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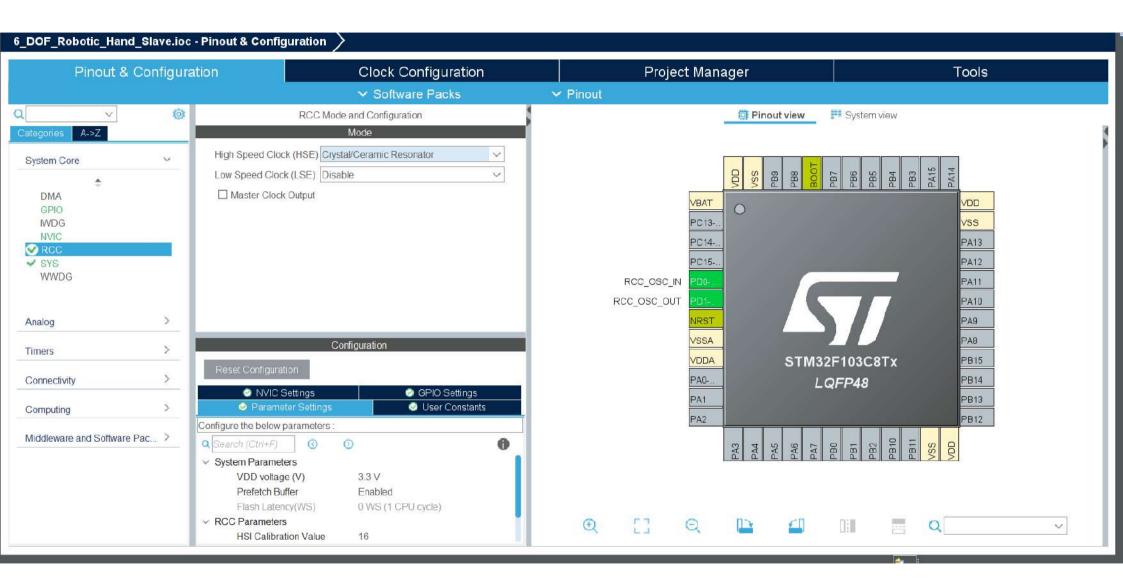
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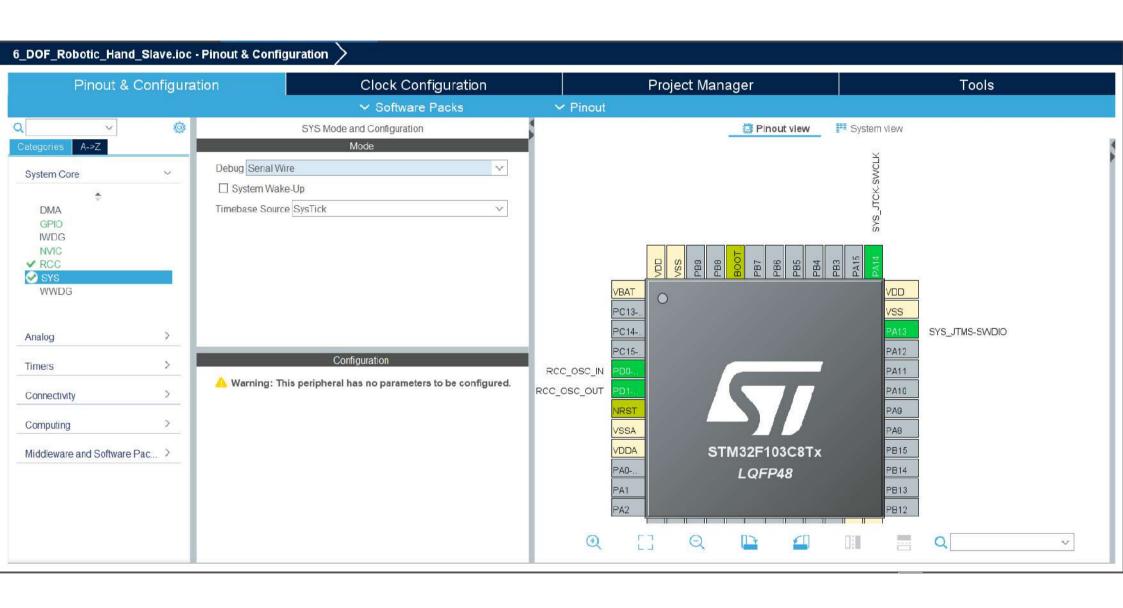
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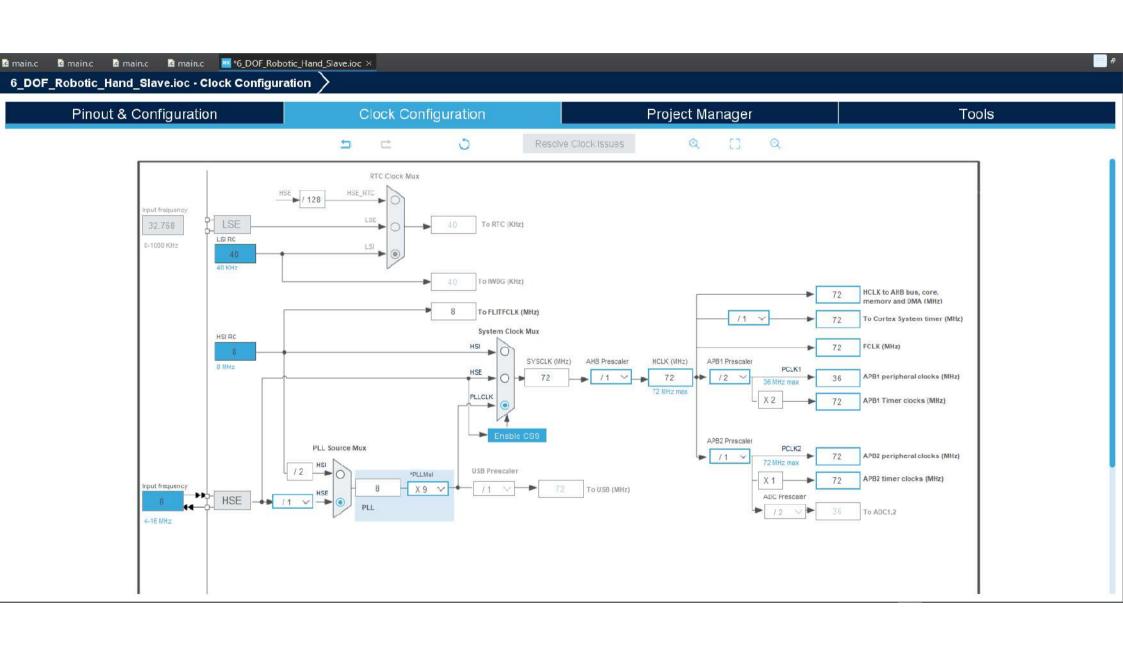
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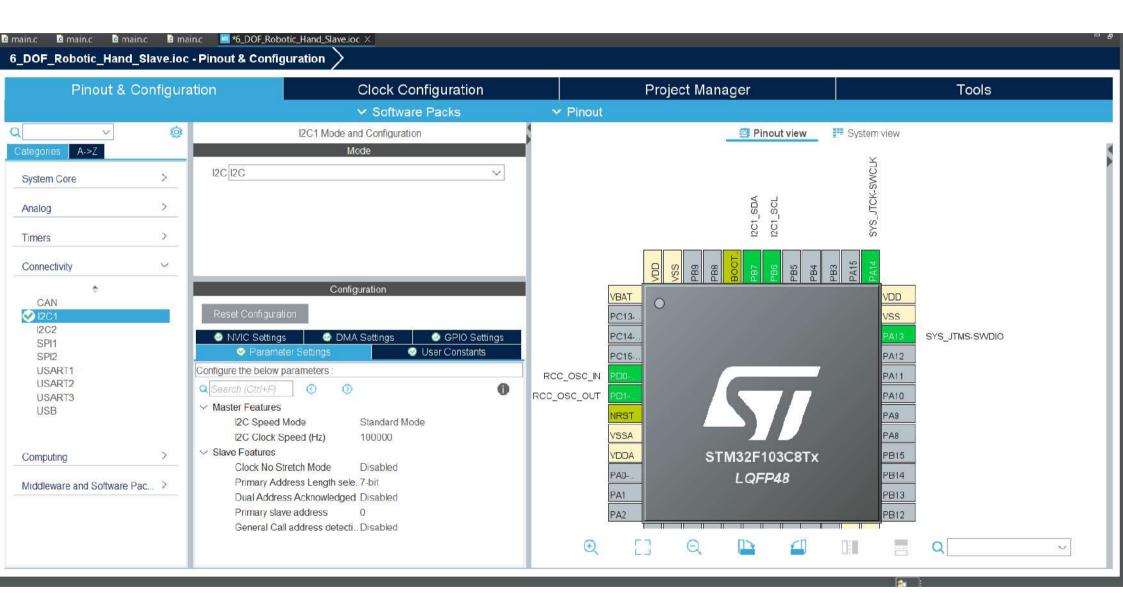


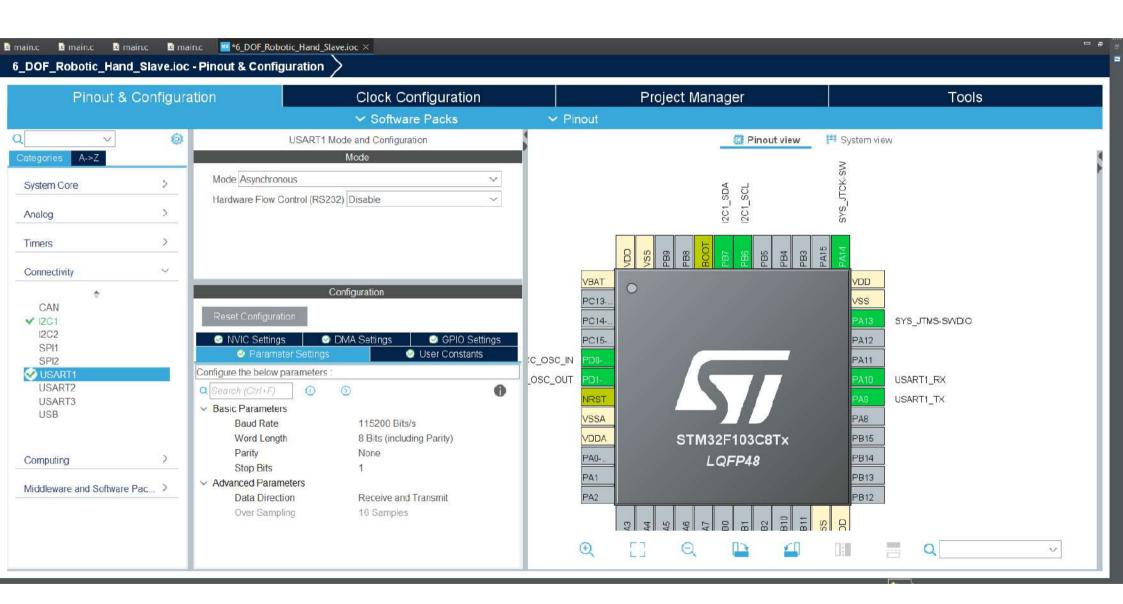
● STM32Cube ● Empty

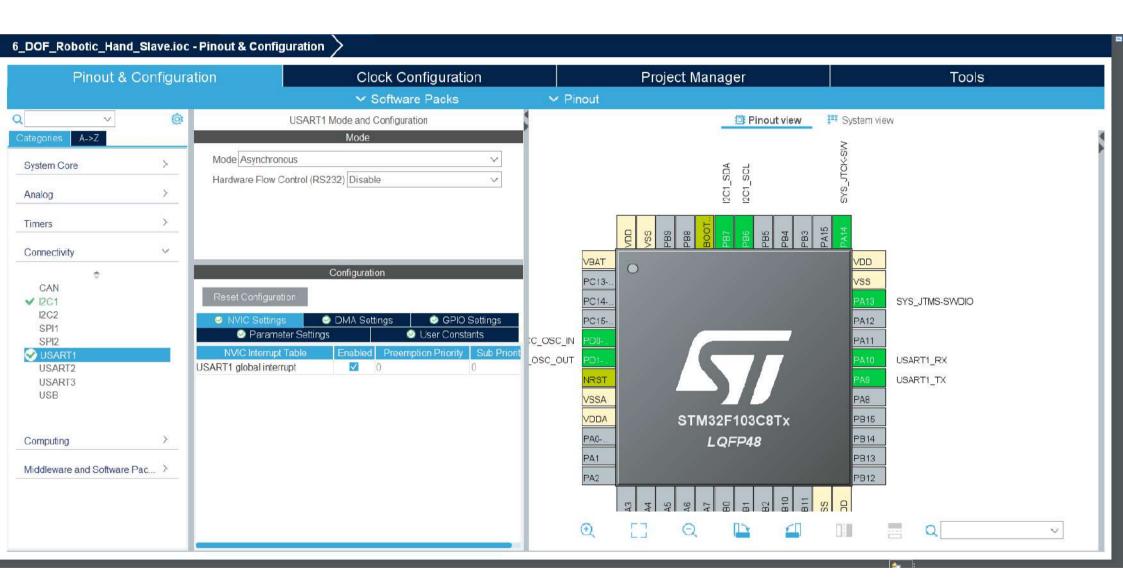




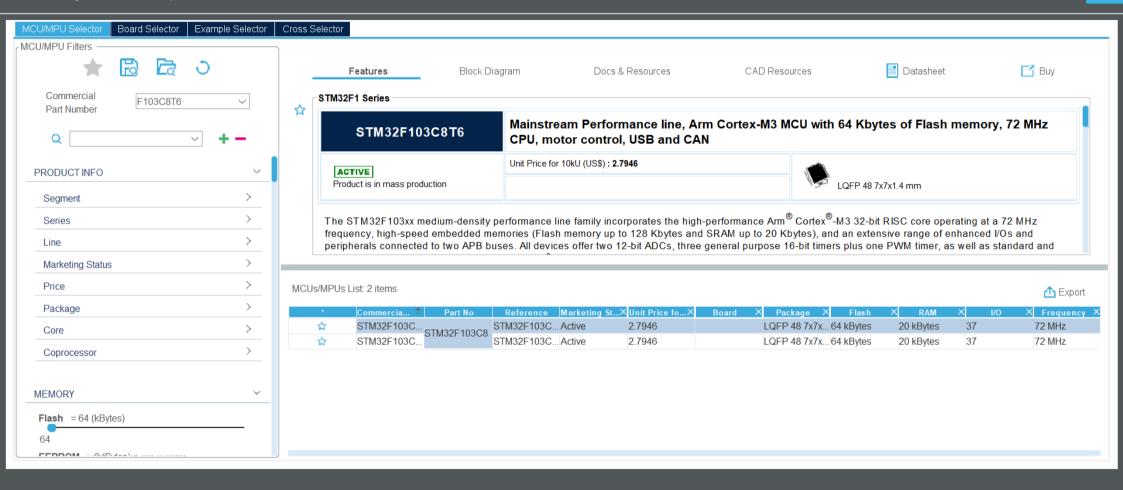








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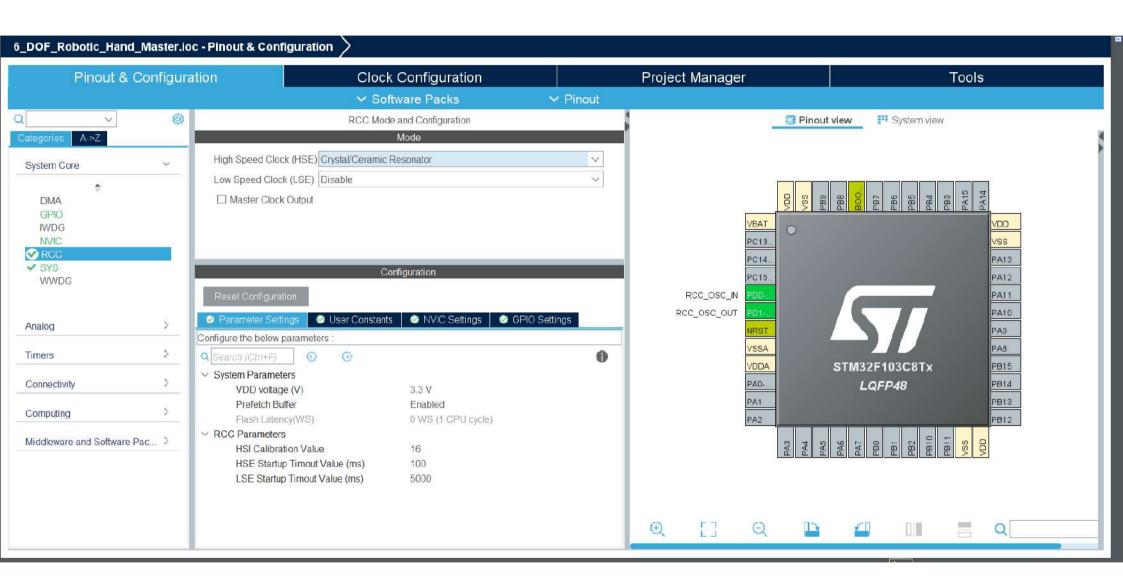
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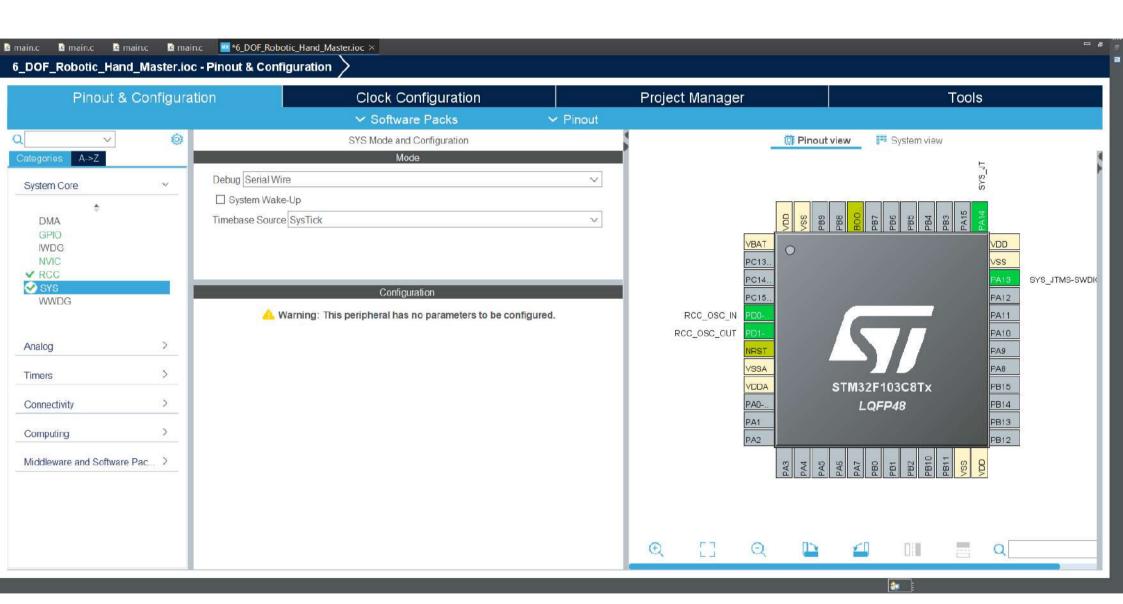
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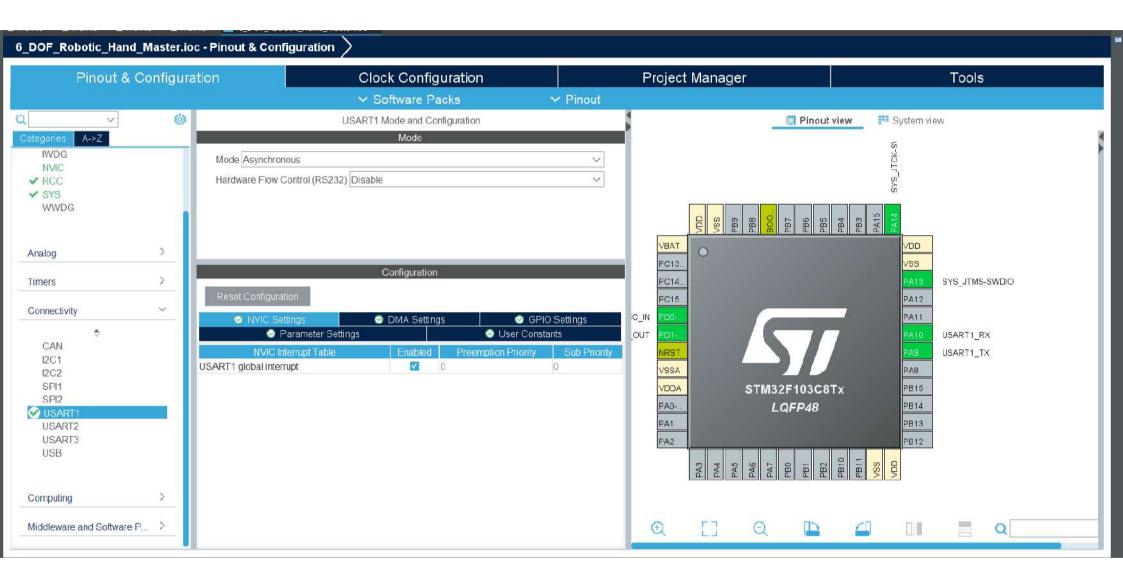


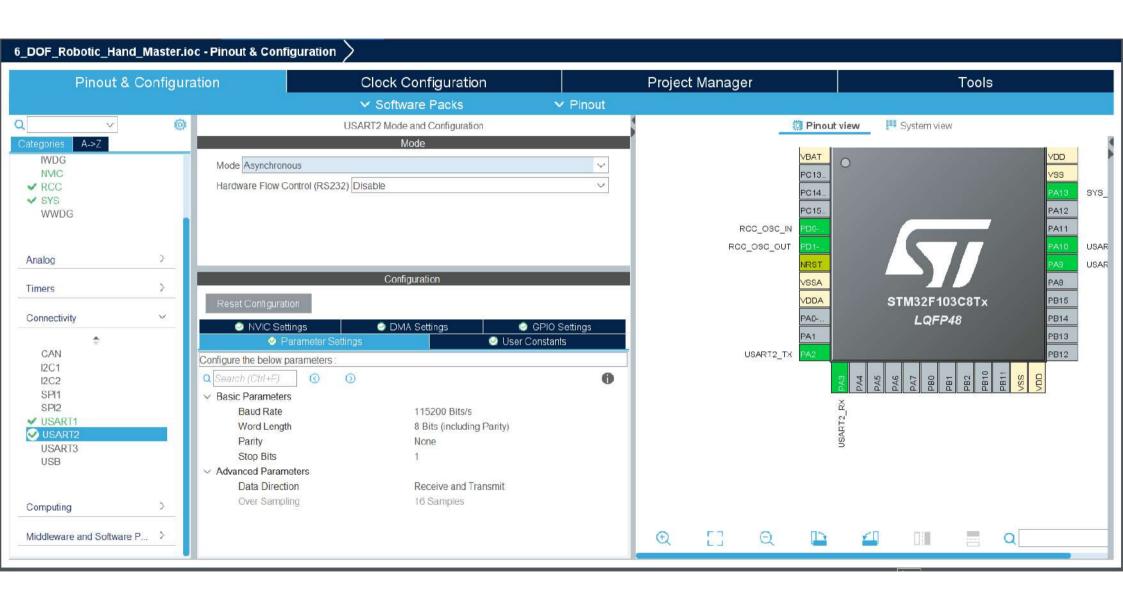
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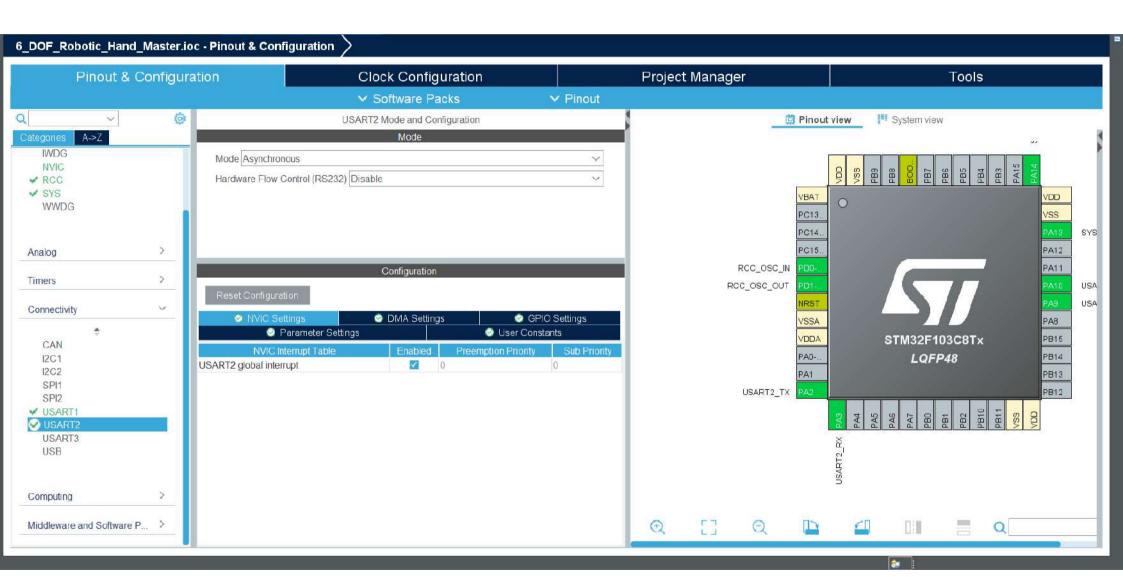


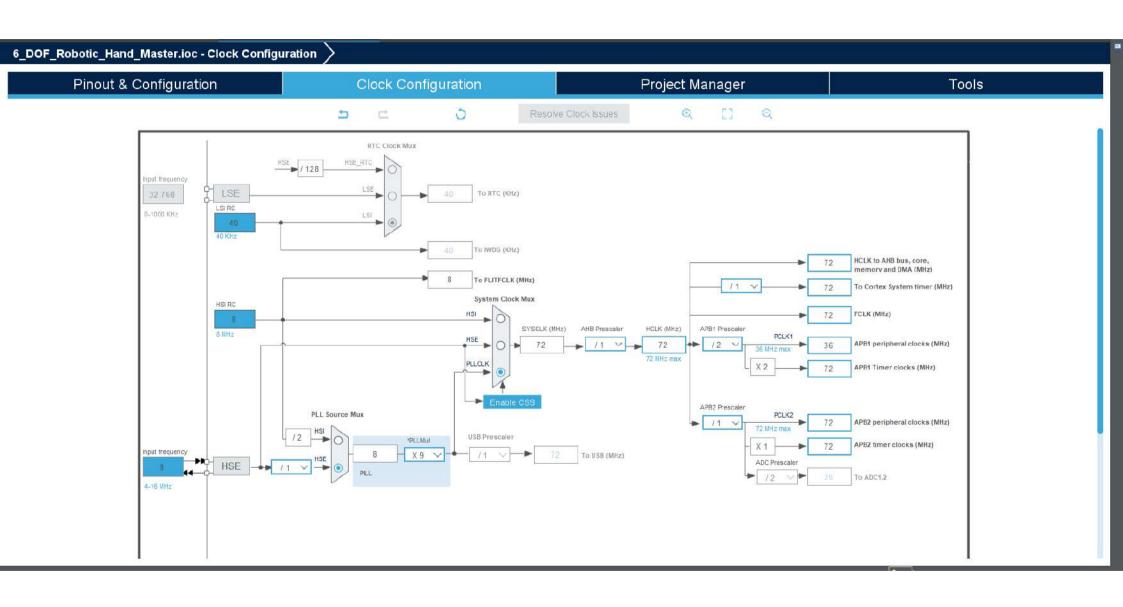




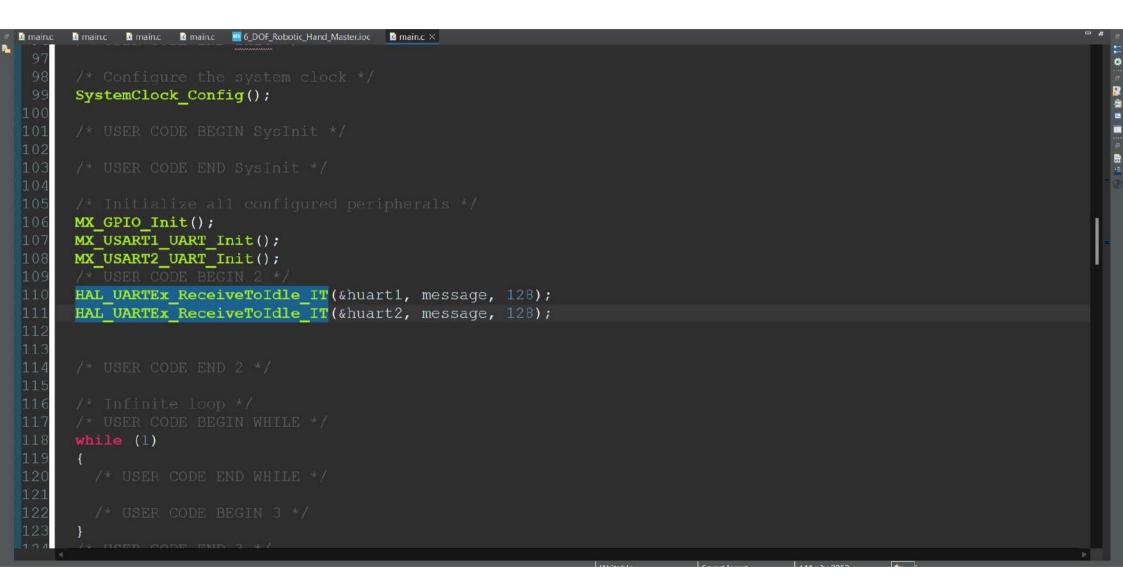


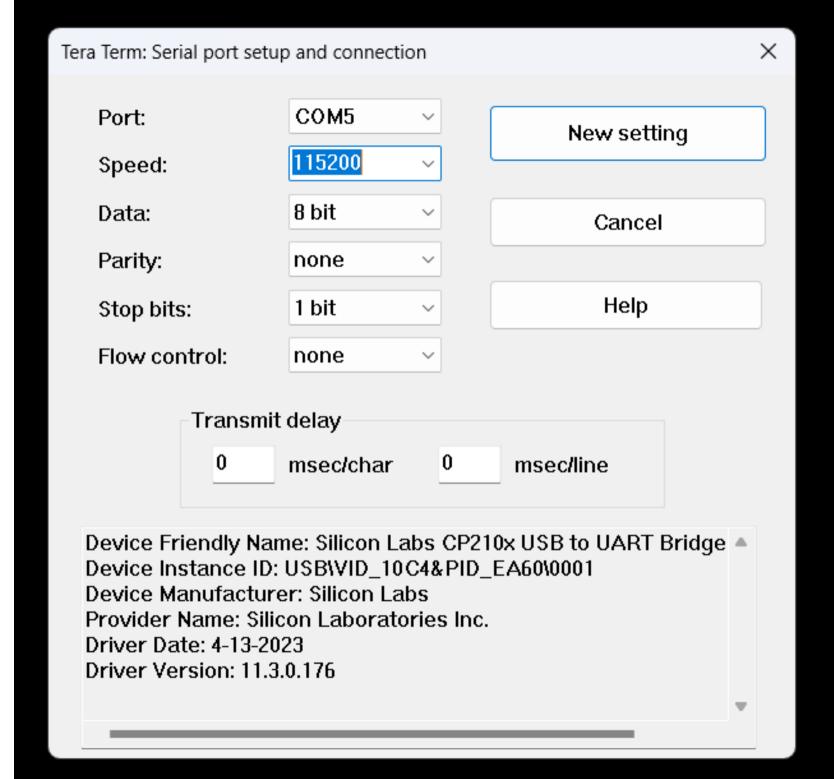


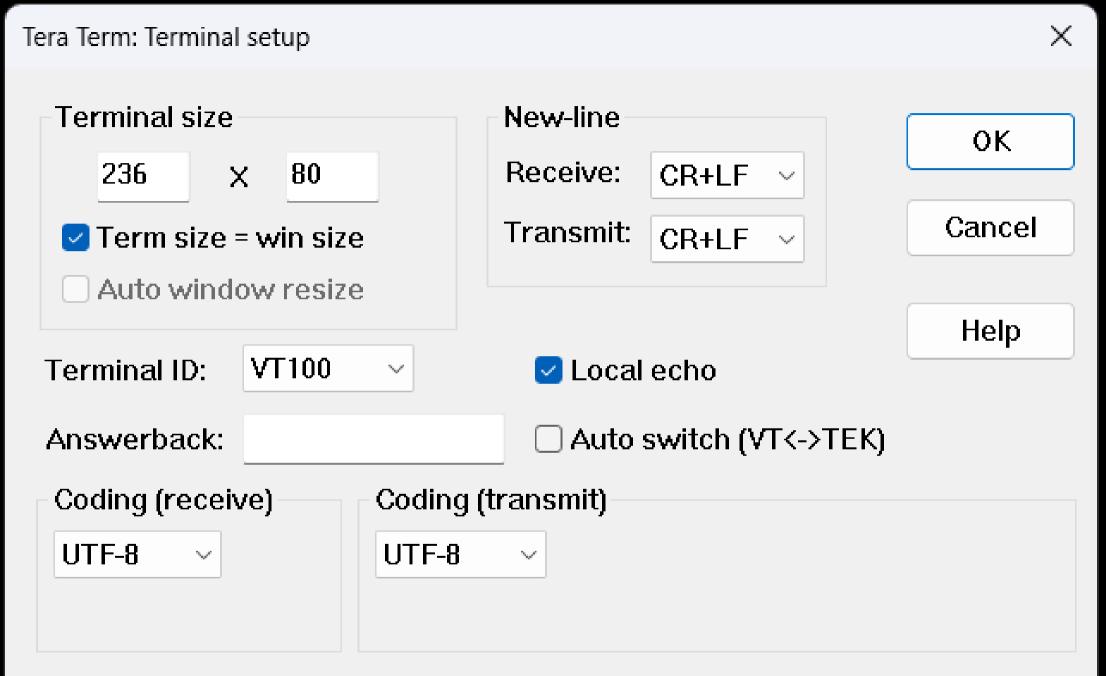




```
■ 6_DOF_Robotic_Hand_Master.ioc 🚨 main.c ×
uint8 t message[128];
roid HAL UARTEx RxEventCallback(UART HandleTypeDef *huart, uint16 t Size)
 if (huart->Instance==USART1)
      HAL UART Transmit(&huart2, message, Size, 1000);
 else if (huart->Instance==USART2)
      HAL UART Transmit(&huart1, message, Size, 1000);
 HAL UARTEx ReceiveToIdle IT (huart, message, 128);
```







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