


SensorDB::SensorDB



```
graph LR; A[SensorDB::SensorDB] --> B[SensorDB::addSensor]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'SensorDB::SensorDB'. The right box is white and contains the text 'SensorDB::addSensor'. A dark blue arrow points from the right side of the gray box to the left side of the white box.

SensorDB::addSensor