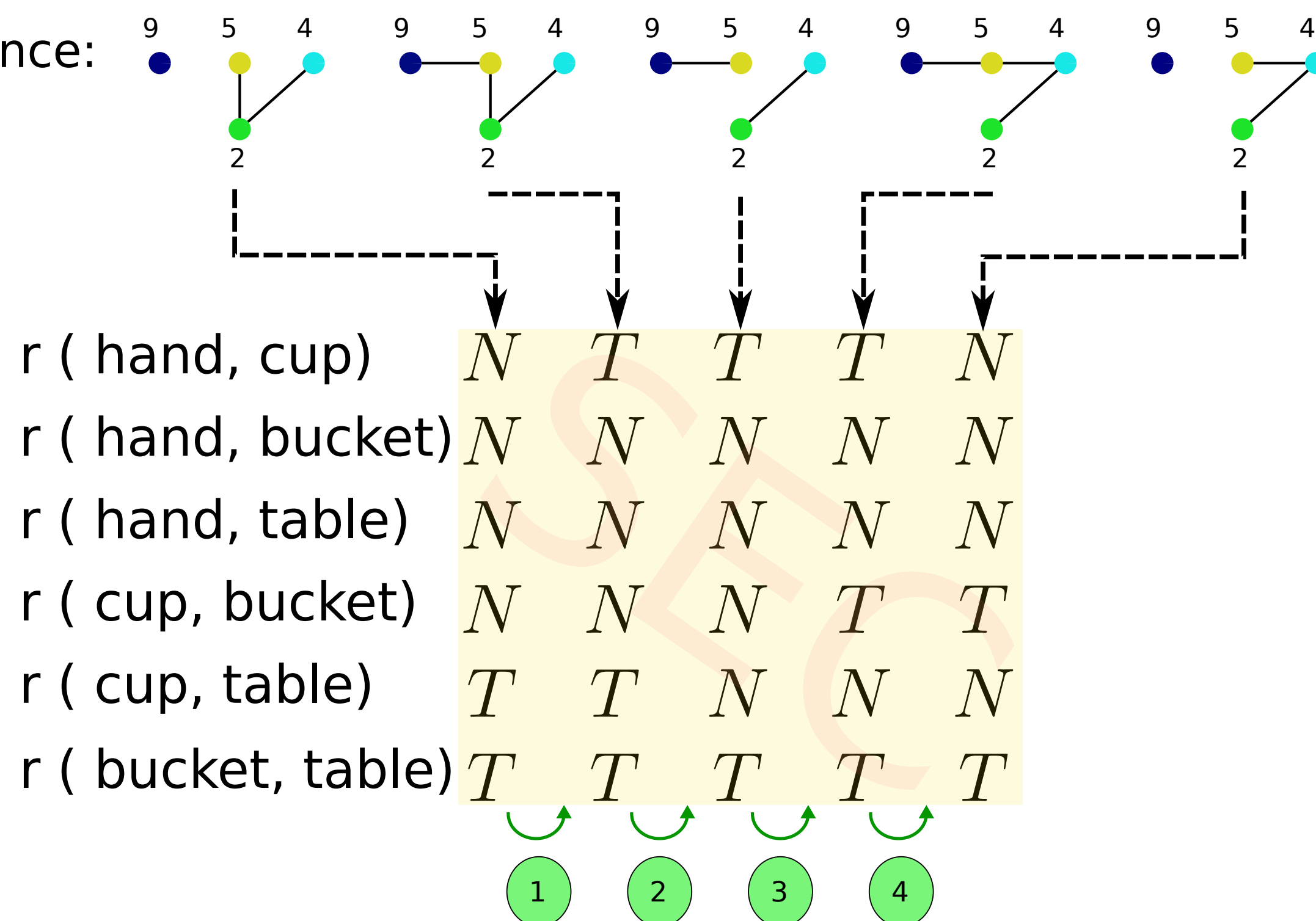


Graph sequence:



Legend:

- hand
- bucket
- box
- table
- objects are touching (T)
- objects are not touching (N)

- 1 [move(bucket) , grasp]
- 2 move(home)
- 3 move(box)
- 4 [ungrasp , move(home)]