

Incoming hit signals

A: Incoming hits are converted to slope values

hit = (strip number, plane, slope)

B: Store hits in a buffer where
address = (slope, plane, BC)
cycles every BC, 2 BC deep

C: Check buffer for
coincidence

slope road index to read

Reading specified slope road from FIFO

D: Read Track from buffer
and send components

X strips

X slopes

U slopes

V slopes

U and V slopes

E: Calculate
local slope

F: Calculate
global X slope

G: Calculate
global U slope

H: Calculate
global V slope

I: Filter background
from stereo hits

global U slope

global V slope

stereo validation

Apply filter validation

stereo global slopes

global X slope

local X slope

J: Calculate
delta theta

delta theta

Dtheta cut?

L: Trigger Signal Output

K: Calculate
cartesian
slopes

(m_x, m_y)

K: Lookup θ, ϕ

local slope < 0

fit not on wedge

delta theta too large

could cut if low
confidence in stereo hits
(not implemented)

M: Abandon Fit