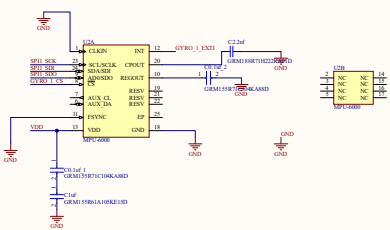
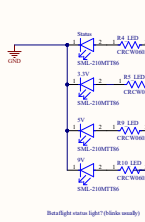


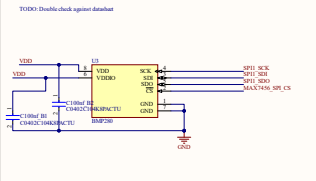
# Gyro / Accelerometer (May need to eventually switch to BM270 due to availability)



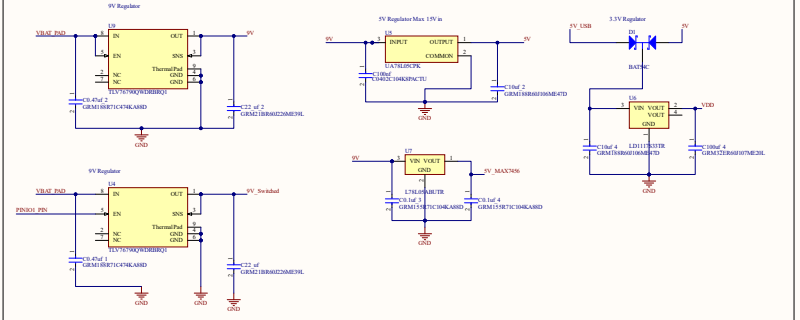
# LED's



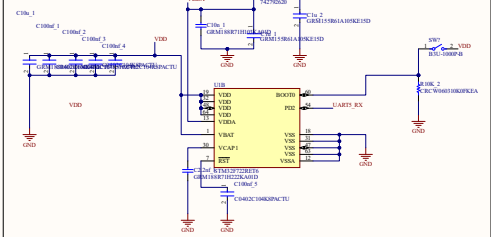
# Barometer pretty straight forward connections 3.3V



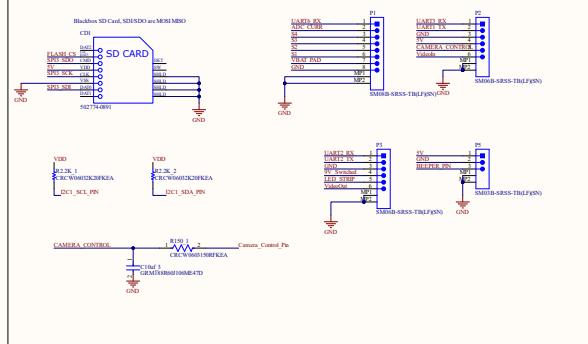
# Power



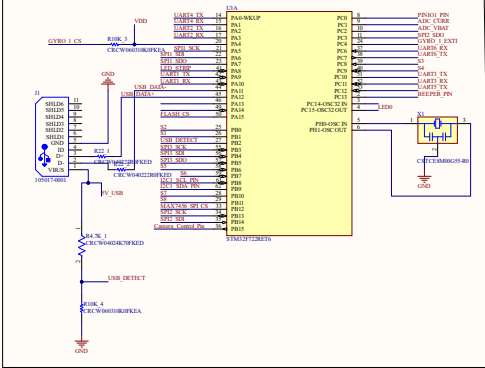
# STM32F7 Power



# Connections, i2c pullups, CameraControl joystick interface



# STM32F7 Data Pins



# Analog OSD

