



EE 242, Win 2022
Homework 3a

HW3 Topics: convolution, LTI systems, impulse response, step response
HW3 References: Lectures 7-10

NOTE: You will notice that some selected problems are given answers through "Show that" statements. Make sure you show all your work clearly for every problem.
Throughout the assignment, $u(t)$ is the unit step function, $r(t) = tu(t)$ and $p(t) = u(t) - u(t-1)$

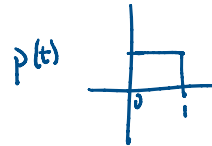
HW3 Problems:

For each of the following LTI systems, compute the system's impulse response $h(t)$ such that:

$$y(t) = (x * h)(t) = \int_{-\infty}^{\infty} x(\tau)h(t-\tau)d\tau$$

If the system is not LTI, show that this is the case.

- a) $y(t) = u(t) \sum_{k=-1}^1 \left(\frac{1}{2}\right)^{|k|} x(t-k)$
b) $y(t) = \int_0^t \tau^a x(t-\tau)d\tau$
c) $y(t) = \int_{-\infty}^t e^{-(t-\tau)} x(\tau)d\tau$
d) $y[n] = -\frac{1}{8}x[n-3] - \frac{1}{4}x[n-2] - \frac{1}{2}x[n-1]$



$$\begin{aligned} \text{a) } ay(t) &= a \sum_{k=-1}^1 \left(\frac{1}{2}\right)^{|k|} x(t-k) \\ ay_1(t) + by_2(t) &= a \sum_{k=-1}^1 \left(\frac{1}{2}\right)^{|k|} x_1(t-k) + b \sum_{k=-1}^1 \left(\frac{1}{2}\right)^{|k|} x_2(t-k) \\ &= \sum_{k=-1}^1 \left(\frac{1}{2}\right)^{|k|} (ax_1(t-k) + bx_2(t-k)) \end{aligned}$$

} same, linear

$$\mathcal{T}\{ax_1(t)\} = \sum_{k=-1}^1 \left(\frac{1}{2}\right)^{|k|} (ax_1(t-k) + bx_2(t-k))$$

$$y(t-t_0) = \sum_{k=-1}^1 \left(\frac{1}{2}\right)^{|k|} x(t-t_0-k)$$

$$\mathcal{T}\{x(t-t_0)\} = \sum_{k=-1}^1 \left(\frac{1}{2}\right)^{|k|} x(t-k-t_0) \quad \left. \begin{array}{l} \text{same} \\ \text{TI} \end{array} \right\}$$

Then: LTI system

$$h(t) = \sum_{k=-1}^1 \left(\frac{1}{2}\right)^{|k|} \delta(t-k)$$

b)

$$y(t-t_0) = \int_0^{t-t_0} \tau^a x(t-\tau-t_0) d\tau$$

$$\mathcal{T}\{x(t-t_0)\} = \int_0^t \tau^a x(t-(\tau-t_0)) d\tau$$

} not same
not TI

$$\begin{aligned} u &= \tau - t_0 \\ \tau &= u + t_0 \end{aligned}$$

$$\begin{aligned}
 1 \{x(t-t_0)\} &= \int_0^{t-t_0} \tau^{-1} x(t-(t-\tau)) d\tau \\
 &= \int_{-t_0}^{t-t_0} (u+t_0)^{-1} x(t-u) du
 \end{aligned}$$

$u = \tau - t_0$
 $\tau = u + t_0$

$$X[T] \rightarrow X[LTI]$$

$$\begin{aligned}
 c) \quad y(t-t_0) &= \int_{-\infty}^{t-t_0} e^{-(t-\tau-t_0)} x(\tau) d\tau \\
 T\{x(t-t_0)\} &= \int_{-\infty}^t e^{-(t-\tau)} x(\tau-t_0) d\tau \\
 &= \int_{-\infty}^{t-t_0} e^{-(t-u-t_0)} x(u) du
 \end{aligned}$$

$u = \tau - t_0$
 $\tau = u + t_0$

→ same T

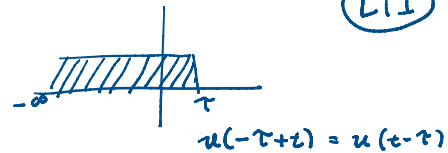
$$\begin{aligned}
 ay(t) + by(t) &= a \int_{-\infty}^t e^{-(t-\tau)} x_1(\tau) d\tau + b \int_{-\infty}^t e^{-(t-\tau)} x_2(\tau) d\tau = \int_{-\infty}^t e^{-(t-\tau)} (ax_1(\tau) + bx_2(\tau)) d\tau
 \end{aligned}$$

} same linear
LTI

$$T\{ax_1(t) + bx_2(t)\} = \int_{-\infty}^t e^{-(t-\tau)} (ax_1(\tau) + bx_2(\tau)) d\tau$$

$$\begin{aligned}
 LTI \quad \int_{-\infty}^t e^{-(t-\tau)} x(\tau) d\tau &= \int_{-\infty}^{\infty} \underbrace{x(\tau)}_{\pi(\tau)} \underbrace{u(t-\tau) e^{-(t-\tau)}}_{h(t-\tau)} d\tau \\
 &= \int_{-\infty}^{\infty} h(t) \pi(t) dt
 \end{aligned}$$

$h(t) = u(t) e^{-t}$



$$\begin{aligned}
 d) \quad y[n-n_0] &= -\frac{1}{8}x[n-n_0-3] - \frac{1}{4}x[n-n_0-2] - \frac{1}{2}x[n-n_0-1] \\
 T\{x[n-n_0]\} &= -\frac{1}{8}x[n-n_0-3] - \frac{1}{4}x[n-n_0-2] - \frac{1}{2}x[n-n_0-1]
 \end{aligned}$$

} same, T

$$\begin{aligned}
 ay_1[n] + by_2[n] &= a\left(-\frac{1}{8}x_1[n-3] - \frac{1}{4}x_1[n-2] - \frac{1}{2}x_1[n-1]\right) + b\left(-\frac{1}{8}x_2[n-3] - \frac{1}{4}x_2[n-2] - \frac{1}{2}x_2[n-1]\right) \\
 T\{ax_1[n] + bx_2[n]\} &= -\frac{1}{8}(ax_1[n-3] + bx_2[n-3]) - \frac{1}{4}(ax_1[n-2] + bx_2[n-2]) - \frac{1}{2}(ax_1[n-1] + bx_2[n-1]) \\
 &= a\left(-\frac{1}{8}x_1[n-3] - \frac{1}{4}x_1[n-2] - \frac{1}{2}x_1[n-1]\right) + b\left(-\frac{1}{8}x_2[n-3] - \frac{1}{4}x_2[n-2] - \frac{1}{2}x_2[n-1]\right)
 \end{aligned}$$

} same, linear

LTI system:

$$h = -\frac{1}{8} \delta[n-3] - \frac{1}{4} \delta[n-2] - \frac{1}{2} \delta[n-1]$$