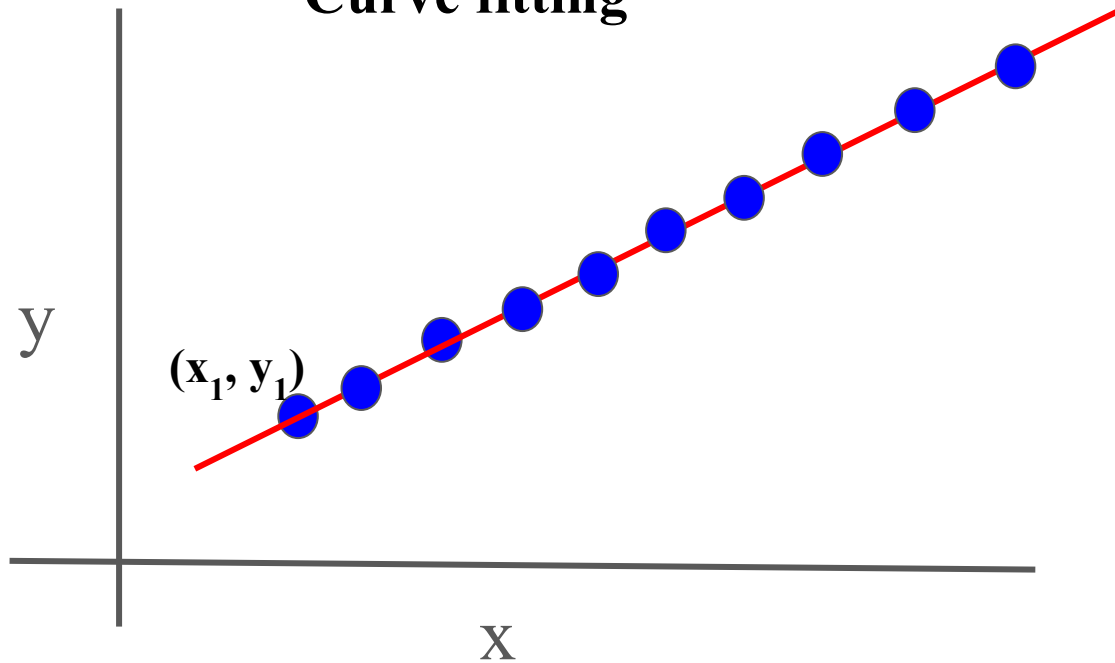
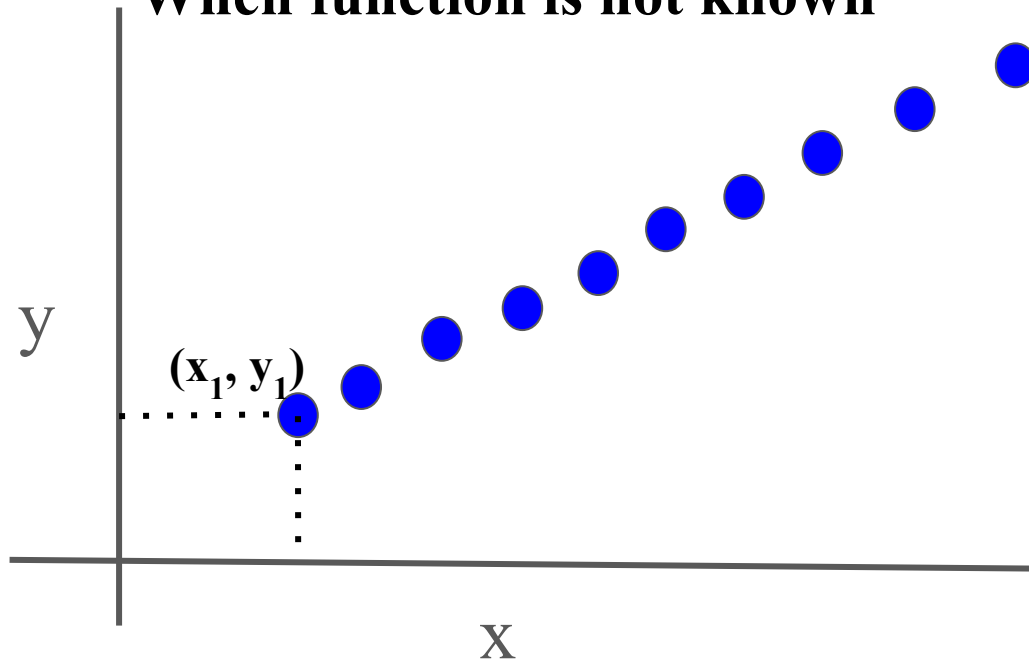


# ***Linear Regression***

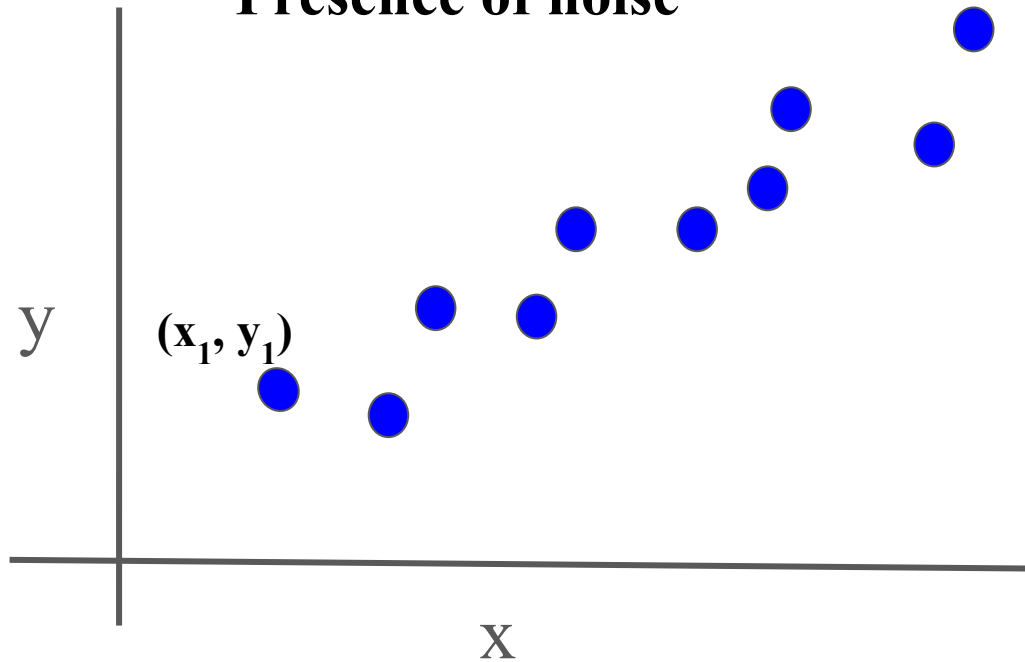
## Curve fitting



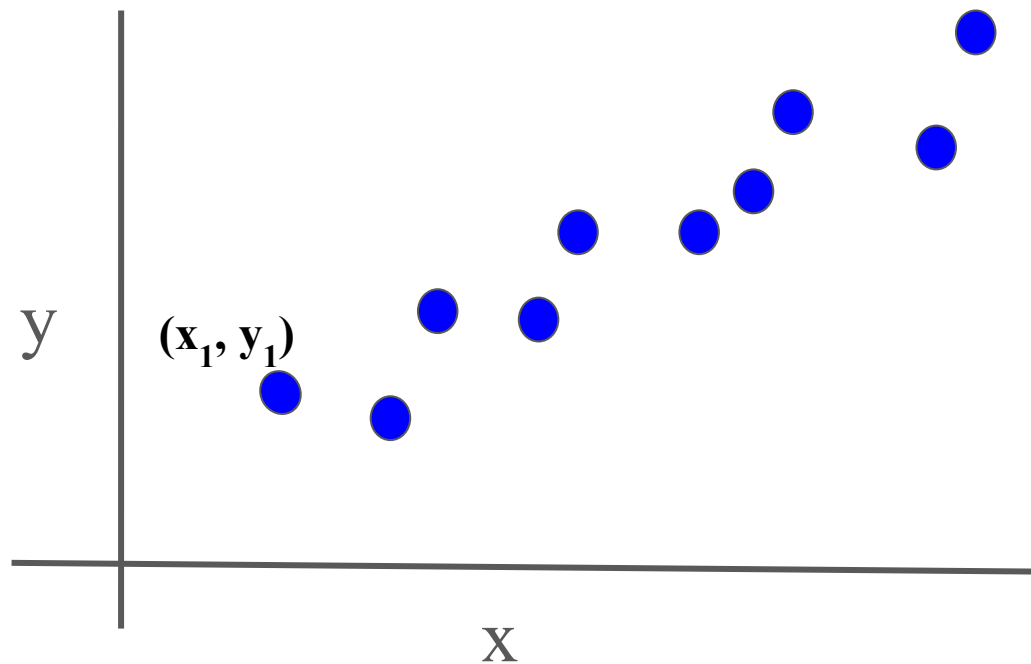
**When function is not known**



## Presence of noise



**Can we recover the true function?**



*Let's try*

*First, we need to choose the function in general*

*What does that mean?*

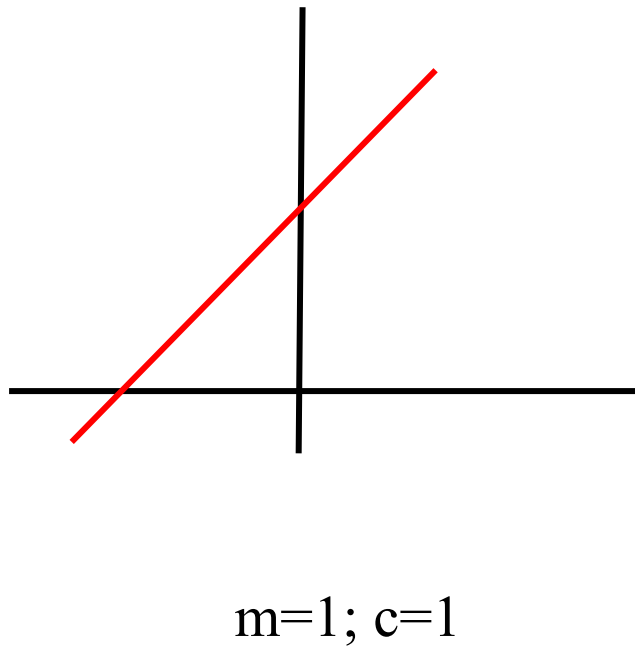
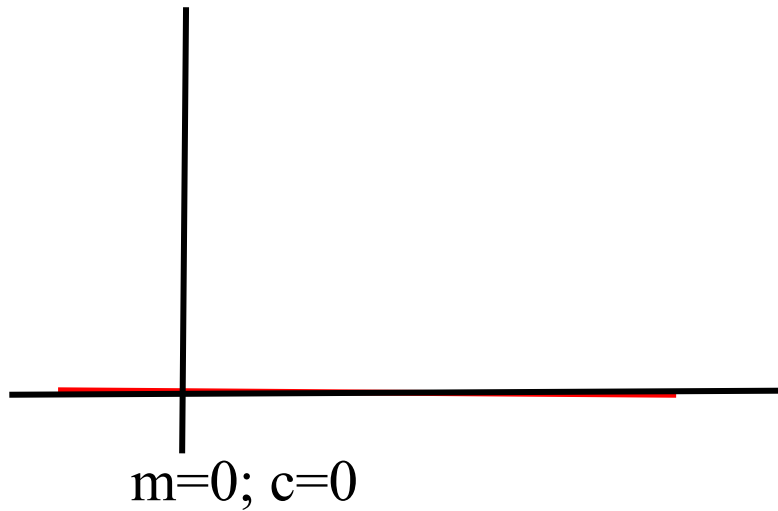
# *Equation of line*

$$y=mx+c$$

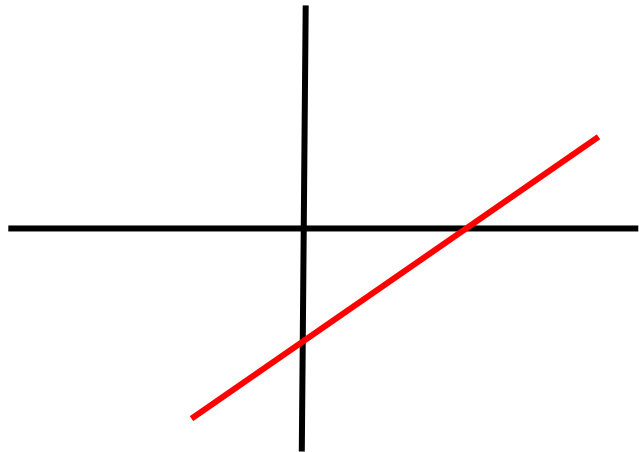


*For different values of  $m$  and  $c$ , we have  
different lines*

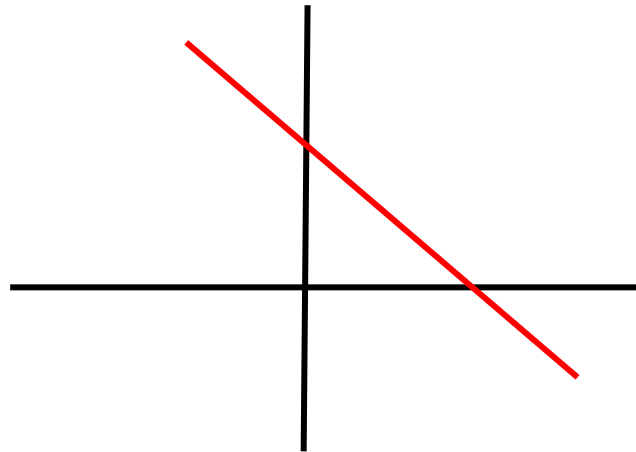
*For example:*



*For example:*



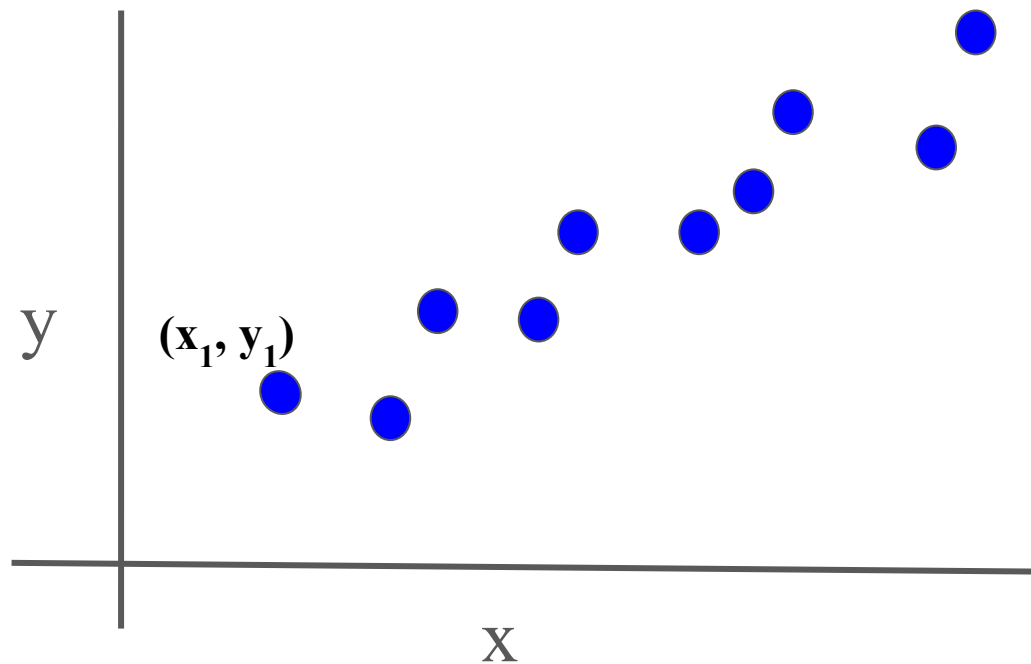
$$m=1; c=-1$$



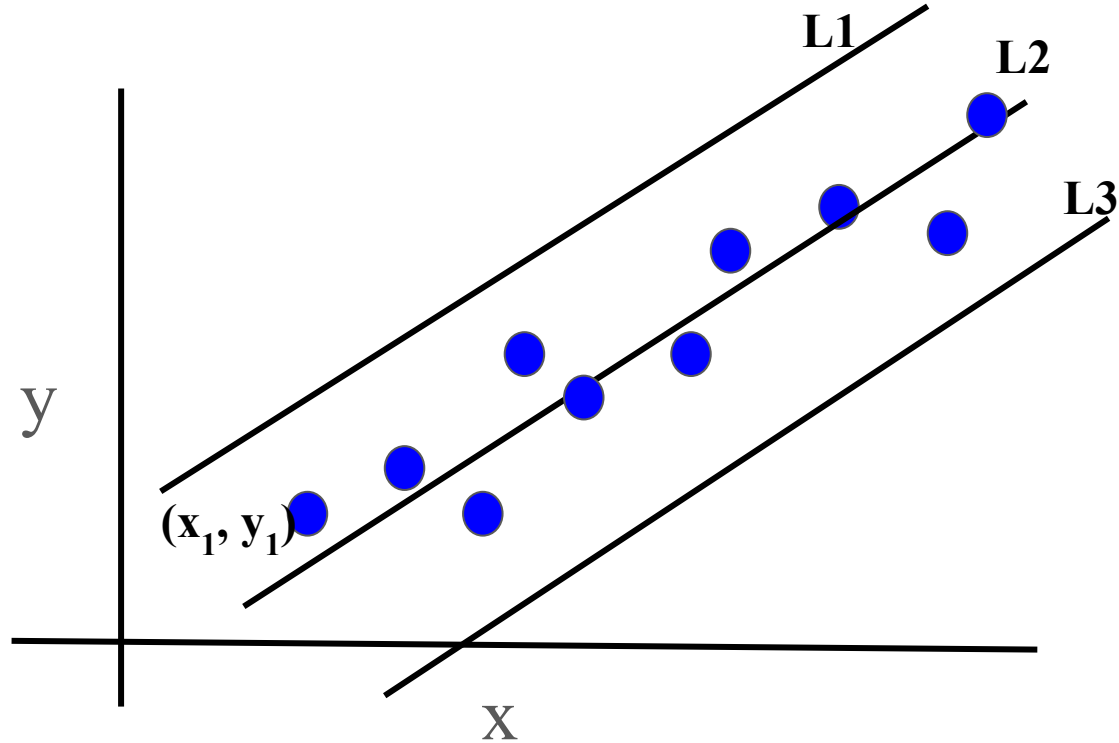
$$m=-1; c=1$$

*Let's come back to the  
problem*

**Can we recover the true function?**



Let's try to fit the line first



Which line is best  $L1$ ,  $L2$ , and  $L3$ ?

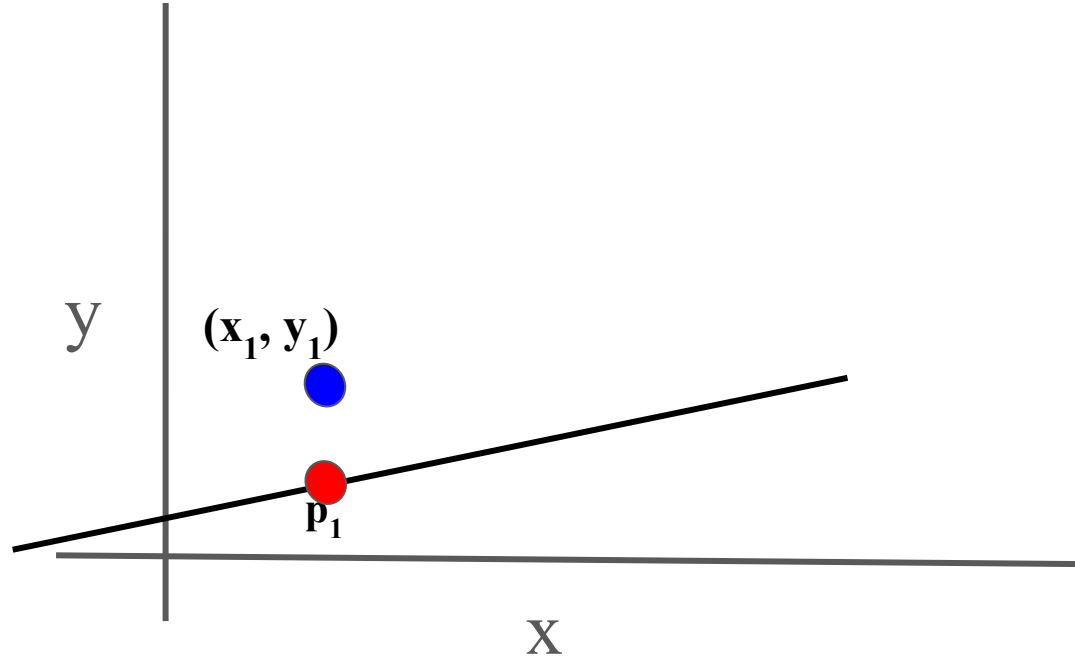
*How to do it in computer?*

*We need to choose the optimal value of  $m$  &  $c$*

*Let's write it as follows:*

$$m * x + c = p$$

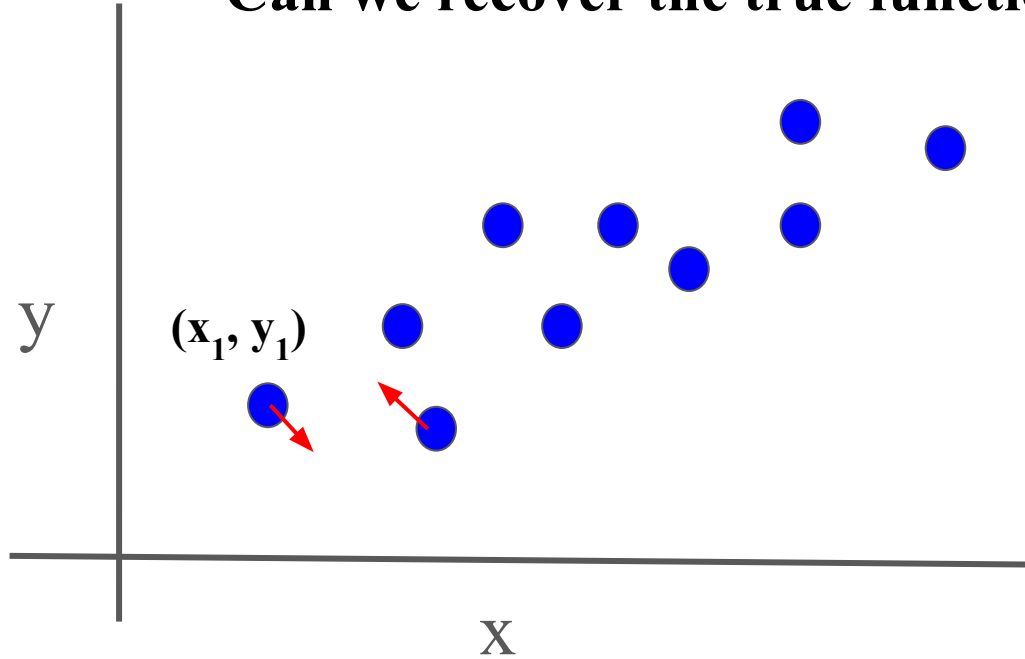
*where,  $m$  &  $c$  is unknown.*





*Our purpose is to make the value of  $\mathbf{p}$  as close to the value of  $\mathbf{y}$  in the data*

**Can we recover the true function?**



We have 10 points:

	Actual	Target	Error
$\mathbf{mx}_1 + \mathbf{c} =$	$\mathbf{p}_1$	$\mathbf{y}_1$	$(\mathbf{y}_1 - \mathbf{p}_1)$
$\mathbf{mx}_2 + \mathbf{c} =$	$\mathbf{p}_2$	$\mathbf{y}_2$	$(\mathbf{y}_2 - \mathbf{p}_2)$
.	.	.	.
.	.	.	.
.	.	.	.
$\mathbf{mx}_{10} + \mathbf{c} =$	$\mathbf{p}_{10}$	$\mathbf{y}_{10}$	$(\mathbf{y}_{10} - \mathbf{p}_{10})$

Now, we take the square of the error.

Why square of the error?

Because +ve and -ve errors can cancel out each other.

Therefore;

	Actual	Target	Error
$mx_1 + c =$	$p_1$	$y_1$	$(y_1 - p_1)$
$mx_2 + c =$	$p_2$	$y_2$	$(y_2 - p_2)$
.	.	.	.
.	.	.	.
.	.	.	.
$mx_{10} + c =$	$p_{10}$	$y_{10}$	$(y_{10} - p_{10})$

$$\text{Total error} = (y_1 - p_1)^2 + (y_2 - p_2)^2 + \dots + (y_{10} - p_{10})^2$$

- Alternatively

$$\text{Total error} = (\mathbf{y}_1 - \mathbf{p}_1)^2 + (\mathbf{y}_2 - \mathbf{p}_2)^2 + \cdots \cdots \cdots + (\mathbf{y}_{10} - \mathbf{p}_{10})^2$$

$$\text{Total error} = \sum_{\{i=1\}}^n (y_i - p_i)^2$$

**Our objective is to minimize the error**

- **Simple trick from Calculus**

**Minimization of function:**

$$\nabla f = 0$$

*Take the derivative of the function and put it equal to zero*



**Hence, we get the optimal value of m & c**

$$y = \mathbf{m}x + \mathbf{c}$$

**We can use this ( $\mathbf{m}, \mathbf{c}$ ) for predicting the output  
for the new values of x**

# CODE

<https://github.com/aksiitbhu/Machine-Learning-2024/blob/main/LinearRegressionLab1GEU2024.ipynb>

# Github link for course materials

<https://github.com/aksiitbhu/Machine-Learning-2024/tree/main>



*Thanks*