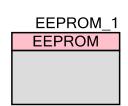


EEPROM 1.10

#### **Features**

- 512B to 2 KB
- 1,000,000 cycles, 20 year retention
- Read byte at a time
- Program 16 bytes at a time



## **General Description**

The EEPROM component provides an API to write a row (16 bytes) of data to the EEPROM. The term write implies Erase and then program in one operation.

#### When to use an EEPROM

You can use an EEPROM component:

- For off-chip storage of data (freeing up on-chip RAM)
- For read-only (or rarely-changing) program data
- For data that must survive power cycles (e.g., calibration tables or device configuration)

# **Input/Output Connections**

There are no IO connections for the EEPROM component. It is an API only.

### **Parameters and Setup**

The EEPROM has no configurable parameters other than standard Instance Name and Built-in parameters.

### **Application Programming Interface**

Application Programming Interface (API) routines allow you to configure the component using software. The following table lists and describes the interface to each function. The subsequent sections cover each function in more detail.

To read from the EEPROM or FLASH, no APIs are needed. The entire contents of the EEPROM are mapped into memory space and can be read directly. The following defines can be used for reading EEPROM:

- CYDEV\_EE\_BASE the base pointer of the EEPROM memory
- CYDEV\_EE\_SIZE The size of the EEPROM memory space in bytes

EEPROM\_1\_EEPROM\_SIZE is also defined as the size of the EEPROM memory space in bytes (where EEPROM\_1 is the instance name of the EEPROM component).

To write to the EEPROM, you must first acquire the die temperature. You only need to acquire the temperature once to use the write functions. If the application will be used in an environment where the die temperature changes 20°C or more, the temperature should be refreshed to allow the Smart Write Algorithm to work correctly.

By default, PSoC Creator assigns the instance name "EEPROM\_1" to the first instance of a component in a given design. You can rename it to any unique value that follows the syntactic rules for identifiers. The instance name becomes the prefix of every global function name, variable, and constant symbol. For readability, the instance name used in the following table is "EEPROM".

Function	Description
EEPROM_EraseSector	Erases an EEPROM sector.
EEPROM_Write	Blocks while writing a row to EEPROM
EEPROM_StartWrite	Starts writing a row of data to EEPROM
EEPROM_QueryWrite	Checks the state of a write to EEPROM

### cystatus EEPROM\_EraseSector(uint8 sectorNumber)

**Description:** Erases a sector (64 rows) of memory. This function blocks until the operation is complete.

**Parameters:** Uint8 sector. Sector number to erase.

**Return Value:** CYRET\_SUCCESS if the operation was successful.

CYRET BAD PARAM if the parameters were invalid.

CYRET\_LOCKED if the SPC is busy.

CYRET\_TIMEOUT if the operation timed out.

CYRET\_UNKNOWN if there was an SPC error.

Side Effects: None



#### cystatus EEPROM\_Write(uint8 \* rowData, uint8 rowNumber)

**Description:** Writes a row (16 bytes) of data to the EEPROM. This is a blocking call. It will not return

until the function succeeds or fails.

**Parameters:** uint8 \* rowData. Address of the data to write to the EEPROM.

uint8 rowNumber. EEPROM row number to program.

**Return Value:** CYRET\_SUCCESS if the operation was successful.

CYRET BAD PARAM if the parameters were invalid.

CYRET\_LOCKED if the SPC is busy.

CYRET\_TIMEOUT if the operation timed out.

CYRET\_UNKNOWN if there was an SPC error.

Side Effects: None

#### cystatus EEPROM\_StartWrite(uint8 \* rowData, uint8 rowNumber)

**Description:** Starts the SPC write function. This function does not block, it returns once the command

has begun the SPC write function. Once this function has been called the SPC will be locked until EEPROM QueryWrite() does not return CYRET STARTED. To abandon the

write, call CySpcUnlock() to unlock the SPC.

**Parameters:** uint8 \* rowData. Address of the data to write to the EEPROM.

uint8 rowNumber. EEPROM row number to program.

**Return Value:** CYRET\_STARTED if the SPC command to write was successfully started.

CYRET\_BAD\_PARAM if the parameters were invalid.

CYRET\_LOCKED if the SPC is busy.

CYRET\_TIMEOUT if the operation timed out.

CYRET\_UNKNOWN if there was an SPC error.

Side Effects: None

### cystatus EEPROM\_QueryWrite(void)

**Description:** Checks the state of a write to EEPROM. This function must be called until the return

value is not CYRET STARTED.

Parameters: void

**Return Value:** CYRET\_SUCCESS if the operation was successful.

CYRET\_BAD\_PARAM if the parameters were invalid.

CYRET\_LOCKED if the SPC is busy.

CYRET\_STARTED if the SPC command to write was successfully started.

CYRET\_TIMEOUT if the operation timed out. CYRET\_UNKNOWN if there was an SPC error.

Side Effects: None



## **Sample Firmware Source Code**

The following is a C language example demonstrating the basic functionality of the EEPROM component. This example assumes the component has been placed in a design with the default name "EEPROM\_1."

**Note** If you rename your component you must also edit the example code as appropriate to match the component name you specify.

```
#include <DEVICE.H>
void main(void)
    reg8 * eeProm;
   uint16 index;
    cystatus status;
    /* Erase all 2k. */
   EEPROM 1 EraseSector(0);
   EEPROM 1 EraseSector(1);
    /* Check to see if entire EEPROM is set to zeros. */
    eeProm = (reg8 *) CYDEV_EE_BASE;
    for(index = 0; index < CYDEV_EE_SIZE; index++)</pre>
        if(eeProm[index] != 0)
            /* Error condition. */
        }
    /* Acquire die temperature before using the write functions. */
    CySetTemp();
    /* Blocking method to write "0123456789ABCDEF" to EEPROM row 0 */
    status = EEPROM 1 Write("0123456789ABCDEF", 0);
    if(status != CYRET SUCCESS)
        /* Error condition. */
    }
    ^{\prime *} Polling method to write "0123456789ABCDEF" to EEPROM row 0 ^{*\prime}
    status = EEPROM_1_StartWrite("0123456789ABCDEF", 0);
    if(status != CYRET_STARTED)
        /* Error condition. */
    }
    do
        status = EEPROM_1_QueryWrite();
        /* Do something else. */
    } while(status == CYRET STARTED);
```



```
/* Check if an '0' was written to the first byte of the EEPROM. */
if(*eeProm != '0')
{
    /* Do something? */
}
if(status == CYRET_SUCCESS)
{
    /* Data was written. */
}
else
{
    /* Error condition. */
}
```

### **Functional Description**

Not applicable.

#### References

Refer also to the Die Temperature component data sheet.

© Cypress Semiconductor Corporation, 2009. The information contained herein is subject to change without notice. Cypress Semiconductor Corporation assumes no responsibility for the use of any circuitry other than circuitry embodied in a Cypress product. Nor does it convey or imply any license under patent or other rights. Cypress products are not warranted nor intended to be used for medical, life support, life saving, critical control or safety applications, unless pursuant to an express written agreement with Cypress. Furthermore, Cypress does not authorize its products for use as critical components in life-support systems where a malfunction or failure may reasonably be expected to result in significant injury to the user. The inclusion of Cypress products in life-support systems application implies that the manufacturer assumes all risk of such use and in doing so indemnifies Cypress against all charges.

PSoC® Creator™, Programmable System-on-Chip™, and PSoC Express™ are trademarks and PSoC® is a registered trademark of Cypress Semiconductor Corp. All other trademarks or registered trademarks referenced herein are property of the respective corporations.

Any Source Code (software and/or firmware) is owned by Cypress Semiconductor Corporation (Cypress) and is protected by and subject to worldwide patent protection (United States and foreign), United States copyright laws and international treaty provisions. Cypress hereby grants to licensee a personal, non-exclusive, non-transferable license to copy, use, modify, create derivative works of, and compile the Cypress Source Code and derivative works for the sole purpose of creating custom software and or firmware in support of licensee product to be used only in conjunction with a Cypress integrated circuit as specified in the applicable agreement. Any reproduction, modification, translation, compilation, or representation of this Source Code except as specified above is prohibited without the express written permission of Cypress.

Disclaimer: CYPRESS MAKES NO WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, WITH REGARD TO THIS MATERIAL, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. Cypress reserves the right to make changes without further notice to the materials described herein. Cypress does not assume any liability arising out of the application or use of any product or circuit described herein. Cypress does not authorize its products for use as critical components in life-support systems where a malfunction or failure may reasonably be expected to result in significant injury to the user. The inclusion of Cypress' product in a life-support systems application implies that the manufacturer assumes all risk of such use and in doing so indemnifies Cypress against all charges.

Use may be limited by and subject to the applicable Cypress software license agreement.

