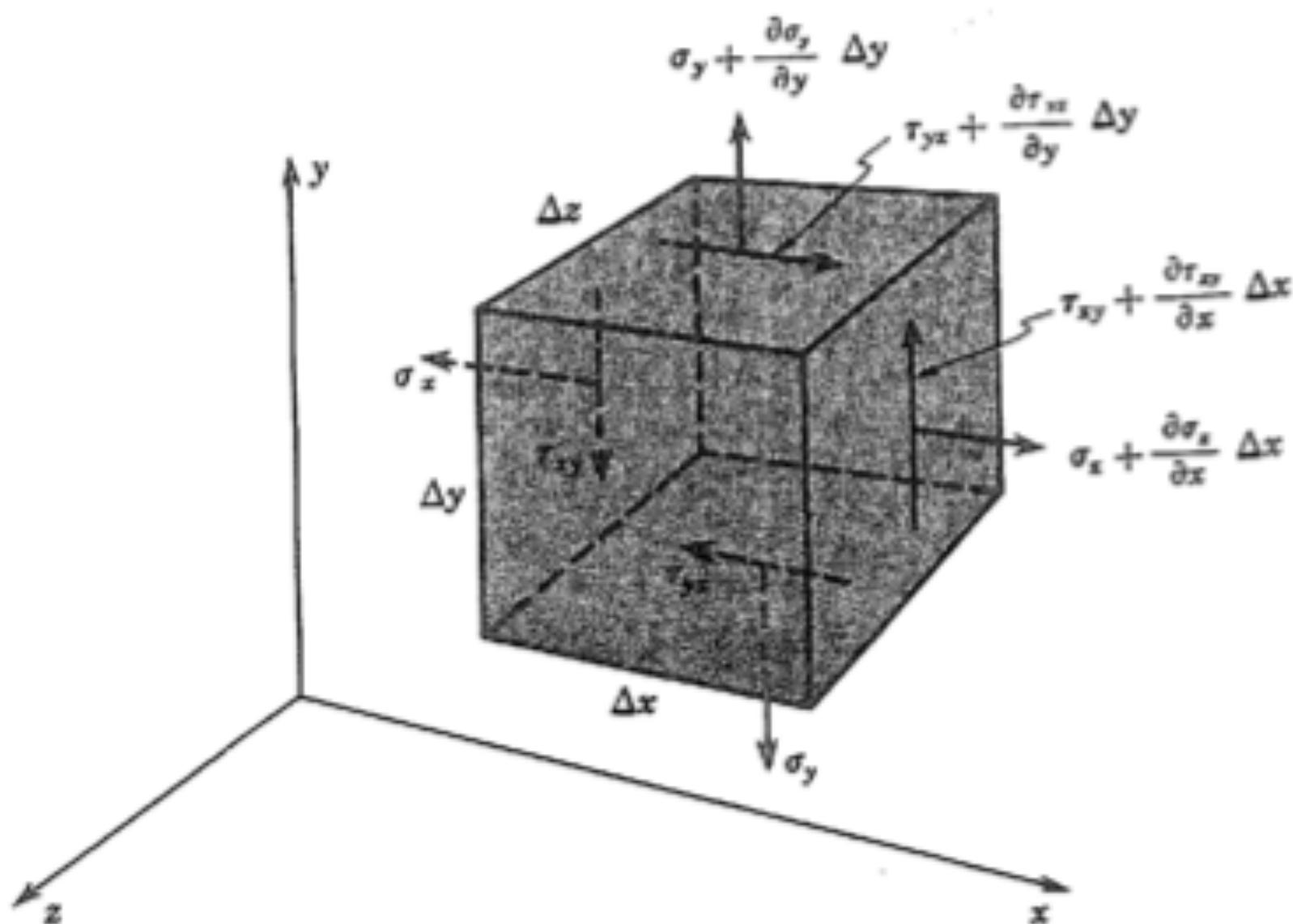
A diagram showing a circular cross-section of a spherical shell. The shell is shaded in light blue. At a point on the surface, a small square indicates a differential element. Two stress vectors, both labeled σ , are shown originating from opposite sides of this element, pointing toward each other and perpendicular to the surface, representing the shear stress at that point.

Plane stress

- Pull on a long thin wire of uniform section along the x-axis.
- Thin sheet being pulled by forces in the plane of the sheet.
- No variation :



Equilibrium



$$\begin{aligned}\Sigma M &= \left\{ (\tau_{xy} \Delta y \Delta z) \frac{\Delta x}{2} + \left[\left(\tau_{xy} + \frac{\partial \tau_{xy}}{\partial x} \Delta x \right) \Delta y \Delta z \right] \frac{\Delta x}{2} \right. \\ &\quad \left. - (\tau_{yx} \Delta x \Delta z) \frac{\Delta y}{2} - \left[\left(\tau_{yx} + \frac{\partial \tau_{yx}}{\partial y} \Delta y \right) \Delta x \Delta z \right] \frac{\Delta y}{2} \right\} k = 0\end{aligned}$$

$$\begin{aligned}\Sigma F_x &= \left(\sigma_x + \frac{\partial \sigma_x}{\partial x} \Delta x \right) \Delta y \Delta z + \left(\tau_{yx} + \frac{\partial \tau_{yx}}{\partial y} \Delta y \right) \Delta x \Delta z \\ &\quad - \sigma_x \Delta y \Delta z - \tau_{yx} \Delta x \Delta z = 0\end{aligned}$$

$$\begin{aligned}\Sigma F_y &= \left(\sigma_y + \frac{\partial \sigma_y}{\partial y} \Delta y \right) \Delta x \Delta z + \left(\tau_{xy} + \frac{\partial \tau_{xy}}{\partial x} \Delta x \right) \Delta y \Delta z \\ &\quad - \sigma_y \Delta x \Delta z - \tau_{xy} \Delta y \Delta z = 0\end{aligned}$$

$$\tau_{xy} + \frac{\partial \tau_{xy}}{\partial x} \frac{\Delta x}{2} - \tau_{yx} - \frac{\partial \tau_{yx}}{\partial y} \frac{\Delta y}{2} = 0$$

$$\tau_{yx} = \tau_{xy}$$

$$\frac{\partial \sigma_x}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} = 0$$

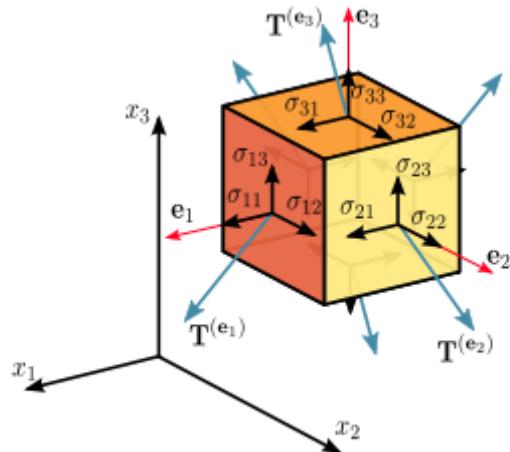
$$\frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_y}{\partial y} = 0$$

$$\frac{\partial \sigma_{11}}{\partial x_1} + \frac{\partial \sigma_{21}}{\partial x_2} + \frac{\partial \sigma_{31}}{\partial x_3} = 0$$

$$\frac{\partial \sigma_{12}}{\partial x_1} + \frac{\partial \sigma_{22}}{\partial x_2} + \frac{\partial \sigma_{32}}{\partial x_3} = 0$$

$$\frac{\partial \sigma_{13}}{\partial x_1} + \frac{\partial \sigma_{23}}{\partial x_2} + \frac{\partial \sigma_{33}}{\partial x_3} = 0$$

What is the strain in terms of stresses



$$\varepsilon_x = \frac{\sigma_x}{E} - \nu \frac{\sigma_y}{E} - \nu \frac{\sigma_z}{E}$$

$$\varepsilon_y = -\nu \frac{\sigma_x}{E} + \frac{\sigma_y}{E} - \nu \frac{\sigma_z}{E}$$

$$\varepsilon_z = -\nu \frac{\sigma_x}{E} - \nu \frac{\sigma_y}{E} + \frac{\sigma_z}{E}$$

$$\gamma_{xy} = \frac{\tau_{xy}}{G} \quad \gamma_{yz} = \frac{\tau_{yz}}{G} \quad \gamma_{zx} = \frac{\tau_{zx}}{G}$$

$$\sigma = E \epsilon$$

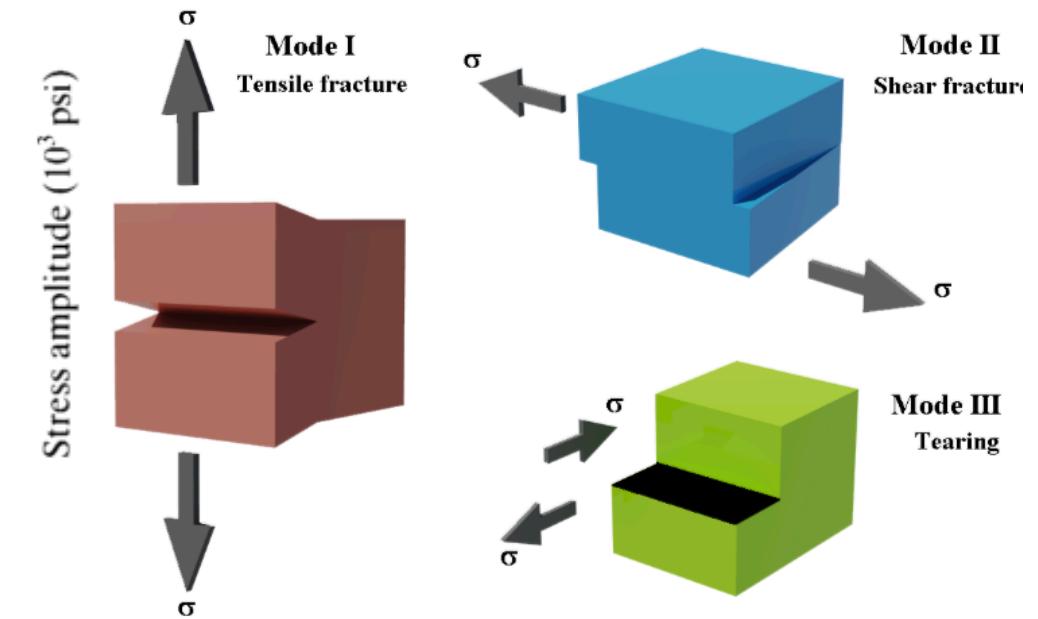
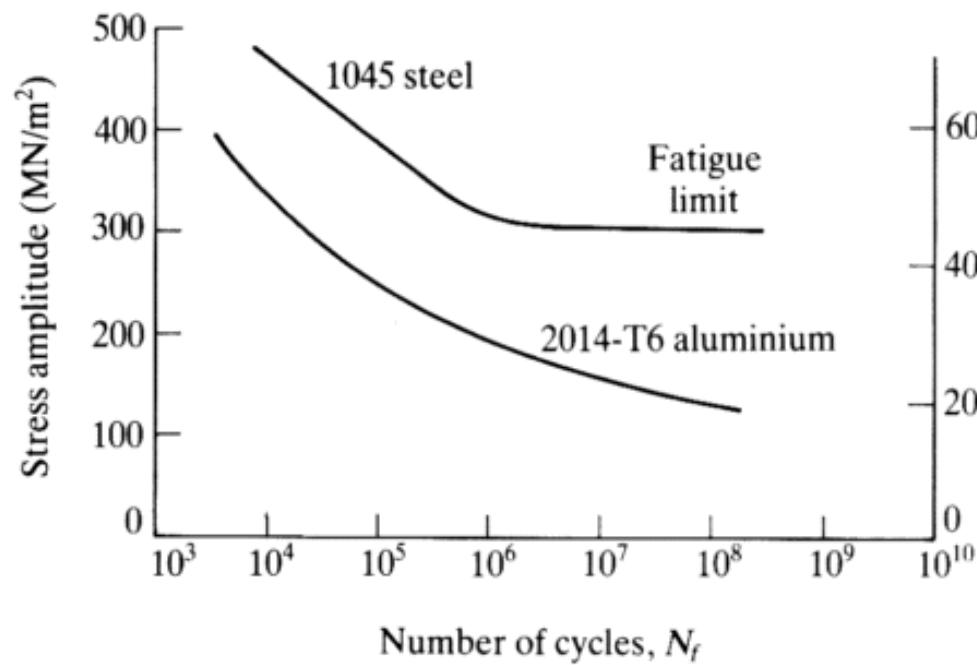
Only applicable in the specific situation of uniaxial stress (along the force) dependence on the strain in the direction of the force.

General dependence for an isotropic body

$$\begin{bmatrix} \epsilon_{xx} \\ \epsilon_{yy} \\ \epsilon_{zz} \\ \epsilon_{yz} \\ \epsilon_{zx} \\ \epsilon_{xy} \end{bmatrix} = \frac{1}{E} \begin{bmatrix} 1 & -\nu & -\nu & 0 & 0 & 0 \\ -\nu & 1 & -\nu & 0 & 0 & 0 \\ -\nu & -\nu & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1+\nu & 0 & 0 \\ 0 & 0 & 0 & 0 & 1+\nu & 0 \\ 0 & 0 & 0 & 0 & 0 & 1+\nu \end{bmatrix} \begin{bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{zz} \\ \sigma_{yz} \\ \sigma_{zx} \\ \sigma_{xy} \end{bmatrix}$$

Ways of characterizing failure

- Yield strength
- Fracture toughness
- Fatigue strength

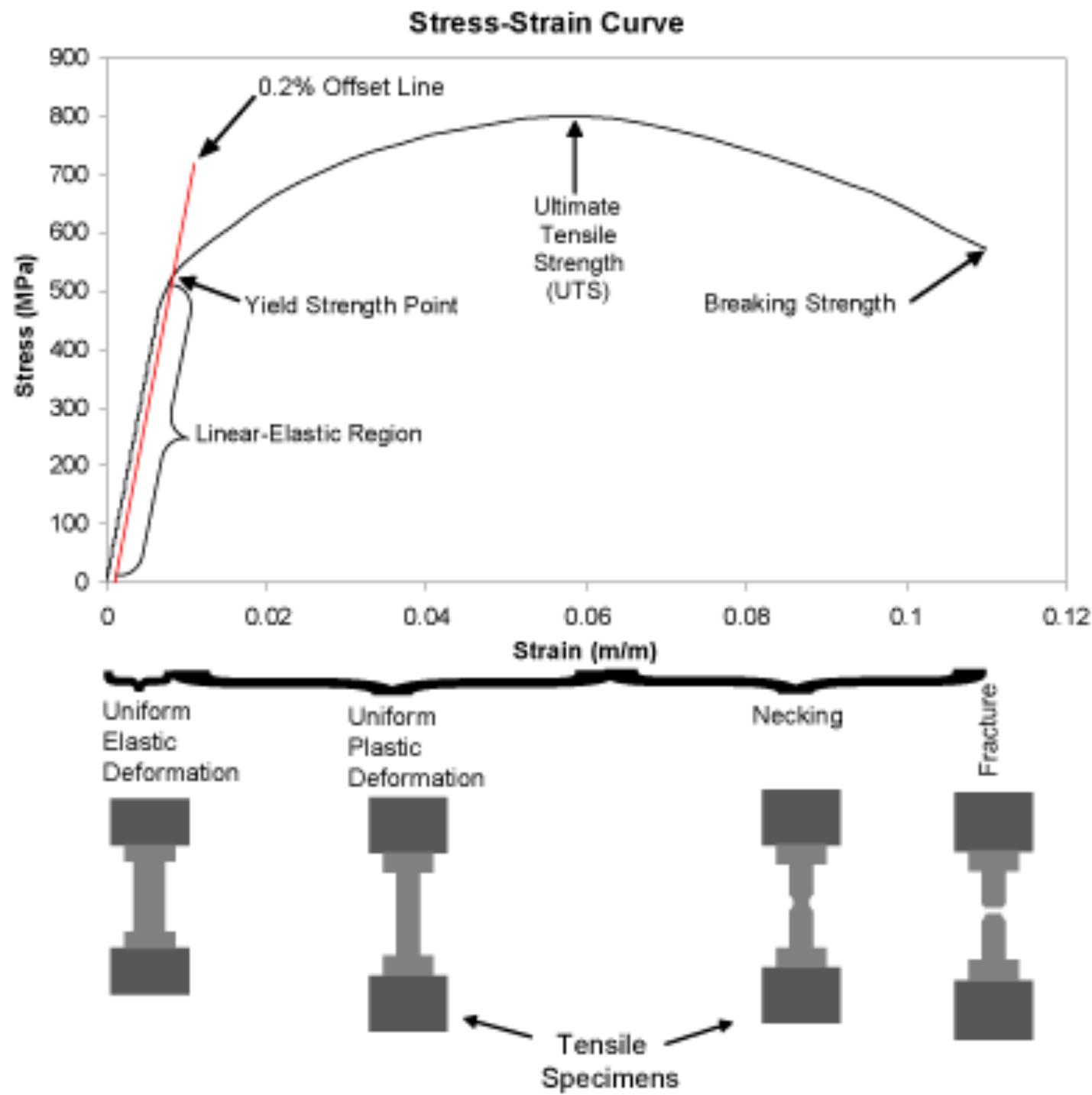


How to test mechanical properties

- Simulations from first principles.
- Experimental methods. (Tensile test)

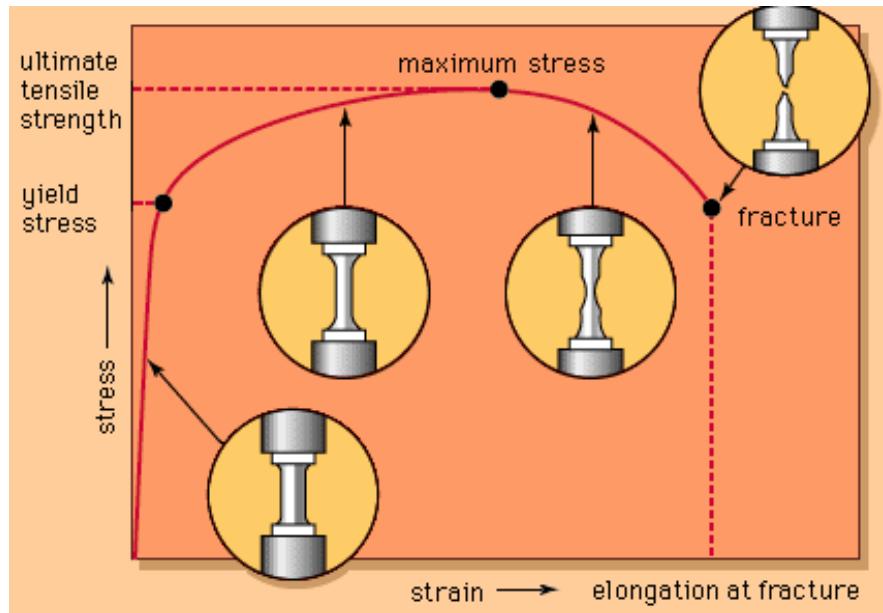
Tensile Test

**Tensile Test
Stainless Steel
Specimen**

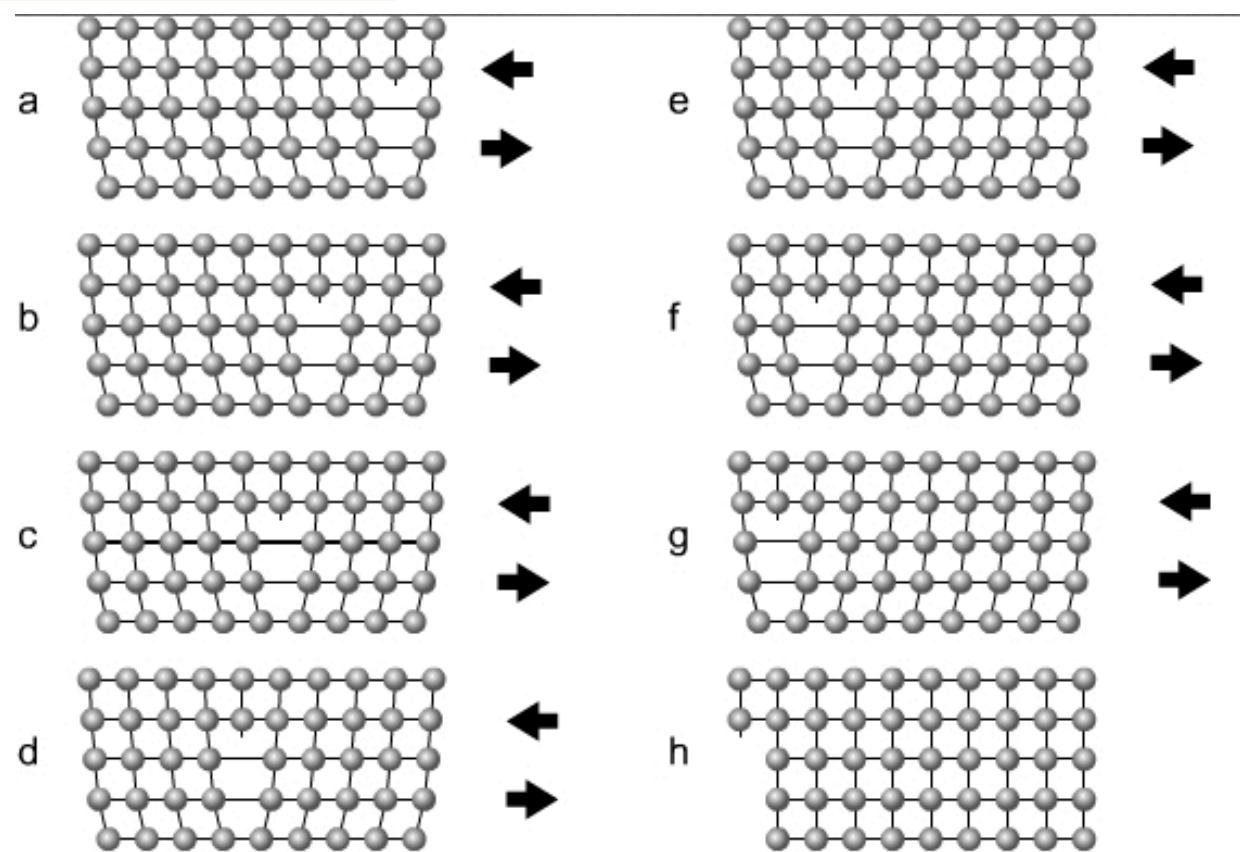


Tensile Test

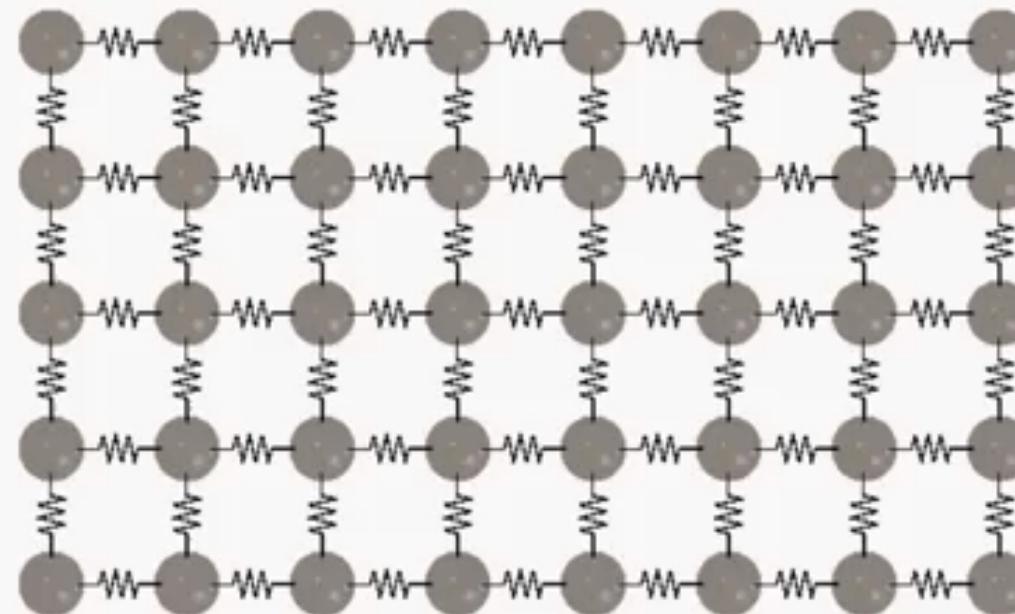
**Tensile Test
Stainless Steel
Specimen**



Dislocations



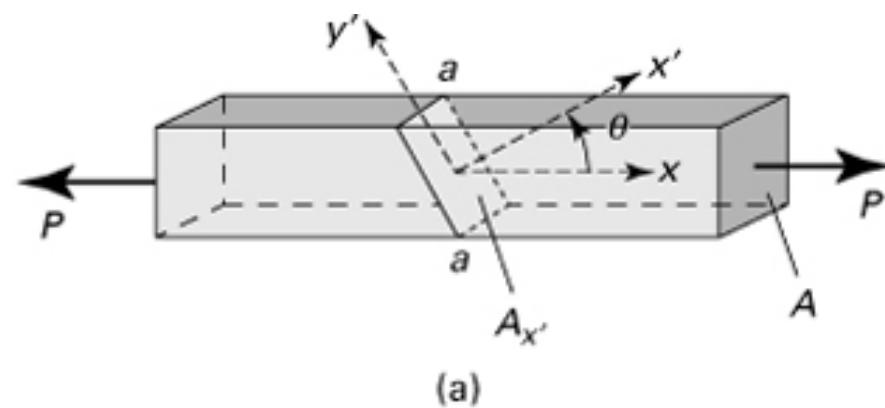
Dislocations



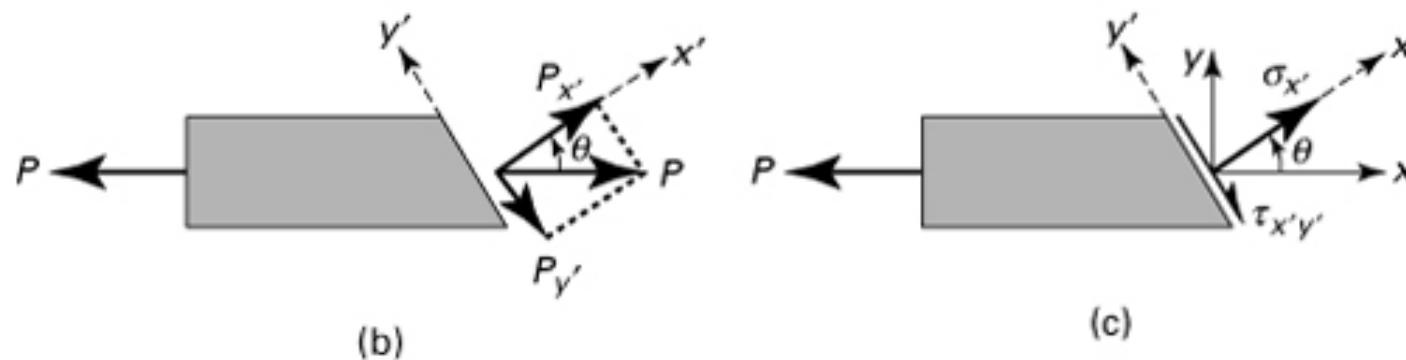
Work Hardening



Stress Transformation

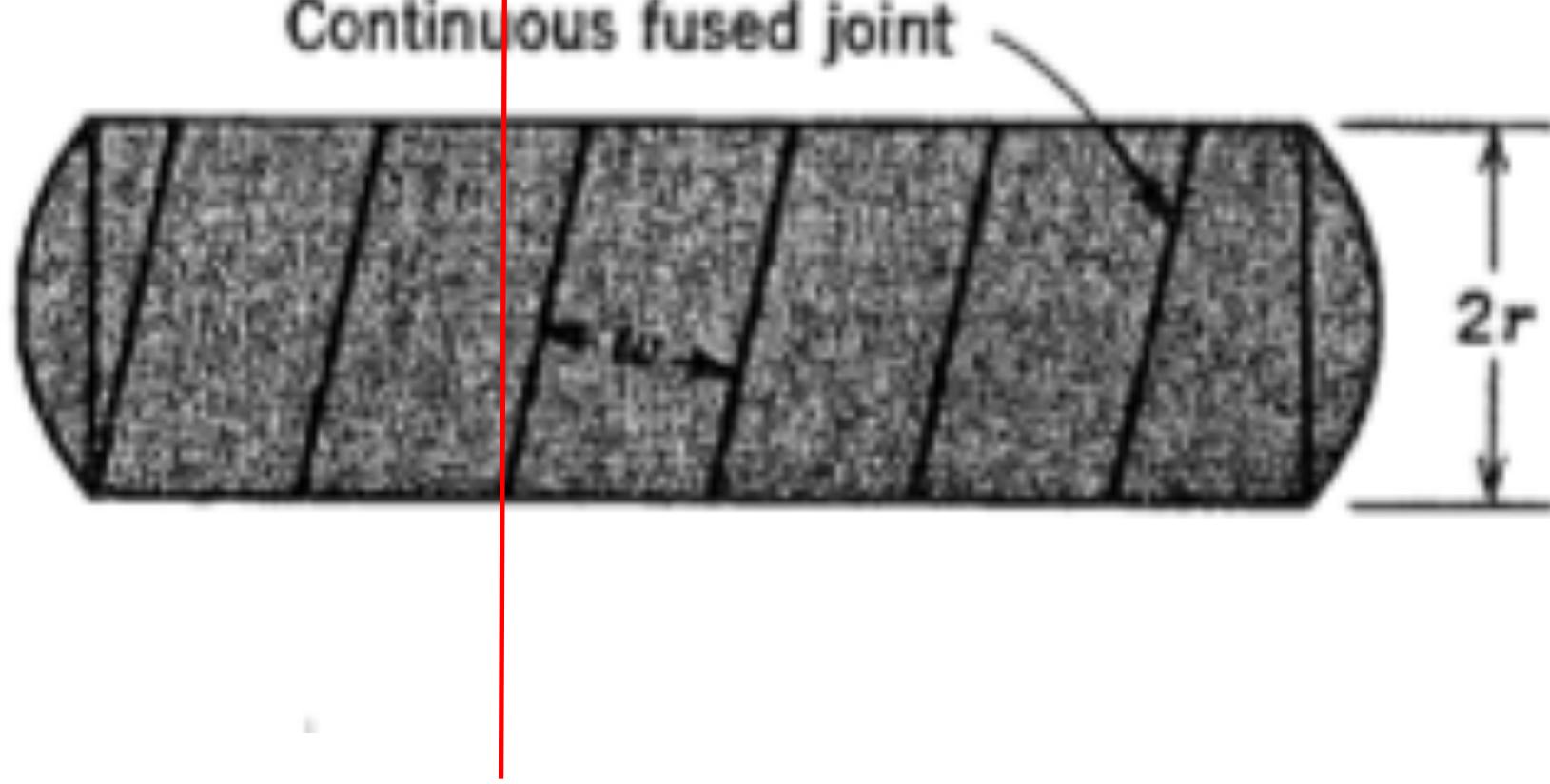


(a)

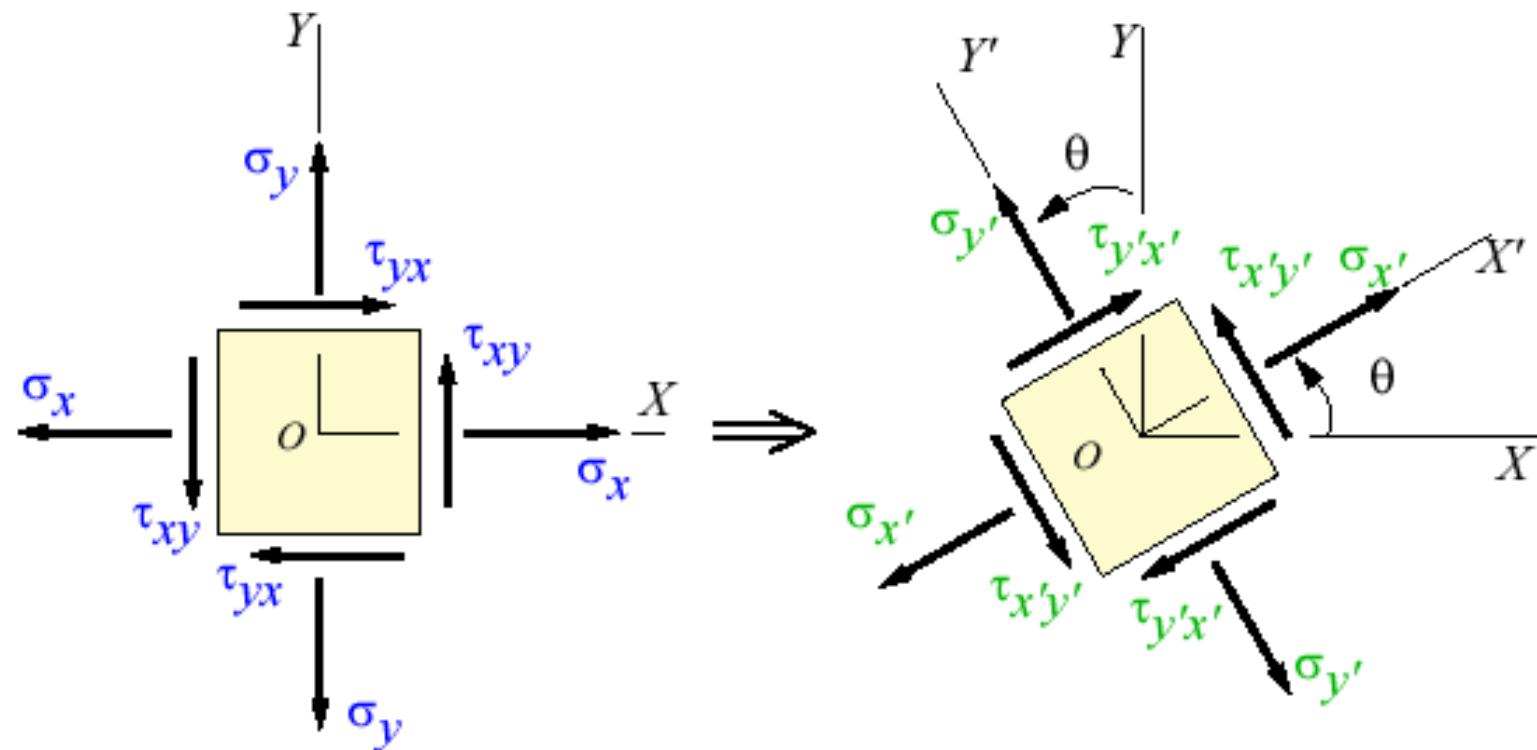


(b)

(c)



Stress Transformation



Stresses at given coordinate system Stresses transformed to another coordinate