AAHLS Final Report - Handwritten number Generation

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1. Problem statement

In this final project, we make a handwritten number generation accelerator with MNIST dataset, which have 60000 images with 0 to 9 handwritten number. Next, we train a Generative Adversarial Network (GAN) to generate the handwritten number image. In this accelerator, we only use the generator network to accelerate the image generation. The generator network will get random noise vector input, and output the generated image. Our generator model architecture is 3 layer fully-connected model, with 100 dimensional noise vector input, and 28*28 image output.

The target platform of our accelerator is PYNQ-Z2, a resource constraint FPGA device on edge. Without using the Xilinx framework – FINN, a Pytorch framework with Binary Neural Network, and compile to the HLS, we write the HLS to build our model accelerator by ourselves. Finally, we want to achieve the higher throughput than CPU and GPU. We run the Pytorch model and get 2951.24 FPS on CPU and 1333.21 FPS on GPU.

2. System overview

The system operation flow is

- 1. Generate random input from PS side.
- 2. Transfer the input from PS side to PL side.
- 3. Calculate each layer of fully-connected model in PL side.
- 4. Receive the output from PL side in PS side
- 5. Show the result in PS side.

3. INT8 Fully-connected model

First, we use the Pytorch framework to train the generator model. In Figure 1, it has three fully-connected layer, which have 256, 512, 784 nodes in each layer. After each layer, it follows an activation layer ReLU or Tanh.

```
class generator(nn. Module):
        def __init__(self):
                super(generator, self).__init__()
                self.quant = torch.quantization.QuantStub()
self.dequant = torch.quantization.DeQuantStub()
                self.main = nn.Sequential(
                        nn.Linear(100, 256, bias=False),
                         nn.ReLU(),
                         nn.Linear(256, 512, bias=False),
                        nn.ReLU(),
                         nn.Linear(512, 784, bias=False),
                         nn. Tanh()
        def forward(self, input):
              y = self.quant(input)
                y = self.main(y)
               y = self.dequant(y)
               return v
```

Figure 1 · Generator model architecture in Pytorch.

Next, we need to quantize our model because we can't store the full Float32 weight on FPGA, the resource on FPGA is limited. Therefore, we quantized the weight into INT8 to save the resource usage. The weight become a quarter with the Float32 to INT8 quantization, and the formula to transfer real value into quantized value is in below

```
real\_value = scale(quant\_value - zero\_point)
```

Next, we accumulate the activation in 32-bit integer and quantize the activation into 8-bit integer by the input and output scales and zero points.

In the baseline architecture, we try to make the accelerator outputs the correct value same with the golden file, and the first fully-connected layer HLS code is in Figure 2. After writing the three layers of the model, we synthesis with the clock in 10 ns, and the synthesis summary report is in Figure 3.

Figure 2 · FC1 HLS code.

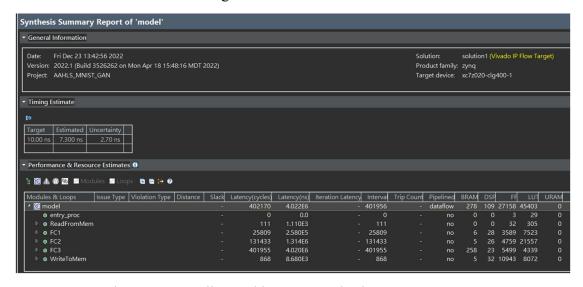


Figure 3 · Baseline architecture synthesis summary report.

According to the high usage of DSP and LUT, we merge the scaling factor and zero points into a single floating point value, in order to reduce the number of floating points multiplication and division, the first fully-connected layer HLS code is in Figure 4.

Figure 4 · FC1 HLS code.

The other optimization is changing the Tanh activation in the last fully-connected layer into HardTanh. This optimization will reduce the resource usage with a little error from the original output. The Tanh and HardTanh equation is below.

$$Tanh(x) = \frac{e^{2x} - 1}{e^{2x} + 1}$$

$$HardTanh(x) = \begin{cases} 1, & \text{if } x > 1 \\ -1, & \text{if } x < -1 \\ x, & \text{otherwise} \end{cases}$$

Finally, the synthesis summary report is in Figure 5. We can see the DSP and LUT usage reduced, but the latency didn't reduce because most of the latency in the layer is accumulation, so we need to do other optimization.

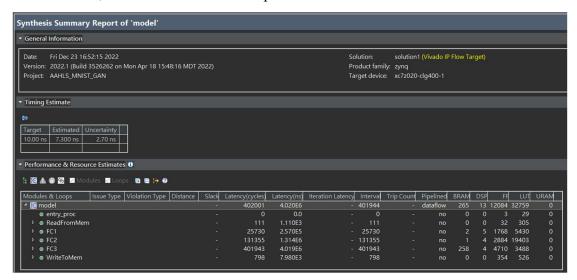


Figure 5 \ Kernel optimization 1 architecture synthesis summary report.

To reduce the kernel latency, we need more PE to calculate the multiplication between inputs and weights at the same time. Therefore, we unroll the inner for loop to calculate the value and accumulation for multiple PEs. As the result in Figure 6, the HLS code of last fully-connected layer have 8 PE for calculation.

Figure 6 • FC3 HLS code.

The synthesis summary report is in Figure 7, we can see latency of second and third layer reduce very much, and the bottleneck layer is third fully-connected layer. Each input vector needs almost 66000 cycles to output an image, like the third fully-connected layer.

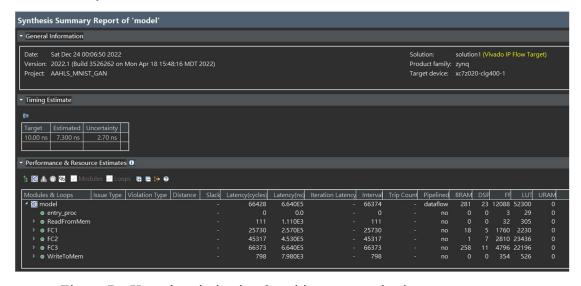


Figure 7 · Kernel optimization 2 architecture synthesis summary report.

Finally, we modified the streaming interface between each kernel into the pingpong buffer. The HLS code of second and third fully-connected layer is in Figure 8.

Figure 8 · FC2 and FC3 HLS code.

The synthesis summary report is in Figure 9, and the Co-simulation timeline report is in Figure 10. We can see when the first fully-connected layer finish first task, it can start the second task. Therefore, it can increase the throughput of the generator model.

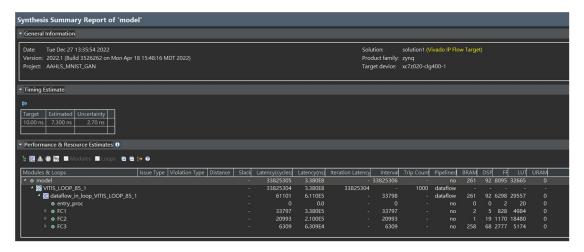


Figure 9 · Kernel optimization 3 architecture synthesis summary report.

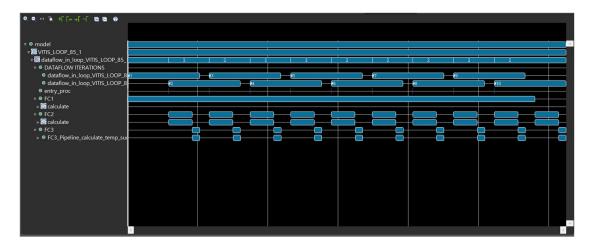


Figure 10 · Kernel optimization 3 architecture co-simulation report.

4. PYNQ-Z2 result

Finally, we put the RTL design generated from Vitis HLS into Vivado, and the block design is in Figure 11. The utilization in post-implementation is in Figure 12. The LUT usage is 58%, FF usage is 10%, BRAM usage is 94%, DSP usage is 42%. The FPGA device usage is in Figure 13.

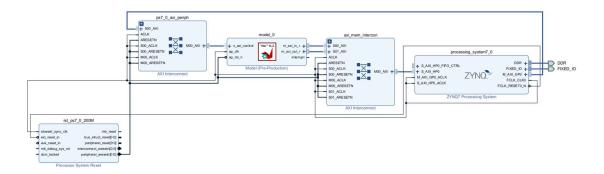


Figure 11 · Block design of generator model.

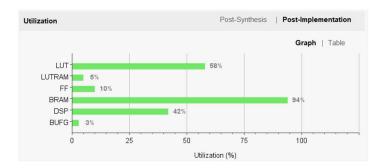


Figure 12 · Utilization.

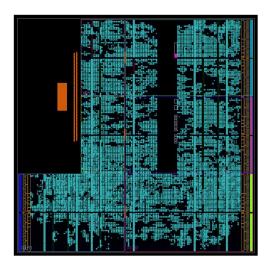


Figure 13 · FPGA device usage.

The result on the PYNQ-Z2 shows in Figure 14. Import the overlay and bitstream generated from Vivado, record the start time and end time of the accelerator generating 1000 images, the throughput is 1575.85 FPS.

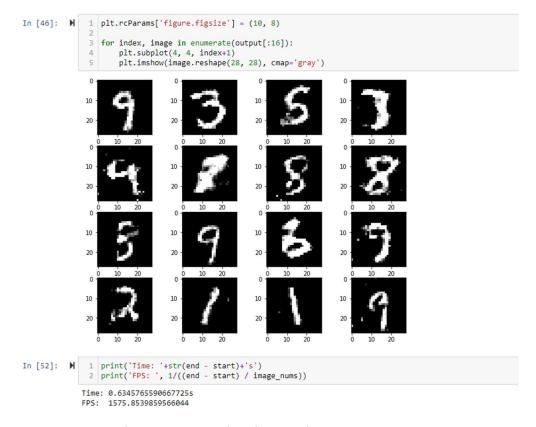


Figure 14 · Accelerating result on PYNQ-Z2.

Next, we change the ZYNQ7 Processing System PL clock from 100 MHz to 200 MHz, and get the result on PYNQ-Z2 in Figure 15. We get the throughput in 3008.36

FPS, which is higher than 2951.24 FPS on CPU and 1333.21 FPS on GPU. It achieves the higher throughput compare to CPU and GPU on our accelerator.

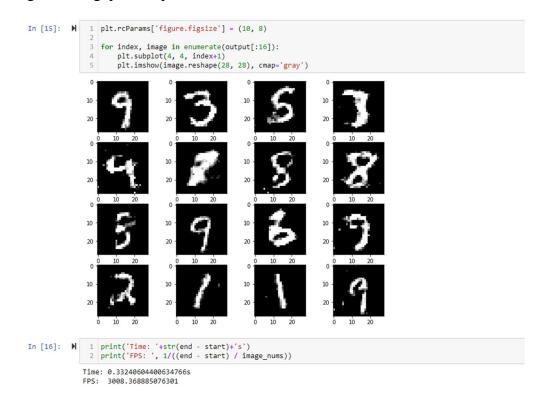


Figure 15 · Accelerating result on PYNQ-Z2.

5. Conclusion

In this final project, we learn how to build a neural network model accelerator on FPGA without using FINN. Otherwise, we learn how to use streaming interface connection between multiple kernels. The experience we learned improve our HLS skills. In the future, we can try to implement more neural network architecture, like convolution, and we can try much lower-bit weight and activation accelerator, like 4-bit, 2-bit or binary neural network.

6. GitHub Link

https://github.com/alankuo04/AAHLS Final