

## hw3b\_ex22

March 6, 2020

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[1]: # -*- coding: utf-8 -*-
      """
      Created on Thu Mar  5 19:23:19 2020

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      """

      # python 3 version
      import numpy as np
      import matplotlib.pyplot as plt
      import mpl_toolkits.mplot3d.axes3d as p3

      def rk4(x,t,tau,derivsRK,param):
          """
          ## Runge-Kutta integrator (4th order)
          ## Input arguments -
          ##   x = current value of dependent variable
          ##   t = independent variable (usually time)
          ##   tau = step size (usually timestep)
          ##   derivsRK = right hand side of the ODE; derivsRK is the
          ##               name of the function which returns dx/dt
          ##               Calling format derivsRK(x,t).
          ## Output arguments -
          ##   xout = new value of x after a step of size tau
          """
          half_tau = 0.5*tau
          F1 = derivsRK(x,t,param)
          t_half = t + half_tau
          xtemp = x + half_tau*F1
          F2 = derivsRK(xtemp,t_half,param)
          xtemp = x + half_tau*F2
          F3 = derivsRK(xtemp,t_half,param)
          t_full = t + tau
          xtemp = x + tau*F3
          F4 = derivsRK(xtemp,t_full,param)
          xout = x + tau/6.*(F1 + F4 + 2.*(F2+F3))
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return xout

def rka(x,t,tau,err,derivsRK,param):
    """
    ## Adaptive Runge-Kutta routine
    ## Inputs
    ## x          Current value of the dependent variable
    ## t          Independent variable (usually time)
    ## tau        Step size (usually time step)
    ## err        Desired fractional local truncation error
    ## derivsRK   Right hand side of the ODE; derivsRK is the
    ##            name of the function which returns dx/dt
    ##            Calling format derivsRK(x,t).
    ## Outputs
    ## xSmall     New value of the dependent variable
    ## t          New value of the independent variable
    ## tau        Suggested step size for next call to rka
    """

    # Set initial variables
    tSave = t; xSave = x    # Save initial values
    safe1 = .9; safe2 = 4.  # Safety factors
    eps = np.spacing(1) # smallest value

    # Loop over maximum number of attempts to satisfy error bound
    maxTry = 100

    for iTry in range(1,maxTry):

        # Take the two small time steps
        half_tau = 0.5 * tau
        xTemp = rk4(xSave,tSave,half_tau,derivsRK,param)
        t = tSave + half_tau
        xSmall = rk4(xTemp,t,half_tau,derivsRK,param)

        # Take the single big time step
        t = tSave + tau
        xBig = rk4(xSave,tSave,tau,derivsRK,param)

        # Compute the estimated truncation error
        scale = err * (np.abs(xSmall) + np.abs(xBig))/2.
        xDiff = xSmall - xBig
        errorRatio = np.max( [np.abs(xDiff)/(scale + eps)] )

        #print safe1,tau,errorRatio

        # Estimate news tau value (including safety factors)
        tau_old = tau

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    tau = safe1*tau_old*errorRatio**(-0.20)
    tau = np.max([tau,tau_old/safe2])
    tau = np.min([tau,safe2*tau_old])

    # If error is acceptable, return computed values
    if errorRatio < 1 :
        xSmall = xSmall
        return xSmall, t, tau

def lotka_volterra(s,t,param):
    a = 10
    b = 10**6
    c = .1

    r = s[0]
    f = s[1]

    deriv = np.zeros(2)
    deriv[0] = a*(1-(r/b))*r - c*r*f
    deriv[1] = -a*f + c*r*f
    return deriv

def lorentz_data_gen(init_r,init_f,param):
    """
    Generates data needed to plot the results
    of lorentz.py using rk4 as in Ch3 ex 25

    Parameters
    -----
    init_r : Int
        Initial rabbits value.
    init_y : Int
        Initial fox value.
    param : list
        List of model parameter (a,b,c).

    Returns
    -----
    rplot : Numpy array
        Array of r-values used to plot.
    fplot : Numpy array

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    Array of f-values used to plot.
tplot : Numpy array
    Array of time-values used to plot.

"""
# Set initial state x,y,z and parameters r,sigma,b
srin,sfin = init_r,init_f
state = np.zeros(2)
state[0] = float(srin)
state[1] = float(sfin)

# Model paramaters
a = param[0]
b = param[1]
c = param[2]
tau = 1          # Timestep from lorenz with n=500
err = 1.e-3      # Error tolerance

# Loop over the desired number of steps
time = 0
nstep = 500
# initialize arrays
tplot = np.array([])
tauplot = np.array([])
rplot = np.array([])
fplot = np.array([])

for istep in range(0,nstep):
    # Record values for plotting
    r = state[0]
    f = state[1]
    tplot = np.append(tplot,time)
    tauplot = np.append(tauplot,tau)
    rplot = np.append(rplot,r)
    fplot = np.append(fplot,f)
    #if( istep%50 ==0 ):
        #print('Finished %d steps out of %d'%(istep,nstep))
        # Find new state using Runge-Kutta4
        #state = rk4(state,time,tau,lotka_volterra,param)
        #time += tau
        [state, time, tau] = rka(state,time,tau,err,lotka_volterra,param)

# Print max and min time step returned by rka
#print('Adaptive time step: Max = %f,  Min = %f'%(max(tauplot[1:]),
↪min(tauplot[1:])))

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plotting = True
if plotting:
    # Graph the time series  $x(t)$ 
    fig,ax = plt.subplots(2,1,sharex = True)
    ax[0].plot(tplot,rplot,'-')
    ax[0].set_ylabel('rabs(t)')
    ax[0].set_title('Rabbits')

    ax[1].plot(tplot,fplot,'-')
    ax[1].set_xlabel('Time');
    ax[1].set_ylabel('foxez(t)')
    ax[1].set_title('Foxes')
    fig.suptitle('%s Foxes, %s rabbits' %(init_f,init_r))

return rplot,fplot,tplot

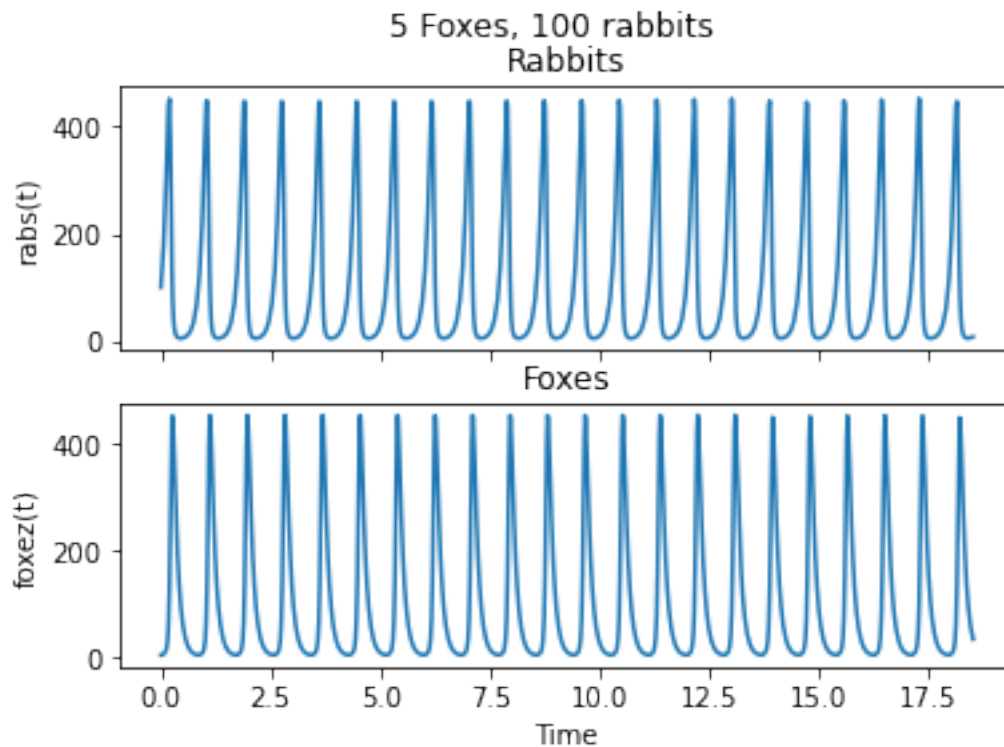
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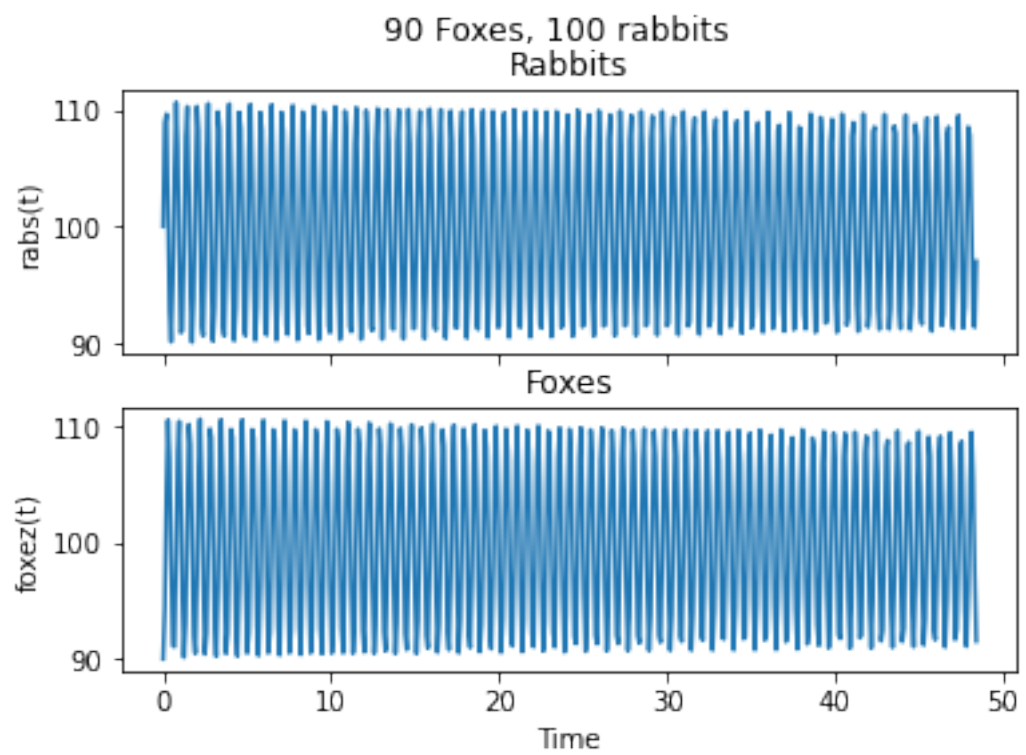
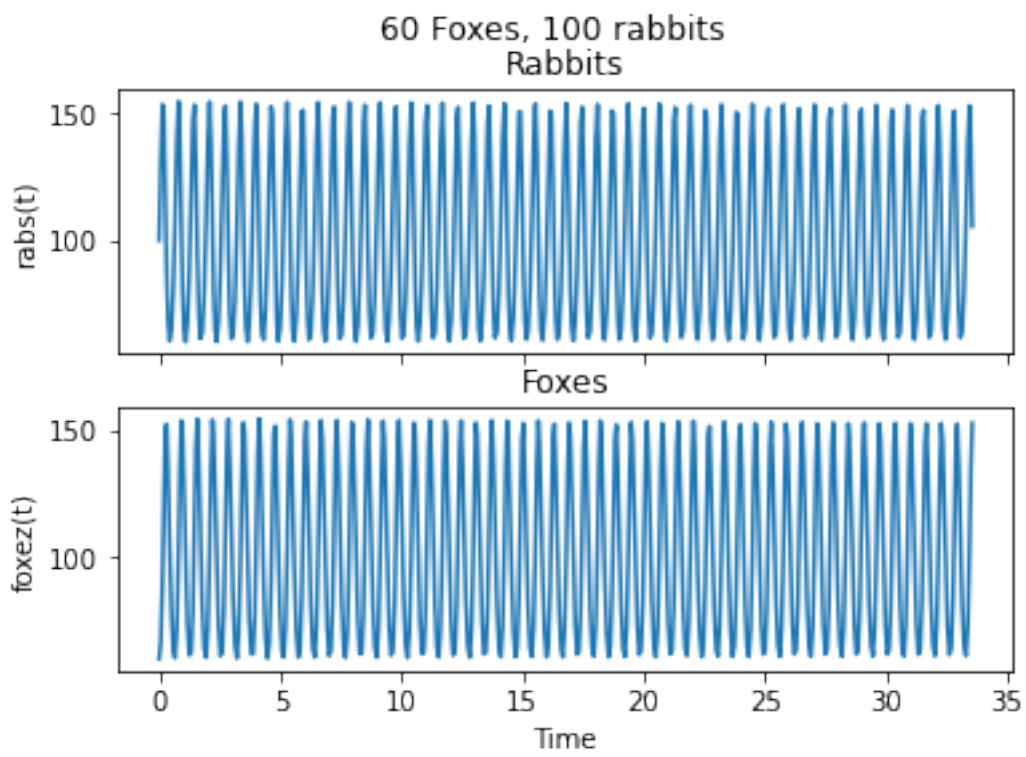
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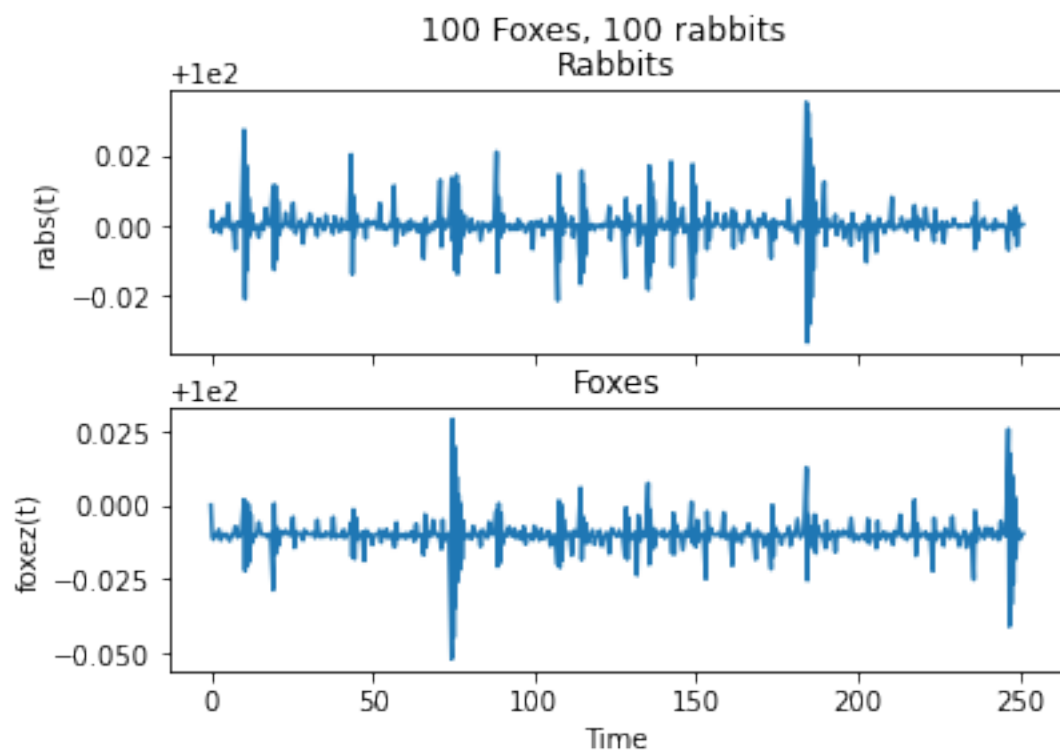
[2]: for initial_foxes in [5,60,90,100,120,140]:
    initial_cond_list = [(100,initial_foxes,(10,10**6,.1) )]
    ic_1 = initial_cond_list[0]
    rplot1,fplot1,tplot1 = lorenz_data_gen(ic_1[0],ic_1[1],ic_1[2])

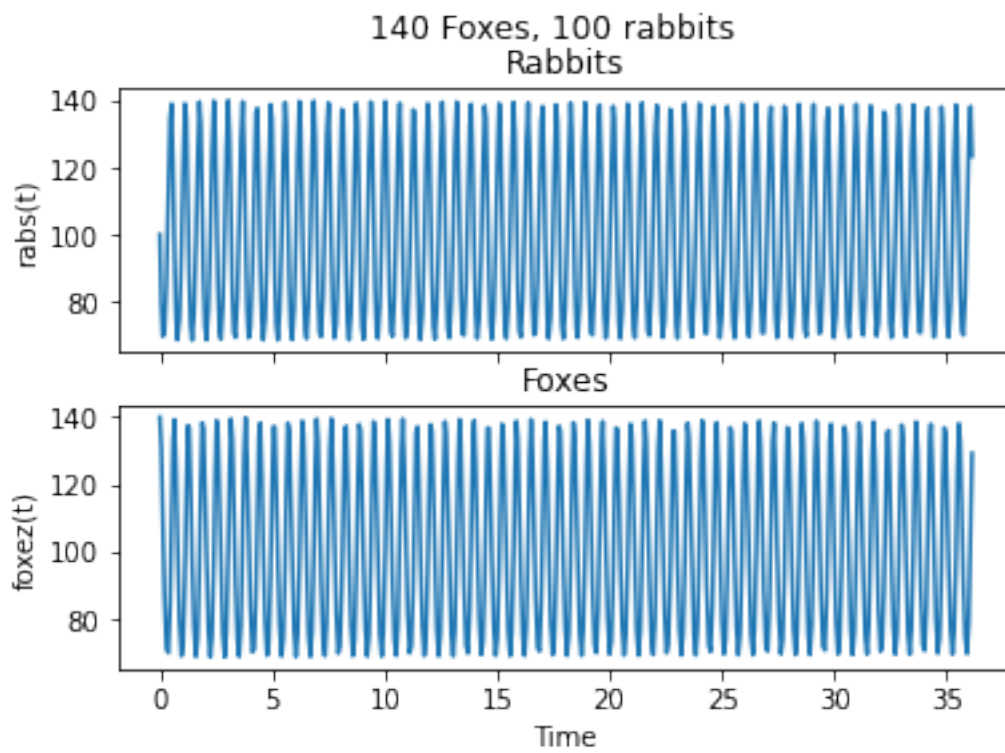
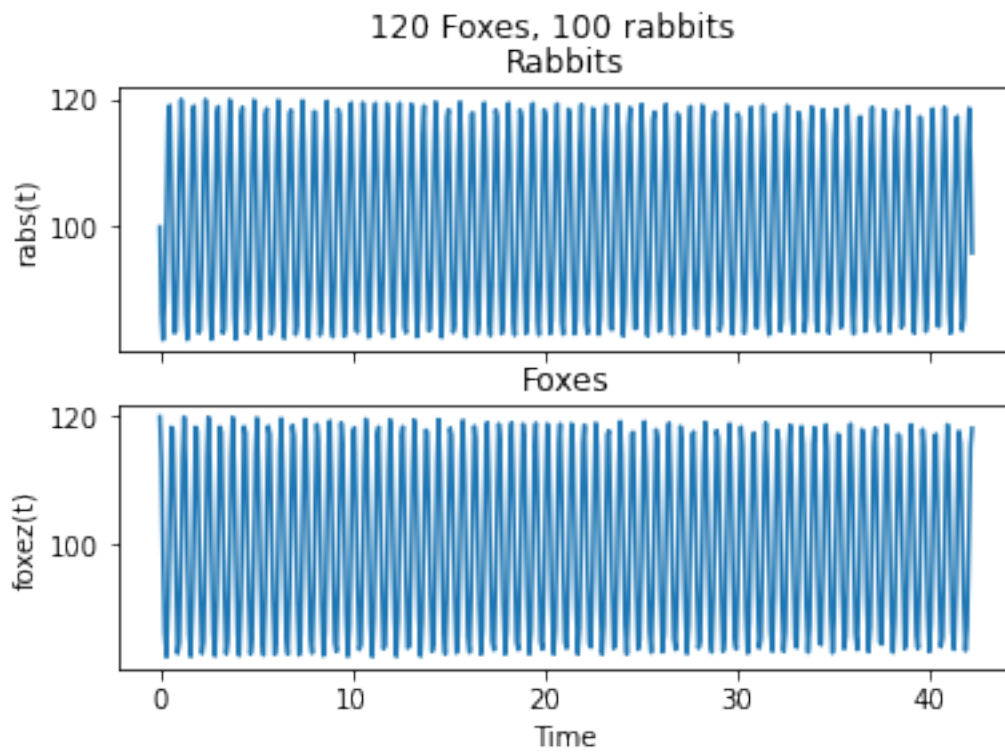
    #lorenz_plot(initial_cond_list)

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