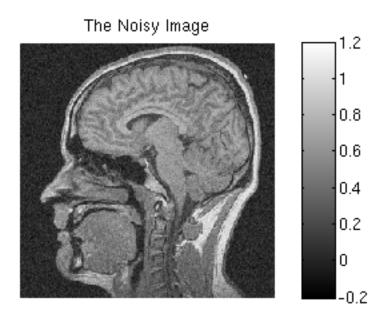
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## Riddhish Bhaodia and Alankar Kotwal: Assignment 2 -- Question 2

## Part B

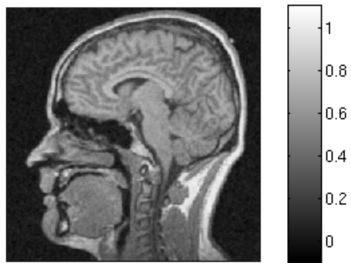
```
[noisy,denoisedquad,denoisedhuber,denoisedadap] = partB(input);
figure;
imshow(noisy,[]);
title('The Noisy Image');
colorbar;
colormap(gray(256)); axis image; axis off
figure;
imshow(denoisedquad,[]);
title('The output of quadratic prior filter');
colorbar;
colormap(gray(256)); axis image; axis off
figure;
imshow(denoisedhuber,[]);
title('The output of huber prior filter');
colormap(gray(256)); axis image; axis off
figure;
imshow(denoisedadap,[]);
title('The output of discontinuity adaptive prior filter');
colorbar;
colormap(gray(256)); axis image; axis off
        Warning: Displaying real part of complex input.
```



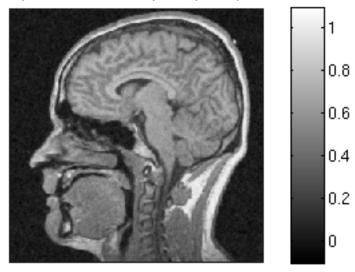
The output of quadratic prior filter



The output of huber prior filter



The output of discontinuity adaptive prior filter



## Part C

dummy = partC(input);
toc;

Elapsed time is 114.382701 seconds.

