USB Stack Device Reference Manual

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Chapter 1 Before You Begin

1.1 About this book

This *USB Stack Device Reference Manual* describes the USB Device driver and the programming interface in the USB Stack.

The audience should be familiar with the following reference material:

- Universal Serial Bus Specification Revision 1.1
- Universal Serial Bus Specification Revision 2.0

Use this book in addition to:

Source Code

1.2 Acronyms and abbreviations

Table 1 Acronyms and abbreviations

Term	Description
API	Application Programming Interface
CDC	Communication Device Class
HID	Human Interface Device
MSD	Mass Storage Device
MSC	Mass Storage Class
PHDC	Personal Healthcare Device Class
ZLT	Zero Length Transfer
LAB	Logical Address Block
LUN	Logical Unit Number

1.3 Function listing format

This is the general format of an entry for a function, compiler intrinsic, or a macro.

function_name()

A short description of what function **function_name()** does.

Synopsis

Provides a prototype for function **function_name**().

```
<return_type> function_name(
<type_1> parameter_1,
<type_2> parameter_2,
...
<type_n> parameter_n)
```

Parameters

- parameter 1 [in] Pointer to x
- parameter_2 [out] Handle for y
- parameter_n [in/out] Pointer to z

Parameter passing is categorized as follows:

- In indicates that the function uses one or more values in the parameter you give it without storing any changes.
- *Out* indicates that the function saves one or more values in the parameter you give it. Examine the saved values to find out useful information about your application.
- In/out indicates that the function changes one or more values in the parameter you give it and saves the result. Examine the saved values to find out useful information about your application.

Description – Describes the function **function_name**(). This section also describes any special characteristics or restrictions that might apply:

- Function blocks or might block under certain conditions
- Function must be started as a task
- Function creates a task
- Function has pre-conditions that might not be obvious
- Function has restrictions or special behavior

Return value – Specifies any value or values returned by function **function_name()**.

Chapter 2 Overview

2.1 USB overview

Universal Serial Bus (USB) is a polled bus. The USB Host configures the devices attached to it, either directly or through a USB hub, and initiates all bus transactions. The USB Device responds only to the requests sent to it by a USB Host.

The USB Device software consists of the following parts:

- USB Device application
- USB Device Class Driver (contains USB Device Class APIs)
- USB Device Common Controller Driver APIs (independent of hardware)
- USB Device controller interface (DCI) low-level functions used to interact with the USB Device controller hardware
- OS adapter to provide unified OS API to USB Stack
- SoC-specific initialization.

In <install_dir>/usb/usb_core/device/sources/bsp/SOC_NAME/usb_dev_bsp.c

```
usb_status usb_dev_soc_init(uint8_t controller_id)
```

```
The controller_id is the enum CONTROLLER_INDEX
```

This function should be implemented by users when porting to a new platform.

• Board-specific initialization.

In <install dir>/examples/BOARD NAME /board.c

```
uint8_t usb_device_board_init(uint8_t controller_id)
The controller id is the enum CONTROLLER INDEX
```

This function must be implemented by users when porting to a new board.

Note

As a result of the FS controller (KHCI) IP limitation, one endpoint can be enabled for one direction only, either IN or OUT. It can't be enabled for both directions.

The whole architecture and components of USB stack are as follows:

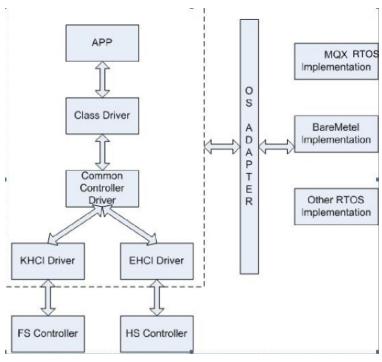


Figure 1 USB Device stack architecture

2.2 API overview

This section describes the API functions. The interfaces between the USB Common Controller driver and xHCI driver are not listed here. All USB device APIs can't be invoked during the interrupt service routine except when the operating system is bare metal.

Table 2 summarizes the USB Common Controller driver APIs.

Table 2 USB Device Controller driver APIs

No.	API Function	Description
1	usb_device_init()	Initializes the USB device controller
2	usb_device_postinit()	Some additional initialization actions need to be done after the device is initialized
3	usb_device_deinit()	Un-initializes the device controller
4	usb_device_recv_data()	Receives data from a specified endpoint
5	usb_device_send_data()	Sends data to a specified endpoint
6	usb_device_cancel_transfer()	Cancels all the pending transfers in a specified endpoint

7	usb_device_register_service()	Registers a callback function for the service
8	usb_device_unregister_service()	Unregisters a callback function for the service
9	usb_device_init_endpoint()	Initializes the specified endpoint
10	usb_device_deinit_endpoint()	Un-initializes the specified endpoint
11	usb_device_stall_endpoint()	Stalls the specified endpoint
12	usb_device_unstall_endpoint()	Un-stalls the specified endpoint
13	usb_device_register_application_ notify()	Registers the callback function for the application related event
14	usb_device_register_vendor_class _request_notify()	Registers the callback function for the vendor class related event
15	usb_device_register_desc_request _notify()	Registers the callback function for the descriptor related event
16	usb_device_set_status()	Sets the current status of the selected item
17	usb_device_get_status()	Gets the current status of the selected item

Table 3 summarizes the common class APIs.

Table 3 Common class driver APIs

No.	API Function	Description
1	USB_Class_Init()	Initializes the class module
2	USB_Class_Deinit()	Un-initializes the class module
3	USB_Class_Send_Data()	Sends data on the specified endpoint

Table 4 summarizes the CDC class APIs.

Table 4 CDC class driver APIs

No.	API Function	Description
1	USB_Class_CDC_Init()	Initializes the CDC class

2	USB_Class_CDC_Deinit()	Un-initializes the CDC class driver
3	USB_Class_CDC_ Recv _Data ()	Receives data on the specified endpoint
4	USB_Class_CDC_Send_	Sends data on the specified endpoint
	Data()	
5	USB_Class_CDC_Cancel()	Cancels all the uncompleted transfers in the specified endpoint
6	USB_Class_CDC_Get_Speed()	Get current USB speed of the CDC device

Table 5 summarizes the HID class APIs.

Table 5 HID class driver APIs

No.	API Function	Description
1	USB_Class_HID_Init()	Initializes the HID class
2	USB_Class_HID_Deinit()	Un-initializes the HID class driver
3	USB_Class_HID_Send _Data()	Sends data on the specified endpoint
4	USB_Class_HID_Cancel()	Cancels all the uncompleted transfers in the specified endpoint
5	USB_Class_HID_Recv_Data ()	Receives data on the specified endpoint
6	USB_Class_HID_Get_Speed ()	Get current USB speed of the HID device

Table 6 summarizes the MSC class APIs.

Table 6 MSC class driver APIs

No.	API Function	Description
1	USB_Class_MSC_Init()	Initializes the MSC class
2	USB_Class_MSC_Deinit()	Un-initializes the MSC class driver
3	USB_Class_MSC_Get_Speed()	Get current USB speed of the MSC device

Table 7 summarizes the AUDIO class APIs.

Table 7 AUDIO class driver APIs

No.	API Function	Description
1	USB_Class_Audio_Init()	Initializes the AUDIO class
2	USB_Class_Audio_Deinit()	Un-initializes the AUDIO class driver
3	USB_Class_Audio_Recv _Data()	Receives data on the specified endpoint
4	USB_Class_Audio_Send _Data()	Sends data on the specified endpoint
5	USB_Class_Audio_Cancel()	Cancels all the uncompleted transfers in the specified endpoint
6	USB_Class_Audio_Get_Speed()	Get current USB speed of the Audio device

Table 8 summarizes the PHDC class APIs.

Table 8 PHDC class driver APIs

No.	API Function	Description
1	USB_Class_PHDC_Init()	Initializes the PHDC class
2	USB_Class_PHDC_Deinit()	Un-initializes the PHDC class driver
3	USB_Class_PHDC_Recv _Data ()	Receives data on the specified endpoint
4	USB_Class_PHDC_Send _Data()	Sends data on the specified endpoint
5	USB_Class_PHDC_Cancel()	Cancels all the uncompleted transfers in the specified endpoint
6	USB_Class_PHDC_Get_Speed()	Get current USB speed of the PHDC device

Table 9 summarizes the Composite class APIs.

Table 9 Composite Class driver APIs

No.	API Function	Description
1	USB_Composite_Init()	Initializes the Composite class
2	USB_Composite_Deinit()	Un-initializes the Composite class driver
6	USB_Composite_Get_Speed()	Get current USB speed of the Composite device

2.3 Using the USB Device API

2.3.1 Using USB Common Controller driver API

It is not recommend using the USB Common Controller driver directly to implement the USB function, but you can see the code implemented in the class driver provided by Freescale for detailed information.

2.3.2 Using CDC class driver API

To use CDC class layer API functions from the application:

- 1. Call **USB_Class_CDC_Init()** to initialize the class driver, all the layers below it, and the device controller. Event callback functions are also passed as parameter to this function.
- 2. When the callback function is called with the USB_DEV_EVENT_ENUM_COMPLETE event, the application should move into the connected state.
- 3. Call **USB_Class_CDC_Send_Data()** to send data to the host through the device layers, when required.
- 4. Call **USB_Class_CDC_Recv_Data()** when the callback function is called with the USB_DEV_EVENT_DATA_RECEIVED event, which implies that the previous reception of data from the host is done.

2.3.3 Using HID class driver API

To use HID class layer API functions from the application:

- 1. Call **USB_Class_HID_Init()** to initialize the class driver, all the layers below it, and the device controller. Event callback functions are also passed as a parameter to this function.
- 2. When the callback function is called with the USB_DEV_EVENT_ENUM_COMPLETE event, the application should move into the ready state.
- 3. Call **USB_Class_HID_Send_Data()** to send data to the host through the device layers, when required.

2.3.4 Using MSC class driver API

To use MSD class layer API functions from the application:

- 1. Call **USB_Class_MSC_Init()** to initialize the class driver, all the layers below it, and the device controller. Event callback functions are also passed as a parameter to this function.
- 2. When the callback function is called with the USB_DEV_EVENT_ENUM_COMPLETE event, the application should move into the ready state.
- 3. The callback function is called with the USB_MSC_DEVICE_READ_REQUEST event to get data from the storage device before sending it to the USB bus. It reads data from the mass storage device to the driver buffer.
- 4. The callback function is called with the USB_MSC_DEVICE_WRITE_REQUEST event to prepare the storage device buffer for USB transfer.
- 5. The callback function is called with the USB_DEV_EVENT_DATA_RECEIVED event to write the storage device buffer data the storage device.

2.3.5 Using AUDIO class driver API

To use AUDIO class layer API functions from the application:

- 1. Call **USB_Class_Audio_Init()** to initialize the class driver, all the layers below it, and the device controller. Event callback functions are also passed as parameter to this function.
- 2. When the callback function is called with the USB_DEV_EVENT_ENUM_COMPLETE event, the application should move into the connected state.
- 3. Call **USB_Class_Audio_Send_Data()** to send data to the host through the device layers, when required.
- 4. Call **USB_Class_Audio_Recv_Data()** when the callback function is called with the USB_DEV_EVENT_DATA_RECEIVED event, which implies that the previous reception of data from the host is done.

2.3.6 Using PHDC class driver API

To use PHDC class layer API functions from the application:

- 1. Call **USB_Class_PHDC_Init()** to initialize the class driver, all the layers below it, and the device controller. Event callback functions are also passed as parameter to this function.
- 2. When the callback function is called with the USB_DEV_EVENT_ENUM_COMPLETE event, the application should move into the connected state.
- 3. Call **USB_Class_PHDC_Send_Data()** to send data to the host through the device layers, when required.

4. Call **USB_Class_PHDC_Recv_Data**() when the callback function is called with the USB_DEV_EVENT_DATA_RECEIVED event, which implies that the previous reception of data from the host is done.

2.3.7 Using composite class driver API

- 1. Call **USB_Composite_Init()** to initialize the composite class driver, all the layers below it, and the device controller. Event callback functions for each interface are also passed as parameter to this function.
- 2. Read <u>class_handle</u> to get every class handle for each interface composited in the composited device.
- 3. When the callback function is called with the USB_APP_ENUM_COMPLETE event, the application should move into the connected state.
- 4. Call the corresponding Send API to send data to the host through the device layers, when required. For example, if the device is composited of HID and AUDIO, **USB_Class_Audio_Send_Data()** can be used to send data to the host with the handle obtained from class_handle.
- 5. Call the corresponding receive API when the callback function is called with the USB_DEV_EVENT_DATA_RECEIVED event, which implies that the previous reception of data from the host is done. For example, if the device is composited of HID and AUDIO, USB_Class_Audio_Recv_Data() can be used to send data to the host with the handle obtained from class handle.

Chapter 3 USB Common Controller Driver API

3.1 usb_device_init

Initializes the USB device controller

Synopsis

Parameters

```
controller_id [in] - controller ID, such as USB_CONTROLLER_KHCI_0

handle [out] - USB Device handle
```

Description

The function initializes the device controller specified by the controller_id and a device handle can be returned from the handle.

Return value

- USB_OK (success)
- Other (failure)

3.2 usb_device_postinit

Initializes the USB device controller

Synopsis

Parameters

```
controller_id [in] - controller ID, such as USB_CONTROLLER_KHCI_0

handle [in] - USB Device handle
```

Description

The function starts the initialization process that cannot be done in the **usb_device_init()** API. For example, the call back functions need to be registered after the device handle can be obtained from the **usb_device_init()** API. Therefore, the USB interrupt cannot be enabled in **usb_device_init()**; otherwise,

the USB interrupt can be issued before the callback functions are registered. To avoid this issue, the USB interrupt will be enabled in the post initialization process.

Return value

- USB_OK (success)
- Other (failure)

3.3 usb_device_deinit

Deinitializes the USB device controller

Synopsis

```
usb_status usb_device_deinit
(
         usb device handle
                                  handle
)
```

Parameters

[in] - USB Device handle handle

Description

The function deinitializes the device controller specified by the handle.

Return value

- USB_OK (success)
- **other** (failure)

3.4 usb_device_recv_data

Receives data from a specified endpoint

Synopsis

```
usb_status usb_device_recv_data
usb_device_handle
                           handle,
uint_8
                     ep_index,
uint_8*
                     buff_ptr,
uint 32
                     size
```

Parameters

```
[in] - USB Device handle
handle
                   [in] - endpoint index
ep_index
                   [in] - memory address to receive the data
buff_ptr
```

```
size [in] – length of the packet to be received
```

Description

The function is used to receive data from a specified endpoint. For each endpoint, this function can only be called once, before the last transmission completed.

Return value

- USB_OK (success)
- **other** (failure)

Note: The return value just indicates if the receiving request is successful or not; the transfer done is notified by the corresponding callback function.

The transmission includes recv_data and send_data.

3.5 usb_device_send_data

Sends data from a specified endpoint

Synopsis

```
usb_status usb_device_send_data
(
usb_device_handle handle,
uint_8 ep_index,
uint_8* buff_ptr,
uint_32 size
)
```

Parameters

```
handle [in] - USB Device handle

ep_index [in] - endpoint index

buff_ptr [in] - memory address hold the data need to be sent

size [in] - length of the packet to be received
```

Description

The function is used to send data to a specified endpoint. For each endpoint, this function can only be called once, before the last transmission completed.

Return value

- USB_OK (success)
- **other** (failure)

Note: The return value just indicates if the sending request is successful or not and the completed transfer is notified by the corresponding callback function.

The transmission includes recv_data and send_data.

3.6 usb_device_cancel_transfer

Cancels all the pending transfers in a specified endpoint.

Synopsis

```
usb_status usb_device_cancel_transfer
(
usb_device_handle handle,
uint_8 ep_index,
uint_8 direction
)
```

Parameters

```
handle [in] - USB Device handle
ep_index [in] - endpoint index
direction [in] - direction of the endpoint
```

Description

The function is used to cancel all the pending transfer in a specified endpoint which is determined by the endpoint index and the direction.

Return value

- USB_OK (success)
- **other** (failure)

3.7 usb_device_register_service

Registers a callback function for one specified endpoint.

Synopsis

```
usb_status usb_device_register_service
(
usb_device_handle handle,
uint8_t type,
usb_event_service_t service,
void* arg
)
```

Parameters

handle [in] – USB Device handle

```
type [in] - service type, type & 0xF is the endpoint index
service [in] - callback function
arg [in] - second parameter for the callback function
```

Description

The function is used to register a callback function for one specified endpoint.

Return value

- USB_OK (success)
- **other** (failure)

3.8 usb_device_unregister_service

Unregisters a callback function for one specified endpoint.

Synopsis

```
usb_status usb_device_unregister_service
(
usb_device_handle handle,
uint8_t type
)
```

Parameters

```
handle [in] - USB Device handle

type [in] - service type, type & 0xF is the endpoint index
```

Description

The function is used to unregister a callback function for one specified endpoint.

Return value

- USB_OK (success)
- **other** (failure)

3.9 usb_device_init_endpoint

Initializes the specified endpoint.

Synopsis

)

Parameters

```
handle [in] - USB Device handle
ep_ptr [in] - endpoint information, see Section 7.1.1
flag [in] - whether the ZLT is enabled for this endpoint
```

Description

The function is used to initialize a specific endpoint which is determined by the ep_ptr.

Return value

- USB_OK (success)
- other (failure)

3.10 usb_device_deinit_endpoint

Un-initializes the specified endpoint.

Synopsis

```
usb_status usb_device_deinit_endpoint
(
usb_device_handle handle,
uint8_t ep_num,
uint_8 direction
)
```

Parameters

```
handle[in] – USB Device handleep\_num[in] – endpoint indexdirection[in] –endpoint direction
```

Description

The function is used to un-initialize a specific endpoint which is determined by the endpoint index and endpoint direction.

Return value

- USB_OK (success)
- **other** (failure)

3.11 usb_device_stall_endpoint

Stalls the specified endpoint.

Synopsis

```
usb_status usb_device_stall_endpoint
(
usb_device_handle handle,
uint8_t ep_num,
uint_8 direction
)
```

Parameters

```
handle [in] - USB Device handle
ep_num [in] - endpoint index
direction [in] - endpoint direction
```

Description

The function is used to stall a specific endpoint which is determined by the endpoint index and endpoint direction.

Return value

- USB_OK (success)
- **other** (failure)

3.12 usb_device_unstall_endpoint

Un-stalls the specified endpoint.

Synopsis

```
usb_status usb_device_unstall_endpoint
(
usb_device_handle handle,
uint8_t ep_num,
uint_8 direction
)
```

Parameters

```
handle [in] - USB Device handle
ep_num [in] - endpoint index
direction [in] - endpoint direction
```

Description

The function is used to un-stall a specific endpoint which is determined by the endpoint index and endpoint direction.

Return value

- **USB_OK** (success)
- **other** (failure)

3.13 usb_device_register_application_notify

Registers the callback function for the application related event.

Synopsis

Parameters

```
handle [in] - USB Device handle

device_notify_callback [in] - callback function

device_notify_param [in] - parameter for the callback function
```

Description

The function is used to register a callback function for the application related event. Currently the following events are supported:

Event	Description
USB_DEV_EVENT_BUS_RESET	A BUS reset is received.
USB_DEV_EVENT_ENUM_COMPLETE	The device enumerated process completes.
USB_DEV_EVENT_CONFIG_CHANGED	Host sends a set_configuration.
USB_DEV_EVENT_ERROR	Error.

Return value

- USB_OK (success)
- **other** (failure)

3.14 usb_device_register_vendor_class_request_notify

Registers the callback function for the vendor class related event.

Synopsis

Parameters

```
handle [in] - USB Device handle

request_notify_callback [in] - callback function

request_notify_param [in] - parameter for the callback function
```

Description

The function is used to register a callback function for the vendor class request related event. Currently the vendor class is not implemented, so both the **request_notify_callback** and **request_notify_param** can be set to NULL.

Return value

- USB_OK (success)
- **other** (failure)

3.15 usb_device_register_desc_request_notify

Registers the callback functions for the device descriptor related request.

Synopsis

Parameters

```
handle [in] - USB Device handle

desc_request_notify_callback [in] - callback function

desc_request_notify_param [in] - parameter for the callback function
```

Description

The function is used to register a set of callback functions for the device descriptor related event. For details, see Section 7.1.7.

Return value

- USB_OK (success)
- **other** (failure)

3.16 usb_device_get_status

Gets the internal USB device state.

Synopsis

Parameters

```
handle [in] - USB Device handle
component [in] - callback function
status [out] - requested status
```

Description

The function is used to get the status of the specified component. The supported components include:

- USB_STATUS_DEVICE_STATE
- USB_STATUS_OTG
- USB_STATUS_DEVICE
- USB_STATUS_ENDPOINT, the LSB nibble carries the endpoint number

Return value

- USB_OK (success)
- **other** (failure)

3.17 usb_device_set_status

Sets the internal USB device state.

Synopsis

```
usb_status usb_device_set_status
(
usb_device_handle handle,
uint8_t component,
uint16_t status
)
```

Parameters

```
handle[in] - USB Device handlecomponent[in] - callback functionstatus[in] - status to set
```

Description

The function is used to set the status of the specified component. The supported components include:

- USB_STATUS_DEVICE_STATE
- USB_STATUS_OTG
- USB_STATUS_DEVICE

Return value

- USB_OK (success)
- **other** (failure)

Chapter 4 USB Device Class API

This section describes the API functions provided as part of class implementations.

4.1 CDC class API function listings

4.1.1 USB_Class_CDC_Init()

Initializes the CDC class.

Synopsis

Parameters

```
controller_id [in] - controller ID, such as USB_CONTROLLER_KHCI_0

cdc_config_ptr [in] - CDC configuration structure, see cdc_config_struct_t
```

Note

In the KSDK 1.3, board_init_callback is added to this configuration structure. Initialize it with an appropriate board initialization function.

```
cdc_handle_ptr [out] - pointer point to the initialized CDC class, see cdc_handle_t
```

Description

The application calls this API function to initialize the CDC class, the underlying layers, and the controller hardware.

Return Value

- USB OK (success)
- **Others** (failure)

4.1.2 USB_Class_CDC_Deinit()

Un-initializes the CDC class.

Synopsis

```
usb_status USB_Class_CDC_Deinit
(
```

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```
\begin{tabular}{c} $\tt cdc\_handle\_t & \tt cdc\_handle \\ \end{tabular} )
```

[in] - The CDC class handler

cdc_handle Description

The application calls this API function to un-initialize the CDC class, the underlying layers, and the controller hardware.

Return Value

- USB_OK (success)
- Others (failure)

4.1.3 USB_Class_CDC_Recv_Data()

Receive the CDC data.

Synopsis

Parameters

```
cdc_handle[in] - CDC class handlerep_num[in] - endpoint numberapp_buff[in] - buffer to save the data from the hostsize[in] - buffer length to receive
```

Description

The application calls this API function to receive data from the host. Once the data is received, the application layer receives a callback event USB_DEV_EVENT_DATA_RECEIVED. The transfer failed when the value of the object that the pointer size points is 0xFFFFFFFF in callback event USB_DEV_EVENT_DATA_RECEIVED.

Return Value

- USB_OK (success)
- Others (failure)

4.1.4 USB_Class_CDC_Send_Data()

Sends the CDC data.

Synopsis

Parameters

```
cdc_handle [in] - CDC class handler

ep_num [in] - endpoint number

app_buff [in] - buffer to send

size [in] - buffer length to send
```

Description

The application calls this API function to send DIC data specified by <code>app_buff</code> and <code>size</code>. Data is sent through DIC_BULK_IN_ENDPOINT. Once the data is sent, the application layer receives a callback event USB_DEV_EVENT_SEND_COMPLETE. The transfer failed when the value of the object that the pointer size points is <code>0xFFFFFFFF</code> in callback event USB_DEV_EVENT_SEND_COMPLETE. The application reserves the buffer until it receives a callback event indicating that the data is sent.

Return Value

- USB_OK (success)
- **Others** (failure)

4.1.5 USB_Class_CDC_Cancel()

Cancels all the uncompleted transfers in the specified endpoint.

Synopsis

Parameters

```
cdc_handle [in] - CDC class handler
ep_num [in] - endpoint number
```

Description

The application calls this API function to cancel all the uncompleted transfers in the specified endpoint.

Return Value

- USB_OK (success)
- Others (failure)

4.1.6 USB_Class_CDC_Get_Speed()

Get the USB speed of the CDC device.

Synopsis

Parameters

```
cdc_handle [in] - CDC class handler speed [out] - current speed
```

Description

The application calls this API function to get the USB speed of the CDC device.

Return Value

- **USB_OK** (success)
- Others (failure)

4.2 HID class API function listings

4.2.1 USB_Class_HID_Init()

Initializes the HID class.

Synopsis

```
hid_config_struct_t* hid_config_ptr,
hid_handle_t* hidHandle
)
```

Parameters

```
controller_id [in] - controller ID, such as USB_CONTROLLER_KHCI_0

hid_config_ptr [in] - HID configuration structure, see hid_config_struct_t
```

Note

In the KSDK 1.3, board_init_callback is added to this configuration structure. Initialize it with an appropriate board initialization function.

hidHandle [out] - pointer point to the initialized HID class, see <a href="hid-handle-to-hid-handle-

Description

The application calls this API function to initialize the HID class, the underlying layers, and the controller hardware.

Return Value

- USB_OK (success)
- Others (failure)

4.2.2 USB_Class_HID_Deinit()

Un-initializes the HID class.

Synopsis

```
usb_status USB_Class_HID_Deinit
(
          hid_handle_t handle
)
```

Parameters

```
handle [in] - HID class handler
```

Description

The application calls this API function to un-initialize the HID class, the underlying layers, and the controller hardware.

Return Value

- USB_OK (success)
- Others (failure)

4.2.3 USB_Class_HID_Send_Data()

Sends the HID data.

Synopsis

```
usb_status USB_Class_HID_Send_Data
(
    hid_handle_t handle,
    uint8_t ep_num,
    uint8_t* app_buff,
    uint32_t size
)
```

Parameters

```
handle [in] - HID class handler
ep_num [in] - endpoint number
app_buff [in] - buffer to send
size [in] - buffer length to send
```

Description

The application calls this API function to send HID data specified by <code>app_buff</code> and <code>size</code>. Once the data is sent, the application layer receives a callback event USB_DEV_EVENT_SEND_COMPLETE. This means that the transfer failed when the value of the object that the pointer size points to, is <code>0xFFFFFFFF</code> in the callback event USB_DEV_EVENT_SEND_COMPLETE. The application reserves the buffer until it receives a callback event indicating that the data is sent.

Return Value

- USB_OK (success)
- Others (failure)

4.2.4 USB_Class_HID_Cancel()

Cancels all the uncompleted transfers in the specified endpoint.

Synopsis

```
usb_status USB_Class_HID_Cancel
(
    hid_handle_t handle,
    uint8_t ep_num,
    uint8_t direction
)
```

Parameters

handle [in] - HID class handler

```
ep_num [in] - endpoint number

direction [in] - direction of the endpoint
```

Description

The application calls this API function to cancel all the uncompleted transfers in the specified endpoint.

Return Value

- USB_OK (success)
- Others (failure)

4.2.5 USB_Class_HID_Recv_Data()

Sends the HID data.

Synopsis

```
usb_status USB_Class_HID_Recv_Data
(
    hid_handle_t handle,
    uint8_t ep_num,
    uint8_t* app_buff,
    uint32_t size
)
```

Parameters

```
handle[in] - HID class handlerep_num[in] - endpoint numberapp_buff[in] - buffer to recvsize[in] - buffer length to recv
```

Description

The application calls this API function to send HID data specified by <code>app_buff</code> and <code>size</code>. Once the data is sent, the application layer receives a callback event USB_DEV_EVENT_DATA_RECEIVED. The transfer fails when the value of the object that the pointer size points is <code>0xFFFFFFFF</code> in callback event USB_DEV_EVENT_DATA_RECEIVED. The application reserves the buffer until it receives a callback event indicating that the data is received.

Return Value

- USB_OK (success)
- Others (failure)

4.2.6 USB_Class_HID_Get_Speed()

Get the USB speed of the HID device.

Synopsis

```
usb_status USB_Class_HID_Get_Speed
(
    hid_handle_t handle,
    uint16_t * speed
)
```

Parameters

```
handle [in] - HID class handler speed [out] - current speed
```

Description

The application calls this API function to get the USB speed of the HID device.

Return Value

- USB_OK (success)
- Others (failure)

4.3 MSC class API function listings

4.3.1 USB_Class_MSC_Init()

Initializes the MSC class.

Synopsis

```
usb_status USB_Class_MSC_Init
(
uint8_t controller_id,
msc_config_struct_t* msd_config_ptr,
msd_handle_t* msd_handle
)
```

Parameters

```
controller_id [in] - controller ID, like USB_CONTROLLER_KHCI_0

msd_config_ptr [in] - MSD configuration structure, see msc_config_struct_t
```

Note

In the KSDK 1.3, board_init_callback is added to this configuration structure. Initialize it with an appropriate board initialization function.

```
msd_handle [out] - pointer point to the initialized MSD class, see msd_handle_t
```

Description

The application calls this API function to initialize the MSD class, the underlying layers, and the controller hardware.

Return Value

- USB_OK (success)
- Others (failure)

4.3.2 USB_Class_MSC_Deinit()

Deinitializes the MSC class.

Synopsis

Parameters

```
msd_handle [in] - MSD class handler
```

Description

The application calls this API function to deinitialize the MSD class, the underlying layers, and the controller hardware.

Return Value

- USB_OK (success)
- Others (failure)

4.3.3 USB_Class_MSC_Get_Speed()

Get the USB speed of the MSD device.

Synopsis

```
usb_status USB_Class_MSC_Get_Speed
(
    msd_handle_t handle,
    uint16_t * speed
)
```

Parameters

```
handle [in] - MSD class handler speed [out] - current speed
```

Description

The application calls this API function to get the USB speed of the MSD device.

Return Value

- USB_OK (success)
- Others (failure)

4.4 Audio class API function listings

4.4.1 USB_Class_Audio_Init()

Initializes the AUDIO class.

Synopsis

```
usb_status USB_Class_Audio_Init
(
uint8_t controller_id,
audio_config_struct_t* audio_config_ptr,
audio_handle_t* audioHandle
)
```

Parameters

```
controller_id [in] - controller ID, such as USB_CONTROLLER_KHCI_0

audio_config_ptr [in] - AUDIO configuration structure, see audio_config_struct_t
```

Note

In the KSDK 1.3, board_init_callback is added to this configuration structure. Initialize it with an appropriate board initialization function.

audioHandle [out] - pointer point to the initialized AUDIO class, see audio_handle_t

Description

The application calls this API function to initialize the AUDIO class, the underlying layers, and the controller hardware.

Return Value

- USB_OK (success)
- **Others** (failure)

4.4.2 USB_Class_Audio_Deinit()

Un-initializes the AUDIO class.

Synopsis

```
usb_status USB_Class_Audio_Deinit
(
```

```
audio_handle_t handle
)
```

Parameters

handle [in] - AUDIO class handler

Description

The application calls this API function to un-initialize the AUDIO class, the underlying layers, and the controller hardware.

Return Value

- USB_OK (success)
- Others (failure)

4.4.3 USB_Class_Audio_Recv_Data()

Receives the AUDIO data.

Synopsis

Parameters

Description

The application calls this API function to receive data from host. Once the data is received, the application layer receives a callback event USB_DEV_EVENT_DATA_RECEIVED.

Return Value

- USB_OK (success)
- **Others** (failure)

4.4.4 USB_Class_Audio_Send_Data()

Sends the AUDIO data.

Synopsis

```
usb_status USB_Class_Audio_Send_Data
(
    audio_handle_t handle,
    uint8_t ep_num,
    uint8_t* app_buff,
    uint32_t size
)
```

Parameters

```
handle [in] - AUDIO class handler
ep_num [in] - endpoint number
app_buff [in] - buffer to send
size [in] - buffer length to send
```

Description

The application calls this API function to send data specified by <code>app_buff</code> and <code>size</code>. Once the data is sent, the application layer receives a callback event USB_DEV_EVENT_SEND_COMPLETE. The application reserves the buffer until it receives a callback event indicating that the data is sent.

Return Value

- USB OK (success)
- Others (failure)

4.4.5 USB_Class_Audio_Cancel()

Cancels all the uncompleted transfers in the specified endpoint.

Synopsis

```
usb_status USB_Class_Audio_Cancel
(
    audio_handle_t handle,
    uint8_t ep_num,
    uint8_t direction
)
```

Parameters

```
handle [in] - AUDIO class handler
ep_num [in] - endpoint number
```

direction [in] - direction of the endpoint

Description

The application calls this API function to cancel all the uncompleted transfers in the specified endpoint.

Return Value

- USB_OK (success)
- Others (failure)

4.4.6 USB_Class_Audio_Get_Speed()

Get the USB speed of the Audio device.

Synopsis

Parameters

```
audio_handle [in] - Audio class handler
speed [out] - current speed
```

Description

The application calls this API function to get the USB speed of the Audio device.

Return Value

- USB_OK (success)
- Others (failure)

4.5 PHDC class API function listings

4.5.1 USB_Class_PHDC_Init()

Initializes the PHDC class.

Synopsis

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Parameters

```
controller_id [in] - controller ID, like USB_CONTROLLER_KHCI_0

phdc_config_ptr [in] - PHDC configuration structure, see phdc_config_struct_t
```

Note

In the KSDK 1.3, board_init_callback is added to this configuration structure. Initialize it with an appropriate board initialization function.

```
phdcHandle [out] - pointer point to the initialized PHDC class, see <a href="phdchandle_t">phdc_handle_t</a>
```

Description

The application calls this API function to initialize the PHDC class, the underlying layers, and the controller hardware.

Return Value

- USB_OK (success)
- Others (failure)

4.5.2 USB_Class_PHDC_Deinit()

Un-initializes the PHDC class.

Synopsis

```
usb_status USB_Class_PHDC_Deinit
(
          phdc_handle_t handle
)
```

Parameters

handle [in] - PHDC class handler

Description

The application calls this API function to un-initialize the PHDC class, the underlying layers, and the controller hardware.

Return Value

- USB_OK (success)
- Others (failure)

4.5.3 USB_Class_PHDC_Recv_Data()

Receives the PHDC data.

```
usb_status USB_Class_PHDC_Recv_Data
```

```
phdc_handle_t handle,
uint8_t qos,
uint8_t* buff_ptr,
int32_t size
```

Parameters

```
handle [in] - PHDC class handler

qos [in] - the qos of the transfer

buff_ptr [in] - buffer to save the data from the host

size [in] - buffer length to receive
```

Description

The application calls this API function to receive data from host. Once the data is received, the application layer receives a callback event USB_DEV_EVENT_DATA_RECEIVED. The transfer failed when the value of the object that the pointer size points is 0xFFFFFFFF in callback event USB_DEV_EVENT_DATA_RECEIVED.

Return Value

- USB_OK (success)
- Others (failure)

4.5.4 USB_Class_PHDC_Send_Data()

Sends the PHDC data.

Synopsis

Parameters

```
handle [in] - PHDC class handler
meta_data [in] - the packet is metadata or not
num_tfr [in] - the number of transfers
```

```
qos [in] - current qos of the transfer

app_buff [in] - buffer to send

size [in] - buffer length to send
```

Description

The application calls this API function to send data specified by <code>app_buff</code> and <code>size</code>. Once the data is sent, the application layer receives a callback event USB_DEV_EVENT_SEND_COMPLETE. The application reserves the buffer until it receives a callback event stating that the data is sent. The transfer failed when the value of the object that the pointer size points is <code>0xFFFFFFFF</code> in callback event USB_DEV_EVENT_SEND_COMPLETE.

Return Value

- USB_OK (success)
- Others (failure)

4.5.5 USB_Class_PHDC_Cancel()

Cancels all the uncompleted transfers in the specified endpoint.

Synopsis

Parameters

```
handle [in] - PHDC class handler
ep_num [in] - endpoint number
direction [in] - direction of the endpoint
```

Description

The application calls this API function to cancel all the uncompleted transfers in the specified endpoint.

Return Value

- USB_OK (success)
- **Others** (failure)

4.5.6 USB_Class_PHDC_Get_Speed()

Get the USB speed of the PHDC device.

Synopsis

```
usb_status USB_Class_PHDC_Get_Speed
(
    phdc_handle_t handle,
    uint16_t * speed
)
```

Parameters

```
handle [in] - PHDC class handler speed [out] - current speed
```

Description

The application calls this API function to get the USB speed of the PHDC device.

Return Value

- USB_OK (success)
- Others (failure)

4.6 Composite class API function listings

4.6.1 USB_Composite_Init()

Initializes the composite class.

Synopsis

Parameters

```
controller_id [in] - controller ID, like USB_CONTROLLER_KHCI_0
composite_callback_ptr [in] - composite configuration structure, see
composite_config_struct_t
```

compositeHandle [out] - pointer point to the initialized composite class, see compositeLandle_t

Note

In the KSDK 1.3, board_init_callback is added to this configuration structure. Initialize it with an appropriate board initialization function.

Description

The application calls this API function to initialize the composite class, the underlying layers, and the controller hardware.

Return Value

- USB_OK (success)
- Others (failure)

4.6.2 USB_Composite_Deinit()

Un-initializes the Composite class.

Synopsis

Parameters

handle

[in] - composite class handler

Description

The application calls this API function to un-initialize the composite class, the underlying layers, and the controller hardware.

Return Value

- USB OK (success)
- **Others** (failure)

4.6.3 USB_Composite_Get_Speed()

Get the USB speed of the Composite device.

Synopsis

```
usb_status USB_Composite_Get_Speed
(
    composite_handle_t handle,
    uint16_t * speed
)
```

Parameters

```
handle [in] - Composite class handler speed [out] - current speed
```

Description

The application calls this API function to get the USB speed of the Composite device.

Return Value

- USB_OK (success)
- Others (failure)

Chapter 5 USB Device Descriptor

During the enumeration process, the host needs to get the device's descriptor. The USB Device Stack defines a set of callback functions to get the device's descriptor from the application and then passes it to the host to finish the enumeration process.

5.1 get_desc

Synopsis

Parameters

```
      handle
      [in] - class handler returned by the class initialization API

      type
      [in] - descriptor type

      desc_index
      [in] - index of descriptor

      index
      [in] - language ID if the type is USB_DESC_TYPE_STR

      descriptor
      [out] - pointer point to the buffer to hold the descriptor

      size
      [out] - descriptor size
```

Description

This callback function needs to be implemented by the application to provide different types of descriptor to the USB Device Stack, and the specified descriptor will be returned through the descriptor and size.

The following descriptors need to be supported in the implementation:

- USB_DESC_TYPE_DEV
- USB_DESC_TYPE_CFG
- USB_DESC_TYPE_STR
- USB_DESC_TYPE_DEV_QUALIFIER
- USB_DESC_TYPE_OTHER_SPEED_CFG

For different classes, the following descriptor may need to be supported:

- USB_HID_DESCRIPTOR
- USB_REPORT_DESCRIPTOR

Return Value

- 0 (success)
- Others (failure)

5.2 get_desc_interface

Synopsis

```
uint8_t (_CODE_PTR_ get_desc_interface)
(
uint32_t handle,
uint8_t interface,
uint8_t* alt_interface
);
```

Parameters

Description

This callback function needs to be implemented by the application to get the current alternate setting for the specified interface.

Return Value

- 0 (success)
- Others (failure)

5.3 set_desc_interface

```
uint8_t (_CODE_PTR_ set_desc_interface)
(
uint32_t handle,
uint8_t interface,
uint8_t alt_interface
);
```

Parameters

```
handle [in] - class handler returned by the class initialization API
interface [in] - interface index
alt_interface [in] - alternate setting for the interface
```

Description

This callback function needs to be implemented by the application to set the current alternate setting for the specified interface.

Return Value

- 0 (success)
- Others (failure)

5.4 set_configuration

Synopsis

```
uint8_t (_CODE_PTR_ set_configuration)
(
uint32_t handle,
uint8_t config
);
```

Parameters

```
handle [in] – The class handler returned by the class initialization API
config [in] – The configuration index
```

Description

This callback function needs to be implemented by the application to get to know which configuration is active by the host.

Return Value

- 0 (success)
- Others (failure)

5.5 get_desc_entity

Synopsis

```
uint8_t (_CODE_PTR_ get_desc_entity)
(
uint32_t handle,
entity_type type,
uint32_t * object
)
```

Parameters

```
handle [in] – class handler returned by the class initialization API

type [in] – entity type need to be obtained

object [out] – target entity object pointer
```

Description

This callback function needs to be implemented by the application to provide descriptor/device related information to the USB Device stack.

The type could be:

USB_CLASS_INFO

Must be implemented by all kinds of devices to provide all the descriptor related information

USB_AUDIO_UNITS

Must be implemented by the AUDIO device to provide the AUDIO units related information

USB_MSC_LBA_INFO

Must be implemented by the MSC device to provide mass storage LAB related information

USB_COMPOSITE_INFO

Must be implemented by the composite device to provide composite device's descriptor related information.

USB_RNDIS_INFO

Must be implemented by the CDC RNDIS device to provide RNDIS related information

USB CLASS INTERFACE INDEX INFO

Must be implemented by the composite device to provide the class index

Return Value

- 0 (success)
- Others (failure)

Chapter 6 USB Device Configuration

The USB Device stack supports different configurations customized by the user in different cases.

The configuration varies depend on different boards, so you can get the configuration file in <USB_ROOT>/usb_core/device/include/<SOC_NAME>.

The following configuration items are supported in the USB Device Stack:

- USBCFG_DEV_KHCI
 - o 1 indicates that the KHCI controller (Full-Speed) is enabled.
 - o 0 indicates that the KHCI controller (Full-Speed) is disabled.
- USBCFG DEV EHCI
 - o 1 indicates that the EHCI controller (High-Speed) is enabled.
 - o 0 indicates that the EHCI controller (High-Speed) is disabled.
- USBCFG_DEV_KHCI_NUM
 - The MACRO indicates how many KHCI devices can be active at the same time. When this MACRO is bigger, more RAM is needed. If USBCFG_DEV_KHCI is nonzero, the default value is 1. Otherwise, the value is 0.
- USBCFG_DEV_EHCI_NUM
 - o The MACRO indicates how many EHCI devices can be active at the same time. When this MACRO is bigger, more RAM is needed. If USBCFG_DEV_EHCI is nonzero, the default value is 1. Otherwise, the value is 0.
- USBCFG_DEV_NUM
 - The MACRO indicates how many devices can be active at the same time. When this MACRO is bigger, more RAM is needed. The default value is sum of USBCFG DEV KHCI NUM and USBCFG DEV EHCI NUM.
- USBCFG_DEV_HID
 - o 1 indicates that the HID class driver is enabled.
 - o 0 indicates that the HID class driver is disabled.
- USBCFG DEV PHDC
 - o 1 indicates that the PHDC class driver is enabled.
 - o 0 indicates that the PHDC class driver is disabled.
- USBCFG DEV AUDIO
 - o 1 indicates that the AUDIO class driver is enabled.
 - o 0 indicates that the AUDIO class driver is disabled.

USBCFG_DEV_CDC

- o 1 indicates that the CDC class driver is enabled.
- o 0 indicates that the CDC class driver is disabled.

USBCFG_DEV_MSC

- o 1 indicates that the MSC class driver is enabled.
- o 0 indicates that the MSC class driver is disabled.

USBCFG DEV SELF POWER

- o 1 indicates self power.
- o 0 indicates bus power.

USBCFG_DEV_REMOTE_WAKEUP

- o 1 indicates that remote wakeup is enabled.
- o 0 indicates that remote wakeup is disabled.

USBCFG_DEV_MAX_ENDPOINTS

o The MACRO indicates how many endpoints can be used in a device. When this MACRO is bigger, more RAM is needed. The default value is 6.

USBCFG_DEV_MAX_XDS

The MACRO indicates how many internal transfer descriptors can be used in a device. When this MACRO is bigger, more RAM is needed. The default value is 12.

USBCFG_DEV_MAX_CLASS_OBJECT

• The MACRO indicates how many instances can be supported for one class type device. When this MACRO is bigger, more RAM is needed. The default value is 1.

USBCFG_KHCI_4BYTE_ALIGN_FIX

- o Effective when USBCFG_DEV_EHCI is nonzero.
- o The Full-Speed controller requires that all the buffers used for the transfer need to be 4 bytes aligned (both the start address and the length). If the application can guarantee it, then the MACRO USBCFG_KHCI_4BYTE_ALIGN_FIX can be set to 0. Otherwise, it needs to set to 1, and then the USB Device Stack will use an internal 4 bytes aligned buffer to replace the buffer provided by the user so that the above requirement can be meet. The internal buffer size is assigned by the MACRO.

USBCFG_DEV_KHCI_SWAP_BUF_MAX.

- o Effective when USBCFG_DEV_EHCI is nonzero.
- o Effective when USBCFG_KHCI_4BYTE_ALIGN_FIX is nonzero.
- USBCFG_DEV_KHCI_ADVANCED_ERROR_HANDLING

- o 1 indicates that the error event will be sent to the application.
- o 0 indicates that the error event will not be sent to the application.
- o Effective for the Full-Speed controller only.

USBCFG_DEV_EHCI_MAX_ENDPOINTS

- o The MACRO indicates how many endpoints can be used in a high-speed device. The default value is depended on the Chip.
- o Effective for the High-Speed controller only.

USBCFG_DEV_EHCI_MAX_DTD

- The MACRO indicates how many DTD can be used in a high-speed device. When this MACRO is bigger, more RAM is needed. The default value is 16.
- o Effective for the High-Speed controller only.

USBCFG_DEV_EHCI_ADVANCED_ERROR_HANDLING

- o 1 indicates that the error event will be sent to the application.
- o 0 indicates that the error event will not be sent to the application.
- o Effective for the High-Speed controller only.

USBCFG_DEV_KEEP_ALIVE_MODE

- o 1 indicates that keep alive is enabled.
- o 0 indicates that keep alive disabled.
- o Effective for the Full-Speed controller only.

USBCFG_DEV_BUFF_PROPERTY_CACHEABLE

- o 1 indicates that the cache maintenance in USB Device Stack is enabled.
- o 0 indicates that the cache maintenance in USB Device Stack is disabled.
- o If the application does not use the cacheable memory in the USB transfer, this MACRO needs to be set to 0. Otherwise, it needs to be set to 1, and the application needs to make sure that the cacheable memory is CACHE LINE size aligned (both start address and length).

USBCFG_DEV_ADVANCED_SUSPEND_RESUME

- Whether the suspend/resume needs to be enabled. It can be set to 0 only, because suspend/resume is not implemented yet.
- USBCFG_DEV_ADVANCED_CANCEL_ENABLE
 - Whether the cancel operation needs to be enabled. The default value is 1.
- USBCFG DEV DETACH ENABLE

- Whether the device detach function needs to be enabled. The default value is 0.
- USBCFG_DEV_IO_DETACH_ENABLE
 - Whether the device detach function uses IO to implement when device detach function is enabled. The default value is 0.

Chapter 7 USB Device Data structures

This section describes the data structures that need to be used from the application.

7.1 USB common controller driver

7.1.1 usb_ep_struct_t

Description

Obtains the endpoint data structure.

Synopsis

Fields

```
ep_number - endpoint number

type - type of endpoint

direction - direction of endpoint

size - maximum packet size of endpoint
```

7.1.2 usb_endpoints_t

Description

Obtains the endpoint group.

Synopsis

```
typedef struct _usb_endpoints
{
    uint8_t count;
    usb_ep_struct_t* ep;
} usb_endpoints_t;
```

Fields

```
count - how many endpoints are described ep - detailed information of each endpoint
```

7.1.3 usb_if_struct_t

Description

Obtains the interface data structure.

Synopsis

```
typedef struct _usb_if_struct
{
     uint8_t index;
     usb_endpoints_t endpoints;
} usb_if_struct_t;

Fields
index - interface index
```

endpoints - endpoints in this interface

7.1.4 usb_interfaces_struct_t

Description

Obtains the interface group.

Synopsis

Fields

count – how many interfaces are described

 $\verb|interface| - detailed information| of each interface$

7.1.5 usb_class_struct_t

Description

Obtains the class data structure.

Fields

```
index - class type
interfaces - interfaces in this class
```

7.1.6 usb_composite_info_struct_t

Description

Obtains the composite information data structure.

Synopsis

Fields

```
count - how many classes in the composite device class - detailed information of each class
```

7.1.7 usb_desc_request_notify_struct_t

Description

Obtains the data structure of the descriptor related callback function. The application needs to implement them and passes it as the configuration parameter.

Synopsis

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```
} usb_desc_request_notify_struct_t;
```

Fields

```
get_desc - to get the descriptor whose type is specified by the type
get_desc_interface - to get the interface's alternate setting
set_desc_interface - to set the interface's alternate setting
set_configuration – to inform the application whose configuration is active
get_desc_entity - to get the descriptor/device related information
```

7.2 CDC class data structure

7.2.1 cdc_handle_t

Description

Represents the CDC class handle.

Synopsis

```
typedef uint32_t cdc_handle_t;
```

7.2.2 _ip_address

Description

Represents the IP address.

Synopsis

```
typedef uint32_t _ip_address;
```

7.2.3 cdc_app_data_struct_t

Description

Holds the information of CDC data struct.

```
typedef struct _cdc_app_data_struct
       uint8_t*
                                                    data_ptr;
       uint32_t
                                                    data_size;
   }cdc_app_data_struct_t;
Fields
```

```
data_ptr - pointer to buffer
data_size - buffer size
```

7.2.4 usb rndis info struct t

Description

Holds the detailed information about the RNDIS.

Synopsis

```
typedef struct _usb_rndis_info_struct
{
    enet_address_t mac_address;
    _ip_address ip_address;
    uint32_t rndis_max_frame_size;
} usb_rndis_info_struct_t;

Fields

mac_address - MAC address

ip_address - IP address
```

rndis max frame size - maximum frame size

7.2.5 cdc_config_struct_t

Description

Holds the detailed information about the CDC configuration.

Synopsis

Fields

cdc_application_callback - application callback function to handle the Device status related event vendor_req_callback - application callback function to handle the vendor request related event, reserved for future use

class_specific_callback - application callback function to handle all the class related events
board_init_callback - application callback function to handle board init
desc_callback_ptr - descriptor related callback function data structure

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7.3 HID class data structure

7.3.1 hid_handle_t

Description

Represents the HID class handle.

Synopsis

```
typedef uint32_t hid_handle_t;
```

7.3.2 hid_config_struct_t

Description

Holds the detailed information about the HID class configuration.

Synopsis

Fields

hid_application_callback – application callback function to handle the Device status related event vendor_req_callback – application callback function to handle the vendor request related event, reserved for future use

class_specific_callback – application callback function to handle all the class related event board_init_callback - application callback function to handle board init desc_callback_ptr – descriptor related callback function data structure.

7.4 MSC class data structure

7.4.1 msc_handle_t

Description

Represents the MSC class handle.

```
typedef uint32_t msc_handle_t;
```

7.4.2 msc_app_data_struct_t

Description

Holds the information of MSC app data struct.

Synopsis

7.4.3 lba_app_struct_t

data_size - buffer size

Description

Holds the information used to perform the logical block access.

Synopsis

```
typedef struct _lba_app_struct
{
    uint32_t offset;
    uint32_t size;
    uint8_t* buff_ptr;
}lba_app_struct_t;

Fields

offset - offset of target block need to access
size - size need to access
```

buff_ptr – used to save the content by access the target block

7.4.4 device_lba_info_struct_t

Description

Holds the detailed information about the LAB.

Synopsis

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```
}device_lba_info_struct_t;
Fields

total_lba_device_supports - blocks number

length_of_each_lab_of_device - size of each block
num_lun_supported - number of LUN
```

7.4.5 msc_config_struct_t

Description

Holds the detailed information about the MSC configuration.

Synopsis

Fields

msc_application_callback - application callback function to handle the Device status related event
vendor_req_callback - application callback function to handle the vendor request related event,
reserved for future use

class_specific_callback – application callback function to handle all the class related event board_init_callback - application callback function to handle board init desc_callback_ptr - descriptor related callback function data structure.

7.5 Audio class data structure

7.5.1 audio_handle_t

Description

Represents the AUDIO class handle.

Synopsis

```
typedef uint32_t audio_handle_t;
```

7.5.2 audio_app_data_struct_t

Description

Holds the information of audio app data struct.

Synopsis

7.5.3 audio_config_struct_t

Description

Holds the detailed information about the AUDIO configuration.

Synopsis

Fields

audio_application_callback - application callback function to handle the Device status related event vendor_req_callback - application callback function to handle the vendor request related event, reserved for future use

class_specific_callback - application callback function to handle all the class related event
board_init_callback - application callback function to handle board
initdesc_callback_ptr - descriptor related callback function data structure.

7.6 PHDC class data structure

7.6.1 phdc_handle_t

Description

Represents the PHDC class handle.

```
typedef uint32_t phdc_handle_t;
```

7.6.2 phdc_app_data_struct_t

Description

Holds the buffer information along with the send complete event.

Synopsis

```
typedef struct _phdc_app_data_struct
{
    uint8_t qos;
    uint8_t* buffer_ptr;
    uint32_t size;
} phdc_app_data_struct_t;

Fields

qos - the qos of the transfer

buffer_ptr - the buffer point

size - the buffer size
```

7.6.3 phdc_config_struct_t

Description

Holds the detailed information about the PHDC configuration.

Synopsis

Fields

phdc_application_callback - application callback function to handle the Device status related event vendor_req_callback - application callback function to handle the vendor request related event, reserved for future use

class_specific_callback - application callback function to handle all the class related event
board_init_callback - application callback function to handle board init
desc_callback_ptr - descriptor related callback function data structure.

7.7 Composite class data structure

7.7.1 composite_handle_t

Description

Represents the composite class handle.

Synopsis

```
typedef uint32_t composite_handle_t;
```

7.7.2 class_config_struct_t

Description

Holds the information one type of class configuration.

Synopsis

```
typedef struct _class_config_struct
 {
     usb_application_callback_struct_t
                                                 application_callback;
     usb_vendor_req_callback_struct_t
                                                 vendor_req_callback;
     usb class specific callback struct t
                                                 class specific callback;
     usb desc request notify struct t*
                                                 desc callback ptr;
    usb_board_init_callback_struct_t
                                               board_init_callback;
     uint32 t
                                                 class handle;
     class_type
                                                 type;
 }class_config_struct_t;
```

Fields

<code>application_callback</code> – application callback function to handle the Device status related event for the specified type of class

vendor_req_callback – application callback function to handle the vendor request related event, reserved for future use

class_specific_callback – application callback function to handle all the class related event for the specified type of class

 $desc_callback_ptr$ – descriptor related callback function data structure for the specified type of class.

class handle – the handle of the class.

board_init_callback - application callback function to handle board init type - class type

7.7.3 composite_config_struct_t

Description

Holds the detailed information about the MSC configuration.

Synopsis

Fields

count – how many classes are supported for the composite deviceclass_app_callback – detailed information for each class

Appendix

A. USB device stack tasks

There are one task as follow:

Task name	Priority macro	Priority value
DEV task	USB_DEVICE_TASK_PRIORITY	6

Note

For RTOS, application unblocked tasks' priorities should be lower than the above priority.

Chapter 8 Revision history

This table summarizes revisions to this document since the release of the previous version

Revision History			
Revision number	Date	Substantive changes	
1	04/2015	KSDK 1.2.0 Release	
2	09/2015	Updated Section 2.1	

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