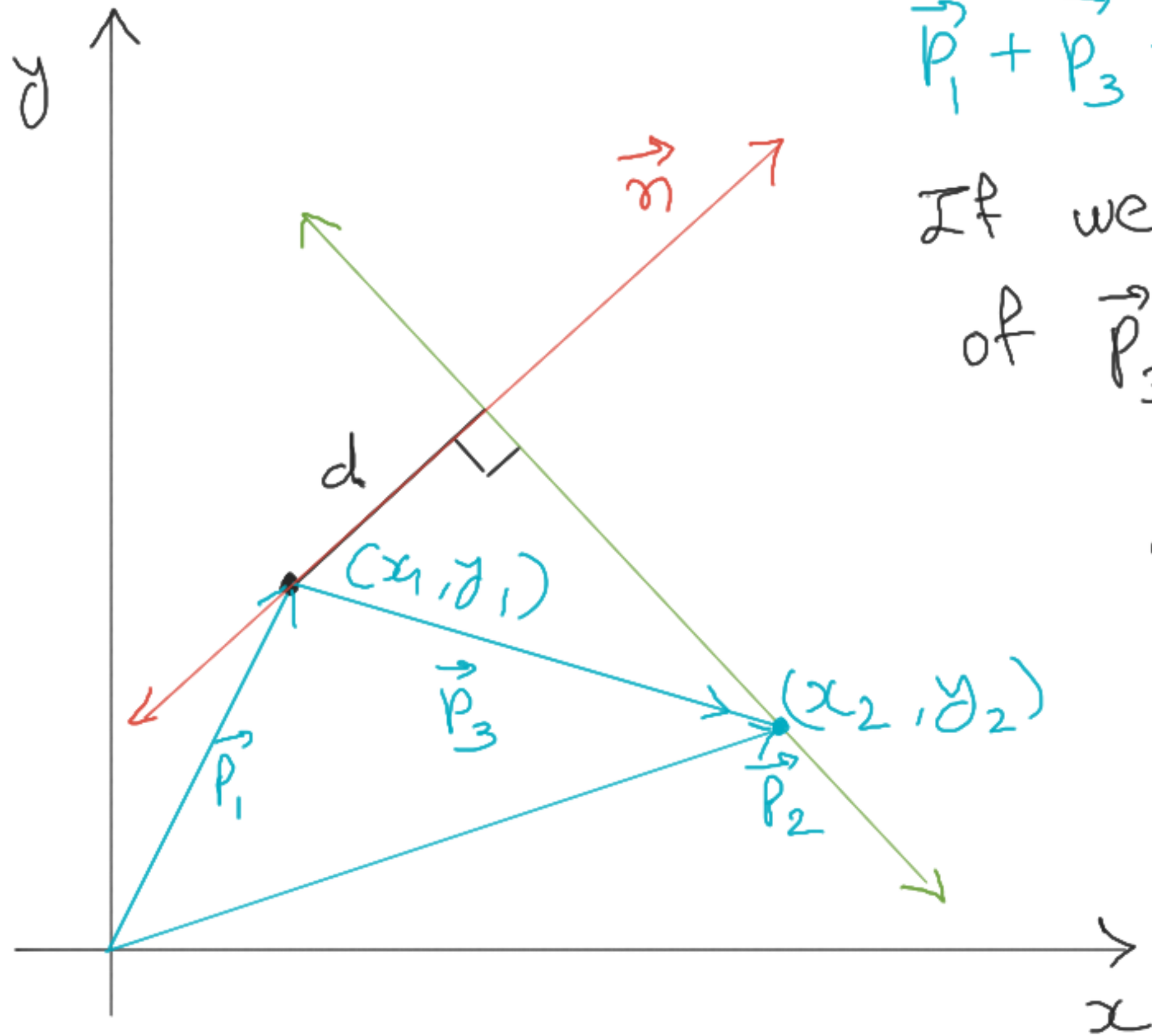


# ☆ Distance of a point from a line



$$\vec{P}_1 + \vec{P}_3 = \vec{P}_2 \Rightarrow \vec{P}_3 = \vec{P}_2 - \vec{P}_1$$

If we find magnitude of projection of  $\vec{P}_3$  on  $\vec{n}$  then it is  $d$ .

$$d = \frac{\vec{P}_3 \cdot \vec{n}}{|\vec{n}|}$$

Now,  $\vec{P}_3 = \vec{P}_2 - \vec{P}_1$

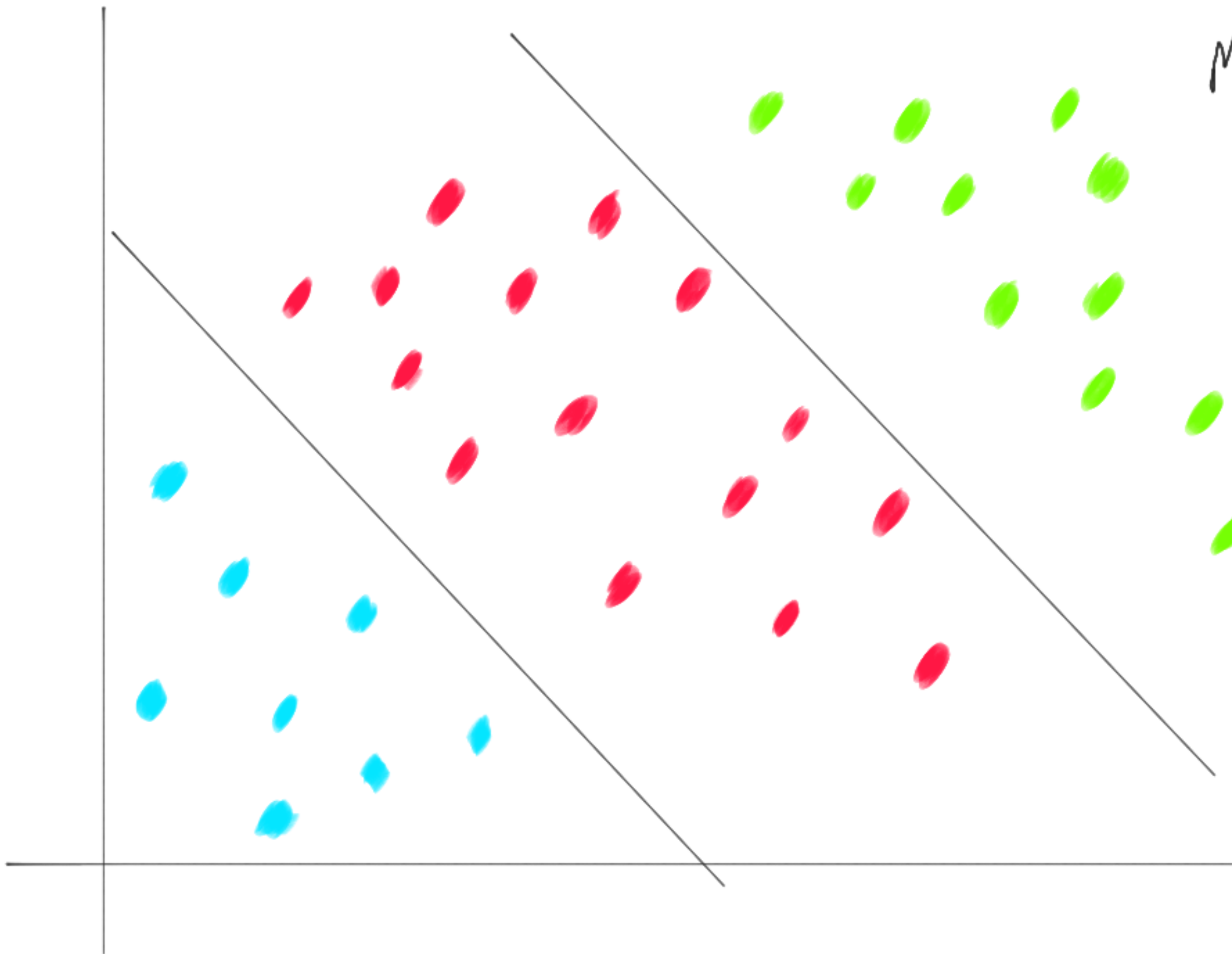
$$\vec{P}_1 = x_1 \hat{i} + y_1 \hat{j} \quad \& \quad \vec{P}_2 = x_2 \hat{i} + y_2 \hat{j}$$

$$\therefore \vec{p}_3 = (x_2 - x_1) \cdot \hat{i} + (y_2 - y_1) \cdot \hat{j}$$

$$\vec{n} = A \cdot \hat{i} + B \cdot \hat{j}$$

$$d = \frac{\vec{p}_3 \cdot \vec{n}}{|\vec{n}|} = \frac{A(x_2 - x_1) + B(y_2 - y_1)}{\sqrt{A^2 + B^2}}$$

Multi-class  
classification



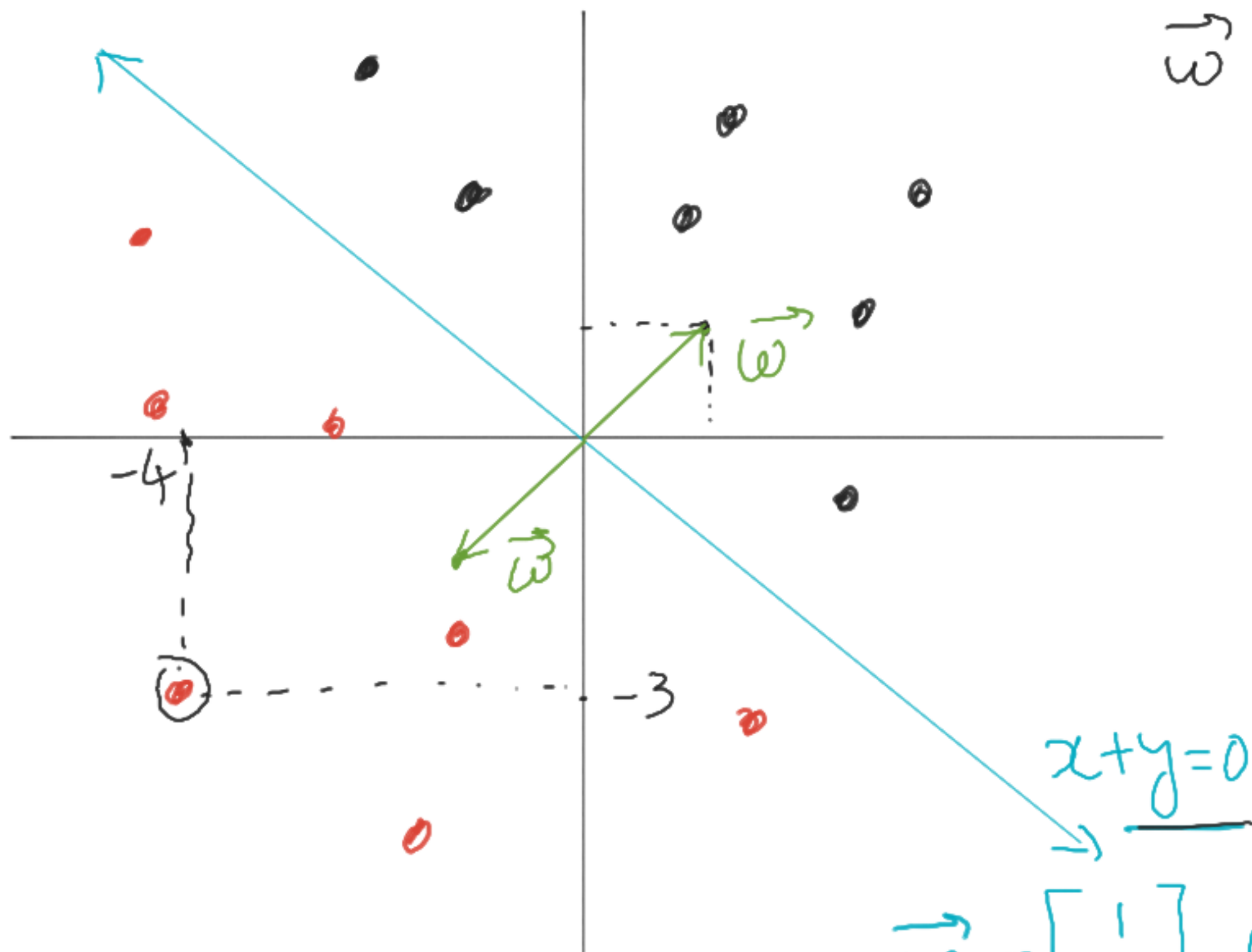
★ Significance of  $\vec{w}$ :

Let's consider another line  
 $-x - y = 0$

$$\vec{w} = \begin{bmatrix} -1 \\ -1 \end{bmatrix}$$

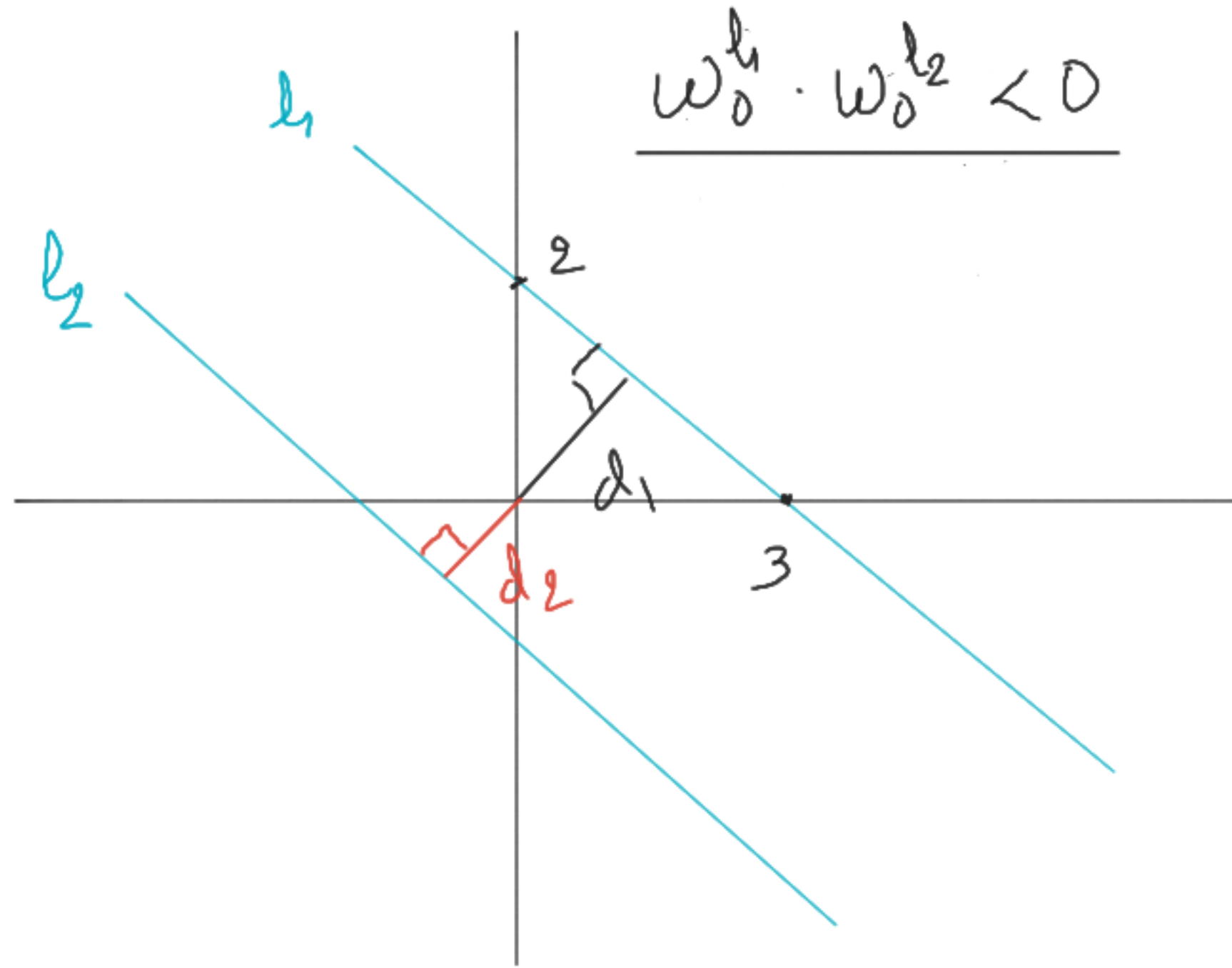
$$-(-4) - (-3) = 7 > 0$$

Hence  $\vec{w}$  changes our  
perception.



$$\vec{w} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad w_0 = 0$$

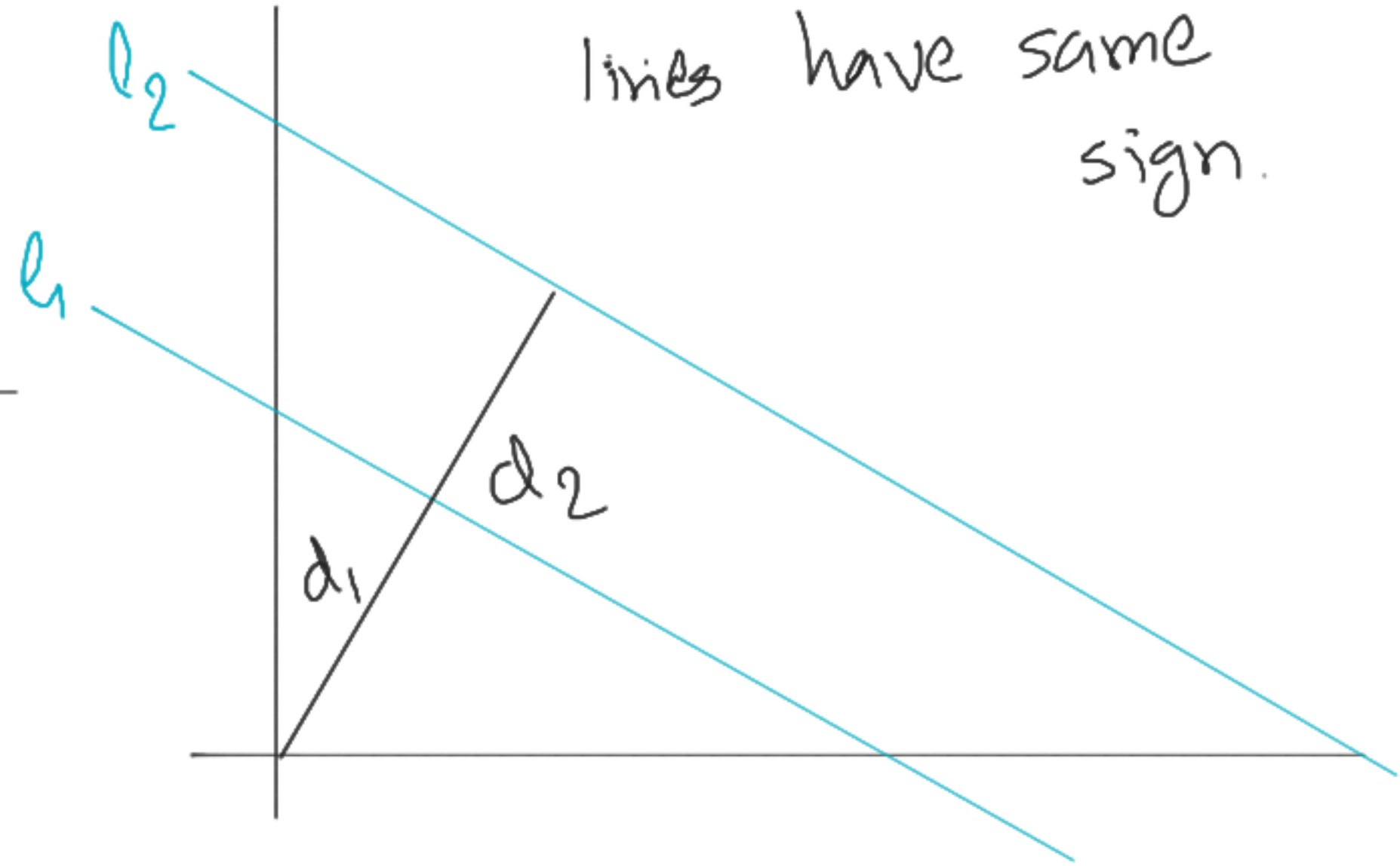
## ☆ Distance between two lines:



distance between  $l_1$  &  $l_2 = d_1 + d_2$   
(when  $\omega_0$  of both lines have diff sign)

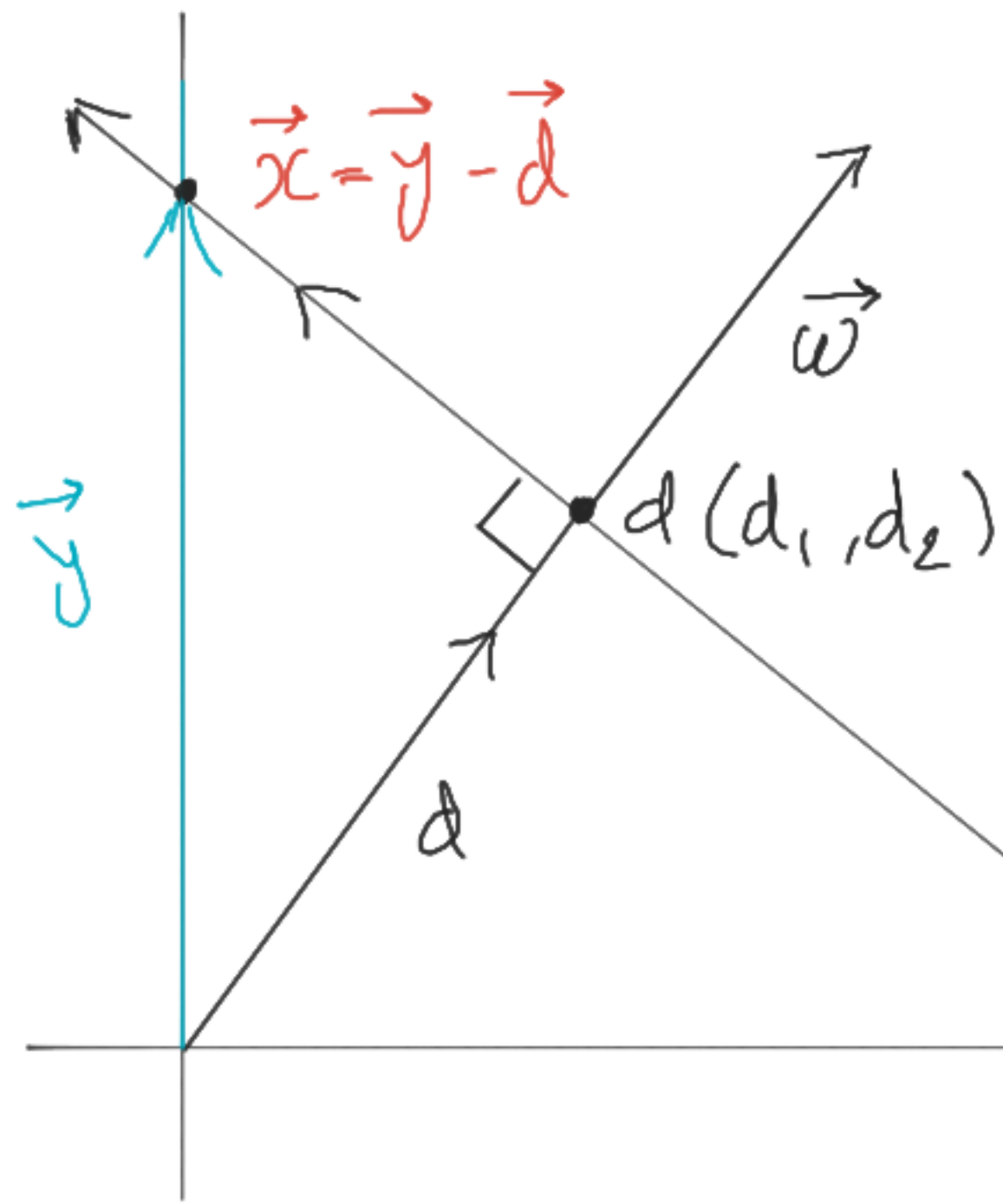
$$\omega_0^{l_1} \cdot \omega_0^{l_2} > 0$$

when  $\omega_0$  of both the lines have same sign.



distance between  $l_1$  &  $l_2$   
 $= |d_1 - d_2|$

☆ Prove that  $\vec{w} \begin{bmatrix} w_1 \\ w_2 \end{bmatrix}$  is always perpendicular to the line  $w_1 x_1 + w_2 x_2 + w_0 = 0$ . Proof: If we prove  $\vec{w}^T \cdot \vec{x} = 0$  then we can solve this problem.



$$\boxed{\vec{x} = \vec{y} - \vec{d}} \quad \text{--- (I)}$$

y-intercept of the line =  $\frac{-w_0}{w_2}$

$$\therefore \vec{y} = \begin{bmatrix} 0 \\ \frac{-w_0}{w_2} \end{bmatrix} \quad \text{--- (A)}$$



$$\vec{d} = k \hat{\omega} \quad \text{But } \hat{\omega} = \frac{\vec{\omega}}{\|\vec{\omega}\|} = \frac{1}{\|\vec{\omega}\|} \begin{bmatrix} \omega_1 \\ \omega_2 \end{bmatrix} = \begin{bmatrix} \frac{\omega_1}{\|\vec{\omega}\|} \\ \frac{\omega_2}{\|\vec{\omega}\|} \end{bmatrix}$$

$$\therefore \vec{d} = \begin{bmatrix} \frac{k\omega_1}{\|\vec{\omega}\|} \\ \frac{k\omega_2}{\|\vec{\omega}\|} \end{bmatrix} \quad \text{--- (B)}$$

But we still don't know 'k'

As point  $d(d_1, d_2)$  is on the line

$\omega_1 x_1 + \omega_2 x_2 + \omega_0 = 0$ ,  $d_1$  &  $d_2$  will satisfy it.

$$\omega_1 d_1 + \omega_2 d_2 + \omega_0 = 0$$

$$\therefore \omega_1 \left( \frac{k\omega_1}{\|\vec{\omega}\|} \right) + \omega_2 \left( \frac{k\omega_2}{\|\vec{\omega}\|} \right) = -\omega_0 \quad \Rightarrow \quad k \left( \frac{\omega_1^2}{\|\vec{\omega}\|} + \frac{\omega_2^2}{\|\vec{\omega}\|} \right) = -\omega_0$$

$$\therefore k = \frac{-\omega_0}{\left( \frac{\omega_1^2}{\|\vec{\omega}\|} + \frac{\omega_2^2}{\|\vec{\omega}\|} \right)}$$

$$\therefore k = \frac{-\omega_0 \|\vec{\omega}\|}{\omega_1^2 + \omega_2^2}$$

putting this in eqn (B)

$$d = \begin{bmatrix} \frac{-\omega_0 \omega_1 \cancel{\|\vec{\omega}\|}}{(\omega_1^2 + \omega_2^2) \cancel{\|\vec{\omega}\|}} \\ \frac{\omega_2 (-\omega_0) \cancel{\|\vec{\omega}\|}}{\cancel{\|\vec{\omega}\|} (\omega_1^2 + \omega_2^2)} \end{bmatrix}$$

$$= \begin{bmatrix} \frac{-\omega_0 \omega_1}{\omega_1^2 + \omega_2^2} \\ \frac{-\omega_0 \omega_2}{\omega_1^2 + \omega_2^2} \end{bmatrix} \quad \text{--- (C)}$$



Substituting values of (A) & (C) into (I)

$$\vec{x} = \begin{bmatrix} \frac{\omega_0 \omega_1}{\omega_1^2 + \omega_2^2} \\ \frac{\omega_0 \omega_2}{\omega_1^2 + \omega_2^2} - \frac{\omega_0}{\omega_2} \end{bmatrix} = \begin{bmatrix} \frac{\omega_0 \omega_1}{\omega_1^2 + \omega_2^2} \\ \frac{\omega_0 \omega_2^2 - \omega_0(\omega_1^2 + \omega_2^2)}{\omega_2(\omega_1^2 + \omega_2^2)} \end{bmatrix} = \begin{bmatrix} \frac{\omega_0 \omega_1}{\omega_1^2 + \omega_2^2} \\ \frac{-\omega_0 \omega_1^2}{\omega_2(\omega_1^2 + \omega_2^2)} \end{bmatrix}$$

Now let's do  $\vec{\omega}^T \cdot \vec{x}$

$$\vec{\omega}^T \cdot \vec{x} = \frac{\omega_0 \omega_1^2}{\omega_1^2 + \omega_2^2} - \frac{\omega_0 \omega_1^2 \cancel{\omega_2}}{\cancel{\omega_2}(\omega_1^2 + \omega_2^2)} = 0 \quad \begin{matrix} \therefore \cos \theta = 0 \\ \therefore \theta = 90^\circ \end{matrix}$$

★ Another formula of distance of a point from a line

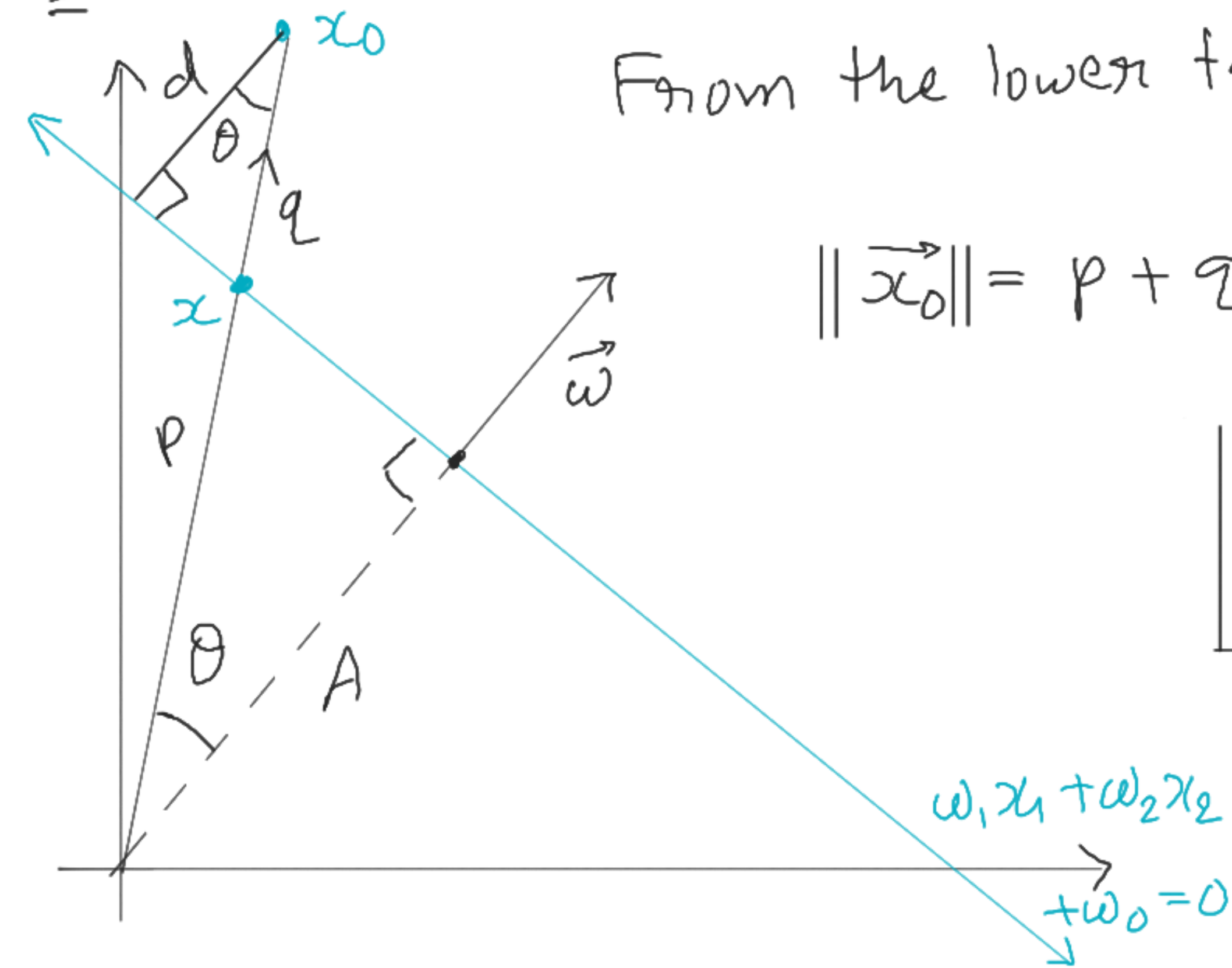
From the lower triangle,  $\cos \theta = \frac{A}{p} \Rightarrow p = \frac{A}{\cos \theta}$

$$\|\vec{x}_0\| = p + q \Rightarrow q = \|\vec{x}_0\| - p$$

$$\therefore q = \|\vec{x}_0\| - \frac{A}{\cos \theta} \quad \text{--- (I)}$$

From the upper triangle,

$$\cos \theta = \frac{d}{q} \Rightarrow \boxed{d = q \cos \theta} \quad \text{--- (II)}$$



Substituting value of  $q$  from (I) into (II)

$$d = \left( \|\vec{x}_0\| - \frac{A}{\cos \theta} \right) \cdot \cos \theta = \|\vec{x}_0\| \cdot \cos \theta - A$$

From the dot product of  $\vec{\omega}^T$  &  $\vec{x}_0$

$$\vec{\omega}^T \cdot \vec{x}_0 = \|\vec{\omega}\| \cdot \|\vec{x}_0\| \cdot \cos \theta \Rightarrow \boxed{\cos \theta = \frac{\vec{\omega}^T \cdot \vec{x}_0}{\|\vec{\omega}\| \|\vec{x}_0\|}}$$

putting this value of  $\cos \theta$  into the eqn of  $d$ :

$$d = \frac{\|\vec{x}_0\| \cdot \vec{\omega}^T \cdot \vec{x}_0}{\|\vec{\omega}\| \|\vec{x}_0\|} - A \quad \text{--- (III)}$$

From the lower triangle,  $p = \|\vec{x}\| \Rightarrow A = \|\vec{x}\| \cos \theta$   
putting value of  $\cos \theta$  (from the dot product formula)  
into this eqn:

$$A = \frac{\|\vec{x}\| \cdot \vec{\omega}^T \cdot \vec{x}}{\|\vec{\omega}\| \cdot \|\vec{x}\|} = \frac{\vec{\omega}^T \cdot \vec{x}}{\|\vec{\omega}\|}$$

But the eqn of line is  $\omega_1 x_1 + \omega_2 x_2 + \omega_0 = 0$  or

$$\vec{\omega}^T \cdot \vec{x} + \omega_0 = 0$$

$$\therefore \vec{\omega}^T \cdot \vec{x} = -\omega_0$$

$$\therefore A = \frac{-\omega_0}{\|\vec{\omega}\|}$$

Substituting this value of A into eqn (III).

$$d = \frac{\vec{\omega}^T \cdot \vec{x}_0}{\|\vec{\omega}\|} + \frac{\omega_0}{\|\vec{\omega}\|}$$

$$d = \frac{\vec{\omega}^T \cdot \vec{x}_0 + \omega_0}{\|\vec{\omega}\|}$$

—— V.V. Imp Result

