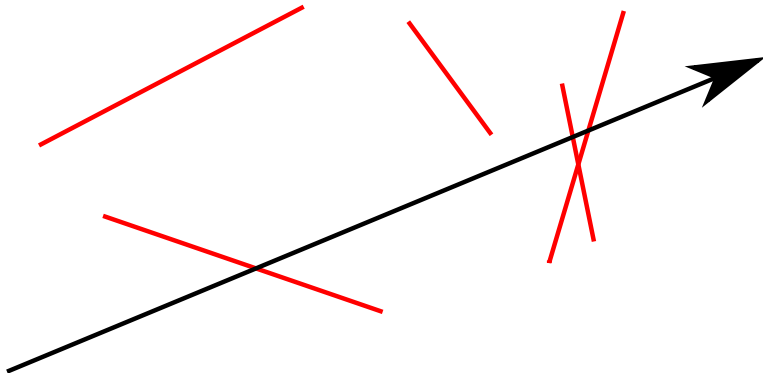


Algolab 2012

CGAL - Exercise Sheet 1

November 21, 2012

Hit – Problem



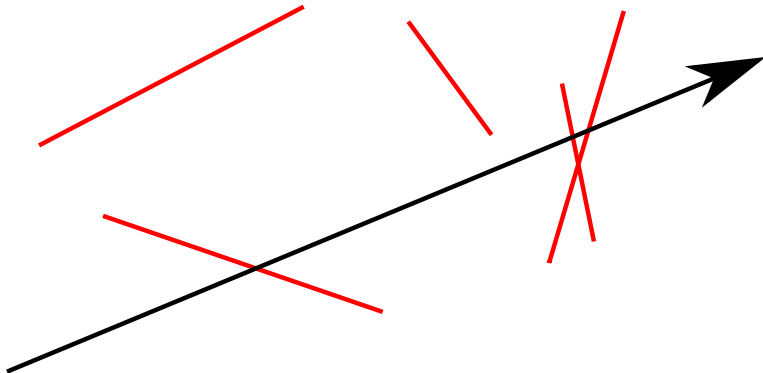
Hit – Solution

- `Ray_2 r` : stored as 2 points, source and one point of the ray
 - `Segment_2 s` : stored as 2 points: source and target
 - `do_intersect(r, s)` : predicate
- ⇒ We only need predicates and trivial constructions.

Hit – Code

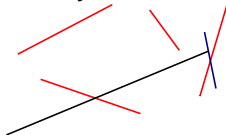
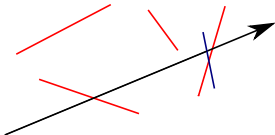
```
1 #include <CGAL/Exact_predicates_inexact_constructions_kernel.h>
3 typedef CGAL::Exact_predicates_inexact_constructions_kernel K;
5 int main()
6 {
7     for (std::size_t n; std::cin >> n && n > 0;) {
8         K::Ray_2 r;
9         std::cin >> r;
10        bool found = false;
11        do {
12            K::Segment_2 s;
13            std::cin >> s;
14            if (!found && CGAL::do_intersect(s,r)) found = true;
15        } while (--n > 0);
16        std::cout << (found ? "yes" : "no") << std::endl;
17    }
18 }
```

First Hit – Problem

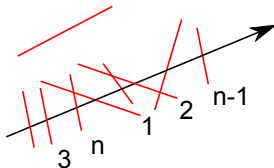
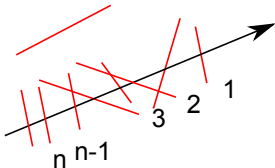


First Hit – Solution

- We need the exact coordinates of the intersection \Rightarrow exact constructions
- invoking `CGAL::intersection(r, s)` for *every* intersection might be too slow \Rightarrow truncate the ray!



- why should this be better?



- process segments in random order!

How many intersections do we need to compute?

Let $\{b_i\}_{i=1}^n$ denote a (uniform) random permutation of $[n]$ and let $c_i := \min\{b_j\}_{j=1}^i$. Let X be the number of different elements in $\{c_i\}_{i=1}^n$. Then

$$E[X] = O(\log n)$$

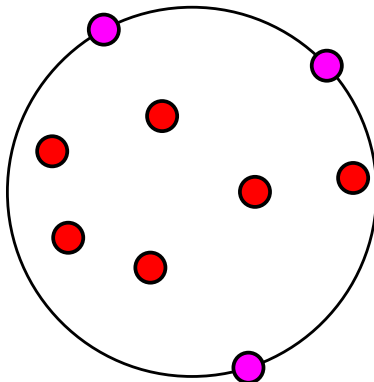
First Hit – Code

```
1  #include <CGAL/Exact_predicates_exact_constructions_kernel.h>
2  #include <vector>
3  #include <algorithm>
4
5  typedef CGAL::Exact_predicates_exact_constructions_kernel K;
6
7  // round down to next double
8  double floor_to_double(const K::FT& x)
9  {
10     double a = std::floor(CGAL::to_double(x));
11     while (a > x) a -= 1;
12     while (a+1 <= x) a += 1;
13     return a;
14 }
15
16 // clip/set target of s to o
17 void shorten_segment(K::Segment_2& s, CGAL::Object o)
18 {
19     if (const K::Point_2* p = CGAL::object_cast<K::Point_2>(&o))
20         s = K::Segment_2(s.source(), *p);
21     else if (const K::Segment_2* t = CGAL::object_cast<K::Segment_2>(&o))
22         // select endpoint of *t closer to s.source()
23         if (CGAL::collinear_are_ordered_along_line
24             (s.source(), t->source(), t->target()))
25             s = K::Segment_2(s.source(), t->source());
26         else
27             s = K::Segment_2(s.source(), t->target());
28     else
29         throw std::runtime_error("Strange_segment_intersection.");
30 }
```


First Hit – Code

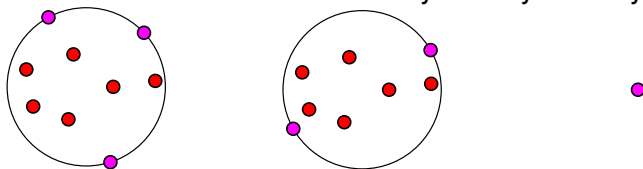
```
32 void find_hit(std::size_t n) {  
    // read input  
34 K::Ray_2 r;  
    std::cin >> r;  
36 std::vector<K::Segment_2> segs;  
    segs.reserve(n);  
38 double ix, iy, jx, jy;  
    for (std::size_t i = 0; i < n; ++i) {  
        // as each coordinate can be represented as double, this is  
        // significantly faster than K::Segment_2 s; std::cin >> s;  
42 std::cin >> ix >> iy >> jx >> jy;  
        segs.push_back(K::Segment_2(K::Point_2(ix, iy), K::Point_2(jx, jy)));  
44 }  
    std::random_shuffle(segs.begin(), segs.end());  
46 K::Segment_2 rc(r.source(), r.source());  
  
48 // find some segment hit by r  
    std::size_t i = 0;  
50 for (; i < n; ++i)  
        if (CGAL::do_intersect(segs[i], r)) {  
            shorten_segment(rc, CGAL::intersection(segs[i], r));  
            break;  
54 }  
    if (i == n) { std::cout << "no\n"; return; }  
56 // check remaining segments against rc  
    while (++i < n)  
        if (CGAL::do_intersect(segs[i], rc))  
            shorten_segment(rc, CGAL::intersection(segs[i], r)); // not rc!  
60  
    std::cout << floor_to_double(rc.target().x()) << "_"  
62 << floor_to_double(rc.target().y()) << "\n";  
}
```

Antenna – Problem



Antenna – Solution

- minimum enclosing circle \Rightarrow example from tutorial
- need to output the squared radius (requires construction of the center)
- use the exact construction kernel only when you really need it!



- (the purple points are called *support points*)

Antenna – Code

```
1 #include <CGAL/Exact_predicates_inexact_constructions_kernel.h>
2 #include <CGAL/Exact_predicates_exact_constructions_kernel_with_sqrt.h>
3 #include <CGAL/Min_circle_2.h>
4 #include <CGAL/Min_circle_2_traits_2.h>
5 #include <vector>
6 #include <iostream>
7 #include <cmath>

9 typedef CGAL::Exact_predicates_inexact_constructions_kernel K;
10 typedef CGAL::Min_circle_2<CGAL::Min_circle_2_traits_2<K> > MC;
11 typedef CGAL::Exact_predicates_exact_constructions_kernel_with_sqrt EK;
12 typedef CGAL::Min_circle_2<CGAL::Min_circle_2_traits_2<EK> > EMC;

13 // round up to next integer double
14 double ceil_to_double(const EK::FT& x)
15 {
16     double a = std::ceil(CGAL::to_double(x));
17     while (a < x) a += 1;
18     while (a-1 >= x) a -= 1;
19     return a;
20 }
```

Antenna – Code

```
22
23 int main()
24 {
    std::cout << std::setiosflags(std::ios::fixed) << std::setprecision(0);
    std::cin.sync_with_stdio(false);

    for (std::size_t n; std::cin >> n && n > 0;) {
        std::vector<K::Point_2> pts;
        pts.reserve(n);
        for (std::size_t i = 0; i < n; ++i) {
            K::Point_2 p;
            std::cin >> p;
            pts.push_back(p);
        }
        MC mc(pts.begin(), pts.end(), true);
        // now we construct the circle using the exact kernel...
        EK::Point_2 spt[3];
        for (std::size_t i = 0; i < mc.number_of_support_points(); ++i)
            spt[i] = EK::Point_2(mc.support_point(i).x(), mc.support_point(i).y());
        EMC emc(spt, spt+mc.number_of_support_points());
        // compute the exact squareroot and then an upper bound in double
        std::cout << ceil_to_double(sqrt(emc.circle().squared_radius())) << "\n";
    }
    return 0;
26 }
```