

Lecture 2.

Basic Camera Models

ECEN 5283 Computer Vision

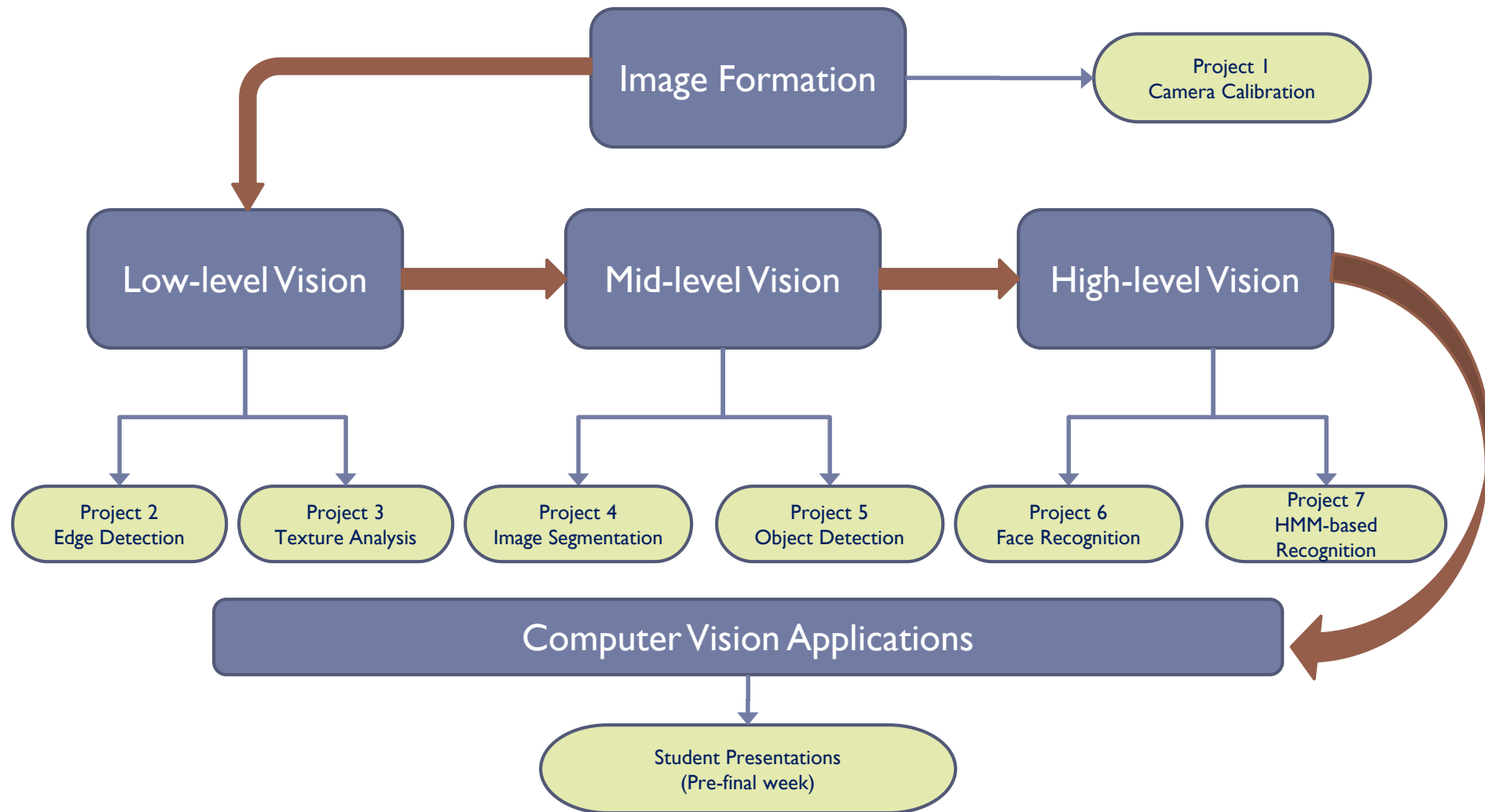
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Goals

- ▶ To review the class structure.
- ▶ To study three basic camera models.
- ▶ To apply three different camera models in different situations.



Class Structure



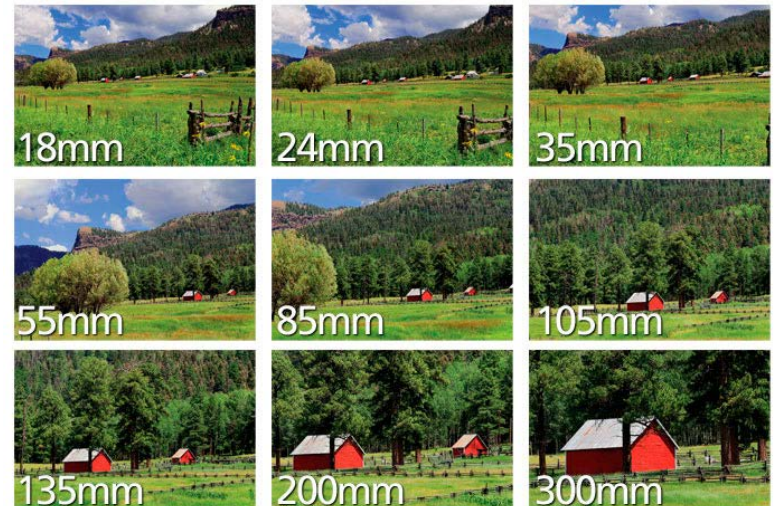
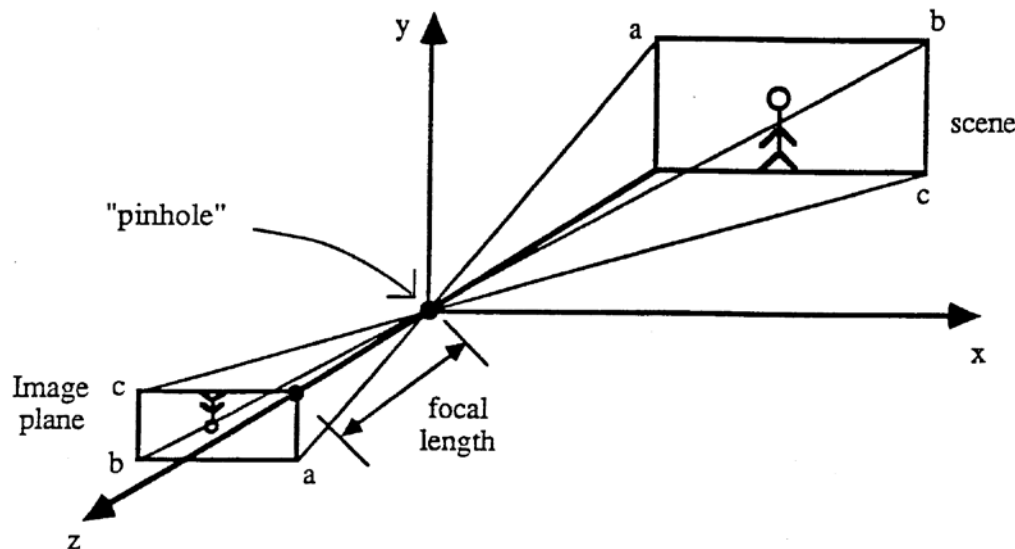
Why do we need a camera model?

- ▶ To build a geometrical mapping relationship between the 3D scene and the 2D image pixels, so that we can infer desired 3D knowledge from 2D image data.

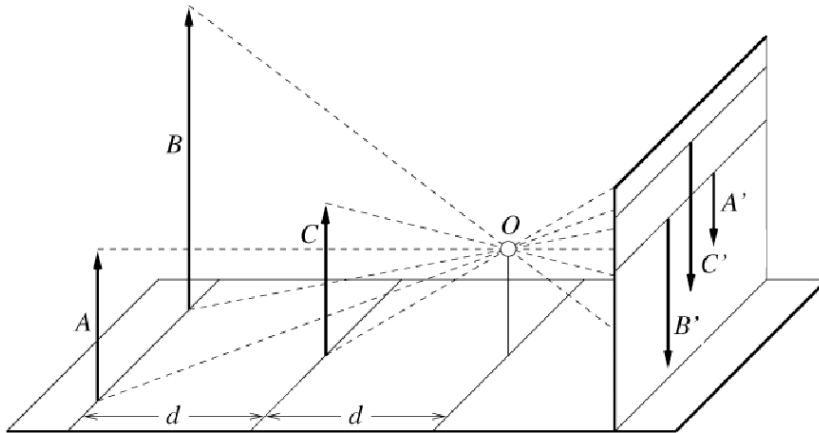


Perspective Projection: Definition

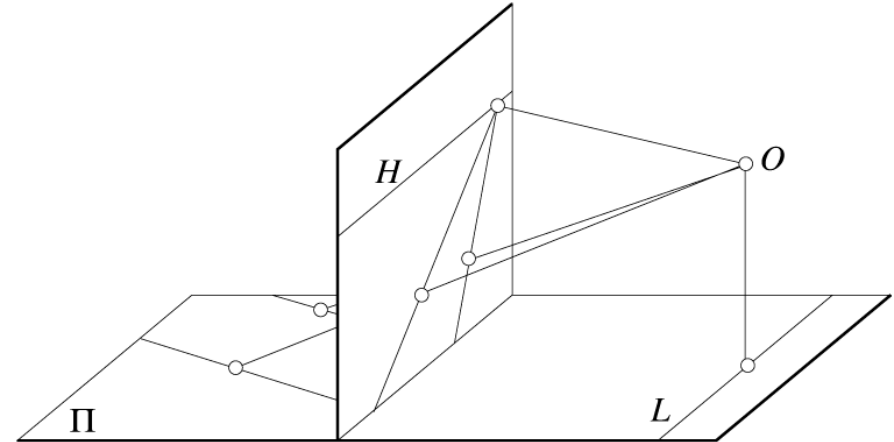
- ▶ Approximate the imaging process as a projection of the object through a single point
 - ▶ Image is reversed and upside-down.



Perspective Projection: Properties



Distant objects are smaller

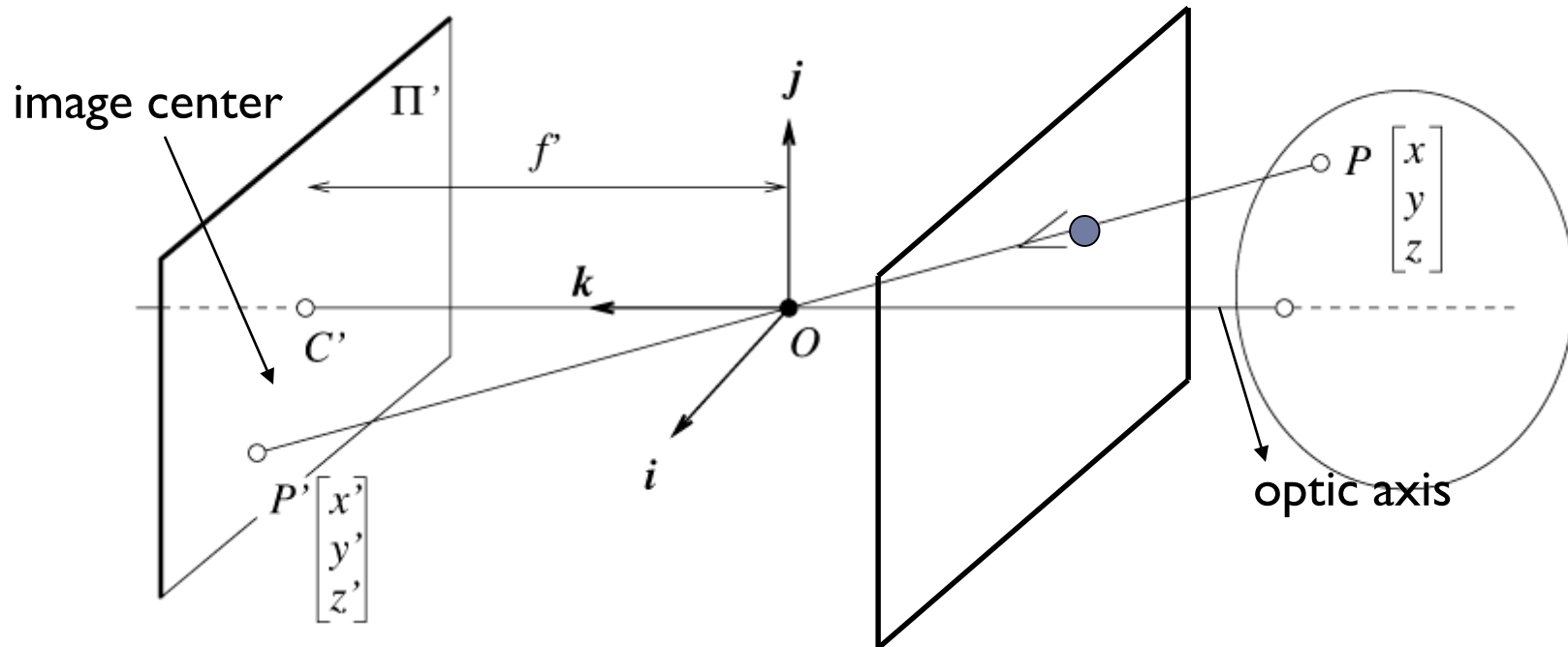


Parallel lines meet





Perspective Projection: Formulation



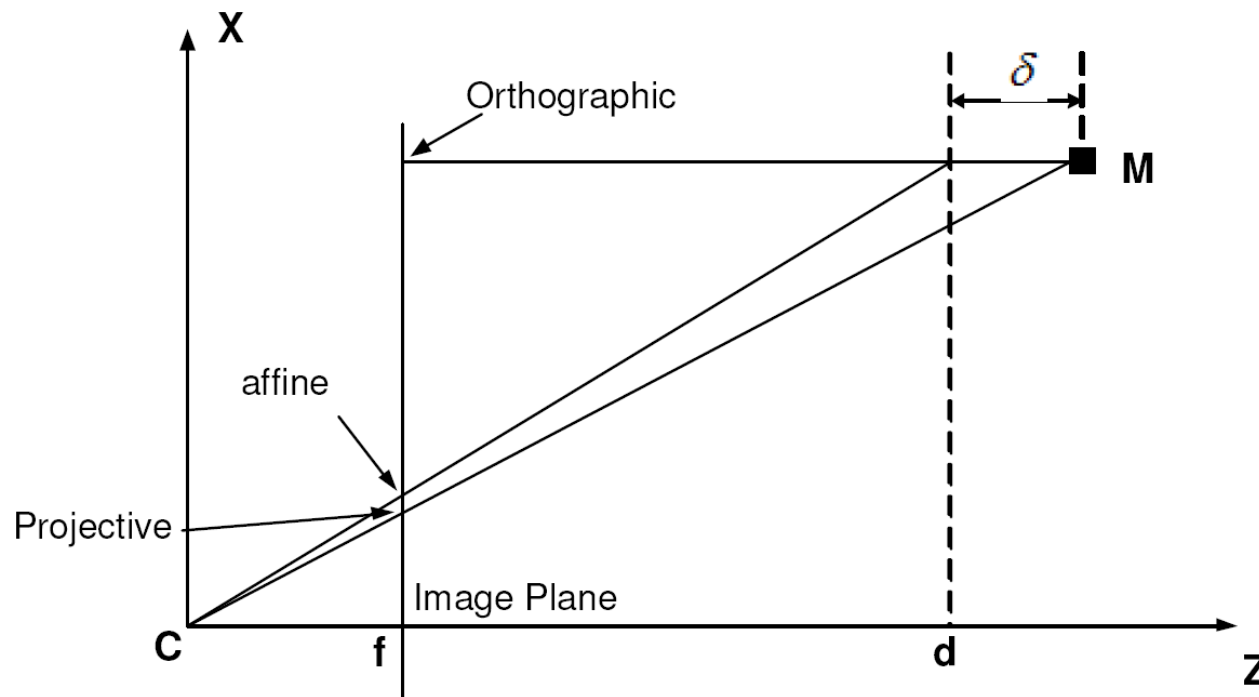
$$\begin{cases} x' = \lambda x \\ y' = \lambda y \\ z' = f' = \lambda z \end{cases} \Leftrightarrow \lambda = \frac{f'}{z} \Rightarrow \begin{cases} x' = f' \frac{x}{z} \\ y' = f' \frac{y}{z} \end{cases}$$

What is the sign of λ of this case shown above?

Is this a linear model?

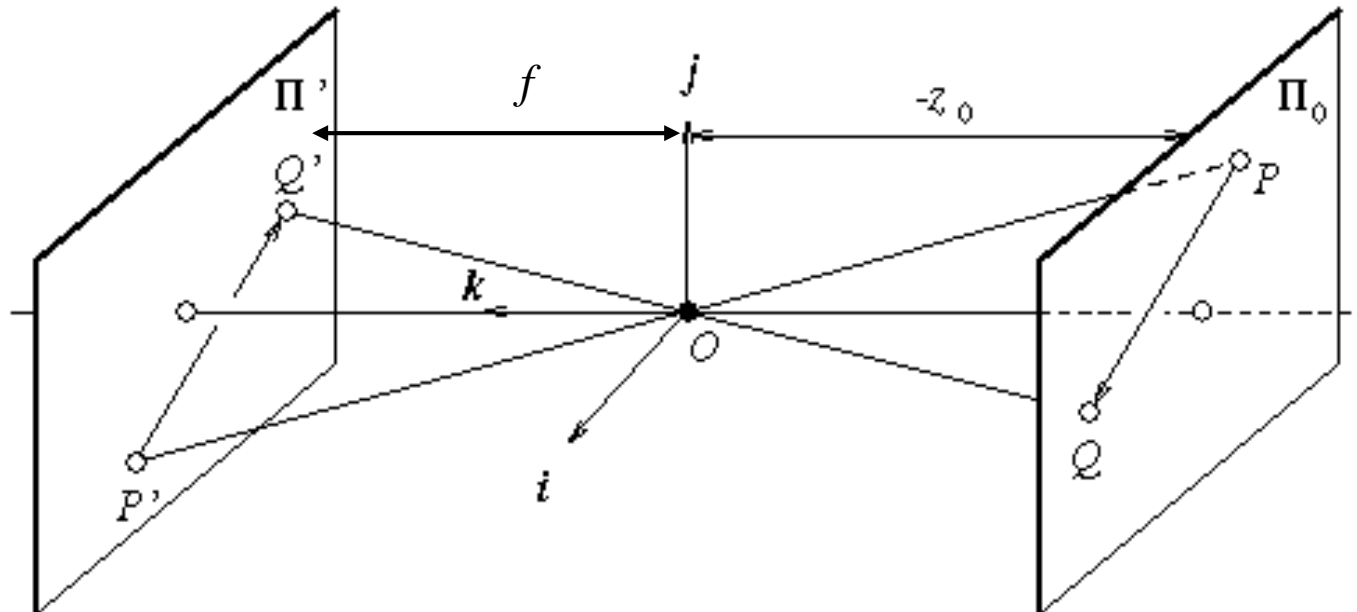
Affine Projection: When?

- **Affine projection:** when *the scene depth is small relative to the average distance from the camera*, the magnification can be taken to be constant.





Affine Projection



Consider two points P and Q and their images P' and Q' . Obviously, the vector PQ and $P'Q'$ are parallel, and we have

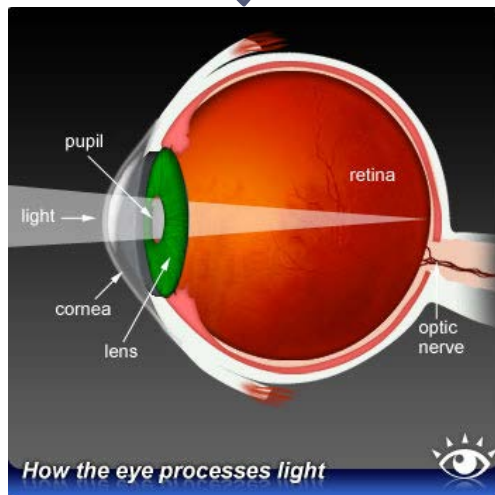
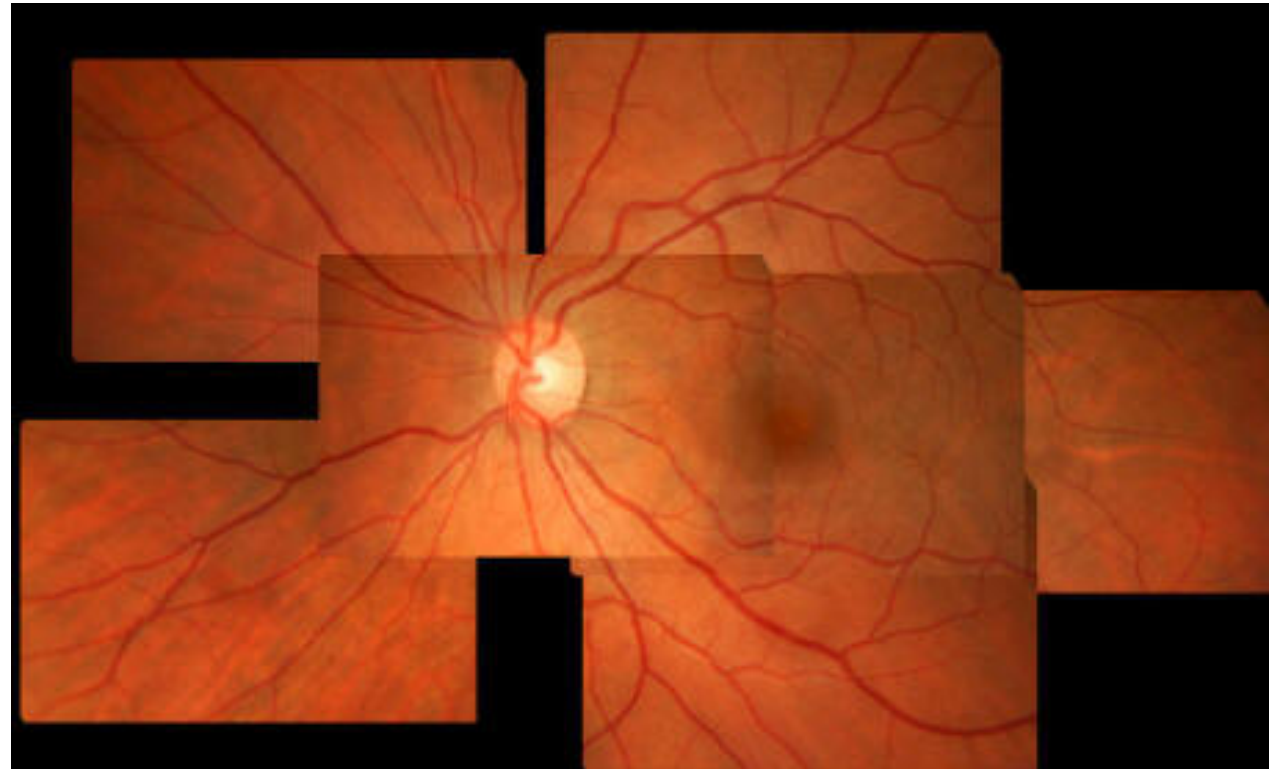
$$|P'Q'| = m|PQ| \quad (\text{Magnification is constant.})$$

$$\text{where } m = \left| \frac{f}{z_0} \right| \quad \begin{cases} x' = -mx \\ y' = -my \end{cases}$$

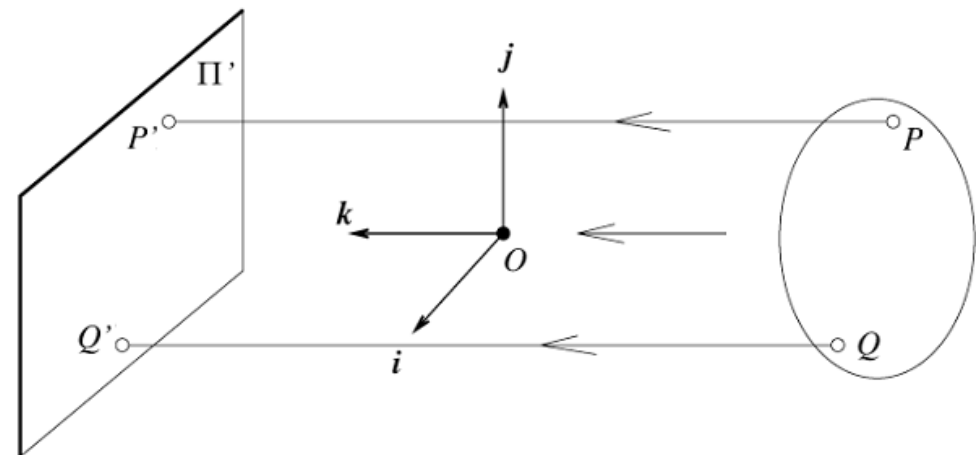
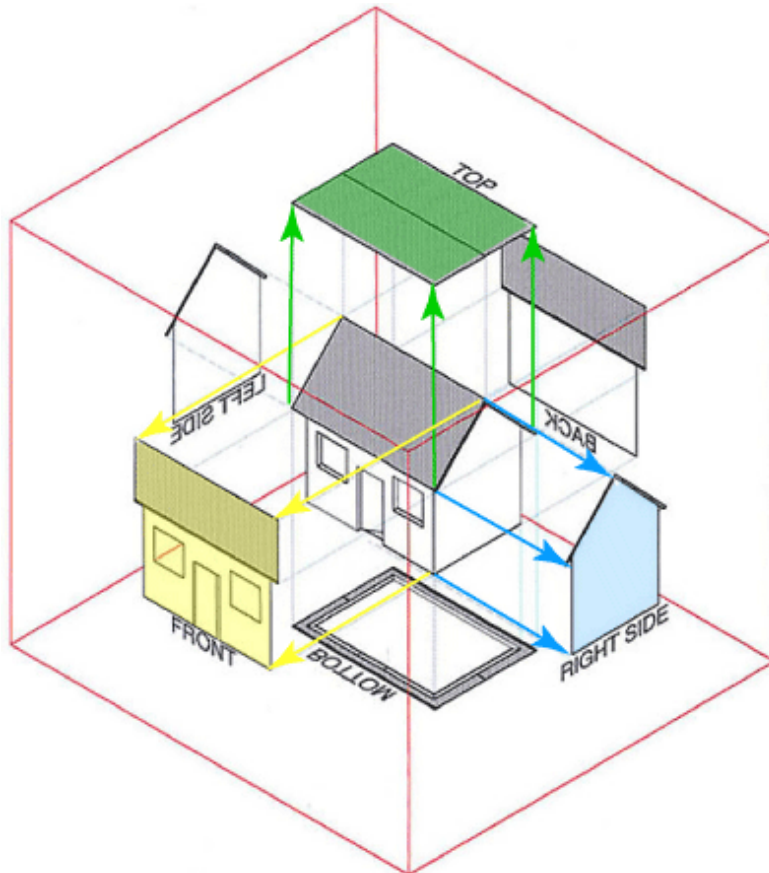
Advantages:

- It is a linear model.
- Easy for optimization.

Affine Projection



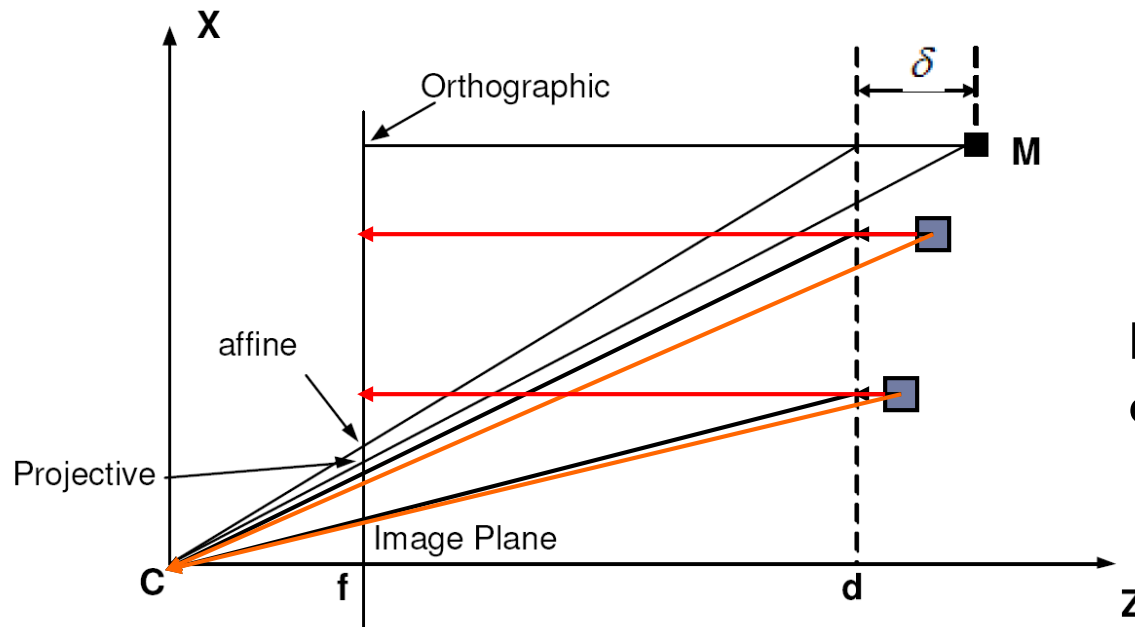
Orthographic Projection: What?



All light rays parallel to the k axis and orthogonal to the image plane Π' . Therefore, the metric is well preserved in the image.

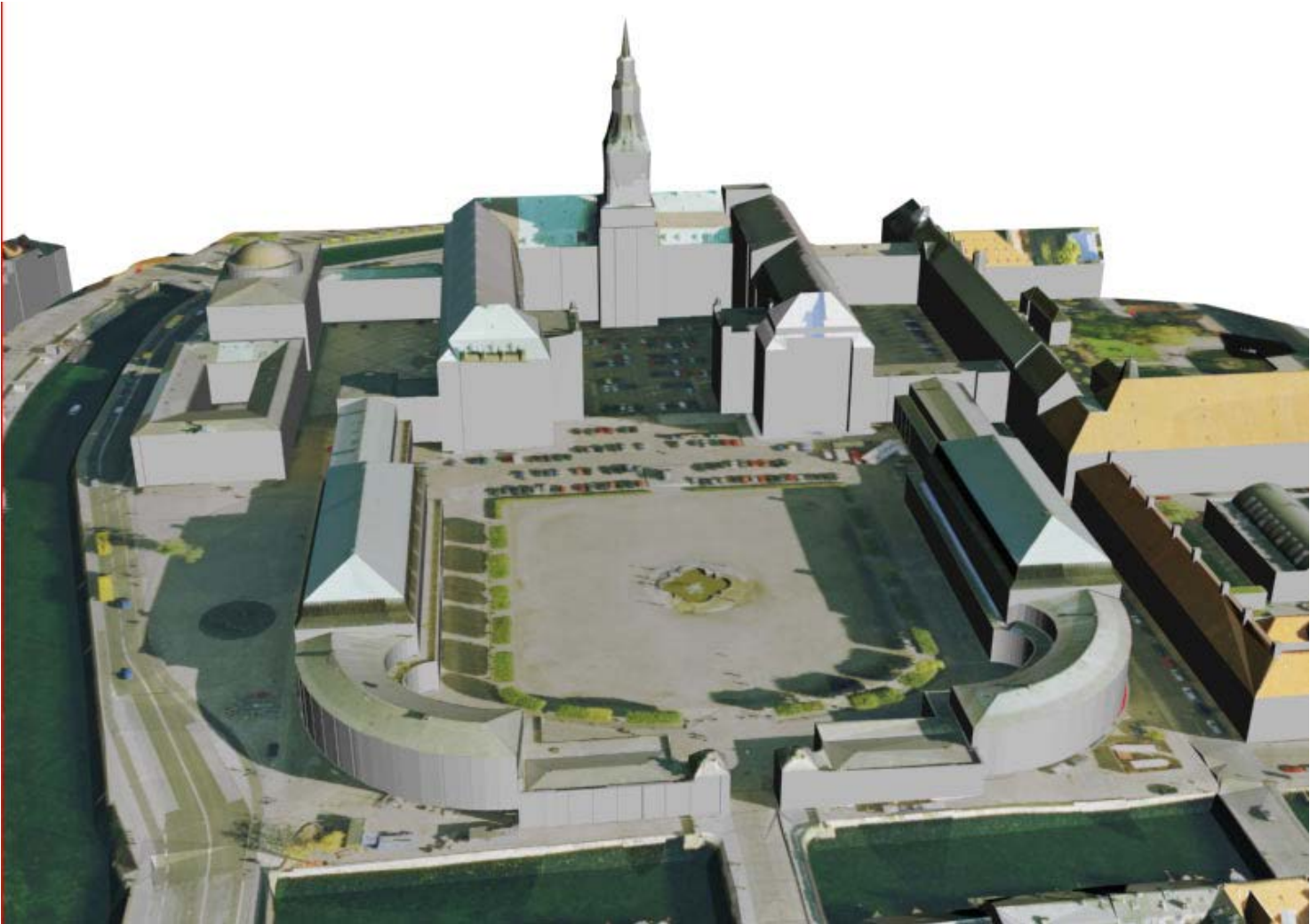
Orthographic Projection: When?

- **Orthographic projection:** When it is a prior known that the camera always remains at a roughly constant distance from the scene, we can go further and normalize the image coordinates.

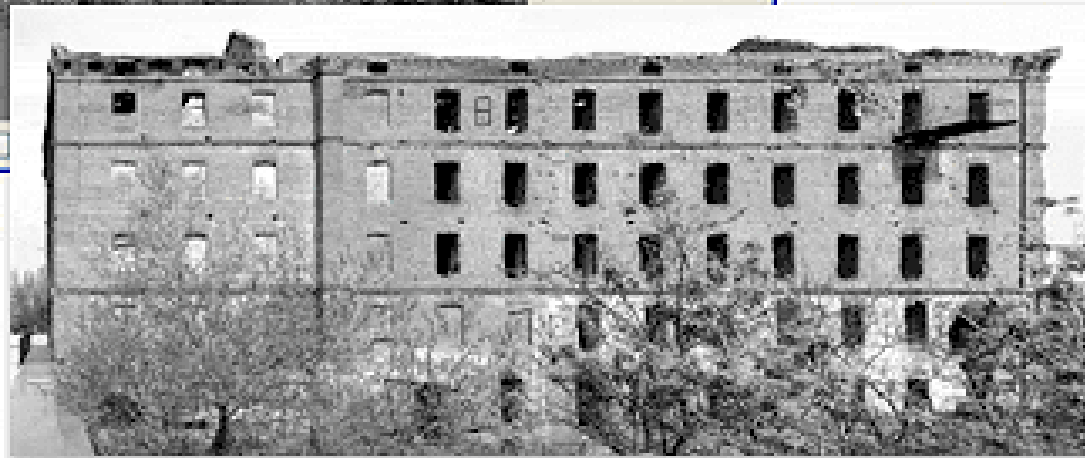
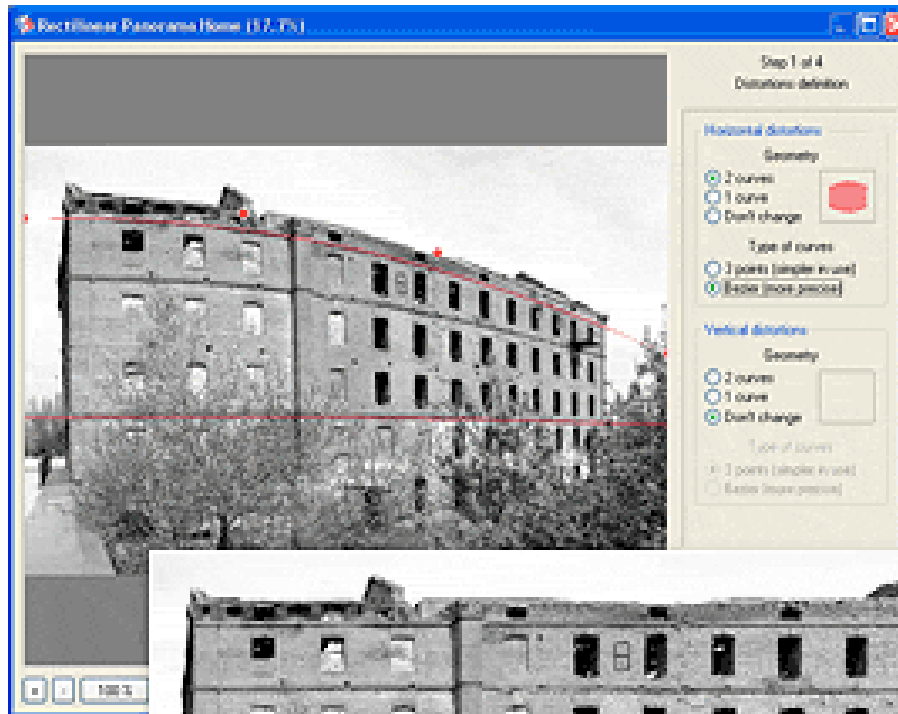


How about the effective focal length?

Orthographic Projection: Why



Orthocorrection





Summary

- ▶ Perspective projection is a **standard camera model** for image formation.
- ▶ Affine projection is a **simplified camera model** that has good linearity and low complexity when there is no much depth variation in the scene.
- ▶ Orthographic projection is **an idealized camera model** with the infinite focal length. It is useful when the metric information must be preserved in the image, and it can be done via orthorectification.