Foundations of Machine Learning

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Lab 1: Gradients and Directional Derivatives

Multivariate Differentiation

Learning Objectives

- 1. Define the directional derivative, and use it to find a linear approximation to $f(\mathbf{x}+h\mathbf{u})$.
- 2. Define partial derivative and the gradient. Show how to compute an arbitrary directional derivative using the gradient.
- 3. For a differentiable function, give a linear approximation near a point \mathbf{x} using the gradient.
- 4. Show that the gradient gives the direction of steepest ascent, and the negative gradient gives the direction of steepest descent.

Concept Check Questions

1. If f'(x; u) < 0 show that f(x + hu) < f(x) for sufficiently small h > 0.

Solution. The directional derivative is given by

$$f'(x;u) = \lim_{h \to 0} \frac{f(x+hu) - f(x)}{h} < 0.$$

By the definition of a limit, there must be a $\delta > 0$ such that

$$\frac{f(x+hu)-f(x)}{h}<0$$

whenever $|h| < \delta$. If we restrict $0 < h < \delta$ then we have

$$f(x + hu) - f(x) < 0 \implies f(x + hu) < f(x)$$

as required.

2. Let $f: \mathbb{R}^n \to \mathbb{R}$ be differentiable, and assume that $\nabla f(x) \neq 0$. Prove

$$\underset{\|u\|_2=1}{\arg\max} f'(x;u) = \frac{\nabla f(x)}{\|\nabla f(x)\|_2} \quad \text{and} \quad \underset{\|u\|_2=1}{\arg\min} f'(x;u) = -\frac{\nabla f(x)}{\|\nabla f(x)\|_2}.$$

Solution. By Cauchy-Schwarz we have, for $||u||_2 = 1$,

$$|f'(x;u)| = |\nabla f(x)^T u| \le ||\nabla f(x)||_2 ||u||_2 = ||\nabla f(x)||_2.$$

Note that

$$\nabla f(x)^T \frac{\nabla f(x)}{\|\nabla f(x)\|_2} = \|\nabla f(x)\|_2 \text{ and } \nabla f(x)^T \frac{-\nabla f(x)}{\|\nabla f(x)\|_2} = -\|\nabla f(x)\|_2,$$

so these achieve the maximum and minimum bounds given by Cauchy-Schwarz.

One way to understand the Cauchy-Schwarz inequality is to recall that the dot-product between two vectors $v, w \in \mathbb{R}^d$ can be written as

$$v^T w = ||v||_2 ||w||_2 \cos(\theta).$$

where θ is the angle between v and w. This value is maximized at $\cos(0) = 1$ and minimized at $\cos(\pi) = -1$.

Computing Gradients

Learning Objectives

- 1. Find the gradient of a function by computing each partial derivative separately.
- 2. Use the chain rule to perform gradient computations.
- 3. Compute the gradient of a differentiable function by determining the form of a general directional derivative.

Concept Check Questions

1. Let $f: \mathbb{R}^2 \to \mathbb{R}$ be given by $f(x,y) = x^2 + 4xy + 3y^2$. Compute the gradient $\nabla f(x,y)$.

Solution. Computing the partial derivatives gives

$$\partial_1 f(x,y) = 2x + 4y$$
 and $\partial_2 f(x,y) = 4x + 6y$.

Thus the gradient is given by

$$\nabla f(x,y) = \begin{pmatrix} 2x + 4y \\ 4x + 6y \end{pmatrix}.$$

2. Compute the gradient of $f: \mathbb{R}^n \to \mathbb{R}$ where $f(x) = x^T A x$ and $A \in \mathbb{R}^{n \times n}$ is any matrix.

Solution. Here we show two methods. In either case we can obtain differentiability by noticing the partial derivatives are continuous.

(a) Since

$$f(x) = x^T A x = \sum_{i,j=1}^n a_{ij} x_i x_j$$

we have

$$\partial_k f(x) = \sum_{j=1}^n (a_{kj} + a_{jk}) x_j$$

SO

$$\nabla f(x) = (A + A^T)x.$$

(b) Note that

$$f(x+tv) = (x+tv)^{T}A(x+tv) = x^{T}Ax + tx^{T}Av + tv^{T}Ax + t^{2}v^{T}Av = f(x) + t(x^{T}A + x^{T}A^{T})v + t^{2}(v^{T}Av).$$

Thus

$$f'(x;v) = \lim_{t \to 0} \frac{f(x+tv) - f(x)}{t} = \lim_{t \to 0} (x^T A + x^T A^T) v + t(v^T A v) = (x^T A + x^T A^T) v.$$

This shows

$$\nabla f(x) = (A + A^T)x.$$

3. Compute the gradient of the quadratic function $f: \mathbb{R}^n \to \mathbb{R}$ given by

$$f(x) = b + c^T x + x^T A x,$$

where $b \in \mathbb{R}$, $c \in \mathbb{R}^n$ and $A \in \mathbb{R}^{n \times n}$.

Solution. First consider the linear function $g(x) = c^T x$. Note that

$$g(x+tv) = c^T(x+tv) = c^Tx + tc^Tv \implies \nabla f(x) = c.$$

As the derivative is linear we can combine this with the previous problem to obtain

$$\nabla f(x) = c + (A + A^T)x.$$

4. Fix $s \in \mathbb{R}^n$ and consider $f(x) = (x - s)^T A(x - s)$ where $A \in \mathbb{R}^{n \times n}$. Compute the gradient of f.

Solution. We give two methods.

(a) Let $g(x) = x^T A x$ and h(x) = x - s so that f(x) = g(h(x)). By the vector-valued form of the chain rule we have

$$\nabla f(x) = \nabla g(h(x))^T Dh(x) = (A + A^T)(x - s),$$

where $Dh(x) = \mathbf{I}_{n \times n}$ is the Jacobian matrix of h.

(b) We have

$$(x-s)^{T}A(x-s) = x^{T}Ax - s^{T}(A+A^{T})x + s^{T}As.$$

Computing the gradient gives

$$\nabla f(x) = (A + A^T)x - (A + A^T)s = (A + A^T)(x - s).$$

5. Consider the ridge regression objective function

$$f(w) = ||Aw - y||_2^2 + \lambda ||w||_2^2,$$

where $w \in \mathbb{R}^n$, $A \in \mathbb{R}^{m \times n}$, $y \in \mathbb{R}^m$, and $\lambda \in \mathbb{R}_{\geq 0}$.

- (a) Compute the gradient of f.
- (b) Express f in the form $f(w) = \|Bw z\|_2^2$ for some choice of B, z. What do you notice about B?
- (c) Using either of the parts above, compute

$$\underset{w \in \mathbb{R}^n}{\arg\min} f(w).$$

Solution.

(a) We can express f(w) as

$$f(w) = (Aw - y)^{T}(Aw - y) + \lambda w^{T}w = w^{T}A^{T}Aw - 2y^{T}Aw + y^{T}y + \lambda w^{T}w.$$

Applying our previous results gives (noting $w^T w = w^T \mathbf{I}_{n \times n} w$)

$$\nabla f(w) = 2A^T A w - 2A^T y + 2\lambda w = 2(A^T A + \lambda \mathbf{I}_{n \times n}) w - 2A^T y.$$

(b) Let

$$B = \begin{pmatrix} A \\ \sqrt{\lambda} \mathbf{I}_{n \times n} \end{pmatrix} \quad \text{and} \quad z = \begin{pmatrix} y \\ \mathbf{0}_{n \times 1} \end{pmatrix}$$

written in block-matrix form. Note B is full rank.

(c) The argmin is $w = (A^T A + \lambda \mathbf{I}_{n \times n})^{-1} A^T y$. To see why the inverse is valid, see the linear algebra questions below.

6. Compute the gradient of

$$f(\theta) = \lambda \|\theta\|_2^2 + \sum_{i=1}^n \log(1 + \exp(-y_i \theta^T x_i)),$$

where $y_i \in \mathbb{R}$ and $\theta \in \mathbb{R}^m$ and $x_i \in \mathbb{R}^m$ for i = 1, ..., n.

Solution. As the derivative is linear, we can compute the gradient of each term separately and obtain

$$\nabla f(\theta) = 2\lambda \theta - \sum_{i=1}^{n} \frac{\exp(-y_i \theta^T x_i)}{1 + \exp(-y_i \theta^T x_i)} y_i x_i,$$

where we used the techniques from Recitation 1 to differentiate the log terms.