

Lecture 31

High-Level Vision: Overview

ECEN 5283 Computer Vision

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Goals

- ▶ To introduce some basic issues about high-level vision.
- ▶ To present the major topics in this chapter.



Pathways in Human Vision System

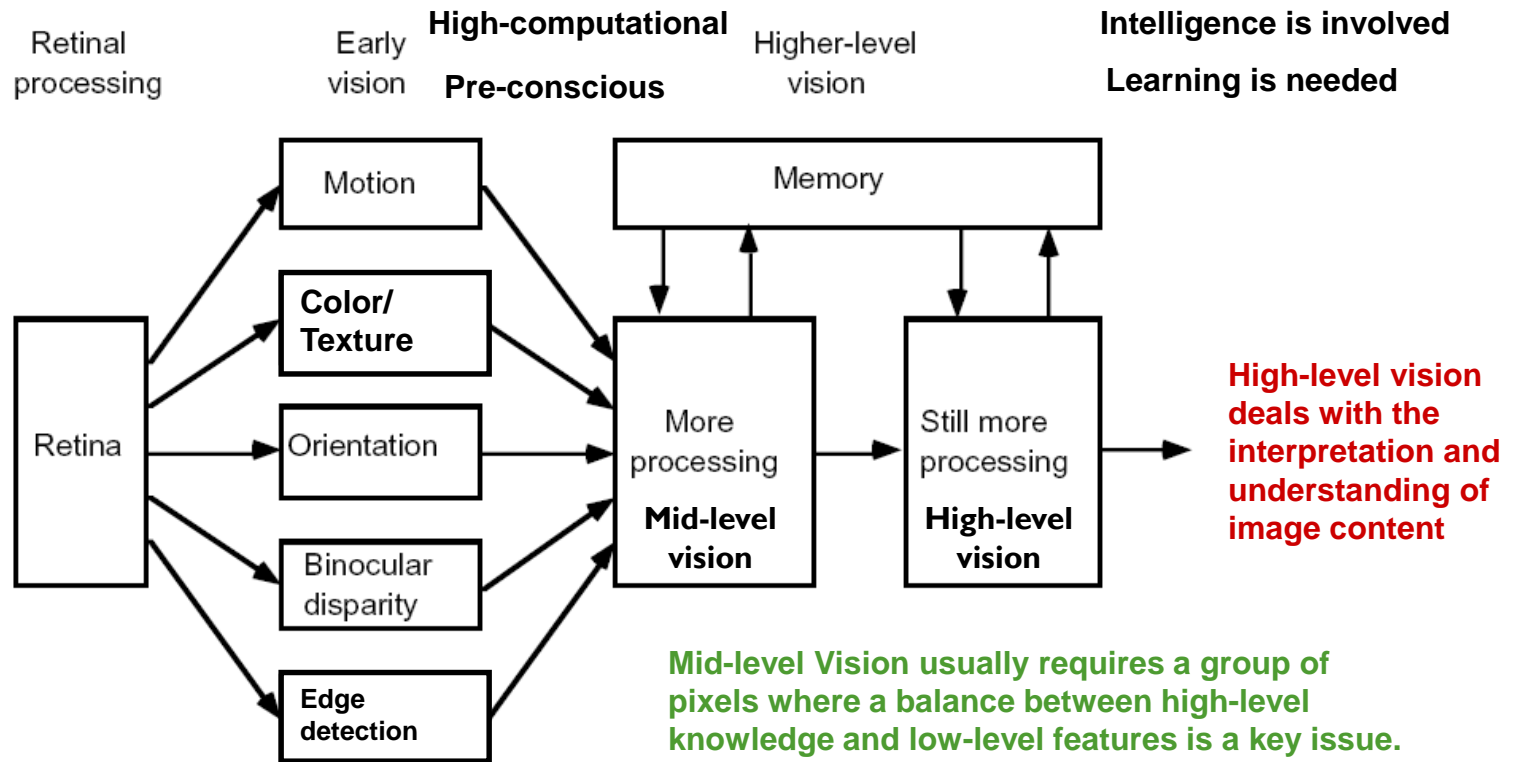


Fig.1.1

A generic diagram for visual processing. In this approach, early vision consists of a set of parallel pathways, each analyzing some particular aspect of the visual stimulus.

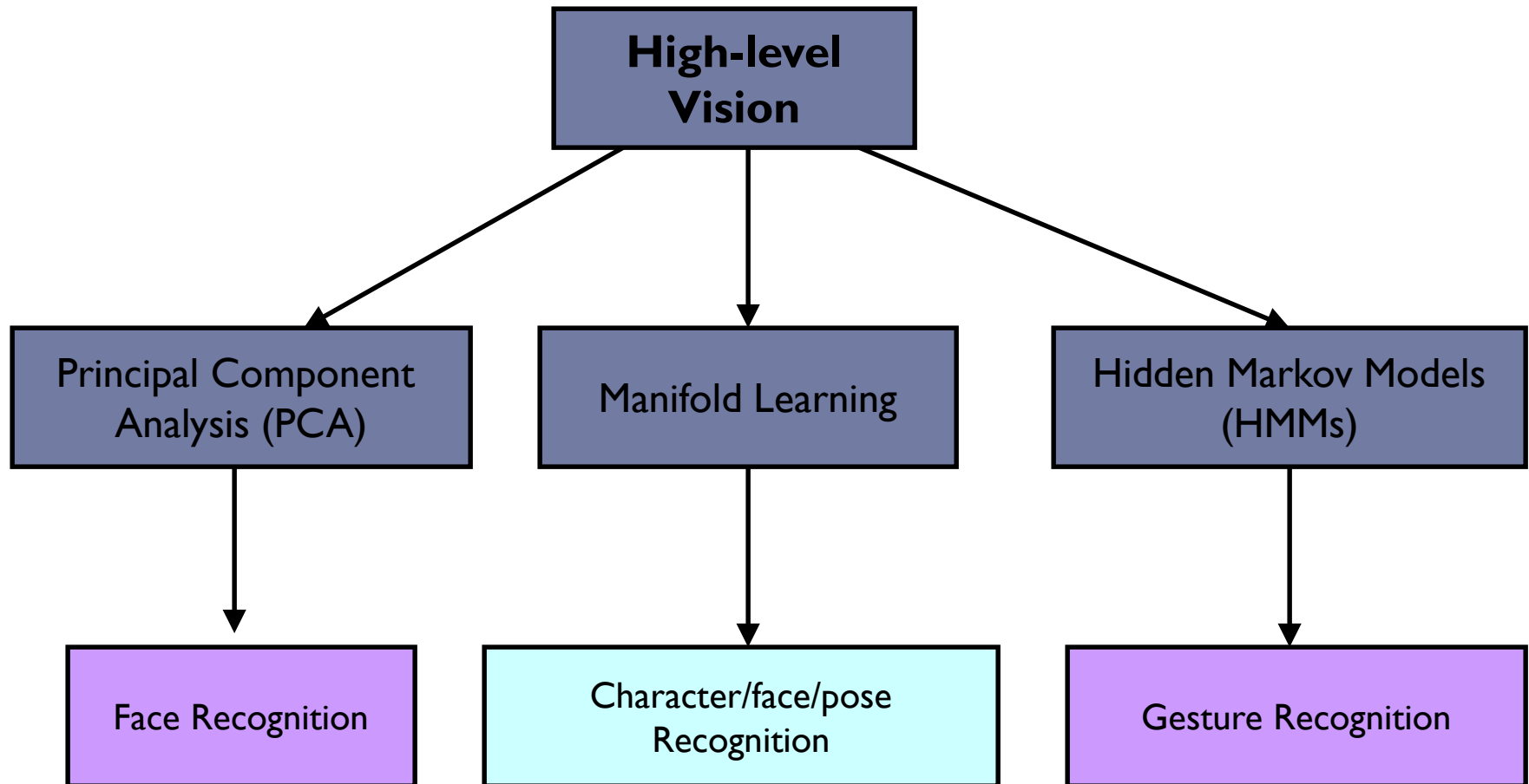
The Plenoptic Function and the Elements of Early Vision web.mit.edu/persci/people/adelson/pub_pdfs/elements91.pdf

What is high-level vision?

- ▶ High-level vision is the final stage of visual perception that deals with the interpretation and use of what is seen in the image or from a scene.

| | Low-level vision | Mid-level vision | High-level vision |
|--------------------------------------|--|---|--|
| Purpose | To extract a set of visual primitives for further processing at the pixel-level. | To bridge low-level vision and high-level vision with some inference of the structure by involving multiple pixels. | To interpret or understand the content of an image, such as object recognition. |
| Computational model | Pixel-level linear filtering (convolution) | Region-level statistical Inference (clustering and state estimation) | Inference based on region-based features or visual cues from the whole image |
| High-level knowledge involved | It is a pre-conscious process. | It is a process that requires some intelligence. | It is a process that requires more intelligence and prior knowledge. |
| Bottom-up and Top-down flow | It is mainly a data-driven bottom-up process. | Both data-driven bottom-up and knowledge-driven top-down are involved. | The knowledge-driven top-down plays a more important role than the data-driven bottom-up flow. |

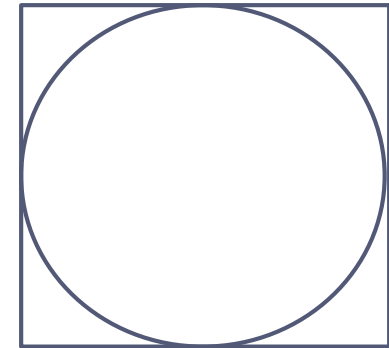
Overview of High-level Vision



Curse of High Dimensionality

- ▶ In recent years, the effect of the **curse of high dimensionality** has been studied in great detail on several problems such as clustering, nearest neighbor search, and indexing.

- ▶ Data become sparse;
- ▶ The data mass is in the corner of hypercube;
- ▶ Distance or similarity is no longer meaningful;
- ▶ The concept of proximity is no longer valid;



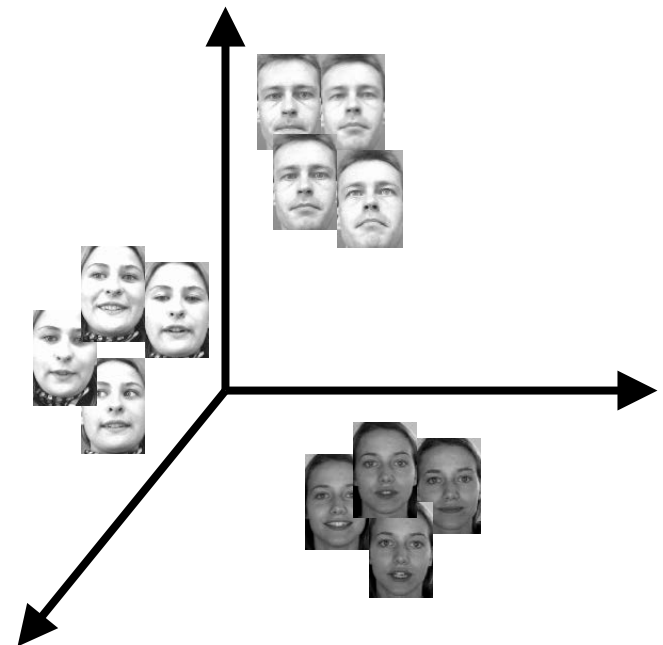
$$\lim_{d \rightarrow \infty} \frac{\pi^{d/2}}{d 2^{d-1} \Gamma(d/2)} = 0 \quad \leftarrow \quad \lim_{d \rightarrow \infty} \frac{\text{volume of hypersphere}}{\text{volume of hypercube}}$$

- ▶ Distance-based clustering and classification become a problem in a high-dimensional space, and dimensionality reduction (DR) is needed which supports low-dimensional analysis.

Dimensionality Reduction (DR): Why?



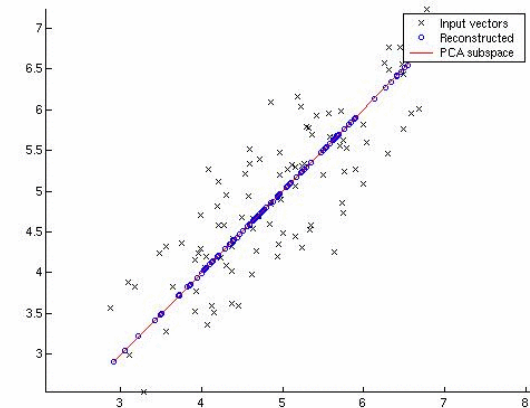
- ▶ DR is the process of reducing the number of random variables under consideration, so that the intrinsic data structure are preserved for efficient and effective data analysis.



DR: How?

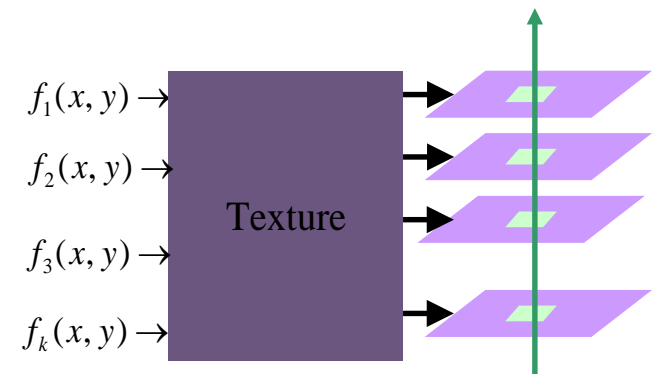
- ▶ The DR techniques can be divided into **feature selection** and **feature extraction**
 - ▶ Feature selection is the DR technique, commonly used in machine learning, of selecting a subset of relevant features for building robust learning models.

Reconstruction is usually possible.



- ▶ Feature extraction transforms the input data that could be notoriously redundant into the set of compact features.

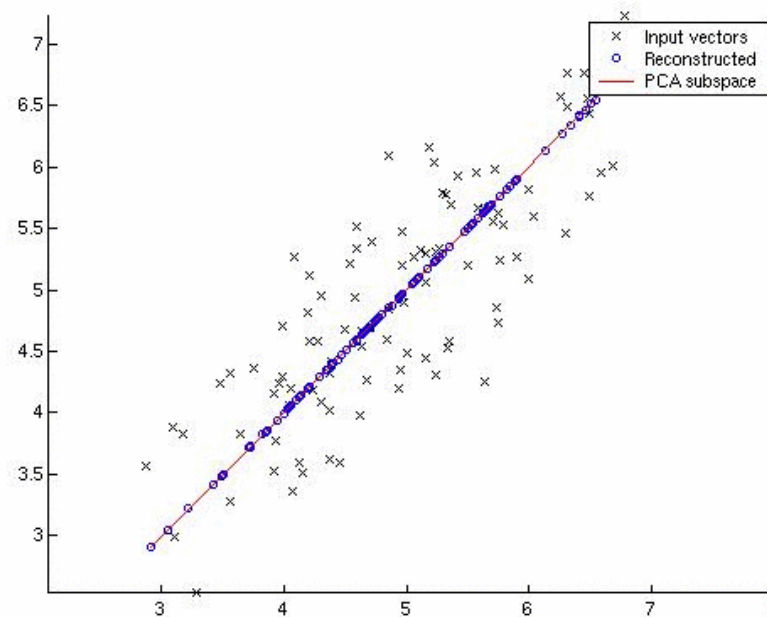
Reconstruction is usually NOT possible.



Principal Component Analysis (PCA)



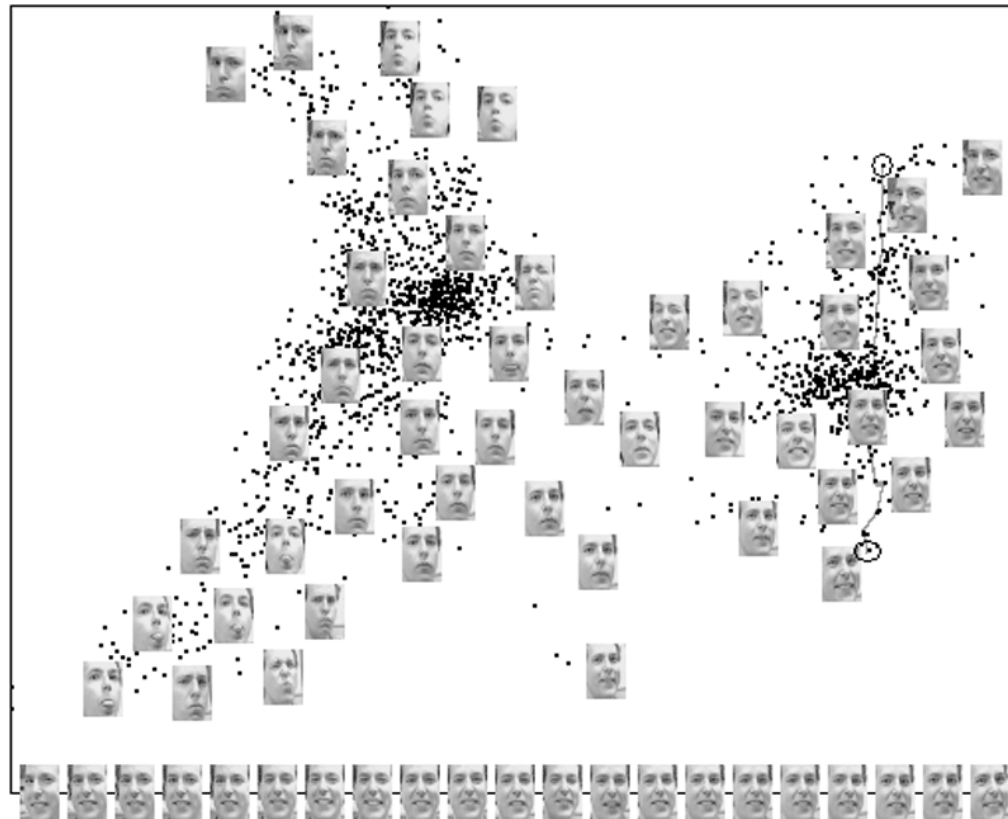
- ▶ **PCA** *provides compact data representation*
 - ▶ We can construct a lower dimensional **linear subspace** that “**best explains**” the variation of these data points from their mean.
 - ▶ All data will be represented in this low-dimension feature space.



Non-linear Dimensional Reduction (Manifold Learning)


















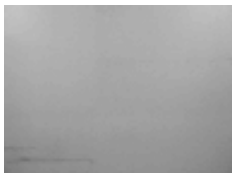




- ▶ Manifold learning is the process of exploring a low-dimensional **non-linear embedding** underlying a set of high-dimensional data.



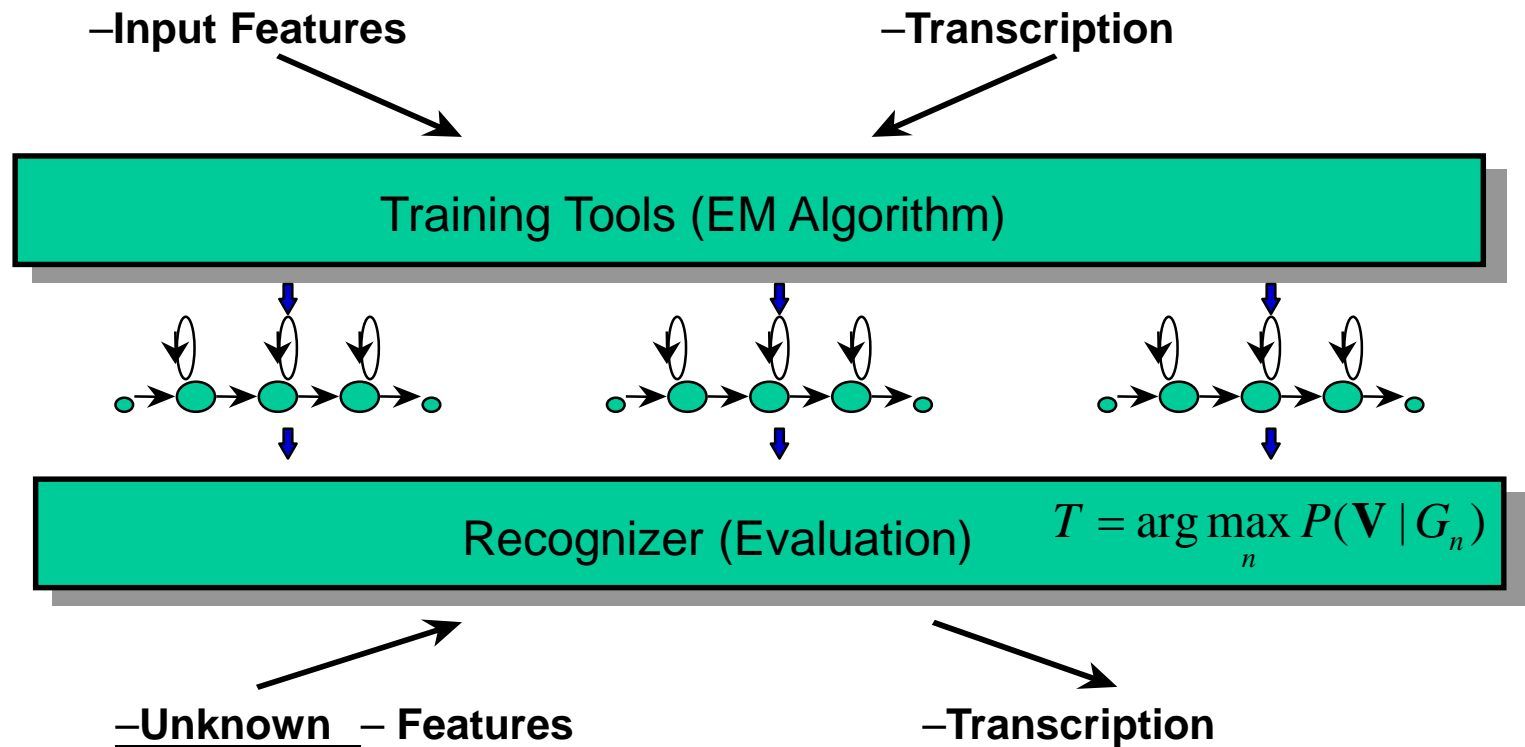
<http://sciencewatch.com/ana/st/face/09mayFacRecHe/>

Why do we need HMMs?

| | | | | |
|---|---|--|---|---|
|  |  |  |  |  |
| Hand-Waving-Both | Hand-Waving-Right | Hand-Waving-Left | Top-Right | To-Left |
|  |  |  |  |  |
| To-Top | To-Bottom | Round-Clockwise | Round-Counterclockwise | Stop |
|  |  |  |  |  |
| Come | Nod-Yes | Nod-No | Clapping | Kotow |
|  |  |  |  |  |
| Spin | Go-Left | Go-Right | Turn-Right | Turn-Left |

http://www.fb9-ti.uni-duisburg.de/projekte/video/video_e.html

HMM Training and Recognition



- Andreas Kosmala and Gerhard Rigoll. On-Line Handwritten Formula Recognition Using Statistical Methods. In *Int. Conference on Pattern Recognition (ICPR)*, pages 1306-1308, Brisbane, August 1998.
- Gerhard Rigoll, Andreas Kosmala, and Stefan Eickeler. High Performance Real-Time Gesture Recognition Using Hidden Markov Models. In *Gesture Workshop*, pages 69-80, Bielefeld, Germany, September 1997.