

Mini-Batch Gradient Descent

e.g. $m = 1,000,000$

→ split into 1000 mini-batches of 1,000 each

$$\text{Mini-Batch } t : X^{(t)}, Y^{(t)} \\ (m, 1000) \quad (1, 1000)$$

for $t=1$ to 1000:

Forward Prop on $X^{(t)}$

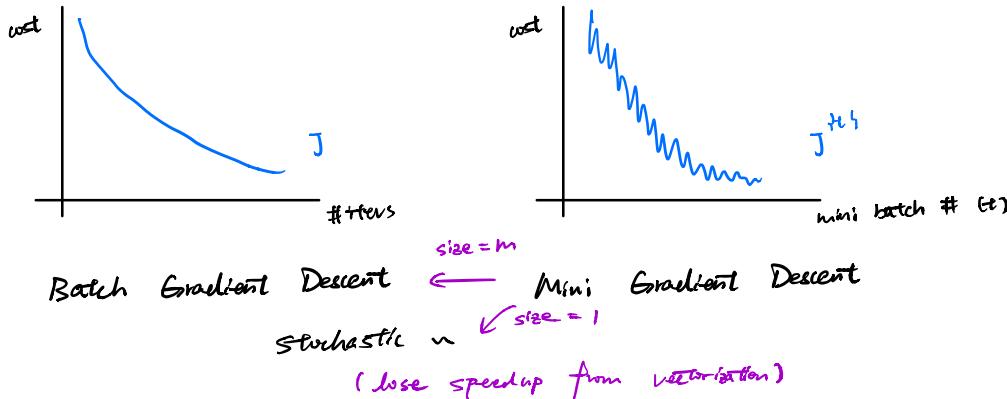
$$\begin{aligned} z^{(t)} &= W^{(t)} X^{(t)} + b^{(t)} \\ A^{(t)} &= g^{(t)}(z^{(t)}) \\ \vdots \\ A^{(t)} &= g^{(t)}(z^{(t)}) \end{aligned} \quad \left. \right\} \text{Vectorized implementation}$$

$$\text{Compute } J^{(t)} = \frac{1}{1000} \sum_{i=1}^{1000} L(\hat{y}^{(i)}, y^{(i)}) + \frac{\lambda}{2 \cdot 1000} \sum_w \|w\|_F^2$$

Backprop → compute gradient w.r.t. $J^{(t)}$ (using $(X^{(t)}, Y^{(t)})$)

$$w^{(t)} := w^{(t)} - \alpha d w^{(t)} ; \quad b^{(t)} := b^{(t)} - \alpha d b^{(t)}$$

"1 epoch" → pass through training set



⇒ typical mini-batch size:

64, 128, 256, ...

make sure mini-batch fits in CPU/GPU memory

Exponentially weighted Averages

e.g. $\theta_1 = 40^\circ\text{F}$

$\theta_2 = 49^\circ\text{F}$

:

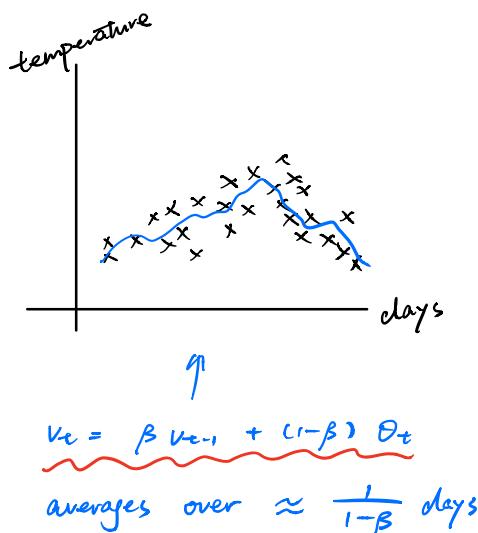
$\Rightarrow V_0 = 0$

$V_1 = 0.9 V_0 + 0.1 \theta_1$

$V_2 = 0.9 V_1 + 0.1 \theta_2$

:

$V_t = 0.9 V_{t-1} + 0.1 \theta_t$



e.g. $V_{100} = 0.1 \theta_{100} + 0.1 \times 0.9 \theta_{99} + 0.1 \times (0.9)^2 \theta_{98} + \dots$

$0.9^{10} \approx 0.35 \approx \frac{1}{e}$

$(1-\varepsilon)^{\frac{1}{\varepsilon}} = \frac{1}{e}$ after $\frac{1}{\varepsilon}$ days.
about $\frac{1}{\varepsilon}$ left

$\Rightarrow V_0 = 0$

Repeat {

Get next θ_t

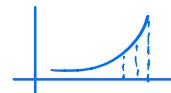
$V_t := \beta V_{t-1} + (1-\beta) \theta_t$

Problem:

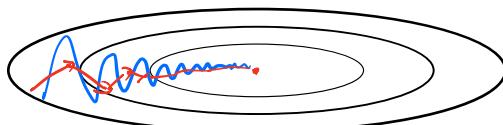
$$\begin{aligned} V_t &= \beta V_{t-1} + (1-\beta) \theta_t \\ &= (1-\beta) \theta_t \end{aligned}$$

Bias Correction $\Rightarrow \frac{V_t}{1-\beta^t}$

(only matters in early stage)



Gradient Descent w/ Momentum



↓ slower
↔ faster

Momentum:

On Iteration t :

Compute dW , db on current mini-batch

$$V_{dw} = \beta V_{dw} + (1-\beta) dW$$

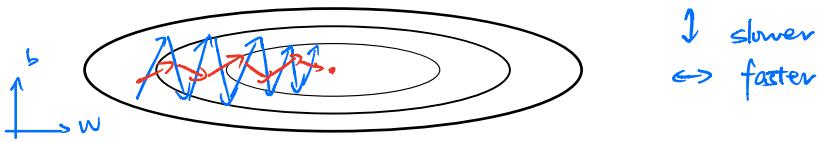
$$V_{db} = \beta V_{db} + (1-\beta) db$$

$$w := w - \alpha V_{dw}, \quad b := b - \alpha V_{db}$$

another form:
 $\beta V_{dw} + dW \leftarrow \text{tune } \alpha$

(α, β hyperparameters)

RMS Prop



On iteration t ,

compute d_w, d_b on current mini-batch

$$S_{dw} = \beta_2 S_{dw} + (1 - \beta_2) d_w^2 \quad \leftarrow \text{small}$$

$$S_{db} = \beta_2 S_{db} + (1 - \beta_2) d_b^2 \quad \leftarrow \text{large}$$

$$w := w - \alpha \frac{d_w}{\sqrt{S_{dw} + \epsilon}} \quad b := b - \alpha \frac{d_b}{\sqrt{S_{db} + \epsilon}} \quad \begin{matrix} \text{Prevent zero error} \\ \text{e.g. } \epsilon = 10^{-8} \end{matrix}$$

Adam Optimization Algorithm — Adaptive Moment Estimation

$$V_{dw} = 0, \quad S_{dw} = 0, \quad V_{db} = 0, \quad S_{db} = 0$$

On iteration t ,

Compute d_w, d_b using current mini-batch

$$V_{dw} = \beta_1 V_{dw} + (1 - \beta_1) d_w, \quad V_{db} = \beta_1 V_{db} + (1 - \beta_1) d_b \quad \swarrow \text{Momentum}$$

$$S_{dw} = \beta_2 S_{dw} + (1 - \beta_2) d_w^2, \quad S_{db} = \beta_2 S_{db} + (1 - \beta_2) d_b^2 \quad \swarrow \text{RMSProp}$$

$$\overset{\text{corrected}}{V_{dw}} = V_{dw} / (1 - \beta_1^t), \quad \overset{\text{corrected}}{V_{db}} = V_{db} / (1 - \beta_1^t)$$

$$\overset{\text{corrected}}{S_{dw}} = S_{dw} / (1 - \beta_2^t), \quad \overset{\text{corrected}}{S_{db}} = S_{db} / (1 - \beta_2^t)$$

$$\Rightarrow w := w - \alpha \frac{\overset{\text{corrected}}{V_{dw}}}{\sqrt{\overset{\text{corrected}}{S_{dw}} + \epsilon}}$$

$$b := b - \alpha \frac{\overset{\text{corrected}}{V_{db}}}{\sqrt{\overset{\text{corrected}}{S_{db}} + \epsilon}}$$

hyperparameters:

α : needs to be tuned

β_1 : 0.9 (V_{dw})

β_2 : 0.999 (S_{dw}^2)

ϵ : 10^{-8}

Learning Rate Decay



⇒ e.g.

$$1 \text{ epoch} = 1 \text{ pass of data}$$

$$\alpha = \frac{1}{1 + \text{decay rate} * \text{epoch \#}} \quad \alpha_0 \quad \swarrow 0.2$$

epoch	1	2	3	4	...
α	0.1	0.067	0.05	0.04	...

Other decay methods:

$$\left. \begin{array}{l} \alpha = 0.95^{\text{epoch \#}} \alpha_0 \\ \alpha = \frac{k}{\sqrt{\text{epoch \#}}} \alpha_0 \\ \alpha = \begin{cases} \alpha & t=0 \\ - & t>0 \end{cases} \end{array} \right\}$$

Problem of Local Optima

In high dimension, saddle points are more common

Unlikely to stuck in a bad local optima

Plateaus can make learning slow