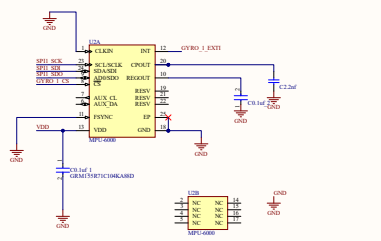
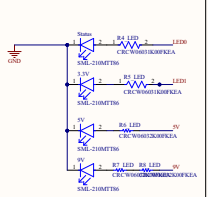


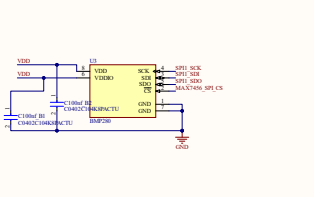
Gyro / Accelerometer (May need to eventually switch to BM270 due to availability)



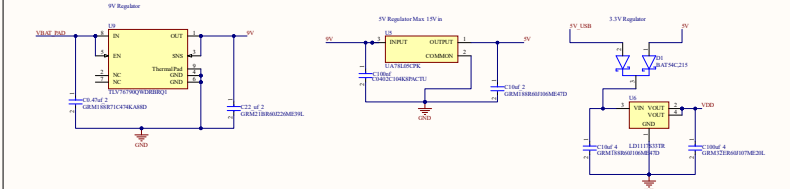
LED's



Barometer pretty straight forward connections 3.3V

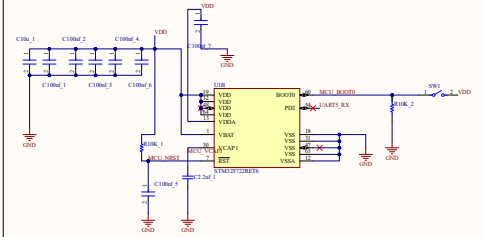


Power

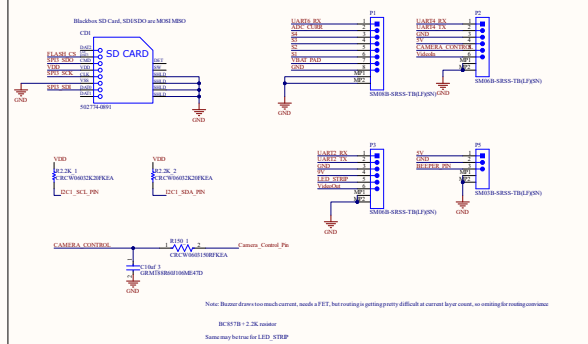


STM32F7 Power

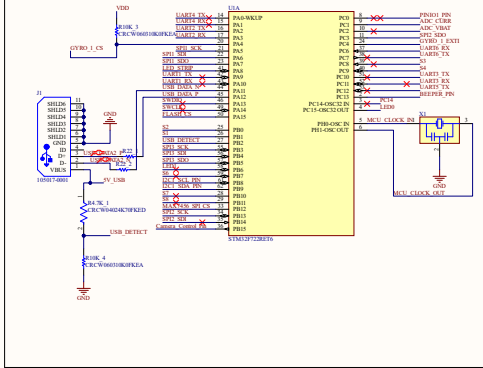
Additional filtering for analog power



Connections, I2C pullups, CameraControl joystick interface



STM32F7 Data Pins



Analog OSD

