

Lecture 20

Unsupervised Clustering

ECEN 5283 Computer Vision

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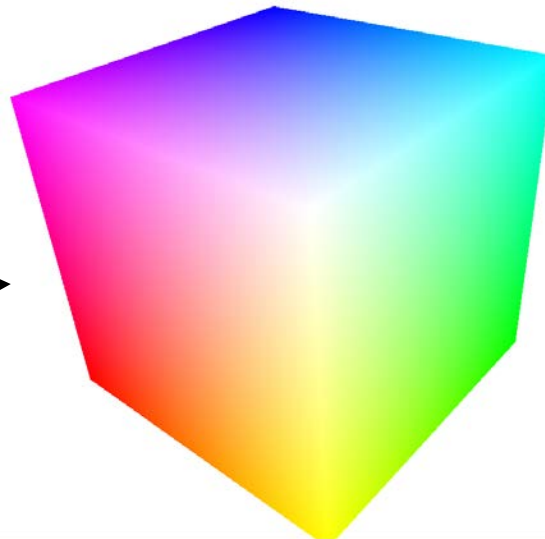
Goals

- ▶ To group a data set into different clusters.
- ▶ To study a few issues related to unsupervised clustering.
- ▶ To introduce the **K-means clustering** method.

Clustering in the Feature Space



3D Color Space



Problem Formulation of Unsupervised Clustering



- ▶ Given a set of unlabelled data samples $\mathbf{D} = \{y_1, y_2, \dots, y_n\}$ in a d -dimensional space, we partition the set \mathbf{D} into a number of disjoint subsets

$$\mathbf{D} = \bigcup_{j=1}^K D_j, \quad D_i \cap D_j = \phi, i \neq j$$

So that points in each subset are coherent according to certain criterion denoted by $f(\cdot)$. We denote a partition by

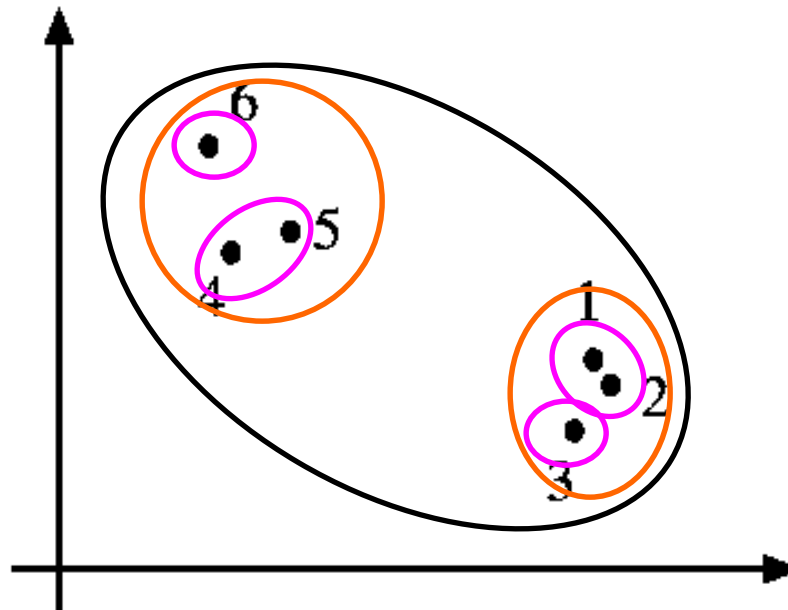
$$\Pi = (D_1 \quad D_2 \quad \dots \quad D_K)$$

Thus the problem is formulated as

$$\Pi^* = \arg_{\Pi} \max f(\Pi).$$

Two Problems to Avoid for Clustering

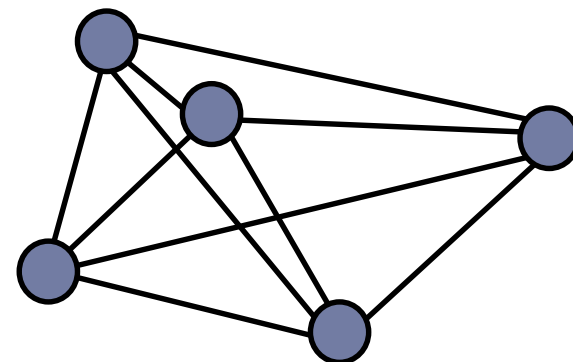
- ▶ There are two problems to avoid during clustering:
 - ▶ Under-fitting
 - ▶ Over-fitting



Two Issues to Consider for Clustering

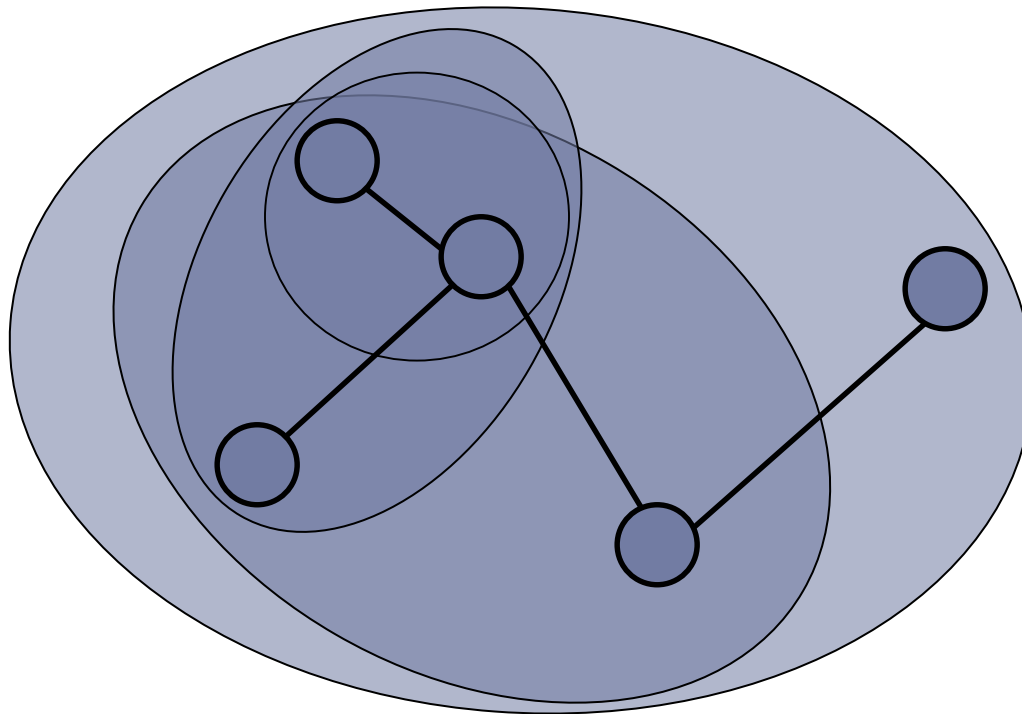


- ▶ There are two major issues in thinking of clustering:
 - ▶ What is a good distance metric?
 - ▶ Between two samples
 - ▶ Between a cluster and a sample
 - ▶ Between two clusters
 - ▶ How many clusters are there?
- ▶ There are two fashions of clustering
 - ▶ Agglomerative
 - ▶ From many to a few
 - ▶ Divisive
 - ▶ From one to a few



Agglomerative Clustering

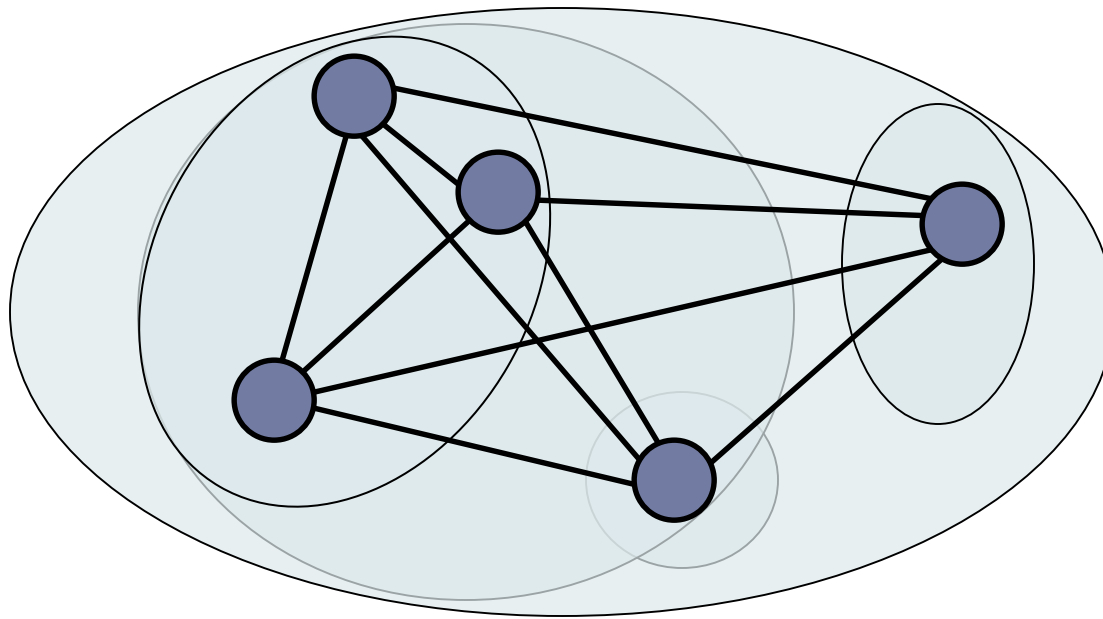
- ▶ Each object is initially placed into its own group. Each group contains only one object. Before we start the clustering, we need to decide on a threshold distance.



<http://fconyx.ncifcrf.gov/~lukeb/agclout.html>

Divisive Clustering (Cont'd)

- ▶ Divisive Clustering starts by placing all objects into a single group. Before we start the procedure, we need to decide on a threshold distance.



<http://fconyx.ncifcrf.gov/~lukeb/diclust.html>



K-means Clustering (Hard K-mean)

- ▶ **Goal:** Given the number of classes k , we attempt to optimize an objective function.
- ▶ **Objective:**
 - ▶ We want to segment data points in the feature space, then \mathbf{y} represent the feature vector, and \mathbf{c} is the center of a cluster.
 - ▶ We assume that elements are close to center of their cluster, yielding the objective function (intra-class divergence)

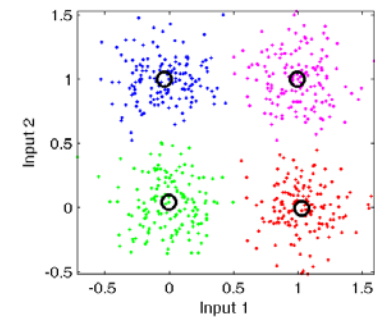
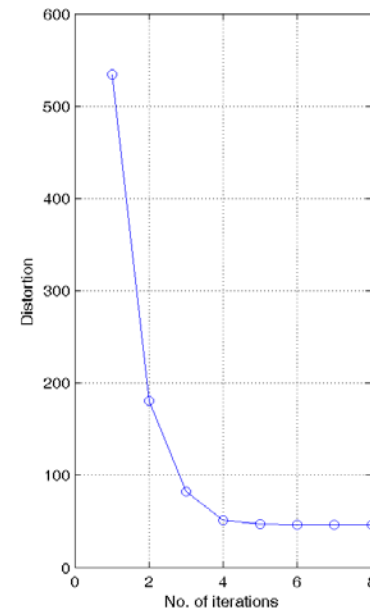
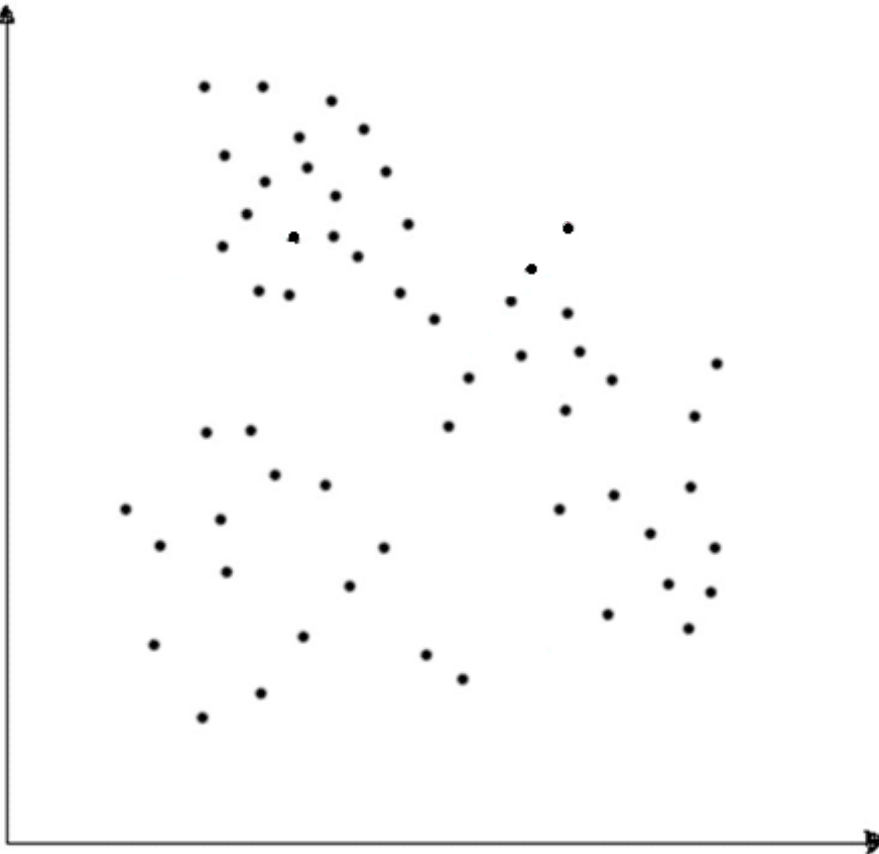
$$\Phi(\text{clusters}, \text{data}) = \sum_{i \in \text{clusters}} \left\{ \sum_{j \in i^{\text{th}} \text{ cluster}} |\mathbf{y}_j - \mathbf{c}_i|^2 \right\}$$

- ▶ **Two activities:**
 - ▶ Assume the cluster centers are known, and allocate each data point to the closest cluster center.
 - ▶ Assume the allocation is known, and compute a new set of cluster centers. Each center is the mean of the points allocated to that cluster.

K-means Algorithm

- ▶ Form K-means clusters from a set of n-dimensional vectors.
 - ▶ Set $N_c = 1$ (iteration number).
 - ▶ Choose randomly a set of K means, $\{\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_k\}$.
 - ▶ For each vector \mathbf{y} , compute $D(\mathbf{y}, \mathbf{c}_k)$ for each $k=1, 2, \dots, K$, and assign \mathbf{y} to the cluster with the nearest distance.
 - ▶ Increment N_c by 1 and update the means based on new class labels to get a new set of centers $\{\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_k\}$.
 - ▶ Repeat until no change to $\{\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_k\}$ or the objective function has insignificant change, or $N_c = N_{max}$
- ▶ This process eventually converges to a local minimum of the objective function.

K-means Clustering Examples



K-means Clustering for Color Quantization

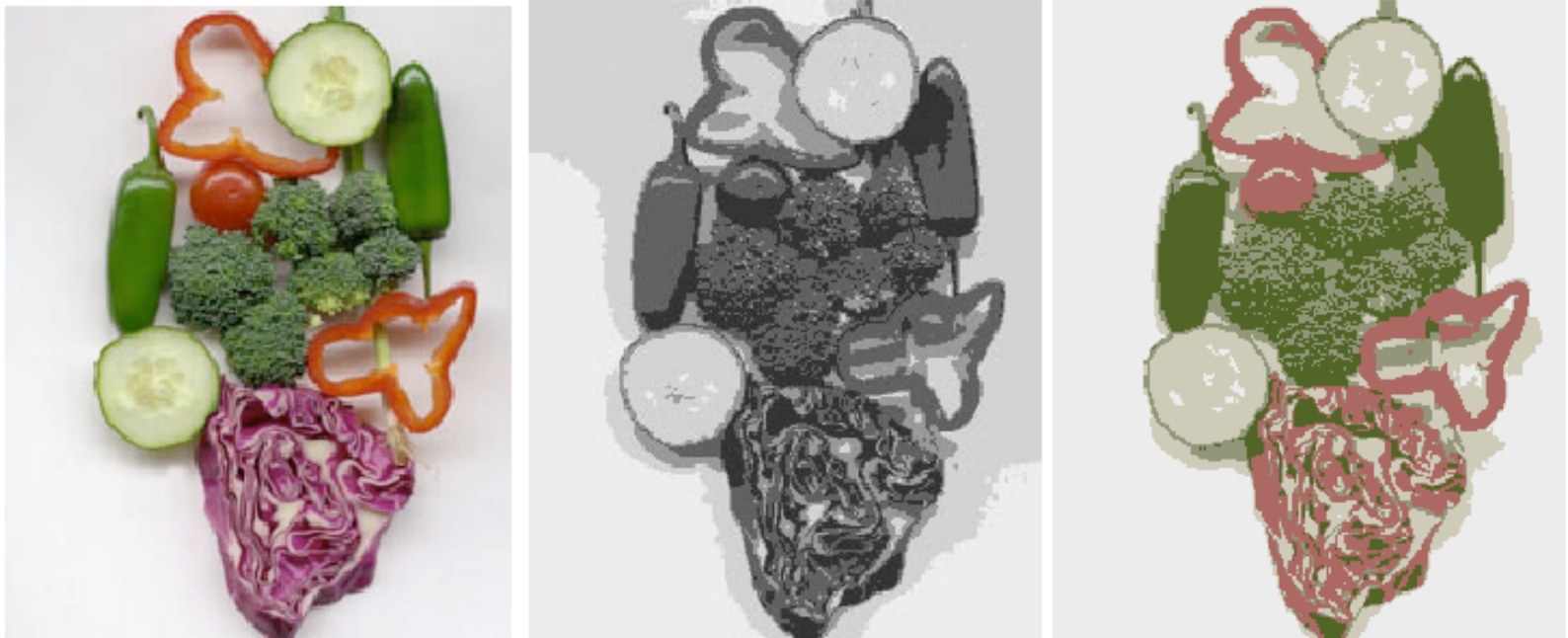
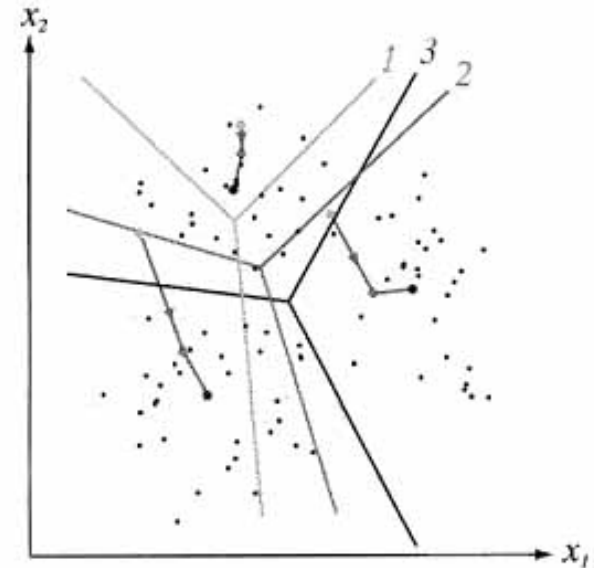


Figure 16.13. On the left, an image of mixed vegetables, which is segmented using k -means to produce the images at center and on the right. We have replaced each pixel with the mean value of its cluster; the result is somewhat like an adaptive requantization, as one would expect. In the center, a segmentation obtained using only the intensity information. At the right, a segmentation obtained using colour information. Each segmentation assumes five clusters.

Why K-means Converge?

- ▶ Whenever an assignment is changed, the sum squared distances of data-points from their assigned cluster centers is reduced.
- ▶ Whenever a cluster center is moved the sum squared distances of the data-points from their currently assigned cluster centers is reduced.
- ▶ If the assignments do not change in the assignment step, we have converged.

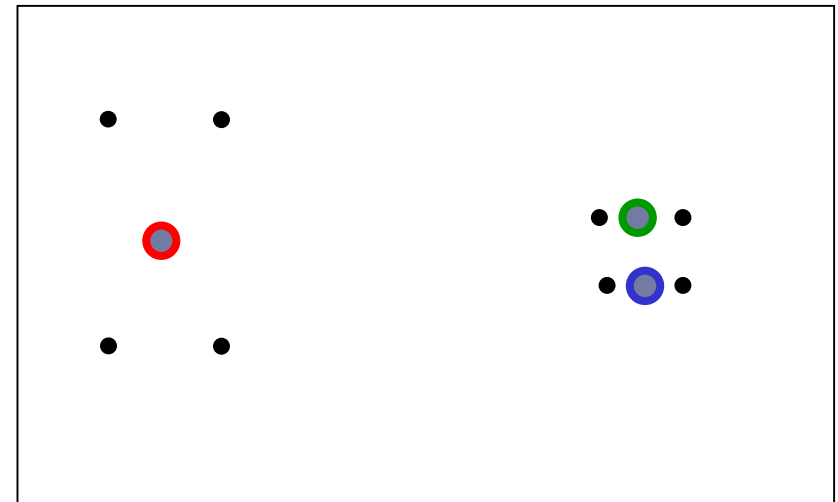


Why K-means can be stuck at a local minima?

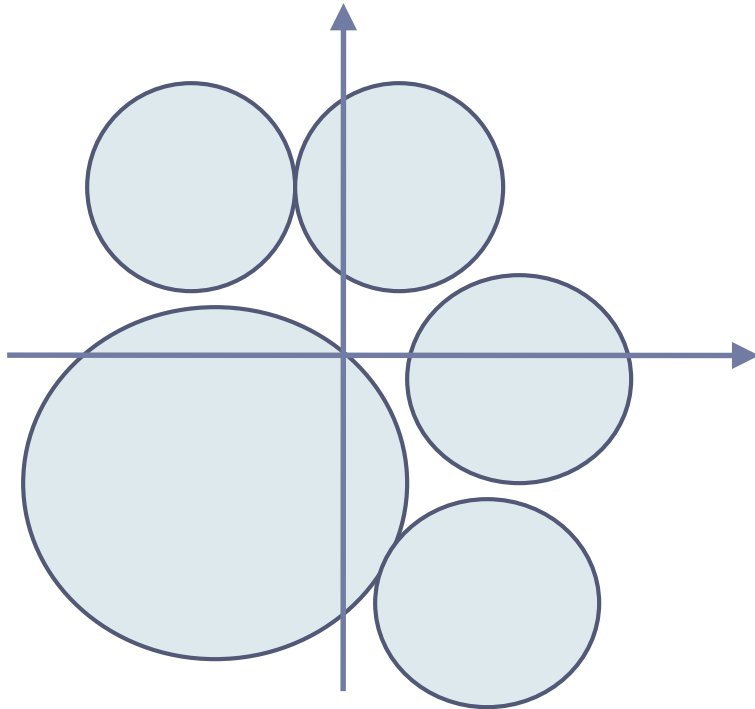


- ▶ There is nothing to prevent k-means getting stuck at local minima.
- ▶ We could try many random starting points
- ▶ We could try non-local split-and-merge moves:
Simultaneously **merge** two nearby clusters and **split** a big cluster into two.

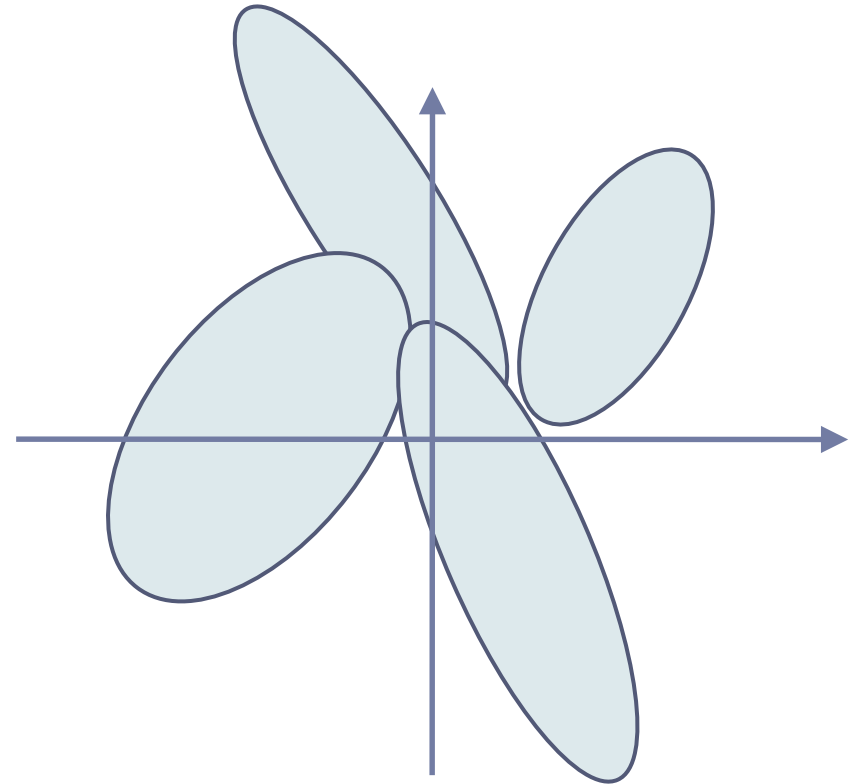
A bad local optimum



Underlying Assumption of K-means



All feature distributions are isotropic



K-mean does not work for the case of non-isotropic feature distributions