

Neuroprothetik Exercise 3

Mathematical Basics 2

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1 Implementations in Matlab or Python

Implement the following methods as functions in Python or Matlab:

- Forward (Explicit) Euler
- Heun Method
- Exponential Euler

2 Solve Functions

Solve the differential equation $\frac{dV}{dt} = 1 - V - t$ where $V(t = -4.5) = V_0 = -4$ with the solvers implemented above. Vary the stepsize (1s, 0.5s, 0.1s, 0.012) and plot the results and answer the following questions.

- Interpret the impact of changing the stepsize.
- Why not just use a very small stepsize.

3 The Leaky Integrate and Fire Neuron

Implement a model of the leaky integrate and fire neuron with the following parameters

$$V_{n+1} = \begin{cases} V_n + \frac{\Delta t}{C_m}(-g_{leak}(V_n - V_{rest}) + I_{input}(t_n)) & V_n < V_{thr} \\ V_{spike} & V_n = V_{thr} \\ V_{rest} & V_n = V_{spike} \end{cases}$$

- $g_{leak} = 100 \mu\text{S}$
- $V_{rest} = -60 \text{ mV}$

- $V_{thr} = -20 \text{ mV}$
- $V_{spike} = 20 \text{ mV}$

And simulate the cell for 50 ms ($\Delta t = 25 \mu\text{s}$ should be sufficient) with the following current inputs:

- constant $10 \mu\text{A}$
- constant $20 \mu\text{A}$
- rectified 50Hz sinus with $10 \mu\text{A}$ amplitude
- rectified 50Hz sinus with $30 \mu\text{A}$ amplitude

Plot the results and interpret what you see.

4 Solution

Here you can see how the resulting plots should look like. This is just to give you an idea if your results are valid.

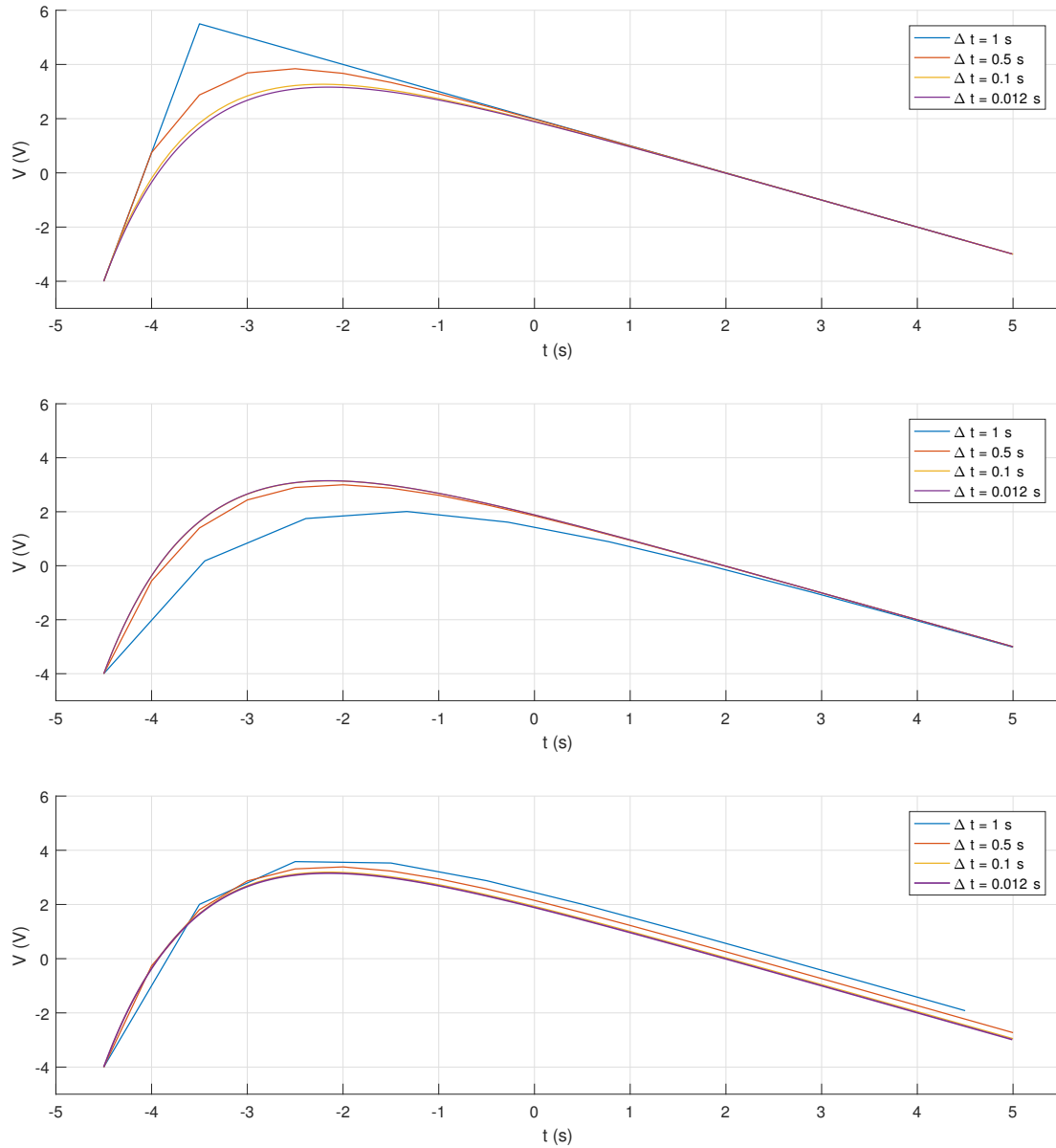
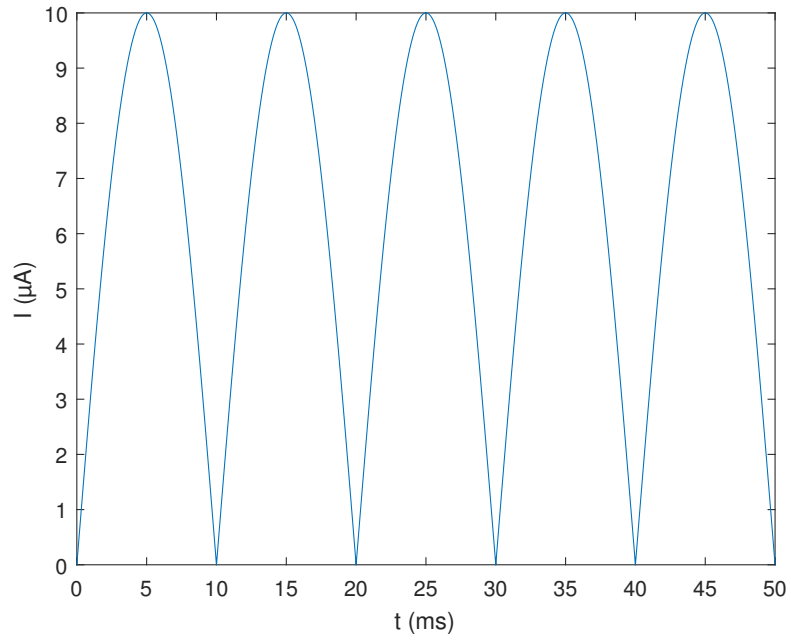
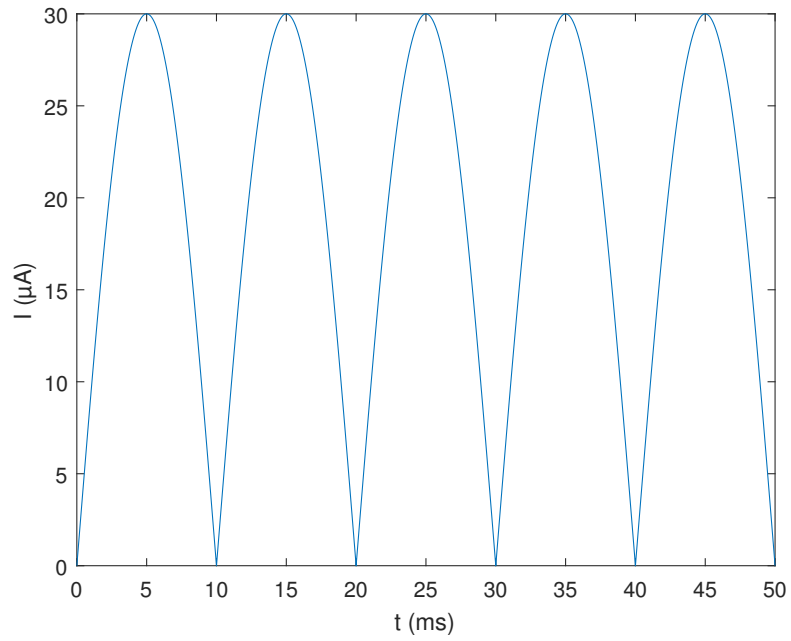


Figure 1: Approximations of the given differential equation in 2 with different methods and different stepsizes. Top: Forward-Euler-Method. Middle: Heun-Method. Bottom: Exponential-Euler Method. The different colors resemble the given timesteps visible in the legend.



(a) Rectified Sine-Input with an amplitude of 10 μA for the model visible in figure 3c



(b) Rectified Sine-Input with an amplitude of 30 μA for the model visible in figure 3d

Figure 2: Current Inputs for LIF-Models visible in figures 3c and 3d

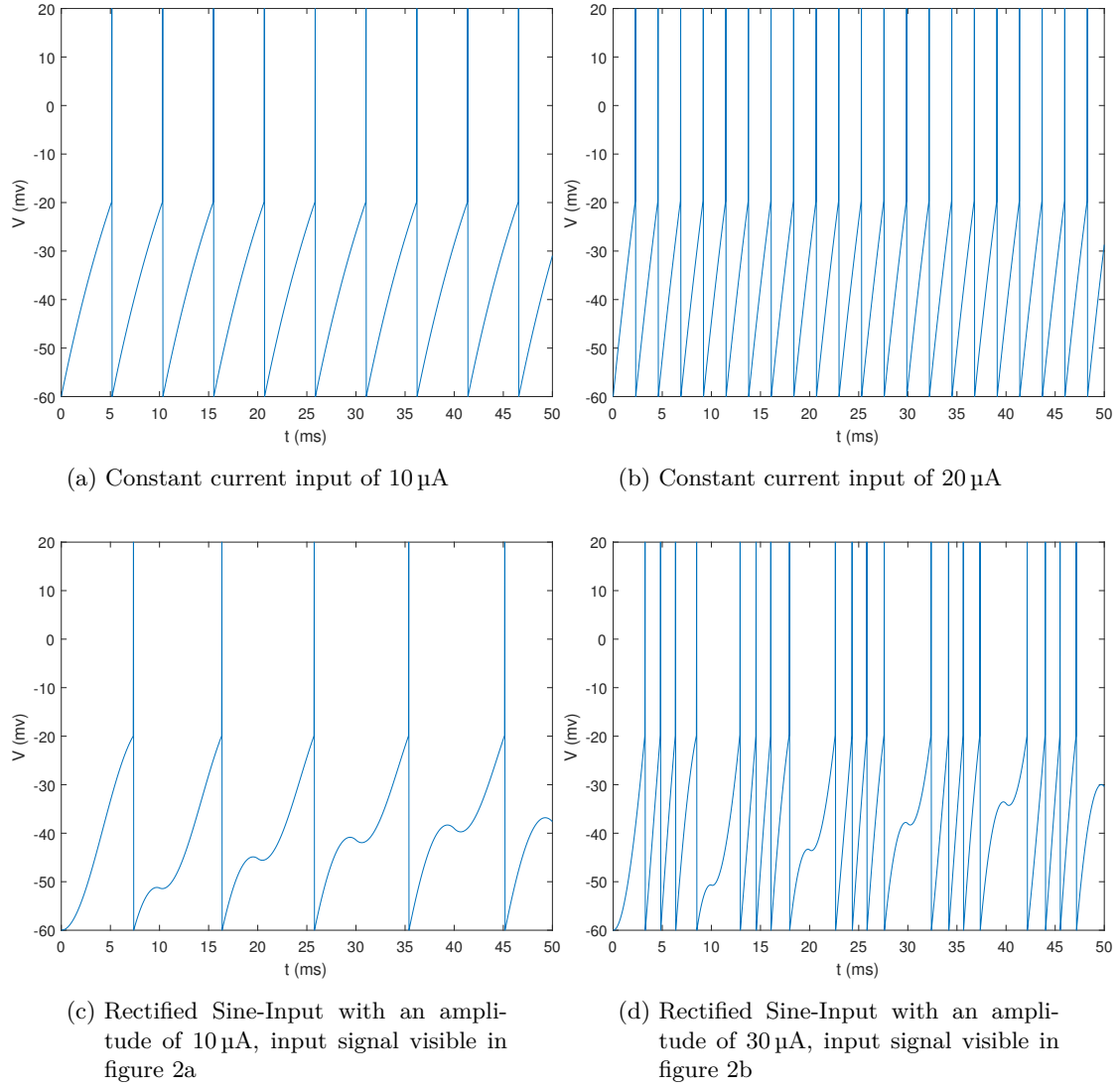


Figure 3: Results for the LIF-Model for different current inputs.