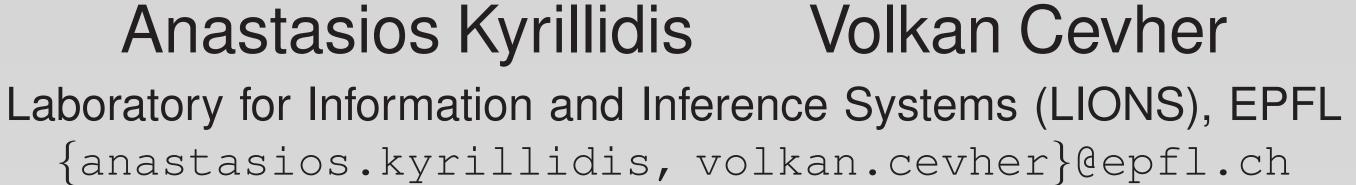


Self-Concordant Function Minimization: Sparse Graph Selection









Motivation: Sparse Gaussian Graph Selection

- Setting: $\mathbf{X} = \{X_1, X_2, \dots, X_n\}$ with joint pdf $f(X_1, \dots, X_n) \sim \mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma})$.
- Goal: infer (conditional/unconditional) independence among X, given a set of samples.
- Sampling: $\{\mathbf{x}_j\}_{j=1}^p$ is a collection of p i.i.d. n-variate vectors where $\mathbf{x}_j \sim \mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma}), \ \forall j$.

Sample covariance: $\widehat{\Sigma} = \frac{1}{p} \sum_{j=1}^{p} (\mathbf{x}_j - \widehat{\boldsymbol{\mu}}) (\mathbf{x}_j - \widehat{\boldsymbol{\mu}})^T$. Empirical mean: $\widehat{\boldsymbol{\mu}} = \frac{1}{n} \sum_{i=1}^{p} \mathbf{x}_{j}$

Connection to graph learning:

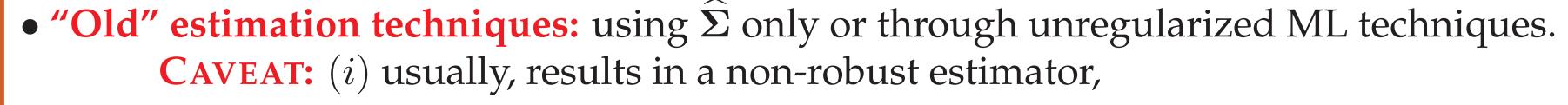
$$G = (V, E)$$
 is a Gaussian Markov network where

$$(ii) X_i \perp \!\!\!\perp X_j \mid X_k, \ \forall k \neq i, j$$

1.
$$V = \{1, \dots, n\}$$
: set of variables.

2. E: contains edge (i, j) iff X_i is conditionally independent to X_i .

Why Gaussian?
$$\Sigma_{ij}^{-1} = 0 \iff X_i \perp \!\!\!\perp X_j \mid X_k, \ \forall k \neq i,j$$



(ii) no easy interpretation since the estimator is usually fully dense!

• Parsimony principle: select the *simplest* graphical model that adequately explains the data.

Let
$$\Theta = \widehat{\Sigma}^{-1}$$
. Given $\widehat{\Sigma}$ and $\rho > 0$:

$$\mathbf{\Theta}^* = \underset{\mathbf{\Theta} \succ 0}{\operatorname{argmin}} \left\{ \underbrace{-\log \det(\mathbf{\Theta}) + \operatorname{trace}(\mathbf{\Theta}\widehat{\boldsymbol{\Sigma}})}_{=f(\mathbf{\Theta})} + \underbrace{\rho \|\mathbf{\Theta}\|_{1}}_{=g(\mathbf{\Theta})} \right\}$$
(1)

 $(i) X_i \perp \!\!\! \perp X_i$

- Contributions:
 - 1. New first-order gradient scheme: fast convergence (# iter.) as compared to state-of-the-art.
 - 2. New ingredient: Adaptive step size selection using self-concordance of the objective.

Challenges and Related Work

- Challenge #1: High-dimensional statistical problems have become the norm.
- Challenge #2: Neither $f(\Theta)$ nor $g(\Theta)$ is Lipschitz-continuous gradient functions; $g(\mathbf{\Theta})$ is a nonsmooth regularizer.
- Challenge #3: (1) is defined over the positivedefinite cone \mathbb{S}^n_{++} .
- Challenge #4: The selection of regularization parameter ρ is crucial.
- Why not use off-the-self Interior-point methods (IPM)?

(BANERJEE, EL GHAOUI, AND D'ASPREMONT (2007)): "... the resulting complexity for existing IPMs is $\mathcal{O}(n^6)$ where n is the number of variables..."

- Plenty of efficient approaches:
 - Block coordinate descent/ascent schemes (Graphical Lasso, CovSel, SINCO, etc.)
 - Lagrangian schemes (ALM, ADMM, etc.)
 - Second-order schemes (QUIC, Newtonbased methods, etc.)

Gradient descent scheme

- $\Theta^* = \operatorname{argmin} f(\Theta) + g(\Theta)$.
- Use $\Delta := -\nabla f(\mathbf{\Theta}_i)$ (ignore $g(\mathbf{\Theta}_i)$).
- Quadratic surrogate for $f(\mathbf{\Theta})$ at $\mathbf{\Theta}_i \in \mathbb{R}^{n \times n}$: $f(\mathbf{\Theta}) \le U(\mathbf{\Theta}, \mathbf{\Theta}_i)$

$$:= f(\mathbf{\Theta}_i) + \operatorname{trace}\left(\nabla f(\mathbf{\Theta}_i)(\mathbf{\Theta} - \mathbf{\Theta}_i)\right) + \frac{1}{2\tau_i} \|\mathbf{\Theta} - \mathbf{\Theta}_i\|_F^2$$

for some $\tau_i > 0$.

• Iteratively, solve:

$$\mathbf{\Theta}_{i+1} = \underset{\mathbf{\Theta} \succ 0}{\operatorname{arg\,min}} \{ U(\mathbf{\Theta}, \mathbf{\Theta}_i) + g(\mathbf{\Theta}) \}$$

or in "proximity operator" form:

$$\Theta_{i+1} = \underset{\Theta \succ 0}{\operatorname{arg\,min}} \left\{ \underbrace{\frac{1}{2\tau_i} \|\Theta - \underbrace{(\Theta_i - \tau_i \nabla f(\Theta_i))}_{=\operatorname{Soft}(\cdot, \tau_i \rho)} \|_F^2 + g(\Theta)}_{=\operatorname{Soft}(\cdot, \tau_i \rho)} \right\}$$

Step size selection τ_i - Part 1

- Gradient descent: $X_i = \Theta_i \tau_i \nabla f(\Theta_i)$.
- Bregman divergence between X_i and Θ_i :

$$\mathcal{D}_{f}(\boldsymbol{X}_{i} \parallel \boldsymbol{\Theta}_{i}) = -\sum_{j=1}^{n} \log(1 - \tau_{i}\lambda_{j}) - \tau_{i} \cdot \operatorname{trace}\left(\boldsymbol{\Theta}_{i}^{-1}\nabla f(\boldsymbol{\Theta}_{i})\right) =: \phi(\tau_{i}), \text{ where } \lambda_{j} : \text{ eigs. of } \boldsymbol{\Theta}_{i}^{-1/2}\nabla f(\boldsymbol{\Theta}_{i})\boldsymbol{\Theta}_{i}^{-1/2}$$

- Condition on τ_i to be satisfied: $\tau_i \leq 1/\lambda_i$, $\forall j$.
- KEY INGREDIENTS:

A convex function $h: \mathbb{R} \to \mathbb{R}$ is self-concordant if $|h'''(x)| \leq 2h''(x)^{3/2}$ for all $x \in \mathbb{R}$. Furthermore, a function $h: \mathbb{R}^{n \times n} \to \mathbb{R}$ is self-concordant if, for any $t \in \mathbb{R}$, the function $\phi(t) := h(\mathbf{X} + t\mathbf{V})$ is self-concordant for all $\mathbf{X}, \mathbf{V} \in \mathbb{R}^{n \times n}$. Given h_1, h_2 are self-concordant functions, then $h_1 + h_2$ is self-concordant.

Let $h: \mathbb{R} \to \mathbb{R}$ be a *strictly convex*, self-concordant function. Then: $\frac{h''(0)}{(1+t\sqrt{h''(0)})^2} \le h''(t) \le \frac{h''(0)}{(1-t\sqrt{h''(0)})^2}$, where the lower bound holds for $t \ge 0$ and the upper bound is valid for $0 \le t \le 1/\sqrt{h''(0)}$.

LEMMA: The function $\phi(\tau_i)$ is strictly convex and self-concordant.

Step size selection τ_i - Part 2

• By the second order expansion of $\phi(\tau_i)$:

LEMMA: The function $\phi(\tau_i)$ satisfies: $\phi(\tau_i) = \frac{1}{2} \cdot \tau_i^2 \cdot \phi''(\widehat{\tau_i})$, for $\widehat{\tau_i} \in (0, \tau_i]$ and $\phi''(\widehat{\tau_i}) = \sum_{j=1}^n \frac{\lambda_j^2}{(1-\widehat{\tau_i}\lambda_j)^2}$

• Since $\phi(\tau_i) := \mathcal{D}_f(\boldsymbol{X}_i \parallel \boldsymbol{\Theta}_i)$ and using $\frac{\delta}{(1+\tau_i\sqrt{\delta})^2} \le \phi''(\widehat{\tau}_i) \le \frac{\delta}{(1-\tau_i\sqrt{\delta})^2}$, we obtain:

$$\frac{\widetilde{\mu}}{2} \leq \frac{\mathcal{D}_f(\boldsymbol{X}_i \parallel \boldsymbol{\Theta}_i)}{\|\boldsymbol{X}_i - \boldsymbol{\Theta}_i\|_F^2} \leq \frac{\widetilde{L}}{2} \longleftarrow \text{Local Lipschitz constants and strong convexity parameter}$$

where $\frac{L}{2} = \frac{\delta}{2(1-\tau_i\sqrt{\delta})^2\|\nabla f(\boldsymbol{\Theta}_i)\|_F^2}$ and $\frac{\tilde{\mu}}{2} = \frac{\delta}{2(1+\tau_i\sqrt{\delta})^2\|\nabla f(\boldsymbol{\Theta}_i)\|_F^2}$.

• Two Nesterov-based step size selection schemes:

LEMMA: For convex and strongly convex (unconstrained) minimization, the step size τ_i^* is uniquely determined as the *minimum and maximum* (resp.) root of the quadratic forms:

$$\tau_i = 1/\widetilde{L} \Longleftrightarrow \tau_i^2 - 2\left(\frac{1}{\sqrt{\delta}} + \frac{1}{2\epsilon}\right)\tau_i + \frac{1}{\delta} = 0 \text{ and } \tau_i = \frac{2}{\widetilde{\mu} + \widetilde{L}} \Longleftrightarrow \tau_i^2 + \frac{1}{\sqrt{\epsilon}}\tau_i - \frac{1}{\delta} = 0$$

respectively, where $\delta := \phi''(0)$ and $\epsilon := \|\boldsymbol{X}_i - \boldsymbol{\Theta}_i\|_F^2$. Moreover, τ_i^* satisfies $0 \le \tau_i^* < 1/\sqrt{\phi''(0)}$.

Experiments

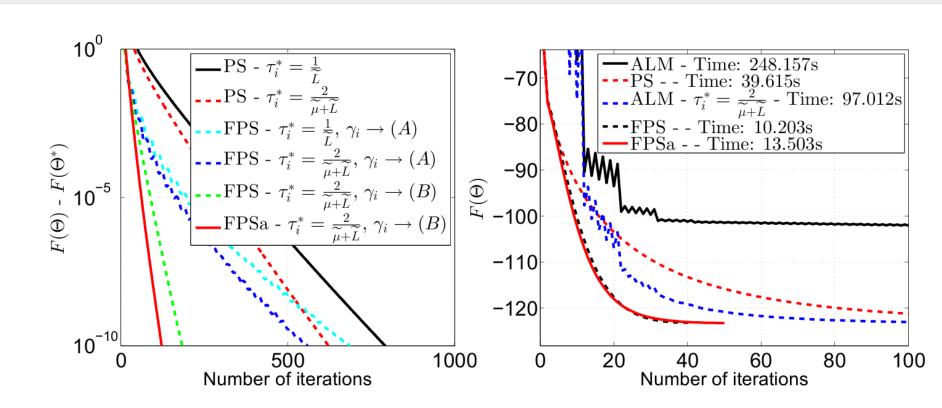


Fig. 1: Convergence rates

Setting (i)

Fig. 2: Comparison plot

FPS FPSa

$rac{\ \mathbf{\Theta}^* - \mathbf{\Sigma}^{-1}\ _F}{\ \mathbf{\Sigma}^{-1}\ _F}$	0.44	0.414	0.413	0.413
Correct	1705	1893	1893	1893
Missed	291	103	103	103
Extra	365	232	228	228
Iterations	400	379	129	114
#Inversions	400	379	129	114
Setting (ii)	ALM	PS	FPS	FPSa
$rac{\ \mathbf{\Theta}^{oldsymbol{*}} - \mathbf{\Sigma}^{-1}\ _F}{\ \mathbf{\Sigma}^{-1}\ _F}$	-	0.444	0.43	0.43
Correct	_	8710	8725	8724
Missed	_	290	275	276
Extra	_	4	4	4
Iterations	_	300	100	92
#Inversions	_	300	100	92

ALM | PS