

# Alankar Kotwal

SENIOR UNDERGRADUATE

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RESEARCH INTERESTS	I am passionate about Computer and Medical Vision, Machine Learning, Optimization, Estimation Theory, Astrophysics and Cosmology. I also like Robotics, Networks & Security and Graphics.	
EDUCATION	<b>Indian Institute of Technology Bombay</b> , Mumbai, India	<i>July 2012 – Present</i>
	Dual Degree, Bachelor & Master of Technology, Department of <a href="#">Electrical Engineering</a> Specialization: <i>Communication and Signal Processing</i> , <b>CGPA: 8.83/10.00</b>	
PUBLICATIONS	<ul style="list-style-type: none"><li>• Kotwal, A., Bhalodia, R., Awate, S., <i>Joint Desmoking and Denoising of Laparoscopy Images</i> (oral), Proc. of the <a href="#">International Symposium on Biomedical Imaging</a>, 2016. Paper <a href="#">here</a>.</li><li>• Clarke, J. D. A., Held, J. M., Dahl, A. <i>et al.</i>, <i>Field Robotics, Astrobiology and Mars Analogue Research on the Arkaroola Mars Robot Challenge Expedition</i>, Proc. of the <a href="#">14th Australian Space Research Conference</a>, 2014. Paper <a href="#">here</a>.</li></ul>	
RESEARCH INTERNSHIPS	<b>The AIR Lab, Carnegie Mellon University Robotics Institute</b> <i>Guide: Prof. Sebastian Scherer &amp; Stephen Nuske</i>	<i>Summer 2015</i>
	<b>Stereo Odometry From A Downward-Facing Stereo Camera On A Vehicle</b> <ul style="list-style-type: none"><li>• Developed correlation-based tracking for aerial vehicles with a downward-facing stereo camera</li><li>• Estimated height, pitch and roll jointly using a robust gradient-descent homography fit between stereo pairs, and position with rigid tracking across frames</li><li>• Achieved performance comparable to, maximum speeds and height ranges better than the standard Pixhawk PX4FLOW camera without an inertial unit</li></ul>	
	<b>Laboratory for Cosmological Data Mining, University of Illinois, Urbana–Champaign</b> <i>Guide: Prof. Robert Brunner, under Google Summer of Code</i>	<i>Summer 2014</i>
	<b>A Pixel-Level Machine Learning Method for Calculating Source Redshifts</b> <ul style="list-style-type: none"><li>• Used broad-band pixel energies from faint sources extracted from SDSS (as a proxy to their entire spectrum) as features for a machine learning algorithm to calculate redshifts</li><li>• Accomplished classification of sources into galaxies, stars and background based on pixel features</li><li>• Worked on creating an image extraction, alignment, cleaning, segmentation and learning pipeline on SDSS images and on performance improvement and got a reasonably good error rate</li></ul>	
RESEARCH PROJECTS	<b>A New Bayesian Framework For Laparoscopic Image Dehazing and Denoising</b> <i>Guide: Prof. Suyash Awate, CSE, IITB</i>	<i>January 2015 – Present</i>
	<ul style="list-style-type: none"><li>• Developed a Bayesian inference problem for jointly undoing the effect of surgical smoke and noise on laparoscopy images for better contrast and post-processing (like segmentation and tracking)</li><li>• Tested this method extensively on simulated and real images yielding significant improvement over state of the art dehazing algorithms in terms of numerical and perceptual accuracy</li><li>• Surveyed laparoscopy experts about quality of our results compared to the existing algorithms and found a statistically significant trend that this method yields superior results</li></ul>	
	<b>Coded Source Separation for Compressed Video Recovery</b> <i>Guide: Prof. Ajit Rajwade, CSE, and Prof. V. Rajbabu, EE, IITB</i>	<i>Dual Degree Thesis December 2015 – Present</i>
	<ul style="list-style-type: none"><li>• Studied applications of the principles of compressed sensing to video for compression along time</li><li>• Currently trying to relax the requirement of a dictionary on both space and time and the requirement of strictly smooth motion using a source-separation approach to this problem</li><li>• Aim to design positive <math>[0, 1]</math>-uniform sensing matrices with low mutual coherence, making them ideal for compressed video using the source-separation approach</li></ul>	
	<b>The IITB Mars Rover Project</b>	<i>May 2013 – Present</i>
	<ul style="list-style-type: none"><li>• Aim to build a prototype Mars rover capable of extra-terrestrial robotics, currently have a rover with a rocker-bogie suspension and novel air-filled beach tires</li><li>• Designed power, logic and communication circuits for on-board control and interfaced peripherals for perception and actuation, currently developing localization and autonomous navigation and exploring the role of machine vision for automating rover operations</li><li>• Participated in a simulated Martian expedition in the Australian outback, at the <a href="#">Arkaroola Mars Robot Challenge</a> and at the Mars Society's <a href="#">Mars Desert Research Station</a>, Utah</li></ul>	

COURSE PROJECTS	<b>Improved Methods for Compressed Sensing Recovery</b>	<i>CS709: Convex Optimization</i>
	Guide: <a href="#">Prof. Ganesh Ramakrishnan</a> , CSE, IITB	<i>Autumn 2015-16</i>
	Using convex approximations to the compressed sensing recovery problem, we reconstructed near-exact versions of images at extremely low compressions, with proofs of correctness. Code <a href="#">here</a> .	
	<b>Hidden Markov Model Part-of-Speech Tagging</b>	<i>EE638: Estimation and Identification</i>
	Guide: <a href="#">Prof. Navin Khaneja</a> , EE, IITB	<i>Autumn 2015-16</i>
ASTROPHYSICS PROJECTS	We implemented part-of-speech tagging with support for unknown words. An error rate of around 5% and capabilities of the system to discern context were observed.	
	<b>Laparoscopic Image Dehazing With Dark Channel Prior</b>	<i>CS736: Medical Image Processing</i>
	Guide: <a href="#">Prof. Suyash Awate</a> , CSE, IITB	<i>Spring 2014-15</i>
	We applied the Dark Channel Prior method for landscape image dehazing to surgical smoke-affected laparoscopic images, accelerated it in time and got good results.	
	<b>Stereo Odometry Via Point Cloud Registration</b>	<i>CS763: Computer Vision</i>
ASTROPHYSICS PROJECTS	Guide: <a href="#">Prof. Ajit Rajwade</a> , CSE, IITB	<i>Spring 2014-15</i>
	Maximizing kernel density correlation with gradient-ascent and coherent point drift, we registered pointclouds and observed good convergence behavior for small transformations.	
	<b>Gravitational Lens Separation With PCA</b>	<i>CS663: Digital Image Processing</i>
	Guide: <a href="#">Prof. Suyash Awate</a> and <a href="#">Prof. Ajit Rajwade</a> , CSE, IITB	<i>Autumn 2014-15</i>
	Gravitationally lensed images of galaxies have rare arc-like artifacts that can be used to calculate the mass of the lens. We used Anscombe denoising followed by PCA to build a basis for galaxy images and used the top few eigengalaxies to subtract sources and detect arcs.	
ASTROPHYSICS PROJECTS	<b>Detection of Short Gamma-ray Bursts from Astrosat Data</b>	<i>PH426: Astrophysics</i>
	Guide: <a href="#">Prof. Vikram Rentala</a> , PH, IITB	<i>Spring 2015-16</i>
	Among the open problems and new datasets in the field, we tackle detecting short gamma-ray bursts from data acquired by the CZTI Hard X-Ray Imager on board the Astrosat.	
	<b>Processing and Inference from CCD Images</b>	<i>NIUS, Astronomy</i>
	Guide: <a href="#">Prof. Priya Hasan</a> , MANUU, Hyderabad	<i>December 2015</i>
ASTROPHYSICS PROJECTS	We analyzed raw data for the globular cluster NGC2419 taken at the <a href="#">HCT</a> , post-processed it and extracted the variation of magnitudes of stars in the cluster on the scale of a day. Code <a href="#">here</a> .	
	<b>An X-Ray Study of Black Hole Candidate X Norma X-1</b>	<i>NIUS, Astronomy</i>
	Guide: <a href="#">Prof. Manojendu Choudhury</a> , Center for Basic Sciences	<i>December 2013</i>
	We analyzed spectral data for the X-Ray Binary 4U 1630-47, in a period that corresponds to an outburst in the source for various system parameters like internal radius, temperature and so on.	
	<b>Estimation of Photometric Redshifts Using Machine Learning</b>	<i>NIUS, Astronomy</i>
ACHIEVEMENTS AND AWARDS	Guide: <a href="#">Prof. Ninan Sajeeth Philip</a> , IUCAA, Pune	<i>December 2012</i>
	Here, we trained a neural network to calculate photometric redshifts and used SDSS data and its redshifted versions to train it, getting good predictions for redshift.	
	<b>Olympiads and Competitive Exams</b>	
	<ul style="list-style-type: none"> <li>Represented India at the <a href="#">6<sup>th</sup> International Olympiad on Astronomy and Astrophysics</a>, Brazil, 2012. Won a Gold Medal with International Rank 4 and a special prize for Best Data Analysis</li> <li>Represented India at the <a href="#">5<sup>th</sup> International Earth Sciences Olympiad</a>, Italy, 2011. Won a Bronze Medal and prizes for best performance in the Hydrosphere section and the team presentation</li> <li>Secured All India Rank (AIR) 105 in <a href="#">IIT-JEE</a> amongst 1.1 million candidates</li> </ul>	
	<b>Scholarships</b>	
TECHNICAL SKILLS	<ul style="list-style-type: none"> <li>Awarded <a href="#">KVPY Scholarship</a> 2011 by Dept. of Science and Technology, Govt. of India</li> <li>Awarded <a href="#">NTSE Scholarship</a> 2008 by NCERT, Govt. of India</li> </ul>	
	<b>Programming</b>	C/C++, Python, Bash, Matlab, Verilog, SQL, HTML, PHP, $\text{\LaTeX}$
	<b>Software Packages</b>	ROS/Gazebo, OpenCV, The Point Cloud Library, SPICE Circuit Simulation, EAGLE PCB Design, SolidWorks, AutoCAD, LabView
	<b>Science Software</b>	Python packages: NumPy, SciPy and Matplotlib, GNUPlot, Scikit-learn, Astropy, SExtractor, SDSS tools
	<b>Hardware</b>	Microprocessors: 8051, 8085, AVR and PIC, CPLDs and FPGAs, Embedded Platforms: Arduino, RaspberryPi, standard digital logic