

Sparse projections onto the simplex

Tasos Kyrillidis[†], Stephen Becker[‡], Volkan Cevher[†], Christoph Koch[§]
{anastasios.kyrillidis,volkan.cevher,christoph.koch}@epfl.ch,
stephen.becker@upmc.fr

[†]Laboratory for Information and Inference Systems (EPFL)

[‡]Laboratory Jacques Louis-Lions (Université Pierre et Marie Curie)

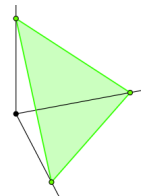
[§]Data Analysis, Theory and Applications Laboratory (EPFL)

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Sparse projections with simplex and simplex-type constraints

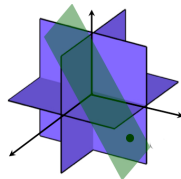
- **Sparse projection onto the simplex hyperplane:**

$$(\mathcal{P}^S) : \quad \beta^* \in \underset{\beta : \|\beta\|_0 \leq s, \beta \in \Delta_\lambda^+}{\operatorname{argmin}} \quad \|\beta - \mathbf{w}\|_2^2$$



- **Sparse projection onto simplex-type hyperplane:**

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- **Subtle difference:**

$$\Delta_\lambda^+ = \left\{ \beta \in \mathbb{R}^n : \beta_i \geq 0, \sum_i \beta_i = \lambda \right\} \quad \text{Vs.} \quad \Delta_\lambda = \left\{ \beta \in \mathbb{R}^n : \sum_i \beta_i = \lambda \right\}$$

Why are these projections interesting?

When convex relaxations conflict with problem constraints...

- **Sparse constrained optimization:**

$$\min_{\beta \in \mathbb{R}^n: \|\beta\|_0 \leq s} f(\beta) \xrightarrow{\text{Convexify...}} \min_{\beta \in \mathbb{R}^n: \|\beta\|_1 \leq \tau} f(\beta)$$

- (i) Specific instances of $f(\beta)$ in the poster session...
- (ii) $\|\beta\|_0$: ℓ_0 -“norm” where its convex relaxation is $\|\beta\|_1$.

- **The power of convex relaxations:** polynomial solvability and provable recovery guarantees.

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- The power of convex relaxations:** polynomial solvability and provable recovery guarantees.
- In many cases, **true constraints result in fixed convex metric:**

E.g.: **simplex constraint Δ_1^+ :**

$$\left. \begin{array}{l} \sum_i \beta_i = 1 \\ \beta_i \geq 0 \end{array} \right\} \implies \|\beta\|_1 = 1. \quad \left| \quad \min_{\beta \in \mathbb{R}^n: \|\beta\|_0 \leq s, \|\beta\|_1 = 1} f(\beta) \xrightarrow{\text{Convexify...}} \text{???}$$

Sparse projections onto the simplex

- **Sparse projection onto the simplex:**

$$(\mathcal{P}^S) : \quad \boldsymbol{\beta}^* \in \underset{\boldsymbol{\beta} : \|\boldsymbol{\beta}\|_0 \leq s, \boldsymbol{\beta} \in \Delta_\lambda^+}{\operatorname{argmin}} \quad \|\boldsymbol{\beta} - \mathbf{w}\|_2^2 \quad (1)$$

- The problem (1) is equivalent to the nested minimization problem:

$$\{S^*, \boldsymbol{\beta}_{S^*}^*\} = \underset{S: S \in \Sigma_s}{\operatorname{argmin}} \left[\min_{\substack{\boldsymbol{\beta}_S \in \Delta_\lambda^+, \\ \boldsymbol{\beta}_{\setminus S} = 0}} \|(\boldsymbol{\beta} - \mathbf{w})_S\|_2^2 + \|(\mathbf{w})_{\setminus S}\|_2^2 \right]$$

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- Given \mathcal{S}^* , $(\boldsymbol{\beta}^*)_{\mathcal{S}^*} = \left[w_i + \frac{1}{|\mathcal{S}^*|} \left(\lambda - \sum_{i \in \mathcal{S}^*} w_i \right) \right]_+$ (1a)

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GREEDY SELECTOR AND SIMPLEX PROJECTOR (GSSP)

$$\mathcal{S}^* = \operatorname{supp}(\mathcal{P}_{L_s}(\mathbf{w})), (\boldsymbol{\beta}^*)_{\mathcal{S}^*} \text{ given by (1}\alpha\text{) and, } (\boldsymbol{\beta}^*)_{\mathcal{S}^c} = 0.$$

\mathcal{P}_{L_s} keeps the s -largest entries (**not in magnitude**).

- **Complexity:** $\mathcal{O}(n \log n)$.

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GREEDY SELECTOR AND HYPERPLANE PROJECTOR (GSHP)

1. $\ell = 1$, $\mathcal{S} = j$, $j \in \arg \max_i (\lambda w_i)$.

2. Repeat: $\ell \leftarrow \ell + 1$, $\mathcal{S} \leftarrow \mathcal{S} \cup j$, where

$$j \in \arg \max_{i \in \mathcal{N} \setminus \mathcal{S}} \left| w_i - \frac{\sum_{j \in \mathcal{S}} w_j - \lambda}{\ell - 1} \right|,$$

until $\ell = k$.

3. Set $\mathcal{S}^* \leftarrow \mathcal{S}$ and solve (2 α)

- THEOREM. GSHP Algorithm provably solves (2).
- **Complexity:** $\mathcal{O}(n \log_2(n))$.

- GSHP selects the index of the largest element with the same sign as λ (Step 1). It then grows the index set one at a time by finding the farthest element from the current mean, as adjusted by λ (Step 2).

More information and applications
in the poster session...

Thank you.