

Mini-Batch Gradient Descent

eg. $m = 1,000,000$

→ split into 1000 mini-batches of 1,000 each

Mini-Batch t : $X^{(t)}$, $Y^{(t)}$
 $(n \times 1000)$ $(1, 1000)$

for $t = 1$ to 1000:

Forward Prop on $X^{(t)}$

$$Z^{[1]} = W^{[1]} X^{(t)} + b^{[1]}$$

$$A^{[1]} = \sigma(Z^{[1]})$$

\vdots

$$A^{[L]} = \sigma(Z^{[L]})$$

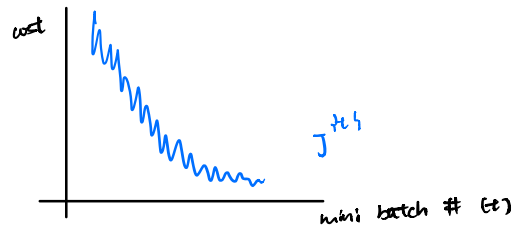
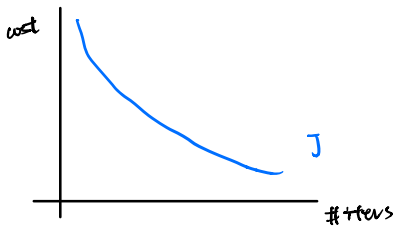
Vectorized implementation

$$\text{Compute } J = \frac{1}{1000} \sum_{i=1}^{1000} \mathcal{L}(\hat{y}^{(i)}, y^{(i)}) + \frac{\lambda}{2 \cdot 1000} \sum_l \|W^{(l)}\|_F^2$$

Backprop to compute gradient w.r.t. $J^{(t)}$ (using $(X^{(t)}, Y^{(t)})$)

$$W^{[1]} := W^{[1]} - \alpha dW^{[1]}, \quad b^{[1]} := b^{[1]} - \alpha db^{[1]}$$

"1 epoch" — pass through training set



Batch Gradient Descent \leftarrow Mini Gradient Descent
 size = m \leftarrow size = 1
 Stochastic \sim (lose speedup from vectorization)

\Rightarrow typical mini-batch size:

64, 128, 256, ...

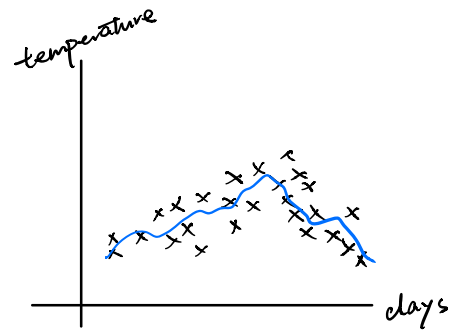
Make sure mini-batch fit in CPU/GPU memory

Exponentially weighted Averages

e.g.

$$\begin{aligned}\theta_1 &= 40^\circ\text{F} \\ \theta_2 &= 49^\circ\text{F} \\ &\vdots\end{aligned}$$

$$\begin{aligned}\Rightarrow V_0 &= 0 \\ V_1 &= 0.9 V_0 + 0.1 \theta_1 \\ V_2 &= 0.9 V_1 + 0.1 \theta_2 \\ &\vdots \\ V_t &= 0.9 V_{t-1} + 0.1 \theta_t\end{aligned}$$



$$V_t = \beta V_{t-1} + (1-\beta) \theta_t$$

averages over $\approx \frac{1}{1-\beta}$ days

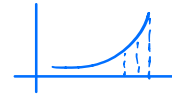
e.g.

$$V_{100} = 0.1 \theta_{100} + 0.1 \times 0.9 \theta_{99} + 0.1 \times (0.9)^2 \theta_{98} + \dots$$

$$0.9^{10} \approx 0.35 \approx \frac{1}{e}$$

$$(1-\epsilon)^{1/\epsilon} = \frac{1}{e}$$

after $\frac{1}{1-\beta}$ days,
about $1/3$ left



$$\Rightarrow V_0 = 0$$

Repeat {

Get next θ_t

$$V_t := \beta V_t + (1-\beta) \theta_t$$

}

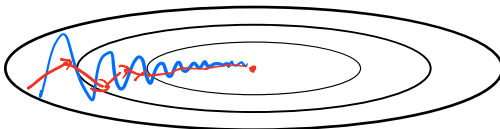
Problem:

$$\begin{aligned}V_1 &= \beta V_0 + (1-\beta) \theta_1 \\ &= (1-\beta) \theta_1\end{aligned}$$

Bias Correction $\Rightarrow \frac{V_t}{1-\beta^t}$

(only matters in early stage)

Gradient Descent w/ Momentum



↓ slower
↔ faster

Momentum:

On iteration t :

Compute dw , db on current mini-batch

$$V_{dw} = \beta V_{dw} + (1-\beta) dw$$

$$V_{db} = \beta V_{db} + (1-\beta) db$$

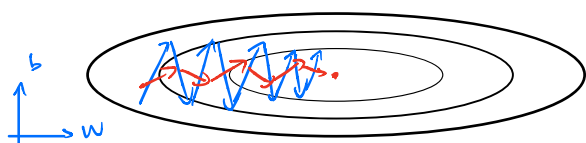
$$w := w - \alpha V_{dw}, \quad b := b - \alpha V_{db}$$

another form:

$$\beta V_{dw} + dw \leftarrow \text{tune } \alpha$$

(α, β hyperparameters)

RMS Prop



↓ slower
↔ faster

On iteration t ,

compute dw, db on current mini-batch

$$S_{dw} = \beta_2 S_{dw} + (1 - \beta_2) dw^2 \quad \leftarrow \text{small}$$

$$S_{db} = \beta_2 S_{db} + (1 - \beta_2) db^2 \quad \leftarrow \text{large}$$

$$w := w - \alpha \frac{dw}{\sqrt{S_{dw} + \epsilon}} \quad b := b - \alpha \frac{db}{\sqrt{S_{db} + \epsilon}}$$

Prevent zero error
e.g. $\epsilon = 10^{-8}$

Adam Optimization Algorithm

— Adaptive Moment Estimation

$$V_{dw} = 0, \quad S_{dw} = 0, \quad V_{db} = 0, \quad S_{db} = 0$$

On iteration t ,

Compute dw, db using current mini-batch

$$V_{dw} = \beta_1 V_{dw} + (1 - \beta_1) dw, \quad V_{db} = \beta_1 V_{db} + (1 - \beta_1) db$$

← Momentum

$$S_{dw} = \beta_2 S_{dw} + (1 - \beta_2) dw^2, \quad S_{db} = \beta_2 S_{db} + (1 - \beta_2) db^2 \quad \leftarrow \text{RMS Prop}$$

$$V_{dw}^{\text{corrected}} = V_{dw} / (1 - \beta_1^t), \quad V_{db}^{\text{corrected}} = V_{db} / (1 - \beta_1^t)$$

$$S_{dw}^{\text{corrected}} = S_{dw} / (1 - \beta_2^t), \quad S_{db}^{\text{corrected}} = S_{db} / (1 - \beta_2^t)$$

$$\Rightarrow w := w - \alpha \frac{V_{dw}^{\text{corrected}}}{\sqrt{S_{dw}^{\text{corrected}} + \epsilon}}$$

$$b := b - \alpha \frac{V_{db}^{\text{corrected}}}{\sqrt{S_{db}^{\text{corrected}} + \epsilon}}$$

hyperparameters:

α : needs to be tuned

β_1 : 0.9 (dw)

β_2 : 0.999 (dw^2)

ϵ : 10^{-8}

Learning Rate Decay

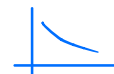


⇒ e.g.

1 epoch = 1 pass of data

$$\alpha = \frac{1}{1 + \text{decay rate} * \text{epoch \#}} \quad \alpha_0^{0.2}$$

epoch	1	2	3	4	...
α	0.1	0.07	0.05	0.04	...



Other decay methods:

$$\left\{ \begin{array}{l} \alpha = 0.95^{\text{epoch \#}} \alpha_0 \\ \alpha = \frac{k}{\sqrt{\text{epoch \#}}} \alpha_0 \\ \alpha = \begin{array}{c} \alpha \\ \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ t \end{array} \end{array} \right.$$

Problem of Local Optima

In high dimension, saddle points are more common

Unlikely to stuck in a bad local optima

Plateaus can make learning slow