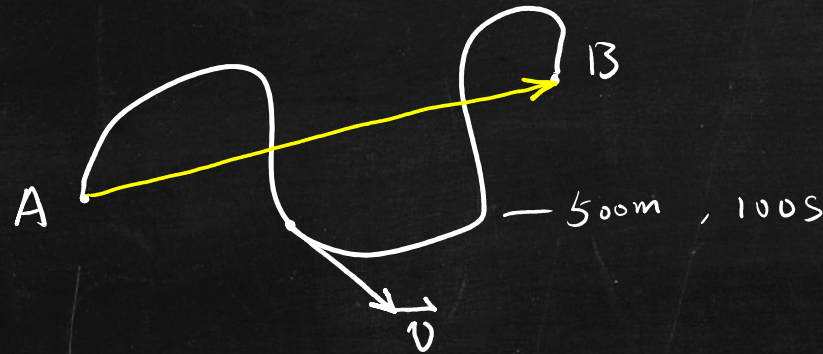
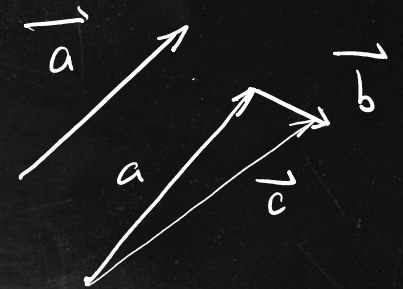


Mechanics

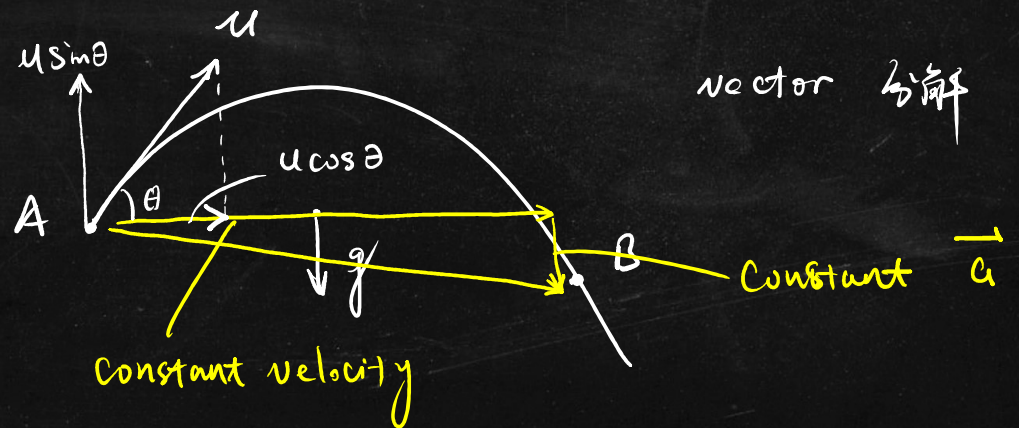
Motion 运动 → displacement 位移
velocity 速度
acceleration 加速度

distance 路程
 speed 速率

$$\vec{a} = \frac{\Delta \vec{v}}{\Delta t}$$



constant acceleration 匀加速运动
 projectile 抛物体



$$a = \frac{\Delta v}{\Delta t}$$

$$0 \sim t \quad \Delta t = t - 0 = t$$

$$\Delta v = v - u$$

→ x

↑ positive direction

$$\star \quad \underline{a = \frac{v - u}{t}}$$

$$\underline{v = u + at}$$

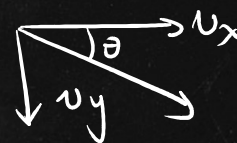
$$v_y = u_y + at = u \sin \theta + (-g)t$$

$$v_y = u \sin \theta - gt$$

$$v_x = u_x = u \cos \theta$$

$$\underline{v = \sqrt{v_x^2 + v_y^2} = \sqrt{(u \cos \theta)^2 + (u \sin \theta - gt)^2}}$$

$$\tan \theta = \frac{v_y}{v_x} = \frac{u \sin \theta - gt}{u \cos \theta}$$



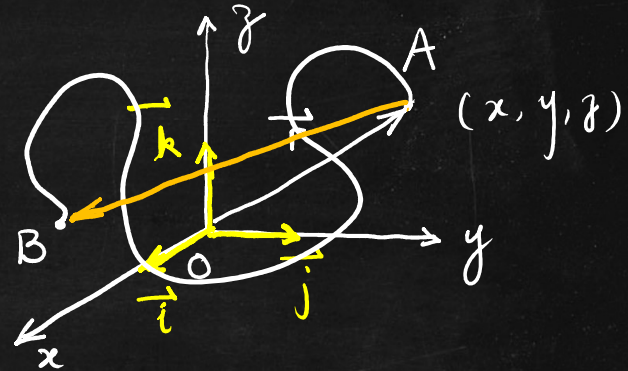
Mechanics

Vector 向量 矢量

Coordinates 坐标系

position vector $\vec{r} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \underbrace{x\vec{i} + y\vec{j} + z\vec{k}}$

displacement 位移 $\vec{s} = \vec{r}_B - \vec{r}_A$



$$= (x_B\vec{i} + y_B\vec{j} + z_B\vec{k}) - (x_A\vec{i} + y_A\vec{j} + z_A\vec{k})$$

$$\vec{s} = (x_B - x_A)\vec{i} + (y_B - y_A)\vec{j} + (z_B - z_A)\vec{k}$$

velocity 速度

$$y = x^2 \quad \frac{dy}{dx} = 2x \quad y = c \quad \frac{dy}{dx} = 0$$

$$\vec{v} = \frac{d\vec{s}}{dt} = \frac{d(\vec{r} - \vec{r}_0)}{dt} = \frac{d\vec{r} - d\vec{r}_0}{dt} = \frac{d\vec{r}}{dt} - \cancel{\frac{d\vec{r}_0}{dt}}$$

$$\vec{v} = \frac{d\vec{r}}{dt} = \frac{dr_x}{dt}\vec{i} + \frac{dr_y}{dt}\vec{j} + \frac{dr_z}{dt}\vec{k}$$

$$\vec{v} = v_x\vec{i} + v_y\vec{j} + v_z\vec{k}$$

constant velocity

Assume an object start from origin

After time t , object is at P

$$\vec{r}_P = (x_P, y_P, z_P) = x_P \vec{i} + y_P \vec{j} + z_P \vec{k}$$

$$\vec{s} = \vec{v} \cdot t$$

$$\vec{s} = \vec{r}_P - \vec{r}_0 = \vec{r}_P = \underline{x_P \vec{i}} + \underline{y_P \vec{j}} + \underline{z_P \vec{k}}$$

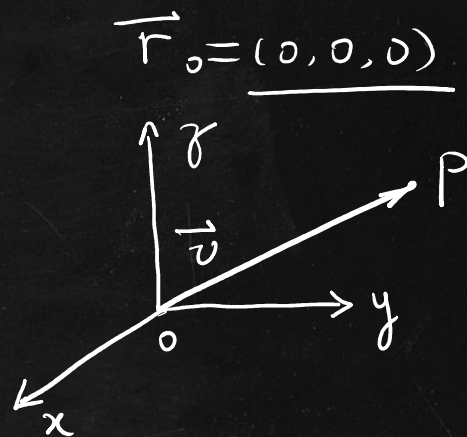
$$\vec{v} t = (v_x \vec{i} + v_y \vec{j} + v_z \vec{k}) t$$

$$= \underline{v_x t \vec{i}} + \underline{v_y t \vec{j}} + \underline{v_z t \vec{k}} = \vec{s}$$

$$\begin{cases} \underline{x_P = v_x t} \\ y_P = v_y t \\ z_P = v_z t \end{cases}$$

$$\swarrow \quad \searrow \quad \swarrow$$
$$x = v_x t$$

$$\underline{\underline{\vec{s} = \vec{v} t}}$$



Acceleration: $\underline{\vec{a}} = \frac{d\vec{v}}{dt} = a_x \vec{i} + a_y \vec{j} + a_z \vec{k}$

constant acceleration: $\frac{d\vec{v}}{dt} = \underline{\vec{a}} \quad \underline{d\vec{v} = \vec{a} dt}$

$\int d\vec{v} = \int \vec{a} dt = \vec{a} \int dt$ initial velocity

$\underline{\vec{v} = \vec{a}t + \vec{c}}$ $\underline{t=0 \quad \vec{v} = \vec{v}_0 \quad \vec{u}}$

$\vec{v}_0 = \vec{a} \cdot 0 + \vec{c} \quad \vec{c} = \vec{v}_0$ boundary condition

$\vec{v} = \vec{v}_0 + \vec{a}t$

$\vec{r} = \vec{r}_0 + \vec{v}_0 t + \frac{1}{2} \vec{a} t^2$

$$\begin{cases} v_x = v_{0x} + a_x t \\ v_y = v_{0y} + a_y t \\ v_z = v_{0z} + a_z t \end{cases}$$

$$\begin{cases} x = x_0 + v_{0x} t + \frac{1}{2} a_x t^2 \\ y = y_0 + v_{0y} t + \frac{1}{2} a_y t^2 \\ z = z_0 + v_{0z} t + \frac{1}{2} a_z t^2 \end{cases}$$

$|\vec{v}| = \sqrt{v_x^2 + v_y^2 + v_z^2}$

$|\vec{r}| = \sqrt{x^2 + y^2 + z^2}$

integration

$y = x^2 \Leftarrow \frac{dy}{dx} = 2x$

$\frac{dy}{dx} = 2x \quad y = ?$

$y = x^2 + c$

$\underline{dy = 2x dx}$

$\int \underline{1} dy = \int \underline{2x} dx$

$y + c_1 = x^2 + c_2$

$\underline{y = x^2 + c}$

Free Falling object.

1° $\vec{v}_0 = 0$

2° Near the surface of the earth $\vec{a} = -g\vec{h}$

3° Air resistance, friction X $\vec{G} = mg(-\vec{h})$

$\vec{a} = -g\vec{h}$ $\vec{v} = \vec{v}_0 + \vec{a}t = \vec{a}t = -mg\vec{h}$

$\vec{v} = -g\vec{h} \cdot t = -gt\vec{k}$

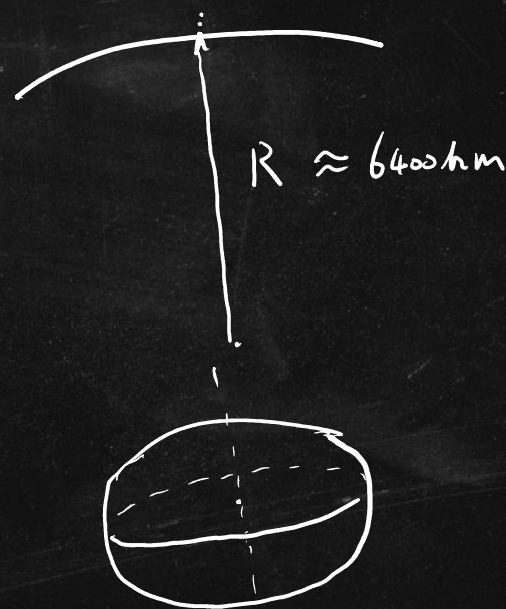
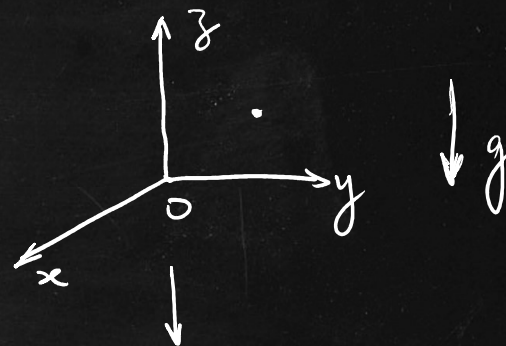
$\vec{v} = v_x\vec{i} + v_y\vec{j} + v_z\vec{k}$
 $= -gt\vec{h} + 0\vec{i} + 0\vec{j}$

$\begin{cases} v_x = 0 \\ v_y = 0 \\ v_z = -gt \end{cases}$

$\vec{r} = \vec{r}_0 + \cancel{\vec{v}_0 t} + \frac{1}{2}\vec{a}t^2$

$= r_{0x}\vec{i} + r_{0y}\vec{j} + r_{0z}\vec{h} + \frac{1}{2} \cdot (-g\vec{k})t^2$

$= r_{0x}\vec{i} + r_{0y}\vec{j} + (r_{0z} - \frac{1}{2}gt^2)\vec{k}$



ex. $\vec{v}_0 = 2\vec{i} + 3\vec{j} + \vec{k}$ (m/s)

$g = -9.8\vec{k}$ (m/s²)

$\vec{r}_0 = 2\vec{i} + 2\vec{j} + 2\vec{k}$ (m)

$t = 3$ (s) $\vec{r} = ?$ $\vec{v} = ?$

$\vec{r} = \vec{r}_0 + \vec{v}_0 t + \frac{1}{2} g t^2 \rightarrow \frac{1}{2} \vec{a} t^2$ $\vec{a} = -9.8\vec{k}$

$\frac{1}{2} (-9.8) \cdot \vec{k} \cdot t^2 = -4.9 t^2 \vec{k}$

$\vec{r} = 2\vec{i} + 2\vec{j} + 2\vec{k} + (2\vec{i} + 3\vec{j} + \vec{k}) \cdot 3 - 4.9 \times 3^2 \cdot \vec{k}$
 $= \underline{8\vec{i} + 11\vec{j} + (-39.1)\vec{k}}$

$\frac{4.9}{44.1}$

