

Workflow-Oriented Cyberinfrastructure for Sensor Data Analytics

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Four Kinds of Big Data

Archetypal

Science Projects

LHC, SKA, LSST

Business/Industry

Genomics, Finance

Government

NASA, NOAA, DOE

Crowd-Sourced

Social Media

Facebook, Twitter

Recommenders

Yelp, Angie, Groupon

Web Commerce

Amazon, Ebay

Long-tail

Science Projects

Small orgs, RDM

Personal

Hobbies, Citizen
Science/Arts

Government

Internal and
unpublished

Sensor Streams

Internet of Things

Appliances, Homes

Smart Cities

Energy grids,
Transportation

Health

Biosensors, ER,OR

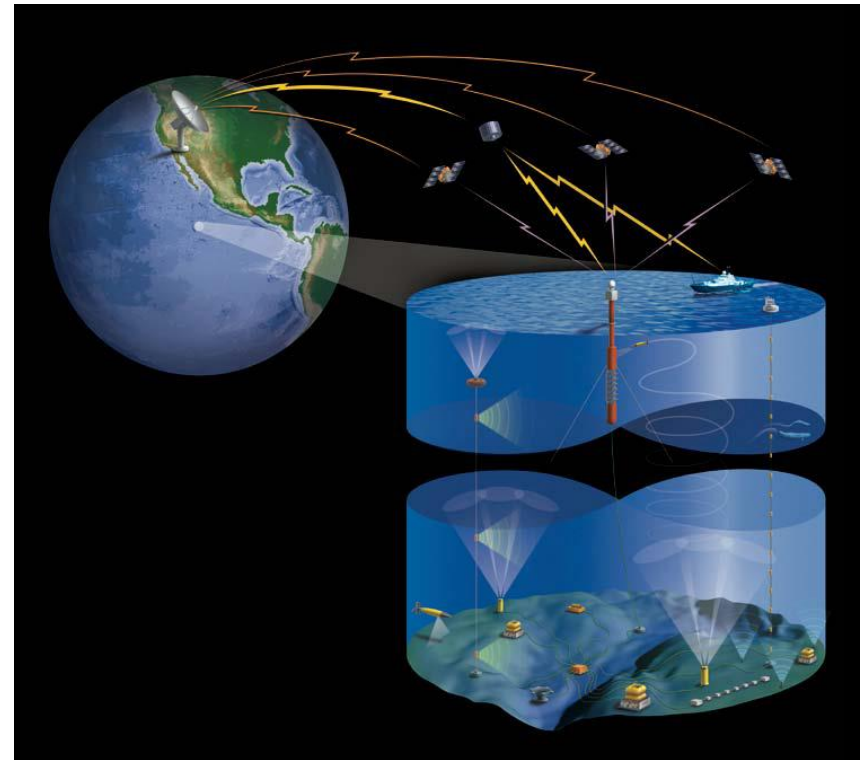
Characterization	Archetypal	Crowd-Sourced	Long-tail	Sensor Streams
Volume	High	High	High	High
Velocity	High	Bursty	Low	High
Variety	Low	High	High	High
Veracity	High	Mixed	Low	Mixed
Value	High	Ephemeral	Unknown	Huge
Findability	High	High	None	None
Availability	High	Short-term	None	Low

Sensor Data

What is a sensor? A sensor acquires a physical parameter and converts it into a signal suitable for processing (e.g. optical, electrical, mechanical)

Sensor data have some peculiar properties:

- Highly distributed network
- Time-related
 - Continuous
- Concept of infinite stream
- Volume – small to large packets
- Velocity – slow mostly
- Variety - Disparate
- Fusion is important
- Metadata is important
- Sensor Concentrators

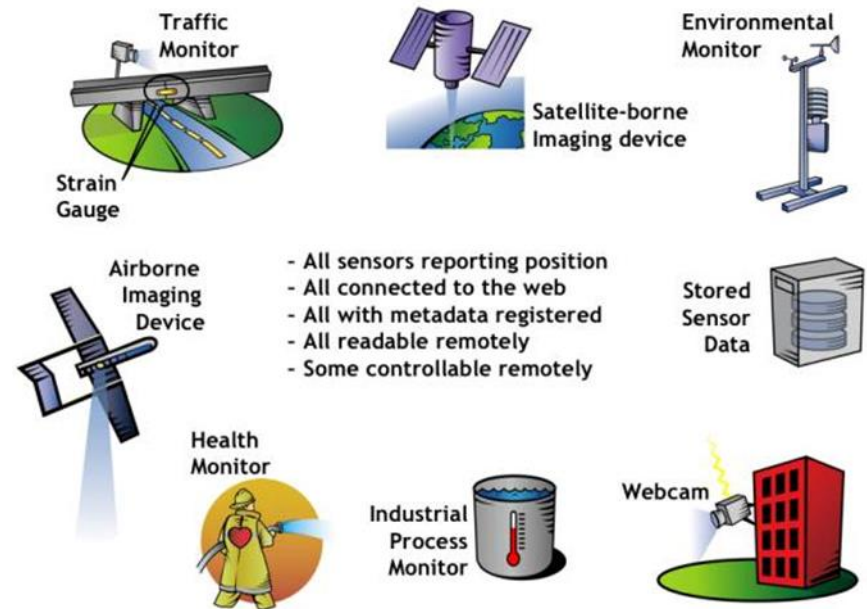


Sensors & DFC

- Multiple partners use sensor data
 - Marine, Seismic & Environment Science (SciON)
 - Hydrology (Hydroshare)
 - Engineering (Smart Cities)
 - Cognitive Science (TDLC)
 - Biology (CyShare)

- DFC development activities:

- Access to sensor data
 - Access control, Authentication,...
- Export to Standard formats
- Archiving of sensor data
 - Reuse & Repurpose
- Integrated Metadata & Discovery
- Integrate into Tools & Workflows
- **Playback: Synchronized**



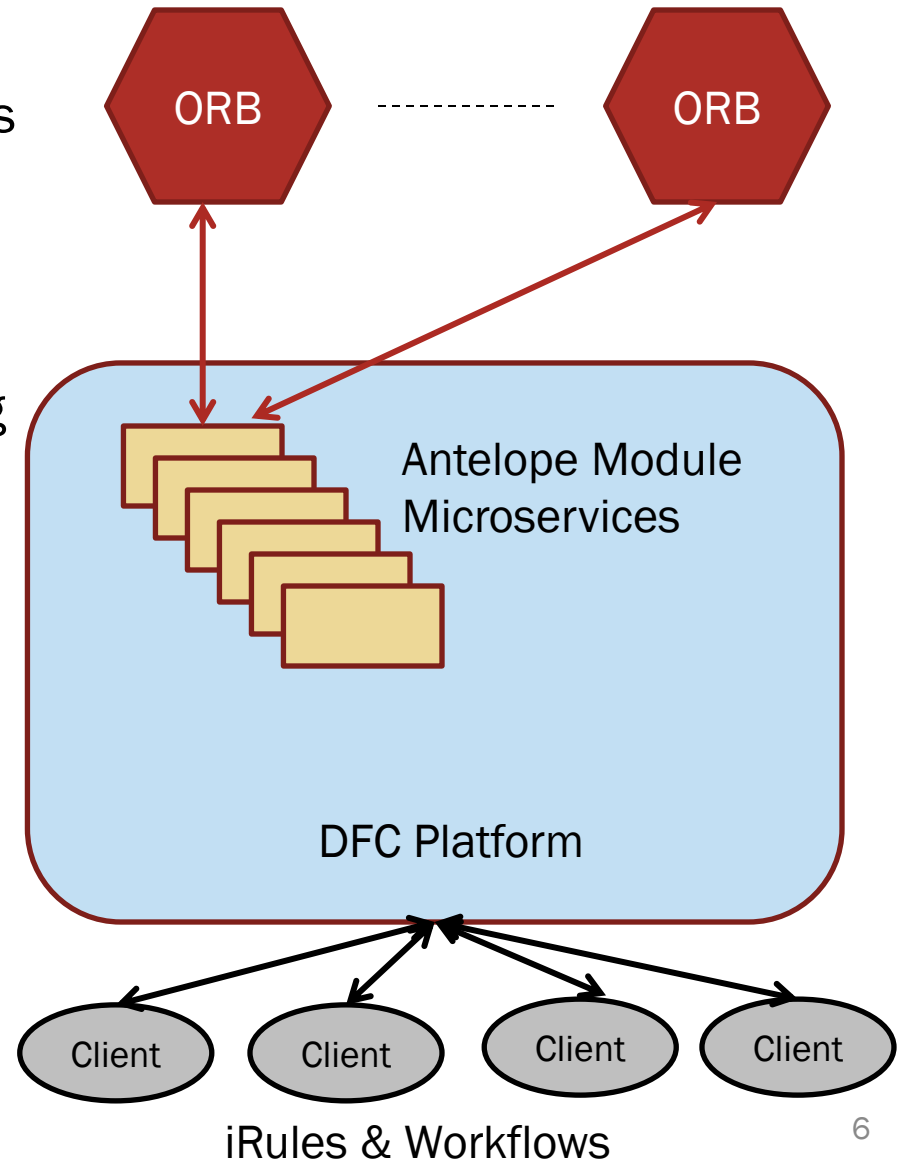
Antelope Real Time System

- **Concentrator**
 - Used by multiple projects
 - High performance Object Ring Buffer
 - Multiple types of sensor
 - Stream processing
 - Network of ORBs
 - Used by UCSD SIO



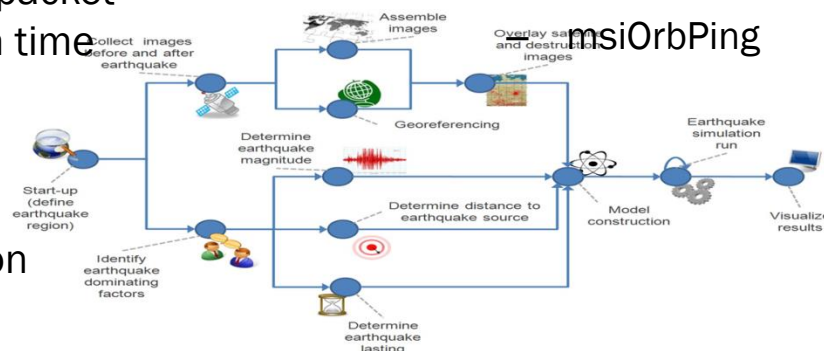
DFC & Antelope

- Loosely-coupled federation
- Connection through Microservices
- Can define MSO for each orb stream
- Can be added to Workflows
- Provide access without burdening ARTS Administrators
- Implementation:
 - Reap Sensor Streams
 - Convert Formats
 - Store Streams as Files
 - Access Packets from Files
 - Push Files as Streams
 - Use Rules to Archive



DFC Antelope Microservices

- Single Packet Microservices
 - msiAntelopeGet - get a packet
 - msiAntelopePut - put a packet
- Connection Microservices
 - msiOrbOpen
 - msiOrbClose
 - msiOrbTell - redirect to an orb
- Stream-level Microservices
 - msiOrbSelect - select streams
 - msiOrbReject - reject streams
 - msiOrbPosition - position read pointer by packetid
 - msiOrbSeek - position read pointer by skipping packet
 - msiOrbAfter - seek with time
- Other Helpers
 - convertExec - format conversion
 - readLine
- Packet Low-level Access (read, write) Microservices
 - msiOrbGet - get current packet
 - msiOrbReap - get next packet
 - msiOrbReapTimeout
 - msiOrbPut - push a packet
- Packet Manipulation Microservices
 - msiOrbUnstuffPkt
 - msiFreeUnstuffPkt
 - msiOrbDecodePkt
 - msiOrbStuffPkt
 - msiOrbEncodePkt
- ARTS Heartbeat Microservices
 - msiOrbStat
 - msiOrbPing



Reaping Rules

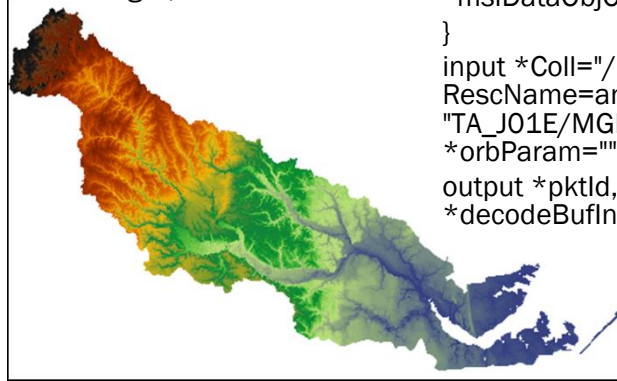
```

antelopRule{
  delay("<PLUSET>30s</PLUSET><EF>10m</EF>") {
    msiAddKeyVal(*KVP,"selectCriteria",*pktSelectInfo);
    msiAntelopeGet(*pktSelectInfo,*firstPktId,*lastPktId,
                  *NumOfPkts,*outBufParam);
    *SColl = *Coll ++ "/" ++ *Sensor
    *SFile = *SColl ++ "/" ++ "firstPktId" ++ "_" ++ "lastPktId" ++ ".data";
    msiCollCreate(*SColl,"1",*STAT_1);
    msiDataObjCreate(*SFile,*Resc,*D_FD);
    msiDataObjWrite(*D_FD,*outBufParam,*WR_LN);
    msiDataObjClose(*D_FD,*STAT_2);
    msiAddKeyVal(*KVP,"firstPktId","firstPktId");
    msiAddKeyVal(*KVP,"lastPktId","lastPktId");
    msiAddKeyVal(*KVP,"numOfPkts","NumOfPkts");
    msiAssociateKeyValuePairsToObj(*KVP,*SFile,"-d");
  }
  writeLine("stdout","Delayed Rule Launched");
}

input
*pktSelectInfo="<ORBHOST>anfexport.ucsd.edu:cascadia</ORBHOST>
<ORBSELECT>TA_M04C/MGENC/EP40</ORBSELECT>
<ORBWHICH>ORBOLDEST</ORBWHICH>
<ORBNUMOFPKTS>8</ORBNUMOFPKTS>
<ORBNUMBULKREADS>4</ORBNUMBULKREADS>",
*Resc="destRescName=anfdemoResc++++forceFlag=",
*Coll="/rajaanf/home/rods/SensorData",
*Sensor="TA/M04C/MGENC/EP40"
output ruleExecOut

```

Continuous Reaper



Reap and Convert

```

antelopRule{
  #Get Packet
  msiOrbOpen(*orbHost,*orbParam,*orbld);
  msiOrbSelect(*orbld,*Sensor,*sresOut);
  msiOrbReap(*orbld,*pktId,*srcName,*oTime,*pktOut,*nBytes,
            *resOut);
  msiOrbDecodePkt(*orbld,*modeln,*srcName,*oTime,*pktOut,
                *nBytes,*decodeBufInOut);
  msiOrbClose(*orbld);
  #Store Packet
  *SColl = *Coll ++ "/" ++ *Sensor
  *SFile = *SColl ++ "/" ++ "waveform.data";
  msiCollCreate(*SColl,"1",*STAT_1);
  openForAppendOrCreate(*SFile,*Resc,*D_FD);
  msiDataObjWrite(*D_FD,*decodeBufInOut,*WR_LN);
  msiDataObjClose(*D_FD,*STAT_2);
}

openForAppendOrCreate(*SFile,*Resc,*D_FD) {
  *SObj = "objPath=" ++ *SFile ++ "++++openFlags=O_RDWR";
  msiDataObjOpen(*SObj,*D_FD);
  msiDataObjLseek(*D_FD,*Offset,*Loc,*Status1);
}

openForAppendOrCreate(*SFile,*Resc,*D_FD) {
  msiDataObjCreate(*SFile,*Resc,*D_FD);
}

input *Coll="/rajaanf/home/rods/newsenstest",*Resc="dest
RescName=anfdemoResc++++forceFlag=",*Sensor=
"TA_J01E/MGENC/SM100",*orbHost="anfexport.ucsd.edu:cascadia",
*orbParam="",*modeln=2,*Offset="0",*Loc="SEEK_END"
output *pktId,*srcName,*oTime,*nBytes,*pktOut,
*decodeBufInOut,ruleExecOut

```


Interactive Packet Ingestion

Ingest Rules

Orb2Orb: Reaped Packet Ingestion

```

antelopRule{
  msiAntelopePut(*orbName, *srcName, *timeStamp,
    *pktPayLoad);
}
input *orbName="anfdevl.ucsd.edu:demo",
  *srcName="DFC_UNC/ch/T1", *timeStamp="",
  *pktPayLoad="$test 3 string"
output ruleExecOut

```

```
#get a MGENC packet from cascadia and put it in demo
```

```
# also write also in a file to compare
```

```
antelopRule{
```

```
# get the packet and the write into file
```

```
  msiAntelopeGet(*pktSelectInfo, *firstPktId, *lastPktId,
    *NumOfPkts, *outBufParam);
```

```
  *SColl = *Coll ++ "/" ++ *Sensor
```

```
  *SFile = *SColl ++ "/" ++ "firstPktId" ++ "_" ++ "lastPktId" ++ ".data";
```

```
  msiCollCreate(*SColl, "1", *STAT_1);
```

```
  msiDataObjCreate(*SFile, *Resc, *D_FD);
```

```
  msiDataObjWrite(*D_FD, *outBufParam, *WR_LN);
```

```
  msiDataObjClose(*D_FD, *STAT_2);
```

```
# write to orb
```

```
  msiAntelopePut(*orbName, *srcName, *timeStamp, *outBufParam);
```

```
}
```

```
input *pktSelectInfo="<ORBHOST>anfexport.ucsd.edu:cascadia</ORBHOST>
```

```
<ORBSELECT>TA_J01E/MGENC/SM1</ORBSELECT>
```

```
<ORBWHICH>ORBOLDEST</ORBWHICH>
```

```
<ORBNUMOFPKTS>1</ORBNUMOFPKTS>
```

```
<ORBNUMBULKREADS>1</ORBNUMBULKREADS>
```

```
<ORBPresentation>ONEPKT</ORBPresentation>",
```

```
*Resc="destRescName=anfdemoResc++++forceFlag=",
```

```
*Coll="/rajaanf/home/rods/SensorData", *Sensor="TA_J01E_MGENC_SM1",
```

```
*orbName="anfdevl.ucsd.edu:demo
```

```
", *srcName="DFC_UNC/MGENC/T1", *timeStamp=""
```

```
output *outBufParam, *firstPktId, *lastPktId, *NumOfPkts, ruleExecOut
```

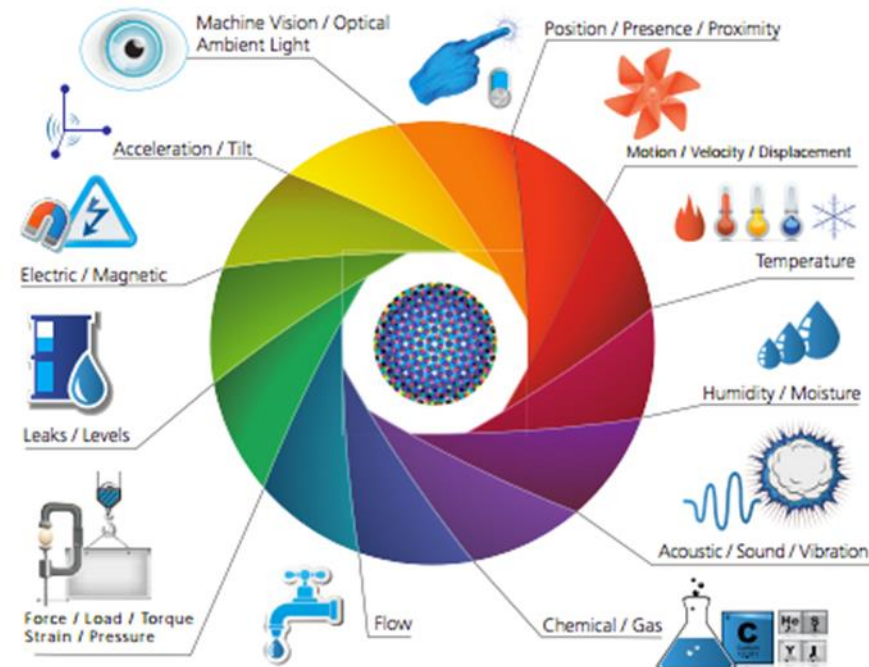


Sensor Data in DFC

- Sensor streams are stored as files in DFC:
 - Raw Orb format – buffer
 - CDL format - Common Data form Language a human-readable text representation of *netCDF* data
 - NC format: NetCDF Format
 - NetCDF 4 – version 4
 - HDF5 compatible
 - Use 'ncgen' for conversion
 - JSON – human-readable format
- Multi-type Sensor's reaped
 - Seismic Sensor
 - 3 sensor measurement per packet
 - North, East, Vertical Movements
 - Pressure Sensor
 - 2 sensor measurement per packet
 - Barometric Pressure, Infrasound

1 SENSORS & ACTUATORS

We are giving our world a digital nervous system. Location data using GPS sensors. Eyes and ears using cameras and microphones, along with sensory organs that can measure everything from temperature to pressure changes.



Sample Data Files

```
netcdf barometric_pressure {
types:
```

```
compound pressure_vector_t {
  double timestamp;
  float pressure;
  float infrasound;
}; // barometric_vector_t
```

```
dimensions:
```

```
time = UNLIMITED;
```

```
variables:
```

```
pressure_vector_t barometric(time);
```

```
barometric:standard_name = "two vector barometric pressure
```

```
data";
```

```
barometric:long_name = "Barometric";
```

```
// global attributes:
```

```
:srcname = "TA_003E/MGENC/EP1";
```

```
:packimetype = "waveform";
```

```
:net = "TA";
```

```
:sta = "003E";
```

```
:chan = "LDO";
```

```
:loc = "EP";
```

```
:sampleratepersec = "1.000";
```

```
:calib = "1";
```

```
:calper = "-1.000";
```

```
:segtype = "5s";
```

```
:nsamps = "120";
```

```
:epochtime = "1446064294.9710000";
```

```
:epochstarttime = "Wed 2015-301 Oct 28 20:31:34.97100";
```

```
:epochendtime = "20:33:34.97100";
```

```
data:
```

```
barometric =
```

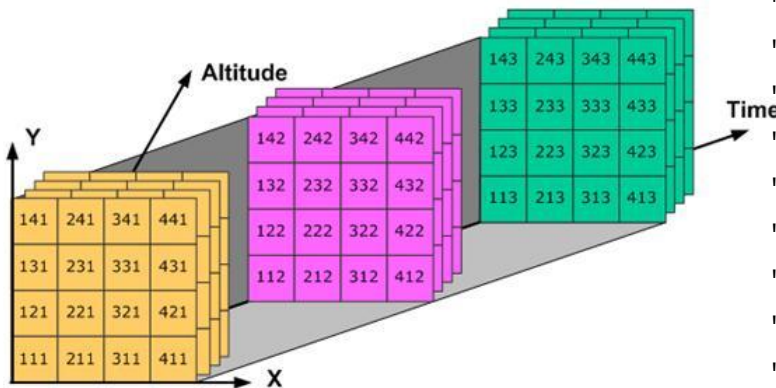
```
{1446064294.9710000, 717022, 10159},
```

```
{1446064295.9710000, 717021, 8821},
```

```
{1446064296.9710000, 717023, 15918},
```

```
{1446064297.9710000, 717026, 21402},
```

CDL Format
Pressure Data



```
"packets":[
```

```
{
```

```
"srcname":"TA_J01E/MGENC/SM100",
```

```
"pktttime":" 6/25/2015 (176) 0:30:23.968",
```

```
"bytes":"535",
```

```
"packimetype":"waveform",
```

```
"channels":[
```

```
{
```

```
"channum":" 0",
```

```
"net":"TA",
```

```
"sta":"J01E",
```

```
"chan":"HNZ",
```

```
"loc":"",
```

```
"sampleratepersec":"100.000",
```

```
"calib":" 1",
```

```
"calper":"-1.000",
```

```
"segtype":"5s",
```

```
"nsamps":"100",
```

```
"epochtime":"1435192223.9683931",
```

```
"epochstarttime":"Thu 2015-176 Jun 25
```

```
0:30:23.96839",
```

```
"epochendtime":" 0:30:24.96839",
```

```
"data":[
```

```
{ "v": -52727 },
```

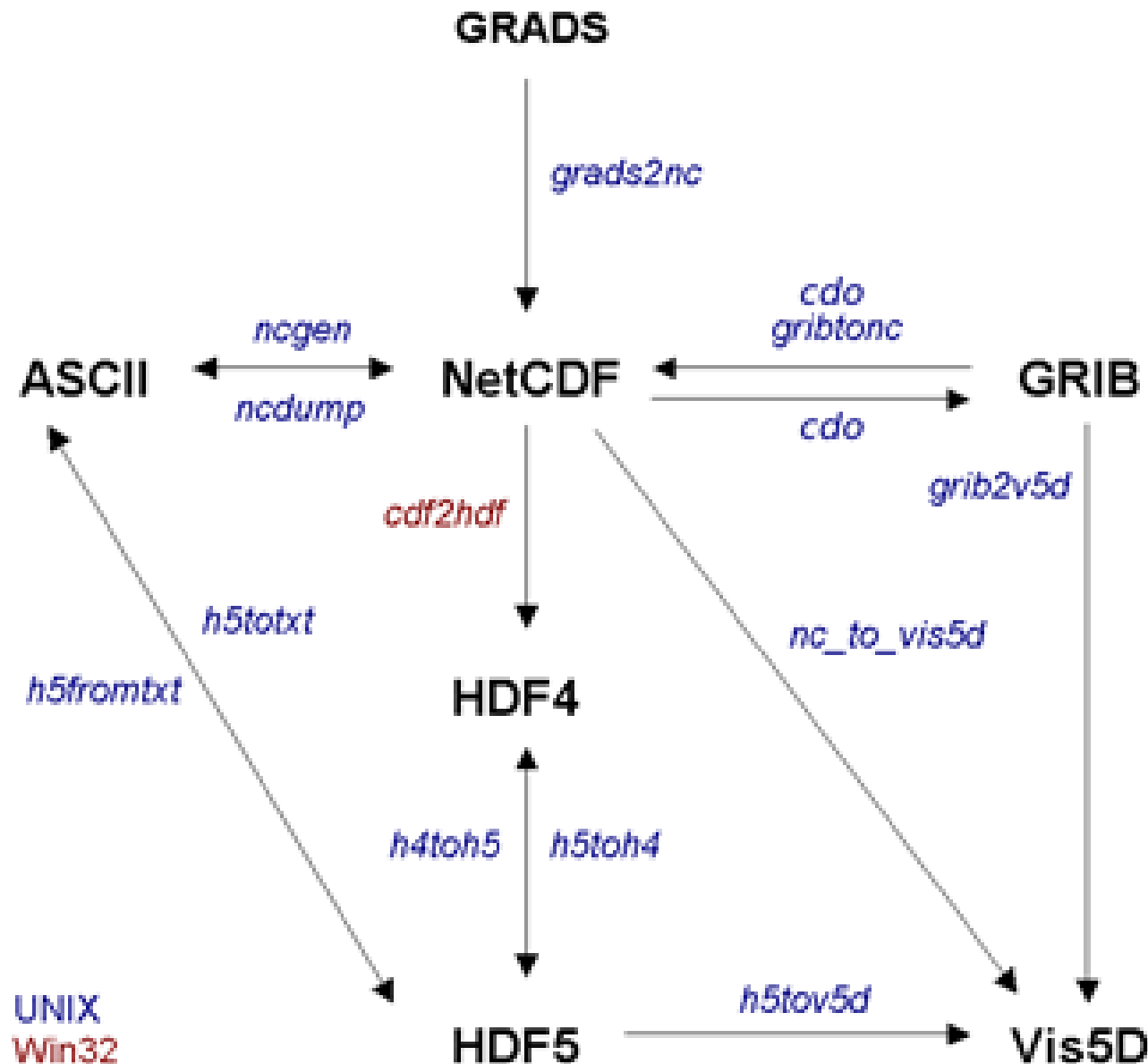
```
{ "v": -52729 },
```

```
{ "v": -52729 },
```

```
{ "v": -52731 },
```

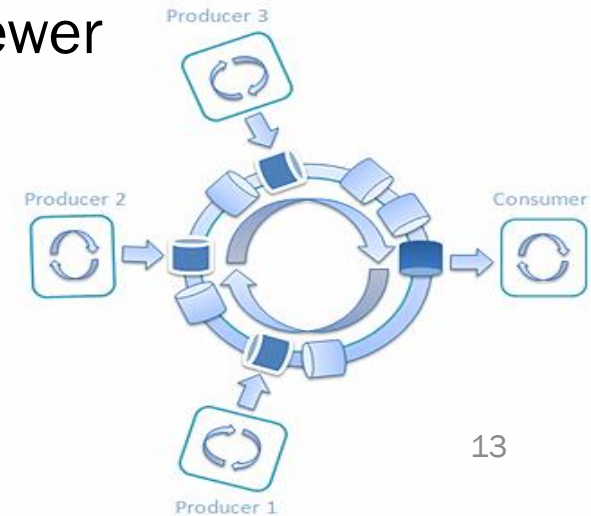
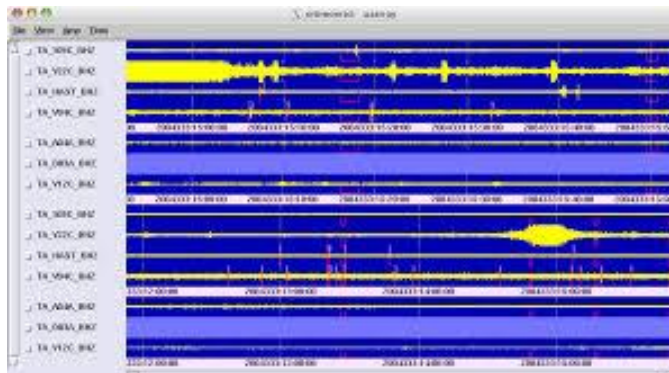
JSON Format
Seismic Data

Formats

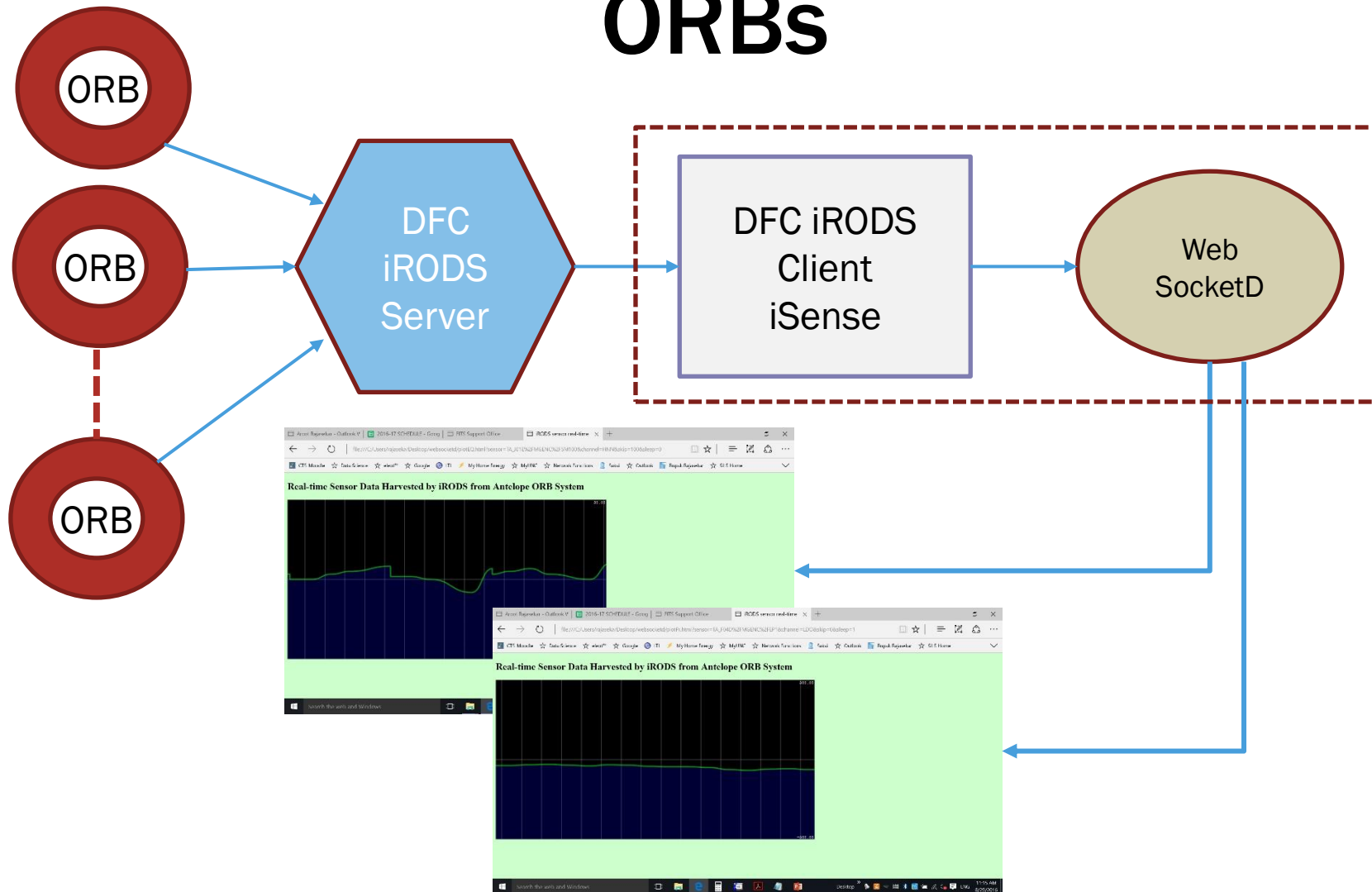


Types of Operation Supported

- Reap 8 Packets as buffers
- Low level Reap
- Archive One Packet in JSON Format
- Archive Multiple Packet in NetCDF CDL Format
- Archive Pressure Data in NetCDF CDL Format
- Convert CDL to NC Format
- Ingest Character Packet
- Access Ingested Packet
- Orb2Orb Copy of Seismic Waveform Packet
- Access NetCDF File from DFC using Cloud Browser
- Show Plots Using HDFViewer



Real-time Sensor Data from ORBs



Sensor Web Pages

Arcot Rajasekar - Outlook V | 2016-17 SC

file:///C:/Users/rajasek

CTS-Moodle ☆ Data Science ☆ eleot™

Sensor name:
TA_F04D/MGENC/EP1

Channel name:
barometric pressure

Submit

Environmental Sensor WebPage

Arcot Rajasekar - Outlook V | 2016-17 SCHEDULE - Goog

file:///C:/Users/rajaseka/Desktop/w

CTS-Moodle ☆ Data Science ☆ eleot™ ☆ Google

Sensor name:
TA_F04D/MGENC/EP1

Channel name:
barometric pressure
infrasound pressure

Submit

Arcot Rajasekar - Outlook V | 2016-17 SCHEDULE - Goog | FITS Support Office

file:///C:/Users/rajaseka/Desktop/websocketd/plotPressureSensor.h

CTS-Moodle ☆ Data Science ☆ eleot™ ☆ Google LTL My Home Energy

Sensor name:

TA_F04D/MGENC/EP1
TA_F04D/MGENC/EP40
TA_G03D/MGENC/EP1
TA_G03D/MGENC/EP40
TA_G05D/MGENC/EP1
TA_G05D/MGENC/EP40
TA_H04D/MGENC/EP1
TA_H04D/MGENC/EP40
TA_I02E/MGENC/EP1
TA_I02E/MGENC/EP40
TA_I03D/MGENC/EP1
TA_I03D/MGENC/EP40
TA_I04A/MGENC/EP1
TA_I04A/MGENC/EP40
TA_I05D/MGENC/EP1
TA_I05D/MGENC/EP40
TA_J01E/MGENC/EP1
TA_J01E/MGENC/EP40
TA_J04D/MGENC/EP1
TA_J04D/MGENC/EP40
TA_J05D/MGENC/EP1
TA_J05D/MGENC/EP40
TA_K02D/MGENC/EP1
TA_K02D/MGENC/EP40
TA_K04D/MGENC/EP1
TA_K04D/MGENC/EP40
TA_L02F/MGENC/EP1
TA_L02F/MGENC/EP40
TA_L04D/MGENC/EP1
TA_L04D/MGENC/EP40

Arcot Rajasekar - Outlook V | 2016-

file:///C:/Users/ra

CTS-Moodle ☆ Data Science ☆ eleot™

Sensor name:
TA_JO1E/MGENC/M1

Channel name:
North

Submit

Earthquake Sensor WebPage

Select Channel

Select Env. Sensors



Search the web and Windows



Conclusion

- Real-time Access to Sensor Data
 - Not just archiving
- Access to any sensor that is available through an ORB
 - No need for registration
- Control sensor data flow
 - Select Sensor
 - From multi-sensor packet streams
 - Sub sample
 - For high frequency data
 - Eg. Send only one value per second
 - Stretch data flow
 - From multi-value packets
 - Eg. 60 per second values in single packet
- Provision Access through the web
 - Using websocketd

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We are giving our world a digital nervous system. Location data using GPS sensors. Eyes and ears using cameras and microphones, along with sensory organs that can measure everything from temperature to pressure changes.

