

Feature Selection for Mixed-Effects Models

Aleksei Sholokhov

Thursday, 3rd of December, 2020

Plan

Introduction

- Linear Mixed-Effects Models
- Feature Selection for Mixed Models

Proposed Algorithm

Experiments

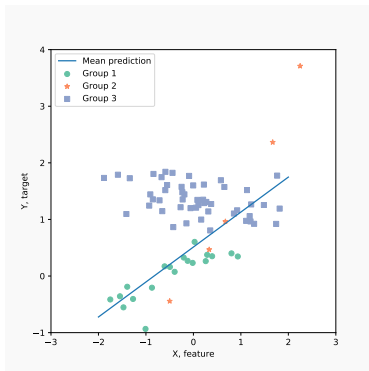
- Application to Synthetic Problems
- Application to Real-World Problems

Future Work

Linear Mixed-Effect Models are a type of regression models for grouped data

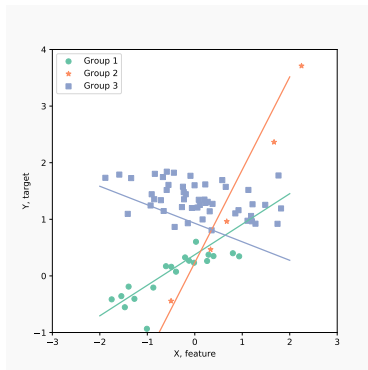
Dataset: m groups (X_i, y_i) , $i = 1, \dots, m$

Standard Linear Regression:



$$y = X\beta + \varepsilon, \quad \varepsilon \sim \mathcal{N}(0, \Lambda)$$

Linear Mixed-Effect Model:



$$y_i = X_i(\beta + \mathbf{u}_i) + \varepsilon_i, \quad \varepsilon_i \sim \mathcal{N}(0, \Lambda_i)$$
$$\mathbf{u}_i \sim \mathcal{N}(0, \Gamma)$$

Notation

$$\begin{aligned}y_i &= X_i(\beta + u_i) + \varepsilon_i \quad i = 1 \dots m \\ \varepsilon_i &\sim \mathcal{N}(\mathbf{0}, \Lambda_i) \\ u_i &\sim \mathcal{N}(\mathbf{0}, \Gamma)\end{aligned}\tag{1}$$

Notation

$$\begin{aligned}y_i &= \mathbf{X}_i(\beta + u_i) + \varepsilon_i \quad i = 1 \dots m \\ \varepsilon_i &\sim \mathcal{N}(0, \Lambda_i) \\ u_i &\sim \mathcal{N}(0, \Gamma)\end{aligned}\tag{1}$$

- $\mathbf{X}_i \in \mathbb{R}^{n_i \times p}$ – features, or covariates,

Notation

$$\begin{aligned}y_i &= X_i\beta + \mathbf{Z}_i u_i + \varepsilon_i \quad i = 1 \dots m \\ \varepsilon_i &\sim \mathcal{N}(0, \Lambda_i) \\ u_i &\sim \mathcal{N}(0, \Gamma)\end{aligned}\tag{1}$$

- ▶ $X_i \in \mathbb{R}^{n_i \times p}$ – **fixed** features, or covariates, $\mathbf{Z}_i \in \mathbb{R}^{n_i \times q}$ – **random features**
- ▶ p – number of fixed features, q – number of random effects.

Notation

$$\begin{aligned}y_i &= X_i \beta + Z_i u_i + \varepsilon_i \quad i = 1 \dots m \\ \varepsilon_i &\sim \mathcal{N}(0, \Lambda_i) \\ u_i &\sim \mathcal{N}(0, \Gamma)\end{aligned}\tag{1}$$

- ▶ $X_i \in \mathbb{R}^{n_i \times p}$ – fixed features, or covariates, $Z_i \in \mathbb{R}^{n_i \times q}$ – random features
- ▶ p – number of fixed features, q – number of random effects.
- ▶ $\beta \in \mathbb{R}^p$ – fixed effects, or mean effects

Notation

$$\begin{aligned}y_i &= X_i\beta + Z_i\mathbf{u}_i + \varepsilon_i \quad i = 1 \dots m \\ \varepsilon_i &\sim \mathcal{N}(0, \Lambda_i) \\ \mathbf{u}_i &\sim \mathcal{N}(0, \Gamma)\end{aligned}\tag{1}$$

- ▶ $X_i \in \mathbb{R}^{n_i \times p}$ – fixed features, or covariates, $Z_i \in \mathbb{R}^{n_i \times q}$ – random features
- ▶ p – number of fixed features, q – number of random effects.
- ▶ $\beta \in \mathbb{R}^p$ – fixed effects, or mean effects
- ▶ $\mathbf{u}_i \in \mathbb{R}^q$ – random effects

Notation

$$\begin{aligned}y_i &= X_i\beta + Z_i u_i + \varepsilon_i \quad i = 1 \dots m \\ \varepsilon_i &\sim \mathcal{N}(0, \Lambda_i) \\ u_i &\sim \mathcal{N}(0, \Gamma)\end{aligned}\tag{1}$$

- ▶ $X_i \in \mathbb{R}^{n_i \times p}$ – fixed features, or covariates, $Z_i \in \mathbb{R}^{n_i \times q}$ – random features
- ▶ p – number of fixed features, q – number of random effects.
- ▶ $\beta \in \mathbb{R}^p$ – fixed effects, or mean effects
- ▶ $u_i \in \mathbb{R}^q$ – random effects
- ▶ $\Gamma \in \mathbb{R}^{q \times q}$ – covariance matrix of random effects

Notation

$$\begin{aligned}y_i &= X_i\beta + Z_i u_i + \varepsilon_i \quad i = 1 \dots m \\ \varepsilon_i &\sim \mathcal{N}(0, \Lambda_i) \\ u_i &\sim \mathcal{N}(0, \Gamma)\end{aligned}\tag{1}$$

- ▶ $X_i \in \mathbb{R}^{n_i \times p}$ – fixed features, or covariates, $Z_i \in \mathbb{R}^{n_i \times q}$ – random features
- ▶ p – number of fixed features, q – number of random effects.
- ▶ $\beta \in \mathbb{R}^p$ – fixed effects, or mean effects
- ▶ $u_i \in \mathbb{R}^q$ – random effects
- ▶ $\Gamma \in \mathbb{R}^{q \times q}$ – covariance matrix of random effects
- ▶ $\varepsilon_i \in \mathbb{R}^{n_i}$ – observation noise

Notation

$$\begin{aligned}y_i &= X_i\beta + Z_iu_i + \varepsilon_i \quad i = 1 \dots m \\ \varepsilon_i &\sim \mathcal{N}(0, \Lambda_i) \\ u_i &\sim \mathcal{N}(0, \Gamma)\end{aligned}\tag{1}$$

- ▶ $X_i \in \mathbb{R}^{n_i \times p}$ – fixed features, or covariates, $Z_i \in \mathbb{R}^{n_i \times q}$ – random features
- ▶ p – number of fixed features, q – number of random effects.
- ▶ $\beta \in \mathbb{R}^p$ – fixed effects, or mean effects
- ▶ $u_i \in \mathbb{R}^q$ – random effects
- ▶ $\Gamma \in \mathbb{R}^{q \times q}$ – covariance matrix of random effects
- ▶ $\varepsilon_i \in \mathbb{R}^{n_i}$ – observation noise
- ▶ $\Lambda_i \in \mathbb{R}^{n_i \times n_i}$ – covariance matrix for noise

Notation

$$\begin{aligned}y_i &= X_i \beta + Z_i u_i + \varepsilon_i \quad i = 1 \dots m \\ \varepsilon_i &\sim \mathcal{N}(0, \Lambda_i) \\ u_i &\sim \mathcal{N}(0, \Gamma)\end{aligned}\tag{1}$$

- ▶ $X_i \in \mathbb{R}^{n_i \times p}$ – fixed features, or covariates, $Z_i \in \mathbb{R}^{n_i \times q}$ – random features
- ▶ p – number of fixed features, q – number of random effects.
- ▶ $\beta \in \mathbb{R}^p$ – fixed effects, or mean effects
- ▶ $u_i \in \mathbb{R}^q$ – random effects
- ▶ $\Gamma \in \mathbb{R}^{q \times q}$ – covariance matrix of random effects
- ▶ $\varepsilon_i \in \mathbb{R}^{n_i}$ – observation noise
- ▶ $\Lambda_i \in \mathbb{R}^{n_i \times n_i}$ – covariance matrix for noise
- ▶ Unknowns: β , u_i , Γ , sometimes Λ_i .

Notation

$$\begin{aligned}y_i &= X_i\beta + Z_i u_i + \varepsilon_i \quad i = 1 \dots m \\ \varepsilon_i &\sim \mathcal{N}(0, \Lambda_i) \\ u_i &\sim \mathcal{N}(0, \Gamma)\end{aligned}\tag{1}$$

- ▶ $X_i \in \mathbb{R}^{n_i \times p}$ – fixed features, or covariates, $Z_i \in \mathbb{R}^{n_i \times q}$ – random features
- ▶ p – number of fixed features, q – number of random effects.
- ▶ $\beta \in \mathbb{R}^p$ – fixed effects, or mean effects
- ▶ $u_i \in \mathbb{R}^q$ – random effects
- ▶ $\Gamma \in \mathbb{R}^{q \times q}$ – covariance matrix of random effects
- ▶ $\varepsilon_i \in \mathbb{R}^{n_i}$ – observation noise
- ▶ $\Lambda_i \in \mathbb{R}^{n_i \times n_i}$ – covariance matrix for noise
- ▶ Unknowns: β , u_i , Γ , sometimes Λ_i .

$\Gamma = \text{Diag}(\gamma)$, $\gamma \in \mathbb{R}^q$ and Λ_i are known.

Likelihood for Mixed Models

Suppose we have a linear mixed effects model

$$\begin{aligned}Y_i &= X_i\beta + Z_i u_i + \varepsilon_i \\u_i &\sim \mathcal{N}(0, \Gamma), \quad \Gamma = \text{Diag } \gamma \\ \varepsilon_i &\sim \mathcal{N}(0, \Lambda_i)\end{aligned}\tag{2}$$

where β , γ , and u_i are unknown model parameters, and λ_i are known.

Noticing that $Z_i u_i + \varepsilon_i \sim \mathcal{N}(0, Z_i \Gamma Z_i^T + \Lambda_i)$ we get the negative log-likelihood:

$$\begin{aligned}\mathcal{L}(\beta, \gamma) &= \sum_{i=1}^m \frac{1}{2} (y_i - X_i \beta)^T (Z_i \Gamma Z_i^T + \Lambda_i)^{-1} (y_i - X_i \beta) + \\ &\quad + \frac{1}{2} \log \det (Z_i \Gamma Z_i^T + \Lambda_i)\end{aligned}\tag{3}$$

Feature Selection for Mixed Models

Consider the following feature selection setup:

$$\begin{aligned} \min_{\beta, \gamma} \mathcal{L}(\beta, \gamma) \\ \text{s.t. } \|\beta\|_0 \leq k \\ \|\gamma\|_0 \leq j \\ \gamma \geq 0 \end{aligned} \tag{4}$$

where k and j is the size of the sparse support for the fixed and random effects respectively.

This is a very hard problem to solve directly.

Methods for Feature Selection

There are several ways to address this setup:

(0) Exhaustive Search:

$$\begin{aligned} \min_{\beta, \gamma} \mathcal{L}(\beta, \gamma) \\ \text{s.t. } \|\beta\|_0 \leq k \\ \|\gamma\|_0 \leq j \\ \gamma \geq 0 \end{aligned}$$

AIC [VB05]

BIC [Jon11]

Methods for Feature Selection

There are several ways to address this setup:

(0) Exhaustive Search:

$$\begin{aligned} \min_{\beta, \gamma} \mathcal{L}(\beta, \gamma) \\ \text{s.t. } \|\beta\|_0 \leq k \\ \|\gamma\|_0 \leq j \\ \gamma \geq 0 \end{aligned}$$

AIC [VB05]
BIC [Jon11]

(1) ℓ_1 -relaxation:

$$\begin{aligned} \min_{\beta, \gamma} \mathcal{L}(\beta, \gamma) \\ \text{s.t. } \|\beta\|_1 \leq \lambda_\beta \\ \|\gamma\|_1 \leq \lambda_\gamma \\ \gamma \geq 0 \end{aligned}$$

M-ALASSO [BKG10]
ALASSO [LPJ13]

Methods for Feature Selection

There are several ways to address this setup:

(0) Exhaustive Search:

$$\begin{aligned} \min_{\beta, \gamma} \mathcal{L}(\beta, \gamma) \\ \text{s.t. } \|\beta\|_0 \leq k \\ \|\gamma\|_0 \leq j \\ \gamma \geq 0 \end{aligned}$$

AIC [VB05]
BIC [Jon11]

(1) ℓ_1 -relaxation:

$$\begin{aligned} \min_{\beta, \gamma} \mathcal{L}(\beta, \gamma) \\ \text{s.t. } \|\beta\|_1 \leq \lambda_\beta \\ \|\gamma\|_1 \leq \lambda_\gamma \\ \gamma \geq 0 \end{aligned}$$

M-ALASSO [BKG10]
ALASSO [LPJ13]

(3) Other types of
sparsity-inducing penalties
(ℓ_p , SCAD).

SCAD [FL01]
SCAD-P [FL12]

Methods for Feature Selection

There are several ways to address this setup:

(0) Exhaustive Search:

$$\begin{aligned} \min_{\beta, \gamma} \mathcal{L}(\beta, \gamma) \\ \text{s.t. } \|\beta\|_0 \leq k \\ \|\gamma\|_0 \leq j \\ \gamma \geq 0 \end{aligned}$$

(1) ℓ_1 -relaxation:

$$\begin{aligned} \min_{\beta, \gamma} \mathcal{L}(\beta, \gamma) \\ \text{s.t. } \|\beta\|_1 \leq \lambda_\beta \\ \|\gamma\|_1 \leq \lambda_\gamma \\ \gamma \geq 0 \end{aligned}$$

(3) Other types of sparsity-inducing penalties (ℓ_p , SCAD).

(2) SR3-type Relaxation [ZAB⁺19]

$$\begin{aligned} \min_{\beta, \gamma, \hat{\beta}, \hat{\gamma}} \mathcal{L}(\beta, \gamma) + \frac{\lambda_\beta}{2} \|\beta - \hat{\beta}\|_2^2 + \frac{\lambda_\gamma}{2} \|\gamma - \hat{\gamma}\|_2^2 \\ \text{s.t. } \|\hat{\beta}\|_0 \leq k \\ \|\hat{\gamma}\|_0 \leq j, \gamma \geq 0 \end{aligned} \tag{5}$$

Relax-and-Split from Optimization Perspective

$$\begin{aligned} \min_{\beta, \gamma, \hat{\beta}, \hat{\gamma}} & \mathcal{L}(\beta, \gamma) + \frac{\lambda_{\beta}}{2} \|\beta - \hat{\beta}\|_2^2 + \frac{\lambda_{\gamma}}{2} \|\gamma - \hat{\gamma}\|_2^2 \\ \text{s.t.} & \|\hat{\beta}\|_0 \leq k, \|\hat{\gamma}\|_0 \leq j \\ & \gamma \geq 0, \hat{\gamma} \geq 0 \end{aligned} \tag{6}$$

We'll find β^* , γ^* , $\hat{\beta}^*$, and $\hat{\gamma}^*$ via alternating partial minimization:

Relax-and-Split from Optimization Perspective

$$\begin{aligned} \min_{\beta, \gamma, \hat{\beta}, \hat{\gamma}} \quad & \mathcal{L}(\beta, \gamma) + \frac{\lambda_{\beta}}{2} \|\beta - \hat{\beta}\|_2^2 + \frac{\lambda_{\gamma}}{2} \|\gamma - \hat{\gamma}\|_2^2 \\ \text{s.t.} \quad & \|\hat{\beta}\|_0 \leq k, \|\hat{\gamma}\|_0 \leq j \\ & \gamma \geq \mathbf{0}, \hat{\gamma} \geq \mathbf{0} \end{aligned} \tag{6}$$

We'll find β^* , γ^* , $\hat{\beta}^*$, and $\hat{\gamma}^*$ via alternating partial minimization:

- Minimization w.r.t. β and γ is done via **Interior Point Method**.

Relax-and-Split from Optimization Perspective

$$\begin{aligned} \min_{\beta, \gamma, \hat{\beta}, \hat{\gamma}} \mathcal{L}(\beta, \gamma) + \frac{\lambda_{\beta}}{2} \|\beta - \hat{\beta}\|_2^2 + \frac{\lambda_{\gamma}}{2} \|\gamma - \hat{\gamma}\|_2^2 \\ \text{s.t. } \|\hat{\beta}\|_0 \leq k, \|\hat{\gamma}\|_0 \leq j \\ \gamma \geq 0, \hat{\gamma} \geq 0 \end{aligned} \quad (6)$$

We'll find β^* , γ^* , $\hat{\beta}^*$, and $\hat{\gamma}^*$ via alternating partial minimization:

- Minimization w.r.t. β and γ is done via **Interior Point Method**.
- Minimization w.r.t. $\hat{\beta}$ and $\hat{\gamma}$ is **projection** of β and γ onto ℓ_0 -balls.

$$\begin{aligned} \hat{\beta}^{(k+1)} \leftarrow \underset{\|\beta\|_0 \leq k}{\text{Proj}} (\beta^{(k)}) &\implies \text{Take max } k \text{ from } \beta, \text{ rest to } 0 \\ \hat{\gamma}^{(k+1)} \leftarrow \underset{\|\gamma\|_0 \leq s}{\text{Proj}} (\gamma^{(k)}) &\implies \text{Take max } j \text{ from } \gamma, \text{ rest to } 0 \end{aligned} \quad (7)$$

Relax-and-Split from Optimization Perspective

$$\begin{aligned} \min_{\beta, \gamma, \hat{\beta}, \hat{\gamma}} \mathcal{L}(\beta, \gamma) + \frac{\lambda_{\beta}}{2} \|\beta - \hat{\beta}\|_2^2 + \frac{\lambda_{\gamma}}{2} \|\gamma - \hat{\gamma}\|_2^2 \\ \text{s.t. } \|\hat{\beta}\|_0 \leq k, \|\hat{\gamma}\|_0 \leq j \\ \gamma \geq 0, \hat{\gamma} \geq 0 \end{aligned} \tag{6}$$

We'll find β^* , γ^* , $\hat{\beta}^*$, and $\hat{\gamma}^*$ via alternating partial minimization:

- ▶ Minimization w.r.t. β and γ is done via **Interior Point Method**.
- ▶ Minimization w.r.t. $\hat{\beta}$ and $\hat{\gamma}$ is **projection** of β and γ onto ℓ_0 -balls.
- ▶ λ_{β} and λ_{γ} are **iteratively increased** until $\hat{\beta} \approx \beta$ and $\hat{\gamma} \approx \gamma$.

Relax-and-Split from Optimization Perspective

$$\begin{aligned} \min_{\beta, \gamma, \hat{\beta}, \hat{\gamma}} \mathcal{L}(\beta, \gamma) + \frac{\lambda_\beta}{2} \|\beta - \hat{\beta}\|_2^2 + \frac{\lambda_\gamma}{2} \|\gamma - \hat{\gamma}\|_2^2 \\ \text{s.t. } \|\hat{\beta}\|_0 \leq k, \|\hat{\gamma}\|_0 \leq j \\ \gamma \geq 0, \hat{\gamma} \geq 0 \end{aligned} \tag{6}$$

We'll find β^* , γ^* , $\hat{\beta}^*$, and $\hat{\gamma}^*$ via alternating partial minimization:

- ▶ Minimization w.r.t. β and γ is done via **Interior Point Method**.
- ▶ Minimization w.r.t. $\hat{\beta}$ and $\hat{\gamma}$ is **projection** of β and γ onto ℓ_0 -balls.
- ▶ λ_β and λ_γ are **iteratively increased** until $\hat{\beta} \approx \beta$ and $\hat{\gamma} \approx \gamma$.

Advantages:

1. Interpretable hyperparameters.
2. No model bias when the k -subspace is chosen.

The pseudocode of the proposed algorithm:

```

1  $\lambda_\beta = 0; \lambda_\gamma = 0$ 
2 repeat
3    $\lambda_\beta \leftarrow 2(1 + \lambda_\beta)$ 
4    $\lambda_\gamma \leftarrow 2(1 + \lambda_\gamma)$ 
5   repeat
6      $\hat{\beta}^{(k+1)} \leftarrow \text{Proj}_{\|\beta\|_0 \leq k}(\beta^{(k)})$ 
7      $\hat{\gamma}^{(k+1)} \leftarrow \text{Proj}_{\|\gamma\|_0 \leq s}(\gamma^{(k)})$ 
8      $\beta^{(k+1)}, \gamma^{(k+1)} \leftarrow \underset{\gamma \geq 0, \beta}{\text{argmin}} \mathcal{L}(\beta, \gamma) + \frac{\lambda_\beta}{2} \|\beta - \hat{\beta}^{(k)}\|_2^2 + \frac{\lambda_\gamma}{2} \|\gamma - \hat{\gamma}^{(k)}\|_2^2$ 
9   until converges;
10 until  $\hat{\beta} \approx \beta, \hat{\gamma} \approx \gamma$ ;

```

Performance in Comparison to Other Algorithms

- **Scenario 1:** $n = 30$, $n_i = 5$, $p = 9$, $q = 4$, with true parameters $\beta = (1, 1, 0, \dots, 0)$ and the covariance matrix Γ being:

$$\Gamma = \begin{bmatrix} 9 & 4.8 & 0.6 & 0 \\ 4.8 & 4 & 1 & 0 \\ 0.6 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad (7)$$

- **Scenario 2:** everything as in Scenario 1, but $n = 60$ and $n_i = 10$.

Competitors:

- **ALASSO:** 2 stage: A-LASSO+Newton and A-LASSO+PCO
- **M-ALASSO:** Adaptive LASSO + EM Algorithm
- **SCAD-P:** SCAD + Proxy Matrix for Γ
- **rPQL:** Quasi-Likelihood + Adaptive LASSO (for GLMMs)

Performance in Comparison to Other Algorithms

| Setup | Algorithm | % C | % CF | % CR | MSE | TIME |
|--------------------|----------------------|-----|------|------|------|-------|
| $n = 30, n_i = 5$ | R&S-Mixed | 58 | 72 | 78 | 0.66 | 0.015 |
| | rPQL | 88 | 98 | 88 | 0.88 | 26-59 |
| | M-ALASSO | 71 | 73 | 79 | - | - |
| | ALASSO | 79 | 81 | 96 | - | - |
| | SCAD-P | - | 90 | 86 | - | - |
| $n = 60, n_i = 10$ | R&S-Mixed | 98 | 100 | 98 | 0.69 | 0.018 |
| | rPQL | 98 | 99 | 98 | 0.97 | 26-59 |
| | M-ALASSO | 83 | 83 | 89 | - | - |
| | ALASSO | 95 | 96 | 99 | - | - |
| | SCAD-P | 100 | 100 | 100 | - | - |

Table: Comparison of feature selection algorithms. % CF – percent of models where true fixed effects were identified correctly, % CR – percent of models where true random effects were identified correctly, % C – both fixed and random effects were identified correctly.

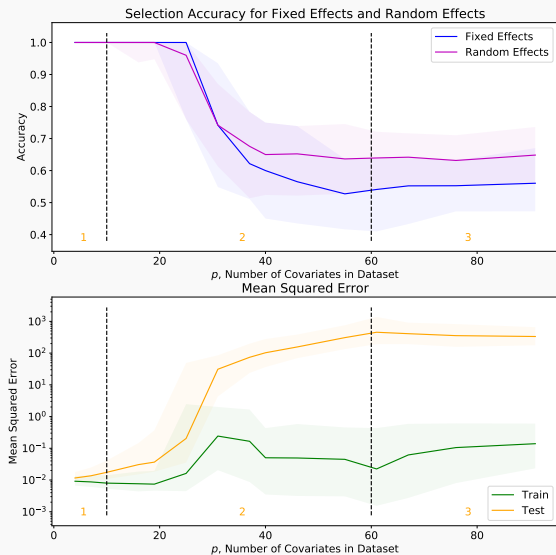
Scalability Experiment

- ▶ $n = 60$, $n_i = 10$
- ▶ $p = q \in [4, 7, 10, \dots, 90]$, 200 experiments for each.
- ▶ $X_i = Z_i$, columns are drawn from $\mathcal{N}(0, \Psi)$ where

$$\Psi = \begin{bmatrix} 9 & 4.8 & 0.6 \\ 4.8 & 4 & 1 \\ 0.6 & 1 & 1 \end{bmatrix}$$

- ▶ 50% random coordinate in β are active
- ▶ 70% of those are also active in γ

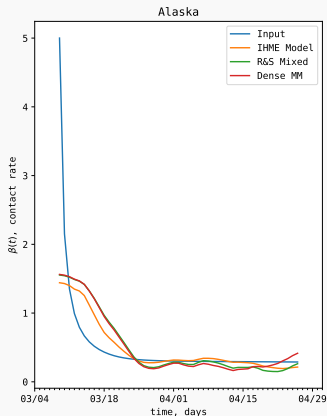
Scalability Experiment



Contact Rate Modeling for COVID-19 Forecasting

- ▶ $n = 60$ groups (countries and US states), $n_i \approx 50$
- ▶ Y_i – contact rate for COVID SEIR Model
- ▶ $p = q = 5$ covariates related to temperature, mobility, population, testing; plus intercept.

Contact Rate Modeling for COVID-19 Forecasting



RMSE:

IHME : 3.85e+00
Dense MM : 3.98e+00 +3%
R&S Mixed : 4.00e+00 +4%

Full MM Coefficients:

| name | local | mean | RE | Var |
|--------------------|-----------|-----------|-----------|----------|
| intercept | 1.23e+01 | 1.34e+01 | -1.08e+00 | 5.66e-01 |
| temperature | -6.75e+02 | -6.75e+02 | 0.00e+00 | 2.19e-20 |
| mobility_lift | 6.44e+01 | 6.13e+01 | 3.09e+00 | 1.83e+03 |
| proportion_over_1k | -7.14e+00 | -7.14e+00 | 0.00e+00 | 9.61e-21 |
| testing_reference | 6.11e+00 | -2.21e+00 | 8.32e+00 | 5.09e+02 |

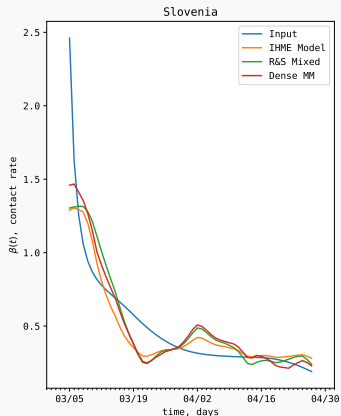
R&S Mixed Coefficients:

| name | local | mean | RE | Var |
|--------------------|-----------|-----------|-----------|----------|
| intercept | 1.22e+01 | 1.43e+01 | -2.05e+00 | 7.95e+01 |
| temperature | -6.75e+02 | -6.75e+02 | 0.00e+00 | 0.00e+00 |
| mobility_lift | 5.78e+01 | 6.00e+01 | -2.20e+00 | 1.83e+03 |
| proportion_over_1k | 0.00e+00 | 0.00e+00 | 0.00e+00 | 0.00e+00 |
| testing_reference | 0.00e+00 | 0.00e+00 | 0.00e+00 | 0.00e+00 |

Legend:

Both Fixed and Random
Fixed Only
Excluded

Contact Rate Modeling for COVID-19 Forecasting



RMSE:

IHME : 1.46e+00
Dense MM : 1.40e+00 -4%
R&S Mixed : 1.56e+00 +7%

Full MM Coefficients:

| name | local | mean | RE | Var |
|--------------------|-----------|-----------|-----------|----------|
| intercept | 1.31e+01 | 1.34e+01 | -3.62e-01 | 5.66e-01 |
| temperature | -6.75e+02 | -6.75e+02 | 0.00e+00 | 2.19e-20 |
| mobility_lift | 3.28e+01 | 6.13e+01 | -2.85e+01 | 1.83e+03 |
| proportion_over_1k | -7.14e+00 | -7.14e+00 | 0.00e+00 | 9.61e-21 |
| testing_reference | -3.16e+01 | -2.21e+00 | -2.93e+01 | 5.09e+02 |

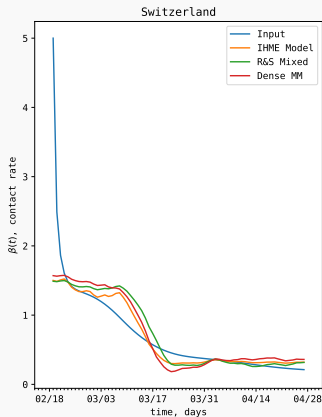
R&S Mixed Coefficients:

| name | local | mean | RE | Var |
|--------------------|-----------|-----------|-----------|----------|
| intercept | 1.27e+01 | 1.43e+01 | -1.55e+00 | 7.95e+01 |
| temperature | -6.75e+02 | -6.75e+02 | 0.00e+00 | 0.00e+00 |
| mobility_lift | 4.27e+01 | 6.00e+01 | -1.73e+01 | 1.83e+03 |
| proportion_over_1k | 0.00e+00 | 0.00e+00 | 0.00e+00 | 0.00e+00 |
| testing_reference | 0.00e+00 | 0.00e+00 | 0.00e+00 | 0.00e+00 |

Legend:

Both Fixed and Random
Fixed Only
Excluded

Contact Rate Modeling for COVID-19 Forecasting



RMSE:

IHME : 3.79e+00
Dense MM : 3.88e+00 +2%
R&S Mixed : 3.98e+00 +5%

Full MM Coefficients:

| name | local | mean | RE | Var |
|--------------------|-----------|-----------|-----------|----------|
| intercept | 1.29e+01 | 1.34e+01 | -5.34e-01 | 5.66e-01 |
| temperature | -6.75e+02 | -6.75e+02 | 0.00e+00 | 2.19e-20 |
| mobility_lift | 4.82e+01 | 6.13e+01 | -1.31e+01 | 1.83e+03 |
| proportion_over_1k | -7.14e+00 | -7.14e+00 | 0.00e+00 | 9.61e-21 |
| testing_reference | -2.31e+01 | -2.21e+00 | -2.09e+01 | 5.09e+02 |

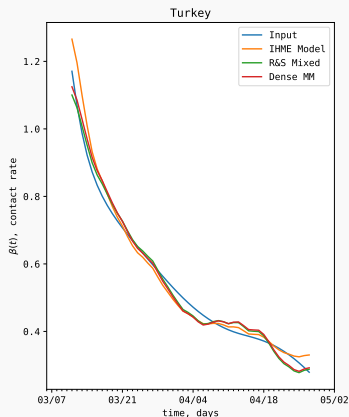
R&S Mixed Coefficients:

| name | local | mean | RE | Var |
|--------------------|-----------|-----------|-----------|----------|
| intercept | 1.27e+01 | 1.43e+01 | -1.61e+00 | 7.95e+01 |
| temperature | -6.75e+02 | -6.75e+02 | 0.00e+00 | 0.00e+00 |
| mobility_lift | 6.65e+01 | 6.00e+01 | 6.49e+00 | 1.83e+03 |
| proportion_over_1k | 0.00e+00 | 0.00e+00 | 0.00e+00 | 0.00e+00 |
| testing_reference | 0.00e+00 | 0.00e+00 | 0.00e+00 | 0.00e+00 |

Legend:

Both Fixed and Random
Fixed Only
Excluded

Contact Rate Modeling for COVID-19 Forecasting



RMSE:

IHME : 2.67e-01
Dense MM : 1.85e-01 -31%
R&S Mixed : 1.71e-01 -36%

Full MM Coefficients:

| name | local | mean | RE | Var |
|--------------------|-----------|-----------|-----------|----------|
| intercept | 1.28e+01 | 1.34e+01 | -6.56e-01 | 5.66e-01 |
| temperature | -6.75e+02 | -6.75e+02 | 0.00e+00 | 2.19e-20 |
| mobility_lift | 3.05e+01 | 6.13e+01 | -3.08e+01 | 1.83e+03 |
| proportion_over_1k | -7.14e+00 | -7.14e+00 | 0.00e+00 | 9.61e-21 |
| testing_reference | 1.49e+00 | -2.21e+00 | 3.70e+00 | 5.09e+02 |

R&S Mixed Coefficients:

| name | local | mean | RE | Var |
|--------------------|-----------|-----------|-----------|----------|
| intercept | 1.26e+01 | 1.43e+01 | -1.69e+00 | 7.95e+01 |
| temperature | -6.75e+02 | -6.75e+02 | 0.00e+00 | 0.00e+00 |
| mobility_lift | 2.88e+01 | 6.00e+01 | -3.12e+01 | 1.83e+03 |
| proportion_over_1k | 0.00e+00 | 0.00e+00 | 0.00e+00 | 0.00e+00 |
| testing_reference | 0.00e+00 | 0.00e+00 | 0.00e+00 | 0.00e+00 |

Legend:

Both Fixed and Random

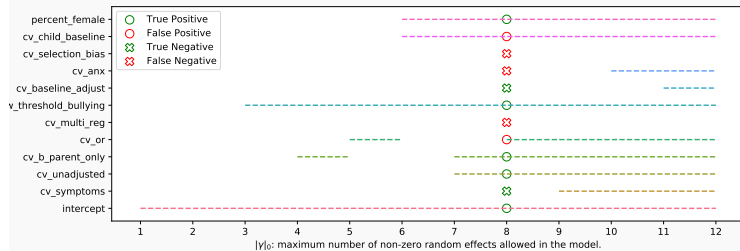
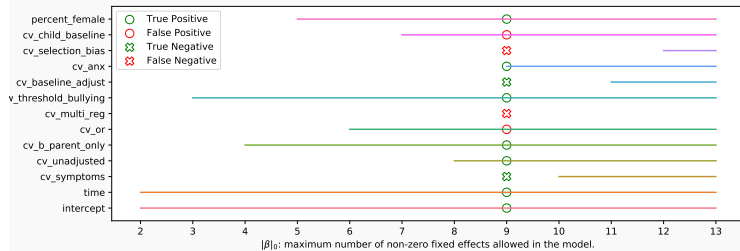
Fixed Only

Excluded

Burden of Anxiety and Depression as Result of Bullying

- ▶ $m = 10$ cohort studies, $n = 77$, highly unbalanced
- ▶ $p = 13$, $q = 12$ (time was preselected fixed-only)
- ▶ Covariates are related to studies' designs.

Burden of Anxiety and Depression as Result of Bullying



Future Work: Theory

Theorem (Conditions for Convergence to True Estimator)

Under certain conditions the method converges in a finite number of iterations to $(\hat{\beta}, \hat{\gamma})$ which projections $(\hat{\beta}, \hat{\gamma})$ belong to a k - and j -subspaces respectively that contain the true minimum (β^, γ^*) .*

Theorem (Consistency of Estimator)

There exists a local minimizer $(\hat{\beta}, \hat{\gamma})$ for the proposed loss function, such that it is asymptotically consistent with true minimum (β^, γ^*) .*

Theorem (Consistency in Zeros)

If some coordinates of the true minimizer (β^, γ^*) are zero, then it is also zero in $(\hat{\beta}, \hat{\gamma})$, given that the later is sufficiently close to the former.*

Theorem (Asymptotic Normality)

The proposed estimator $(\hat{\beta}, \hat{\gamma})$ asymptotically normally distributed around true minimizer (β^, γ^*) in its true non-zero $k + j$ -subspace.*

Future work: Algorithm

Question: Will exponential smoothing of projection improve the accuracy?

```
1  $\lambda_\beta = 0; \lambda_\gamma = 0$ 
2 repeat
3    $\lambda_\beta \leftarrow 2(1 + \lambda_\beta)$ 
4    $\lambda_\gamma \leftarrow 2(1 + \lambda_\gamma)$ 
5   repeat
6      $\hat{\beta}^{(k+1)} \leftarrow \delta \text{Proj}_{\|\beta\|_{\mathbf{0} \leq k}}(\beta^{(k)}) + (1 - \delta)\hat{\beta}^{(k)}$ 
7      $\hat{\gamma}^{(k+1)} \leftarrow \delta \text{Proj}_{\|\gamma\|_{\mathbf{0} \leq s}}(\gamma^{(k)}) + (1 - \delta)\hat{\gamma}^{(k)}$ 
8      $\beta^{(k+1)}, \gamma^{(k+1)} \leftarrow \text{argmin}_{\gamma \geq \mathbf{0}, \beta} \mathcal{L}(\beta, \gamma) + \frac{\lambda_\beta}{2} \|\beta - \hat{\beta}^{(k)}\|_2^2 + \frac{\lambda_\gamma}{2} \|\gamma - \hat{\gamma}^{(k)}\|_2^2$ 
9   until converges;
10 until  $\hat{\beta} \approx \beta, \hat{\gamma} \approx \gamma;$ 
```

Future Work: Implementation

Can we increase λ_β and λ_γ in a more careful way to avoid potential stacking? The approach can be based on the theorem:

Theorem (Distance Between Minima)

For a fixed dataset (X_i, Y_i) and relaxation parameters $\lambda_\beta, \lambda_\gamma$ the distance between (β^, γ^*) , the unconstrained minimizers of relaxed problem, and their projections $(\hat{\beta}^*, \hat{\gamma}^*)$ is bounded by a constant M depending on (X_i, Y_i) and the relaxation parameters.*

The End

Thank you for your attention!

References I

- [BKG10] Howard D. Bondell, Arun Krishna, and Sujit K. Ghosh. Joint Variable Selection for Fixed and Random Effects in Linear Mixed-Effects Models. Biometrics, 66(4):1069–1077, dec 2010.
- [FL01] Jianqing Fan and Runze Li. Variable Selection via Nonconcave Penalized Likelihood and its Oracle Properties. Journal of the American Statistical Association, 96(456):1348–1360, dec 2001.
- [FL12] Yingying Fan and Runze Li. Variable selection in linear mixed effects models. The Annals of Statistics, 40(4):2043–2068, aug 2012.
- [Jon11] Richard H. Jones. Bayesian information criterion for longitudinal and clustered data. Statistics in Medicine, 30(25):3050–3056, nov 2011.
- [LPJ13] Bingqing Lin, Zhen Pang, and Jiming Jiang. Fixed and random effects selection by REML and pathwise coordinate optimization. Journal of Computational and Graphical Statistics, 22(2):341–355, 2013.
- [VB05] Florin Vaida and Suzette Blanchard. Conditional Akaike information for mixed-effects models. Biometrika, 92(2):351–370, jun 2005.
- [ZAB⁺19] Peng Zheng, Travis Askham, Steven L. Brunton, J. Nathan Kutz, and Aleksandr Y. Aravkin. A Unified Framework for Sparse Relaxed Regularized Regression: SR3. IEEE Access, 7:1404–1423, 2019.