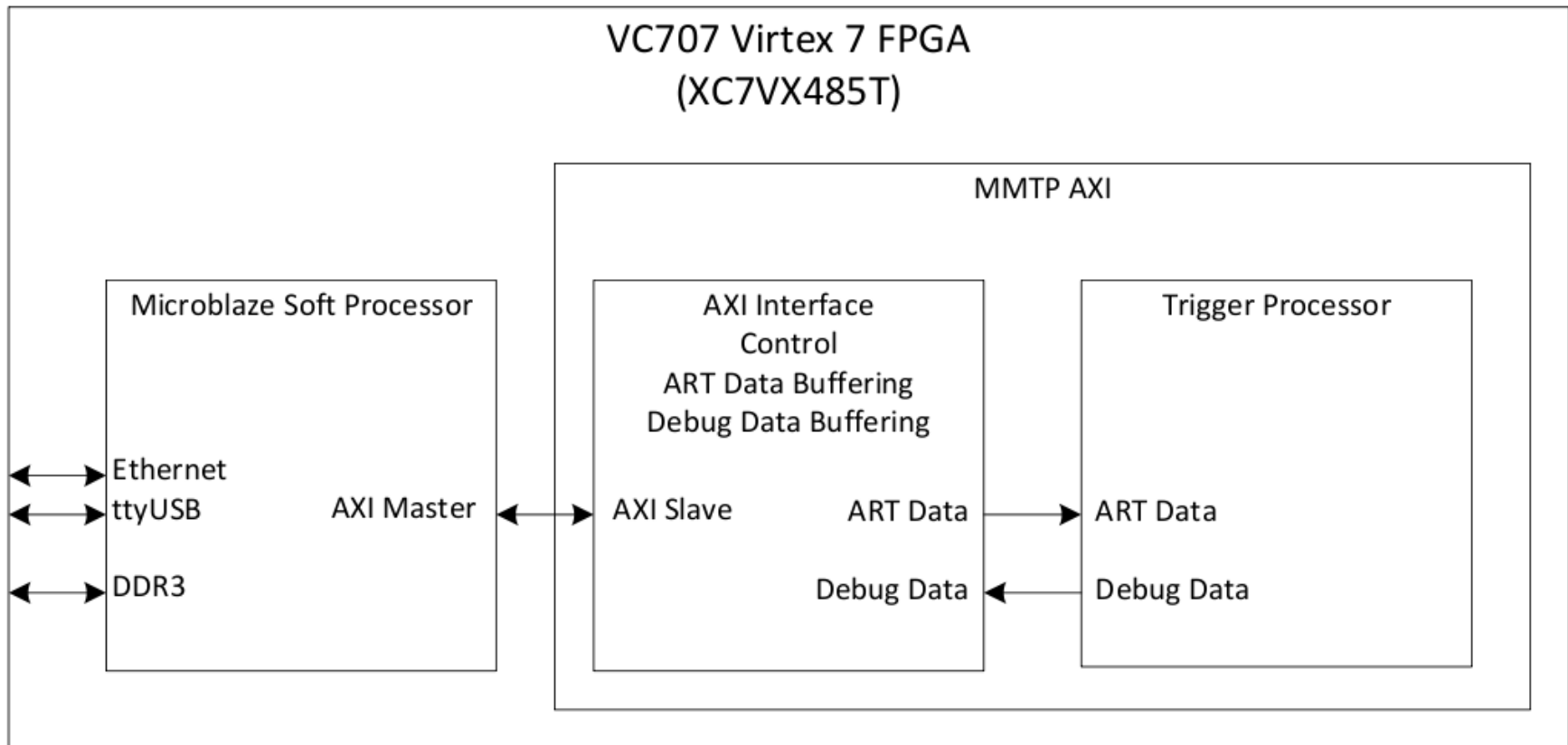


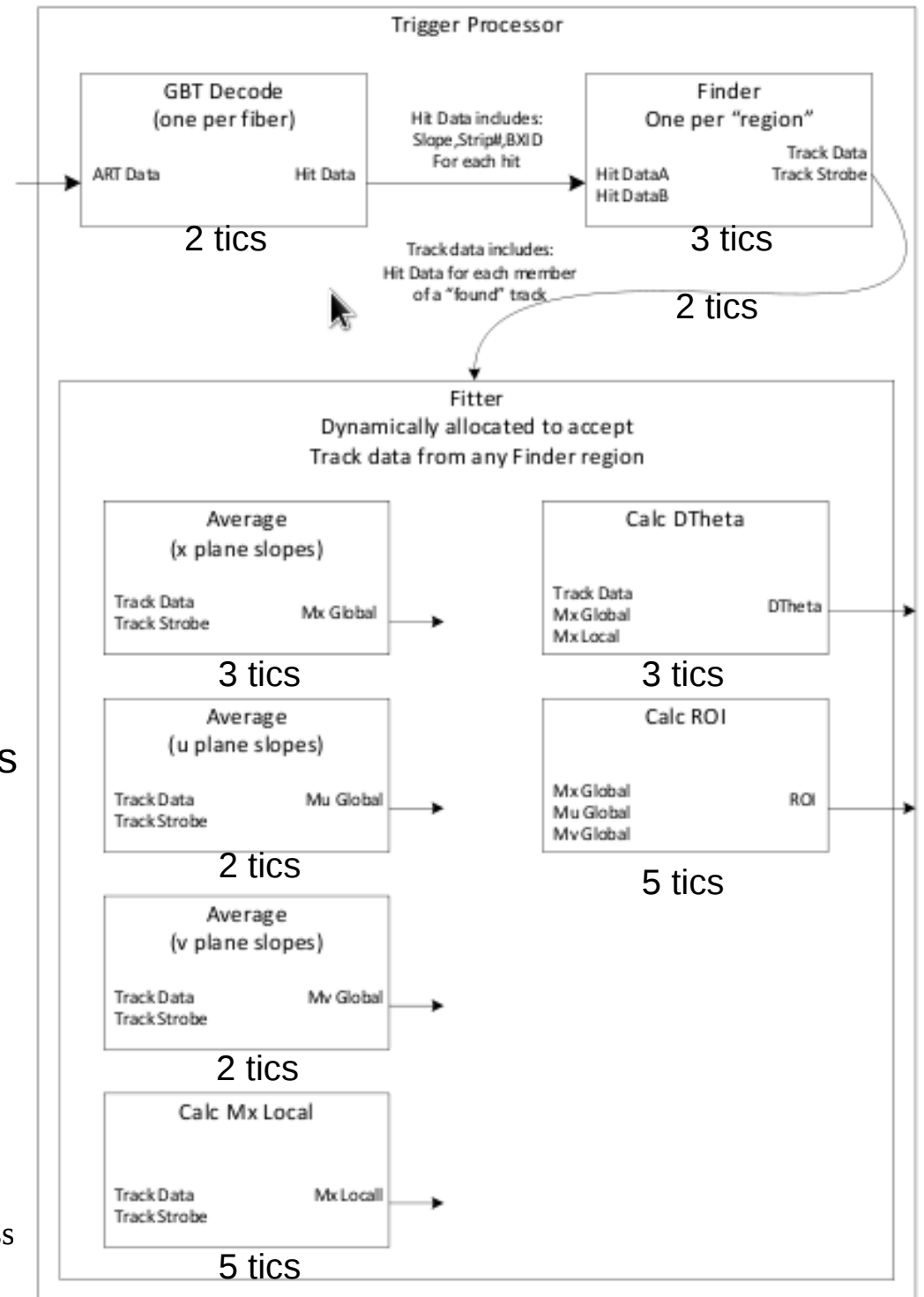
# Trigger Processor Implementation

Nathan Felt  
Harvard University  
2014 July 10

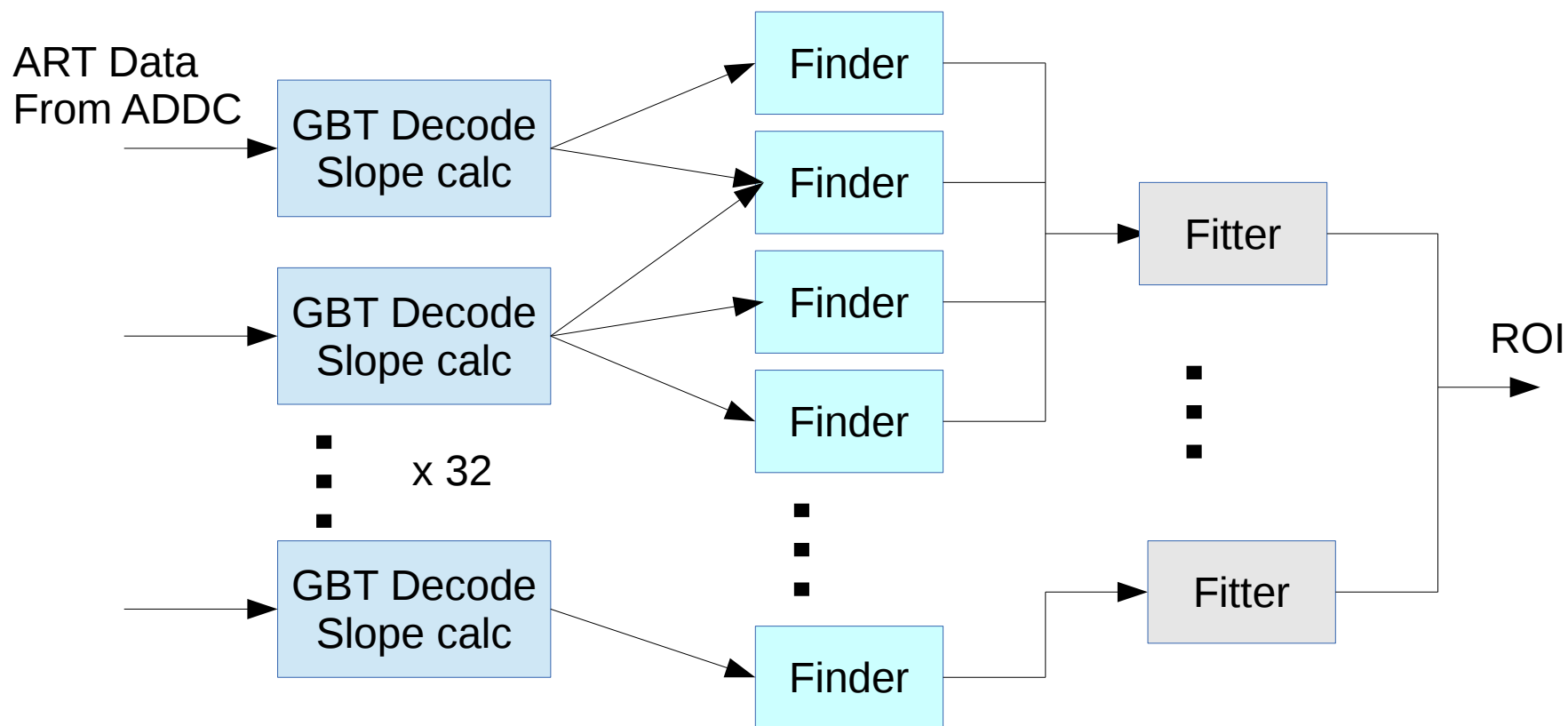
# Eval Board Overview



- GBT Decode
  - Deserialize ART data
  - Calc slope using mult DSP slice
- Finder
  - Each finder has unique upper and lower slope road boundaries
  - Collect hits within its boundaries
  - Regions have overlapping boundaries
  - Pass hits only from track candidate that satisfy plane occupancy requirements to Fitter
  - Background hits will expire in Finder
- Fitter
  - Calculate ROI,  $d\theta$



# Multi-Region Structure

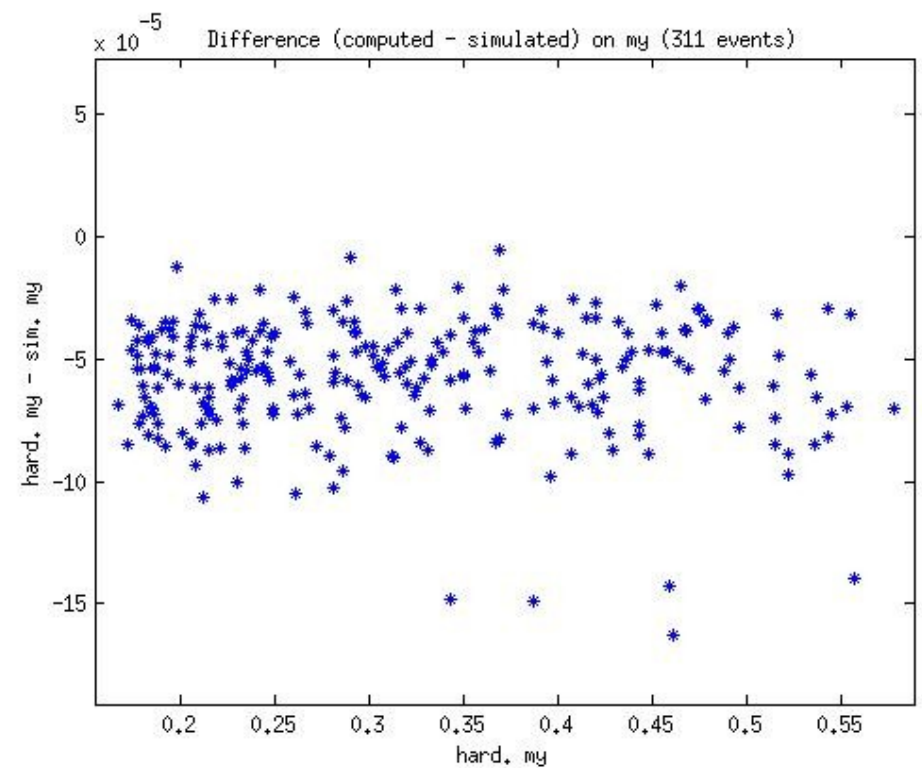
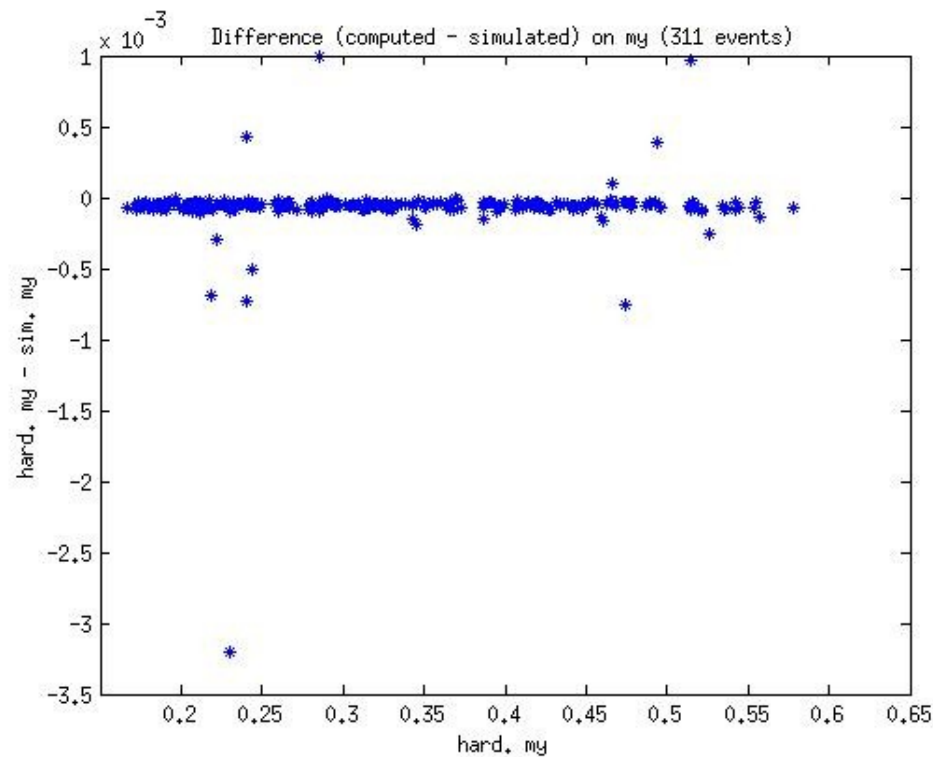


# Software

- Simulation using Mentor Graphics Modelsim and Matlab
- Trigger Processor algorithm synthesized using Mentor Graphics Precision Synthesis
- Place and route using Xilinx Vivado
- DAQ and analysis in Matlab

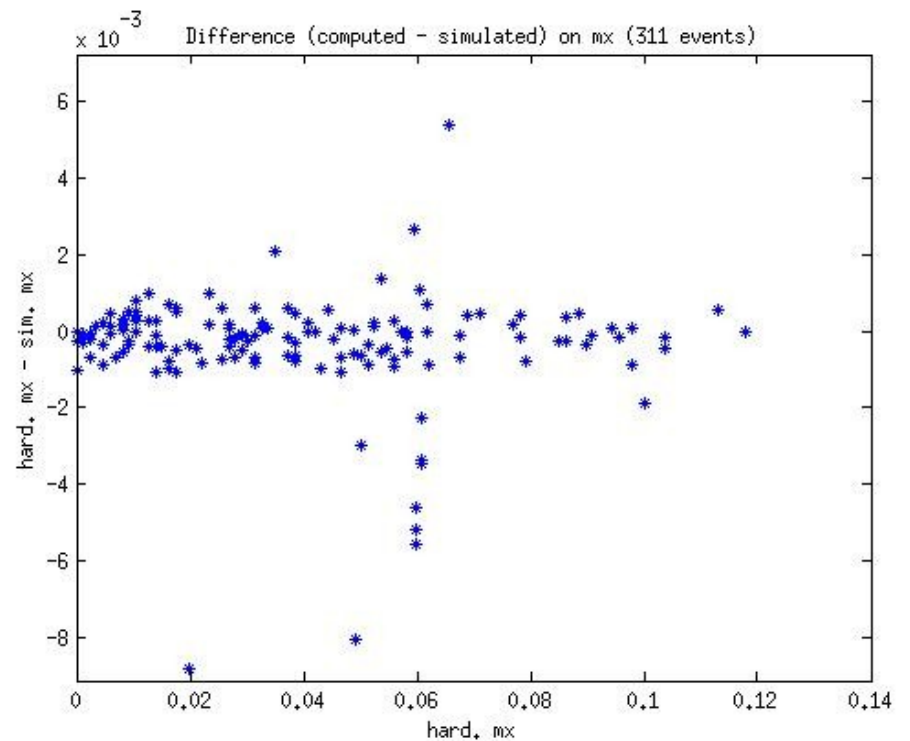
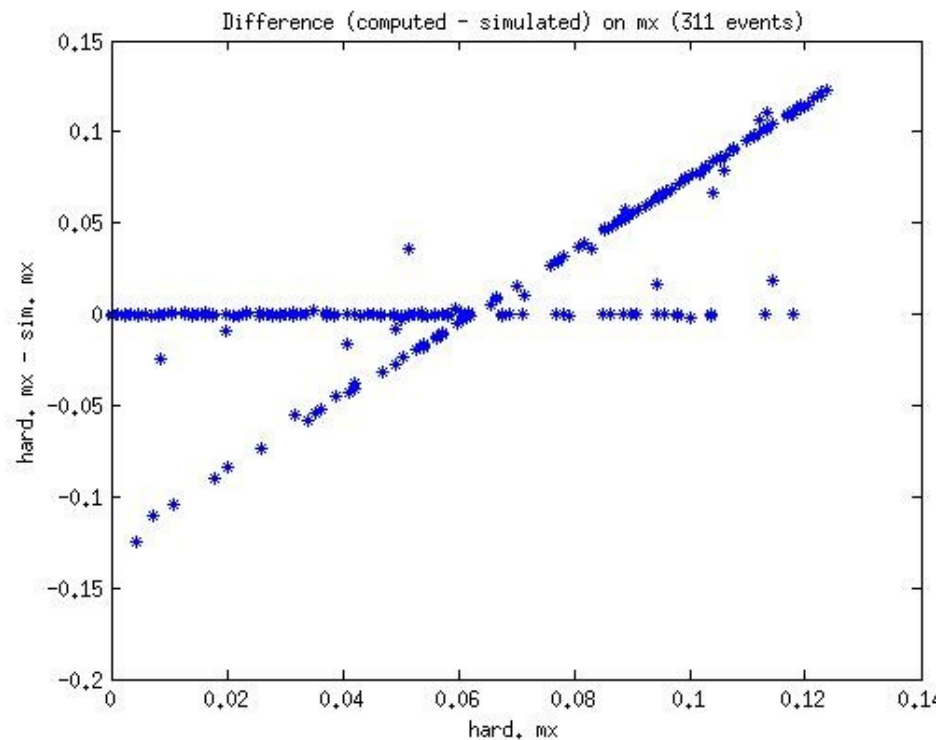
# ROI Coordinates

## Hardware vs Simulation



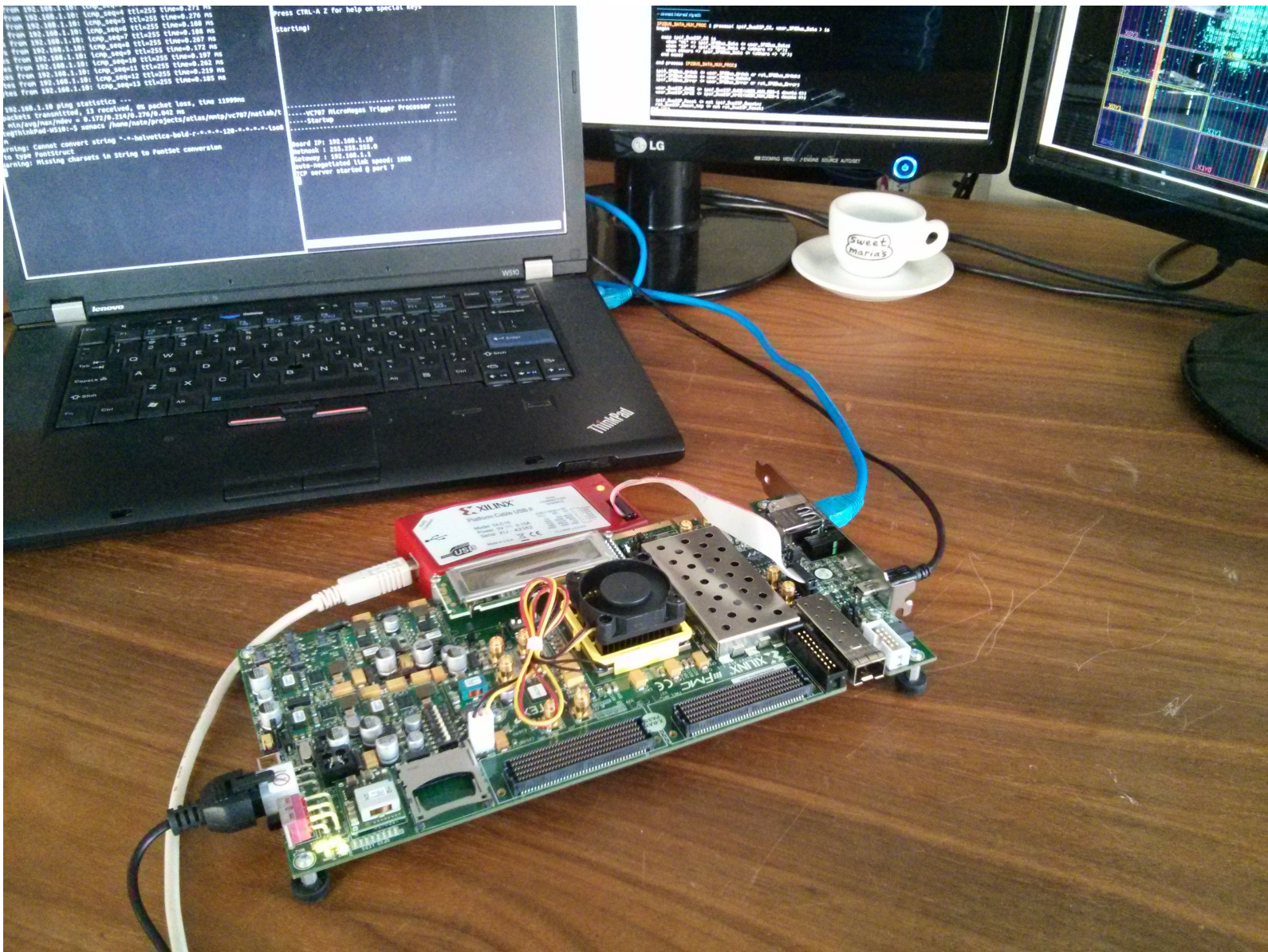
# ROI Coordinates

## Hardware vs Simulation



# Backup







# Timing Simulation

Arrival of the last hit  
on the GBT link

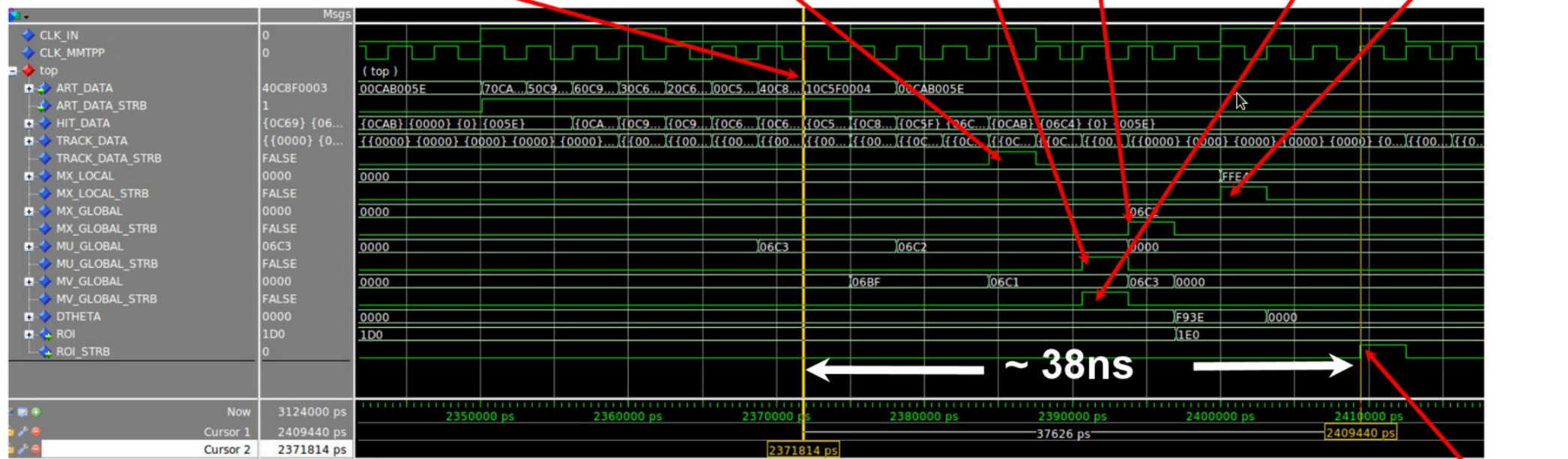
Possible track formed

Mu\_global calc'ed

Mx\_global calc'ed

Mv\_global calc'ed

Mx\_local\_calc'ed



Result of the ROI