Resources, lifecycles, and structured concurrency

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Kotlin relies on scope-based resource management, but lacks mechanisms to enforce scope confinement, guarantee lifecycle safety, and rule out conflicting actions statically. We devise a mechanism addressing these issues in a manner compatible with structured concurrency and localized capturing in general. Our model can be seen as a generalization of Rust approach.

1 Introduction

We propose an extension to the Kotlin type system and flow-sensitive typing mechanism providing static control over resource lifecycles. Our contribution is threefold:

- a mechanism to confine references inside the receiving scope, which opens the way for
- modal methods, the statically checked counterpart of Java's synchronized methods, and
- modes (= typestates) such as File.Open to keep track of object lifecycle at compile time.

Example 1. Well-scoped resource acquisition

```
var roqueWriter : File.Writable?
file.open {
  file.write("Hello!")
                        // Error: `file : File.Writable` is confined inside open@
  rogueWriter = file
Example 2. Mutual exclusion of conflicting actions using modal methods
modal class Buffer {
  fun append(item : Byte) { ... }
  modal fun clear() { ... }
 modal fun iterate(block : inner (inner Iterator)-> Unit) { ... }
buf.iterate { iterator ->
  buf.append(0xFE) // This is ok
                    // Error: Modal `buf.clear()` can't be invoked while
 buf.clear()
                    // `buf` is borrowed by the modal `buf.iterate()`
Example 3. Staged builders
class Html : Tag("html") with AwaitsHead {
 modal! extension AwaitsHead {
                                                                   // Html.AwaitsHead
    break continue@AwaitsBody
                                                                  //
    fun head(head : once Head.()-> Unit) = initTag(Head(), head) //
                                                                         head { ... }
                                                                  //
                                                                  // Html.AwaitsBody
 modal! extension AwaitsBody {
    break
                                                                  //
    fun body(body : once Body.()-> Unit) = initTag(Body(), body) //
                                                                         body { ... }
                                                                  //
  }
}
                                                                  // Html
fun html(block : once Html.AwaitsHead.()-> Unit) : Html {
                                                                   // Usage:
  val html = Html()
                                                                  val h = html {
                                                                    head \{ \dots \}
 html.block()
  return html
                                                                    body { ... }
```

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2 Scope confinement

Kotlin relies on scope-based resource management, but does not enforce scope confinement:

Kotlin already provides a contract called CallsInPlace which allows declaring that a parameter lambda is invoked in place. To enforce confinement, we have to generalize this contract to arbitrary types. We propose using inner modifier in argument types for inplace arguments:

```
fun <R> Writer.use(block : (inner Writer)-> R) : R
```

CallsInPlace also provides a function-specific feature: limiting invocation multiplicity. Being essential for lifecycle-safety checking, it also belongs to the signature:

```
fun <T> Array<T>.forEach(action : inner (T)-> Unit)  // supersedes the CallsInPlace
fun <T> Maybe<T>.forEach(action : once? (T)-> Unit)  // ... with AT_MOST_ONCE,
fun <T> Boxed<T>.forEach(action : once (T)-> Unit)  // ... EXACTLY_ONCE, or
fun <T> NonEmptyArray<T>.forEach(action : once+ (T)-> Unit)  // ... AT_LEAST_ONCE
```

Just like the structural jumps (return, break, continue, and their qualified forms), inplace arguments cannot be stored (someVar = action) or captured, except by function literals that are themselves used as inplace arguments. In fact, inplace arguments can be used only for method invocations (like it.println(), or action()) or passed on as inplace arguments. We rule out the assignment rogueWriter = it as desired, but unfortunately, we also rule out concurrency:

```
file.printWriter().use {
  coroutineScope {
    for (i in 1..99) launch {
      delay(Random.nextInt(0, 100))
      it.println("${i.th} asynchronous bottle of beer")  // <- Problem
    }
  }
  it.println("No more bottles of beer!")
}</pre>
```

Here, we acquire a PrintWriter, launch 99 jobs populating it by "\${i.th} asynchronous bottle of beer" after a random delay, and add "No more bottles of beer!" when they're all done.

We attempt to invoke it.println(...) inside a function literal that outlives the invocation of the launch function we pass it to. The invocation it.println(...) is still safe because it does not outlive the enclosing coroutineScope. But how can we make the compiler see this fact?

This form of confinement can be expressed using member classes and interfaces. Kotlin features their half-hearted form, the inner classes. Their constructors $val \ x = obj.Foo(...)$ are members of the host object, but the classes themselves are not x : obj.Foo, but rather x : HostType.Foo. If we correct this and limit type inference and smart casts to reachable types, expressions of the type obj.Foo can never appear outside of the scope where obj is available.

Now if obj is an inplace argument, it is impossible to expose an object x: obj.Foo beyond that scope without upcasting to an external base type such as Any. This way, obj.Foo-specific members that are not exposed via overridden external base type members are unreachable beyond that scope. Thus, we can safely allow such members to store or capture the inplace arguments of any parent scope. Crucially, objects capturing inplace arguments can be safely stored inside properties and containers such as List<obj.Foo>: typability guarantees confinement.

Now let us refine the definition of the CoroutineScope taking advantage of member interfaces:

```
interface CoroutineScope {
   fun <R> coroutineScope(block : once (inner CoroutineScope).()-> R) : R
   fun <R> async(block : this.Coroutine<R>) : this.Deferred<R>
   fun launch(block : this.Coroutine<Unit>) : this.Job

inner fun interface Coroutine<T> {
    abstract suspend fun invoke() : T
   }
   inner interface Job {...}
...
}
```

Now the function coroutineScope passes a fresh coroutine scope as an inplace argument this, and launch expects coroutine literals of its member type this@coroutineScope.Coroutine<Unit>, which are now allowed to capture inplace arguments from the parent scopes of the coroutineScope, in particular the it: PrintWriter in the above example.

Advanced applications such as mutable concurrent collection libraries and actor frameworks additionally require host-object polymorphism and open / abstract nominal type members.

2.1 Host-object polymorphism

Host-object polymorphism is a typed counterpart of the Rustacean lifetime-polymorphism:

```
fun <cs : *CoroutineScope> join(x : cs.Job, y : cs.Job) : cs.Job
class Foo<cs : *CoroutineScope>(job : cs.Job) // Rudimentary dependent type
```

Here, cs is an erasable compile-time parameter used solely for type checking and it can only be used in type annotations, but not in expressions: join cannot invoke cs.launch. To make it accessible inside the function, reified modifier can be used:

```
fun <T, reified cs : *CoroutineScope> bar(x : cs.Deferred<T>) // Dependent function
```

Here, cs is also invisibly passed as a genuine runtime argument, so bar can invoke cs.launch.

The HostType.InnerType-notation can still be used in argument signatures as a shorthand:

```
fun foo(x : CoroutineScope.Job) --> fun <cs : *CoroutineScope> foo(x : cs.Job)
```

2.2 Type members (a cautionary note)

Type members were first introduced into mainstream programming by Scala, and had a pretty bad reputation ever since. In Scala, abstract type members can be used to express both nominal and structural subtyping, as well as bounded parametric polymorphism, but lead to undecidable subtyping and exhibit very tricky behavior. While attractive regarding the economy of concepts, they are quite the opposite regarding the principle of least astonishment.

Unlike Scala, we only propose to introduce nominal type members² (classes and interfaces), which behave in a fairly predictable way and coexist with type parameters (like in List<T>) rather than replacing them. It does not only reduce the mental burden, but is also more future-proof: As opposed to abstract type members in Scala, parametric polymorphism in Java (and Kotlin) features transitive decidable subtyping, and does so even in the presence of typeclass bounds, higher kinds, and dependent types, assuming material-shape separation.³

¹Which can be seen as zero runtime multiplicity, complementing once?, once, once+, and ordinary arguments.

 $^{^2}$ as introduced in https://dl.acm.org/doi/pdf/10.1145/3371134, 3.4.3

 $^{^3}$ https://www.cs.cornell.edu/~blg59/resources/doc/effing-bound-polymorphism.pdf

3 Modal objects

Kotlin type system, as it stands, does not reflect the fact that object members may become unavailable after certain actions, or for the duration of certain actions. For instance, closeable resources cannot be accessed after being closed and mutable collections cannot be mutated while being iterated. Structured confinement opens the way to represent that at type level.

Let us use break modifier for methods that finalize their host object and modal for methods that lock their host object for the duration of their invocation, ruling out invocation of other modal or finalizing methods. Classes with modal methods must also be modal:

```
modal class Buffer {
   fun append(item : Byte) { ... }
   modal fun clear() { ... }
   modal fun iterate(block : inner (inner Iterator)-> Unit) { ... }
}
Classes with finalizing methods must be modal! if finalization is mandatory or modal? otherwise:
modal! fun interface ExactlyOnceFunction<X, Y> { // Implementation of once (X)-> Y
   break fun invoke(x : X) : Y // must be invoked exactly once
}
modal? fun interface OnceOrLessFunction<X, Y> { // Implementation of once? (X)-> Y
   break fun invoke(x : X) : Y // can be invoked at most once
}
```

References m: M, where M is a modal or modal? class, will be called modal references. A modal reference is always either principal or locking. Modal and finalizing methods can only be invoked through the principal reference, which can only happen if there are no other accessible locking references. Locking references are always confined to some scope, but can be freely aliased and captured within this scope. For a mutable object where all setters are modal and getters non-modal, locked and principal references behave as read-only and mutable references in Rust.

Confinement of locking references is essential to ensure that principal references remain essentially unique, i.e. unique modal references to the underlying object if we don't count references captured inside orphaned objects waiting to be garbage-collected or inside fields that cannot be accessed without reflection. Beware that we only control aliasing for modal aliases, and since every class has at least one non-modal supertype (namely Any), modal references can always coexist with non-modal references to the same object, providing additional flexibility.

Non-modal reference can be used to access non-modal non-finalizing members of a modal type using atomic guarded invocations (r as M).foo() and (r as? M)?.foo(), but can never be cast to M because it could violate principal reference uniqueness.

The original reference obtained by creating an object is automatically principal. When used to invoke a finalizing method or passed to a new owner, primary references cease to be primary and change their type to the nearest non-modal superclass (possibly Any). We propose the syntax fun foo(o: object M) { ... } for ownership transfer. When used to invoke a modal method or passed as an implace argument, principal references are shadowed by locking references:

Modal functions may have a finally { ... } block after their main body, which is executed after the confined locked reference ceases to exist and the principal reference is recovered. This block may invoke other modal functions but is not allowed to finalize the principal reference.

When a principal reference is passed as an argument without inner or object it is "borrowed". The lent reference immediately ceases to be principal and changes its type to the nearest non-modal superclass, and the receiving scope acquires a confined principal reference. If the reference is modal!, the receiving scope is obliged to finalize the object. After the invocation, the original reference regains its principality. In case of non-finalizable classes, it also regains its original type. For modal! and modal? its modal type can be reestablished by (smart)casts:

```
val f = OnceOrLessFunction<Int, Unit> { println(it) }
foo(f)
when(f) {
  is OnceOrLessFunction<*, *> -> // f was not consumed by foo
  else -> // f was consumed by foo
}
```

We also want to briefly mention that modal! objects confined in a particular scope are allowed to capture principal references confined in the same scope. Non-confined principal references can be captured by any objects of the same modality. To deal with captured principal references, we need to introduce modal fields which can only be accessed in modal methods and thus can temporarily lose principality or change type inside those methods. The ability to capture principal references inside modal objects is essential for many concurrent applications.

3.1 Recovering 'Rust'

To embed the Rust model, we need the following ingredients:

Modal data classes (their setters are declared modal, and they can have fields of modal types)

```
modal data class User(var name : String, var age : Int)
modal data class Var<T>(var value : T)

fun foo(user : User) { ... } // Passing a mutable reference
fun bar(user : inner User) { ... } // Passing a read-only reference
```

Indentation-sparing using var syntax from C#

Now we can define lifetimes analogously to coroutineScope above:

```
class Lifetime {
  inline fun <modal T, R> local(t : object T, block : once (T)-> R) = block(t)
}
inline fun <R> lifetime(block : once (inner Lifetime).()-> R) = Lifetime().block()

// usage:
fun foo() {
    // lifetimes introduce no runtime overhead
    lifetime {
        using val user = local(User("John Doe", 39))
        using val intVar = local(Var<Int>(40))
        user.age = intVar.value
        ...
} // user and intVar are guaranteed to be unreachable by now
}
```

For a native experience, introduce qualified variable syntax and implicit lifetime scopes:

```
val@foo user = User("John Doe", 39)
var@foo intVar = 40
```

3.2 Join-blocks for parallel initialization and finalization

Quite often, independent resources are being initialized and finalized sequentially:

```
withB { b ->
 }
}
In many cases, parallel initialization and finalization would be beneficial:
join(withA, withB) { (a, b) ->
To implement join in a structured concurrent way we need the notion of a join block, 4 a
simultaneous definition of local suspending once-functions with a common body:
join fun f(x : Int) \& fun g(y : Int) {
   return@f(x + y)
   return@q (x - y)
}
launch {
  delay(Random.nextInt(0, 100))
  println(f(5))
launch {
  delay(Random.nextInt(0, 100))
  println(g(3))
And that's how one implements parallel resource initialization and finalization:
```

Join-blocks allow elegant implementations of arbitrary communication and synchronization patterns highly amenable to structured formal reasoning.

3.3 Modes

withA { a ->

To represent objects with a complex lifecycle, we propose borrowing (pun intended) yet another mechanism from Scala, namely the extension classes, described in https://docs.scala-lang.org/tour/self-types.html. Kotlin-style semantics of extension classes could be easily described if inheritance by delegation were available not only for interfaces but also for classes:

```
extension Parent.Mode(...) { ... } --> class Mode(p : Parent, ...) : Parent by p { ... }
```

⁴See https://en.wikipedia.org/wiki/Join-calculus

Extensions can be declared inside the class they extend, in which case the Parent. prefix is omitted. They can also be nested. Extensions are used to refine objects (that is, add and override members) after they have been constructed. Extensions can be constructed using with-clauses: Parent(...) with Mode. We'll be using extensions to introduce method modifiers continue@Mode, break@Mode, and modal@Mode. It will be crucial to allow overriding modal methods by non-modal ones in extensions.

The Buffer definition above is not quite satisfactory since the modality of the iterate() method rules out nested and parallel iteration. Let us introduce an extension AppendOnly where iterate() is non-modal and change the signature of the original iterate() to modal@AppendOnly. With this modifier, the locked reference that shadows the original principal reference while iterate() is executed will be substituted by its AppendOnly-extension. The body of iterate() can be omitted to delegate to its overriding method in AppendOnly. Additionally, we'll introduce the modal method open that locks the buffer in AppendOnly state to enable parallel iteration:

```
class Buffer {
  fun append(item : Byte) { ... }
  modal fun clear() { ... }
  modal@AppendOnly fun open(block : once ()-> R) : R = block()
  modal@AppendOnly fun iterate(block : inner (inner Iterator)-> Unit)
  extension AppendOnly {
    fun iterate(block : inner (inner Iterator)-> Unit) { ... }
  }
}
Now we can use buffer.iterate {...} inside buffer.iterate {...}, and perform parallel iteration:
buffer.open {
  coroutineScope {
    for (i in 1..99) launch {
      buffer.iterate {...}
    }
  }
}
```

Methods with continue@Mode modifier substitute the principal reference used to invoke them by its Mode-extension. Delegation by omission is allowed as well:

Since extensions can be nested, we also need qualified break@Mode. Unqualified break finalizes the outermost modal parent.

Both break and modal can be combined with continue@Mode allowing arbitrary typelevel state automata. For an example let us consider an HTML builder.⁶ It provides an embedded type-safe DSL for constructing HTML:

```
val h = html {
  head { ... }
  body { ... }
}
```

⁵The parallels to ordinary break and continue become evident when introducing type-safe actor model.

 $^{^6}$ If you are unfamiliar with this example, please consult https://kotlinlang.org/docs/type-safe-builders.html

To require exactly one head and exactly one body after it, we'll need a staged builder:

```
class Html : Tag("html") with AwaitsHead {
  modal! extension AwaitsHead {
                                                                   // Html.AwaitsHead
    break continue@AwaitsBody
    fun head(head : once Head.()-> Unit) = initTag(Head(), head) //
                                                                         head { ... }
  }
  modal! extension AwaitsBody {
                                                                   // Html.AwaitsBody
    break
                                                                   //
    fun body(body : once Body.()-> Unit) = initTag(Body(), body) //
 }
                                                                  //
                                                                  // Html
}
```

Here we declare a staged class Html that extends Tag("html") and has two additional modes AwaitsHead and AwaitsBody with methods head() and body() respectively. Both methods are finalizing methods, but head() additionally continues to the AwaitsBody, while body() leaves the bare non-modal Html object which provides members inherited from Tag. The initial mode of this object is specified using a with-clause borrowed from Scala.

Finally, we want to mention that non-abstract class Parent with Mode is allowed to have abstract members as long as they are implemented by Mode. Also note that if the extension Mode has constructor arguments and/or abstract methods, continue@Mode functions, modal@Mode and the constructor of class Parent with Mode must contain an init Mode(args) {methods} block providing those arguments and/or methods. modal continue@NextMode functions initialize NextMode in their finally { ... } block. This is also where modal@Mode functions have/can to finalize Mode if it is modal! or modal? respectively.

3.4 Join methods

Join blocks can be also used to define methods in multi-modal objects, e.g.

Modal objects and modes tightly intertwine type-checking and control-flow analysis.

4 Conclusion

We have devised a coherent system of mechanisms for lifecycle-aware resource handling, providing the most comprehensive correctness guarantees of any general-purpose programming language currently available. Our approach has to be evaluated by developing a library of concurrent mutable collections and heaps⁷ supporting fine-grained concurrent separation logic.

⁷Heaps with various transactional operators, heap-native structures, ghost variables, and conflict-free replicated data types in addition to pure ones, provide implementations for arbitrary flavors of separation logic.