

# A Gentle Introduction to Model Order Reduction via Proper Orthogonal Decomposition

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**ODEN INSTITUTE**

FOR COMPUTATIONAL ENGINEERING & SCIENCES



The University of Texas at Austin

# Outline

- 1 The Model Reduction Problem
- 2 Solution Strategy
- 3 Example: Heat Equation

# Large Dynamical Systems

Many computational science, engineering, and mathematics applications eventually reduce to the problem of solving a (very) large system of ordinary differential equations:

$$\frac{d}{dt}\mathbf{x}(t) = \mathbf{f}(t, \mathbf{x}(t)), \quad \mathbf{x}(0) = \mathbf{x}_0, \quad (*)$$

where

$$\mathbf{x} : \mathbb{R} \rightarrow \mathbb{R}^n, \quad \mathbf{f} : \mathbb{R} \times \mathbb{R}^n \rightarrow \mathbb{R}^n, \quad \mathbf{x}_0 \in \mathbb{R}^n.$$

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- The dimension  $n$  is large ( $n \sim 10^8$ )
- We can solve  $(*)$ , but it is computationally expensive to do so

## Small Dynamical Systems

The goal of model order reduction (MOR) is to construct a low-dimensional system

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The goal is typically  $r < 50$  or so.

## Strategy: Projection to a Linear Subspace

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To approximate the solution set  $\{\mathbf{x}(t) \mid t \geq 0\}$ , simulate the FOM (\*) and record the solution  $\mathbf{x}(t)$  at times  $0 = t_0 < t_1 < \dots < t_{k-1}$ . Stack the results column-wise to get the *snapshot matrix*,

$$X = \left[ \begin{array}{c|c|c|c} \mathbf{x}(t_0) & \mathbf{x}(t_1) & \dots & \mathbf{x}(t_{k-1}) \end{array} \right] \in \mathbb{R}^{n \times k}.$$

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Now the column space (range) of  $X$  is an approximation to  $\{\mathbf{x}(t) \mid t \geq 0\}$ .

But we want  $V \in \mathbb{R}^{n \times r}$  (probably  $r < k < n$ )...

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## Theorem

Let  $A \in \mathbb{R}^{n \times k}$  have the singular value decomposition

$$A = \Phi \Sigma \Psi^T.$$

Then the first  $r$  columns of  $\Phi$  are the best rank- $r$  approximation of the column space of  $A$ . In other words,  $\{\phi_j\}_{j=1}^r$  solves the minimization problem

$$\operatorname{argmin}_{\tilde{\phi}_1, \dots, \tilde{\phi}_r \in \mathbb{R}^n} \sum_{j=1}^k \left\| \mathbf{x}_j - \sum_{i=1}^r \langle \mathbf{x}_j, \tilde{\phi}_i \rangle_{\mathbb{R}^n} \tilde{\phi}_i \right\|_{\mathbb{R}^n}^2$$

such that

$$\langle \tilde{\phi}_i, \tilde{\phi}_j \rangle_{\mathbb{R}^n} = \delta_{ij} \quad \text{for } 1 \leq i, j \leq r.$$

## Strategy: Use POD to Define the Linear Subspace

Define

$$V_r := \Phi_{:,r}(X) \in \mathbb{R}^{n \times r},$$

the POD basis of rank  $r$  corresponding to the snapshot matrix  $X$ .

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- $V_r^T V_r = I \in \mathbb{R}^{r \times r}$
- $V_r V_r^T$  is the orthogonal projector onto

$$\text{Range}(V_r) \approx \text{Range}(X) \approx \{\mathbf{x}(t) \mid t \geq 0\}$$

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Since  $V_r$  is orthonormal,

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- 1 Project the initial value as  $\hat{\mathbf{x}}_0 = V_r^T \mathbf{x}_0$ .
- 2 Solve the ROM with initial value  $\hat{\mathbf{x}}_0$ , obtaining  $\hat{\mathbf{x}}(t)$
- 3 Reconstruct the solution in the initial space as  $\mathbf{x}_{\text{ROM}}(t) = V_r \hat{\mathbf{x}}(t)$ .

## Example: Heat Equation

Consider the following one-dimensional parabolic PDE.

$$x_t(t, \omega) = \frac{1}{\pi^2} x_{\omega\omega}(t, \omega), \quad (t, \omega) \in (0, T] \times \Omega,$$

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We can reduce this system!

<https://tinyurl.com/y28qhsf1>