Computer Vision I (922 U0610) - Homework 2

Author: alanhc ID: r10944007

Date: 9/30

README

- create env: conda env create -f environment.yml
- 2. enter env: conda activate ntu-cv
- 3. run jupyter jupyter notebook
- Write a program to generate:
 - (a) a binary image (threshold at 128)
 - (b) a histogram
 - (c) connected components(regions with + at centroid, bounding box)

```
In [1]:

from PIL import Image
import numpy as np

# Todo: 讀檔,確定影像大小
img = Image.open("input/lena.bmp")
img = np.array(img)
h, w = img.shape
print("image shape:", img.shape)
show = Image.fromarray(img).resize((256,256))
show
```

image shape: (512, 512)
Out[1]:



(a) - a binary image (threshold at 128)

```
In [2]:
# Todo: 建立一個128的閥值
# Algorithm:
## 1. pixel >= 128 set to 255 else set to 0

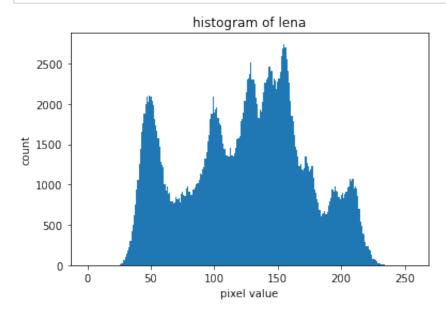
img_threshold = np.zeros((h,w), dtype="uint8")
for y in range(h):
    for x in range(w):
        img_threshold[y][x] = (255 if img[y][x]>=128 else 0) # 1.
    show = Image.fromarray(img_threshold).resize((256,256))
    show.save("output/1_lena_binary.png")
    show
```

Out[2]:



(b) - a histogram

```
In [3]:
         # Todo: 建立histogram
         # Algorithm:
         ## 1. 計算value的count
         ## 2. 畫圖,縱軸為次數,橫軸為pixel值
         count = np.zeros(256, dtype="int")
         for y in range(h):
            for x in range(w):
                count[ img[y][x] ]+=1
         # 2.
         import matplotlib.pyplot as plt
         plt.bar(range(256), count, width=1)
         plt.title("histogram of lena")
         plt.xlabel("pixel value")
        plt.ylabel("count")
         plt.savefig("output/2_lena_histogram.png")
```



(c) - connected components(regions with + at centroid, bounding box)

```
In [4]:
         # Todo: connected components (iterative)
         # Algorithm:
         ## 1. inital unique value
         ## 2. iteration of top-down by bottom-up pass until to change
         ## 3. draw bbox
         ## 1. inital unique value
         h, w = img_threshold.shape
         img_ccl = np.zeros((h+2,w+2)) #+2是因為 周圍留0,之後取最小值比較好做
         label=1
         for y in range(h):
            for x in range(w):
                if (img_threshold[y][x]>0):
                    img_ccl[y+1][x+1] = label
         print(h,w)
         plt.imshow(img_ccl)
```

plt.savefig("output/3_lena_ccl.png")

```
In [7]:
         ## 2. iteration of top-down by bottom-up pass until to change
         change = False
        i=0
         while True:
            change = False
             if i%2==0: #top-down
                start_y, end_y, d = 1, h-1, 1
                start_x, end_x, d = 1, h-1, 1
             else: #bottom-up
                start_y, end_y, d = h-2, 0, -1
                start_x, end_x, d = h-2, 0, -1
             _min = np.zeros(img_ccl.shape)
             for y in range(start_y, end_y, d):
                 for x in range(start_x, end_x, d):
                     # find min
                     window_min = 1e9
                     for w_y in range(y-1, y+2):
                         for w_x in range(x-1, x+2):
                             if img_ccl[ w_y ][ w_x ] < window_min and img_ccl[ w_y ][ w_x ]!=0:</pre>
                                 window_min = img_ccl[ w_y ][ w_x ]
                     # 填區域最小
                     if window_min!= img_ccl[y][x] and img_ccl[y][x]!=0:
                         img_ccl[y][x] = window_min
                         change = True
             i+=1
             if not change:
                break
         # 過濾小於 500次數的pixel,並畫出bbox
         img_ccl = img_ccl.astype(int)
         ct = np.zeros(h*w)
         pos = []
         for i in range(h*w):
             pos.append([])
         # 統計並計算每個component的座標
         for y in range(h):
             for x in range(w):
                 ct[ img_ccl[y+1][x+1] ] += 1
                 pos[ img_ccl[y+1][x+1] ].append([y,x])
         ## 3. draw bbox
         import cv2
         show = cv2.cvtColor(img_threshold, cv2.COLOR_GRAY2RGB)
         for _ct in ct[ ct > 500 ][1:]:
             idxs = np.where(ct == _ct)[0]
             for idx in idxs:
                 #左上座標即為x,y最小
                 start_point = [ int(np.array(pos[idx])[:,1].min()), int(np.array(pos[idx])[:,0].min()) ]
                 end_point = [ int(np.array(pos[idx])[:,1].max()), int(np.array(pos[idx])[:,0].max()) ]
                 #右下座標即為x,y最小
                 centroid = [int(np.array(pos[idx])[:,1].mean())-15, int(np.array(pos[idx])[:,0].mean())+10]
                 #重心即為x,y的平均 (mean),15,10為使十字置中的bias
                 show = cv2.rectangle(show, start_point, end_point, [0,0,255], 5)
                 show = cv2.putText(show, '+', centroid, cv2.FONT_HERSHEY_SIMPLEX,
                            1, [255,0,0], 3, cv2.LINE_AA)
         plt.imshow(show)
```

```
100 -
200 -
300 -
400 -
500 0 100 200 300 400 500
```

```
import matplotlib.pyplot as plt
filenames = ["1_lena_binary", "2_lena_histogram", "3_lena_ccl"]
plt.figure(figsize=(16,16))
for i in range(len(filenames)):
    p = plt.subplot(1, len(filenames), i+1)
    plt.imshow( Image.open("output/"+filenames[i]+".png") )
    plt.text(0.25, -0.1, filenames[i], transform=p.transAxes)
```

