CSIR Defence, Peace, Safety and Security

Pyradi: an open-source toolkit for infrared calculation and data processing

SPIE S+D 8543-19

Willers, Willers, Santos, van der Merwe, Calitz, de Waal & Mudau



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Infrared Data Analysis

Who has done infrared measurement data analysis?

You will understand the next slide....





Infrared Data Analysis

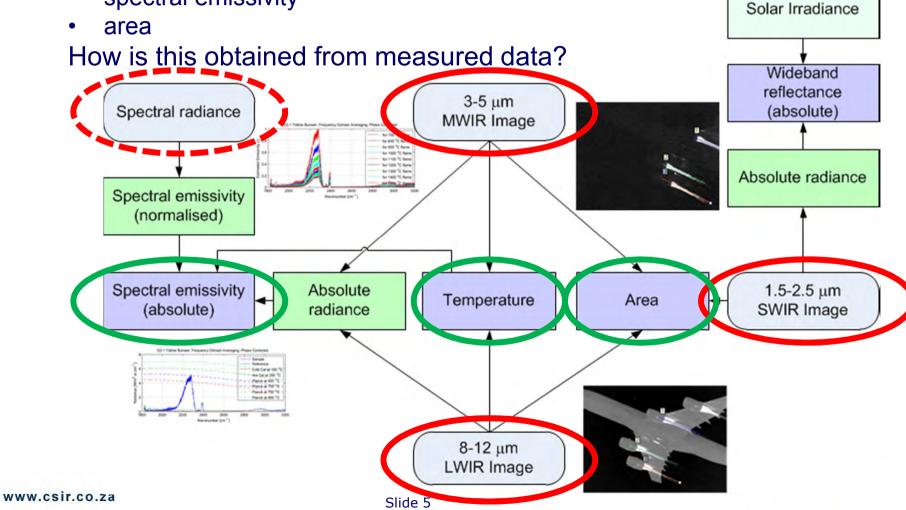




Signatures From Measurements

Main focus of infrared target modelling:

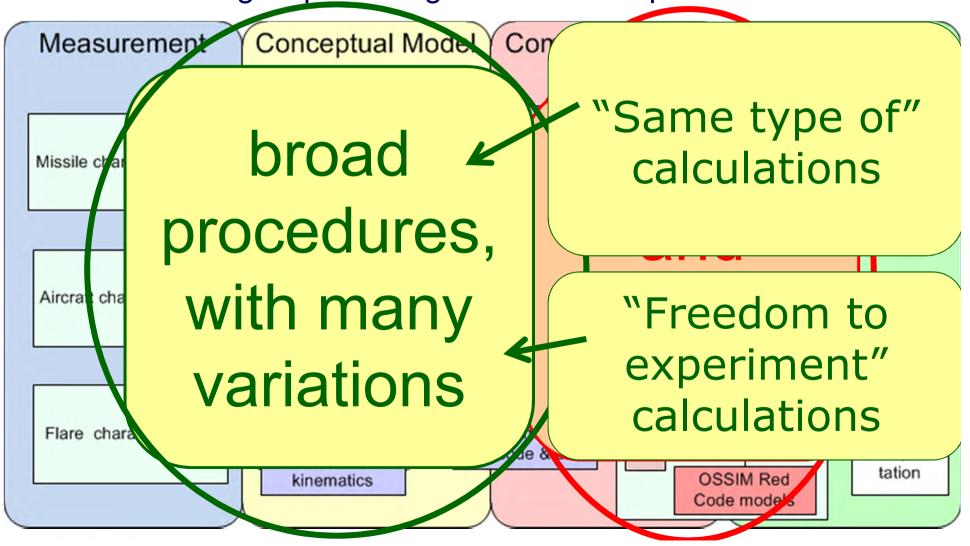






From Measurements to Results

Model building requires huge amount of repetitive calculation



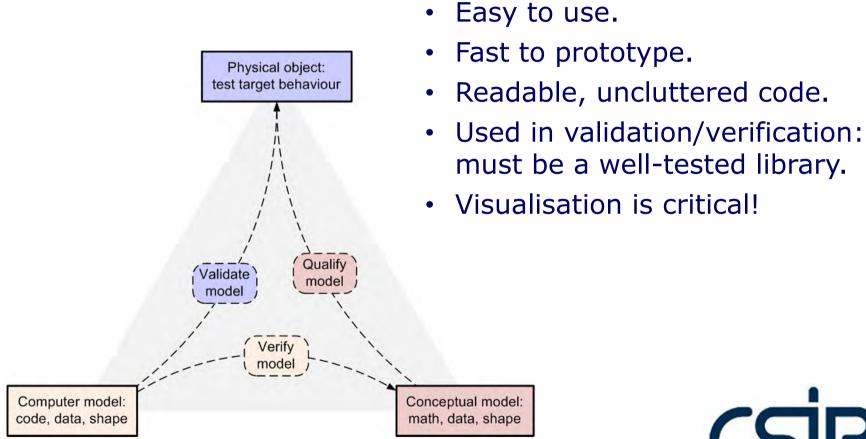


Vital to Insight!





Key Requirements



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pyradi

Focussed on electro-optics calculations.

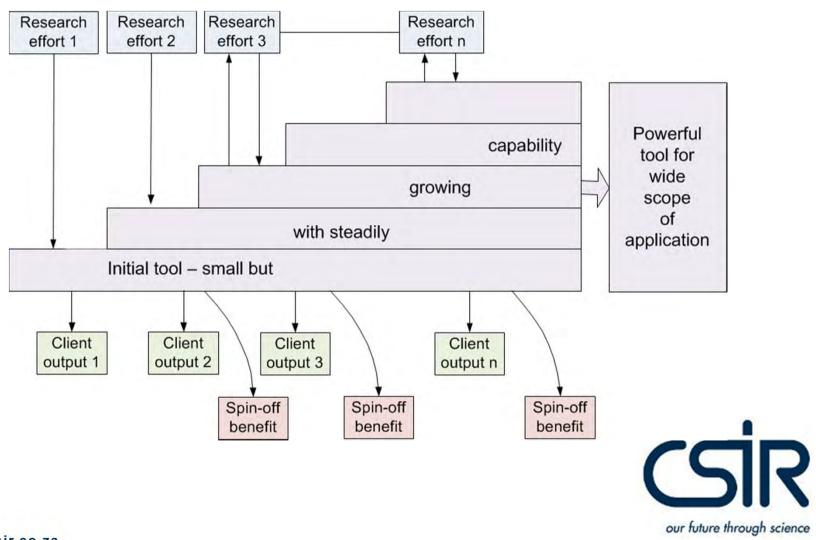
The toolkit covers

- models of physical concepts,
- mathematical operation,
- data manipulation, and
- graphical visualisation.





Cumulative Development



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Scripting Language

Matlab vs Python.

Extensive experience with both languages.

Python won:

- General purpose, mainstream, language.
- A more powerful and productive language.
- Many extensions in very many application areas.
- Numpy & Scipy equal to Matlab for scientific work.
- Superior visualisation & graphics tools.
- Easy to learn & very strong open source support.
- Zero acquisition cost & low usage cost.
- Negative: no Simulink, fewer toolboxes.

SIR



Unix Tool Philosophy

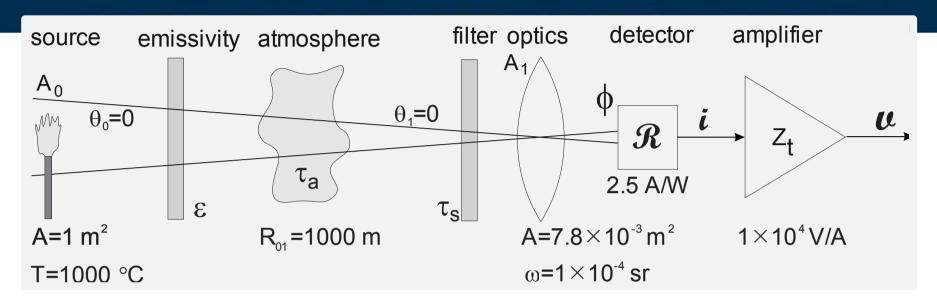
Write programs that do one thing and do it well. Write programs to work together.

- Simple parts connected by clean interfaces.
- Clarity in coding.
- Write big programs putting together building blocks.
- Programmer time is expensive; conserve it.
- Quick prototyping before polishing.
- Design for the future, because it will be here sooner than you think.

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Example: Flame Detection



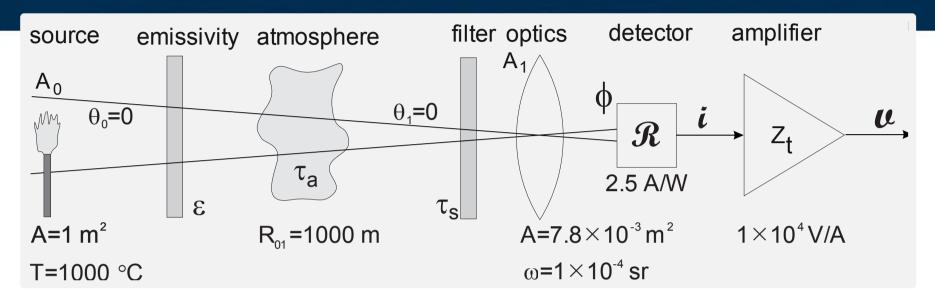
Detect the presence or absence of a flame, through the atmosphere in 3-5 μ m band.



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Example: Flame Detection



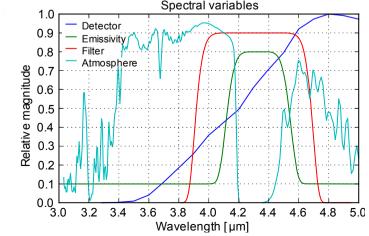
Signal from the flame:

$$v = Z_t \int_{A_0} \int_{A_1} \frac{1}{r_{01}^2} \int_0^\infty \epsilon_\lambda L_\lambda(T,A_0) au_{a\lambda} au_{s\lambda}(A_1) \mathcal{R}_\lambda \ d\lambda \ d(\cos heta_0 A_0) \ d(\cos heta_1 A_1).$$

Signal from the atmospheric radiance:

$$v = Z_t \omega_{
m optics} A_{
m optics} \int_0^\infty L_{
m path} \tau_{s\lambda} \mathcal{R}_{\lambda} \ d\lambda,$$

Modtran spectral transmittance & path radiance





Solution Page 1 of 2

```
#load atmospheric transmittance from file created in Modtran in wavenumbers
# the transmittance is specified in the wavenumber domain with
# 5 cm-1 intervals, but we want to work in wavelength with 2.5 cm-1
waven = numpy.arange(2000.0, 3300.0, 2.5).reshape(-1, 1)
wavel= rvutils.convertSpectralDomain(waven, type='nw')
#remove comment lines, and scale path radiance from W/cm2.sr.cm-1 to W/m2.sr.cm-
tauA = ryfiles.loadColumnTextFile('data/path1kmflamesensor.txt',
       [1],abscissaOut=waven, comment='%')
lpathwn = ryfiles.loadColumnTextFile('data/pathspaceflamesensor.txt',
                                                                                Only two
       [9],abscissaOut=waven, ordinateScale=1.0e4, comment='%')
                                                                                pages
#convert path radiance spectral density from 1/cm^-1 to 1/um, at the sample
#wavenumber points
(dum, lpathwl) = ryutils.convertSpectralDensity(waven, lpathwn, type='nw')
#load the detector file in wavelengths, and interpolate on required values
detR = ryfiles.loadColumnTextFile('data/detectorflamesensor.txt',
      [1],abscissaOut=wavel, comment='%')
#construct the flame emissivity from parameters
emis = ryutils.sfilter(wavel,center=4.33, width=0.45, exponent=6, taupass=0.8,
        taustop=0.1)
#construct the sensor filter from parameters
sfilter = ryutils.sfilter(wavel,center=4.3, width=0.8, exponent=12,
        taupass=0.9, taustop=0.0001)
                                                                                 our future through science
```

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Solution Page 2 of 2

```
# define sensor scalar parameters
opticsArea=7.8e-3 # optical aperture area [m2]
                                                                             The code is:
opticsFOV=1.0e-4 # sensor field of view [sr]
transZ=1.0e4 # amplifier transimpedance gain [V/A]

    Compact

responsivity=2.5 # detector peak responsivity =A/W1

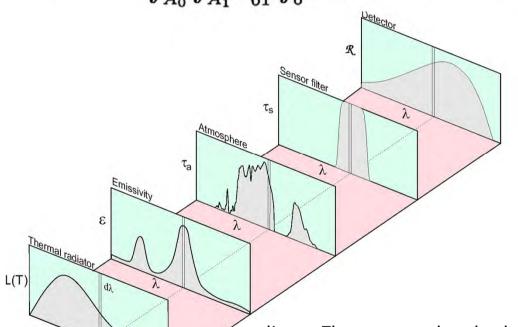
    Clean

# define the flame properties
flameTemperature = 1000+273.16 # temperature in [K]
                                                                               Intuitive
flameArea = 1 \# in \lceil m2 \rceil
distance = 1000 # [m]
fill = (flameArea /distance**2) / opticsFOV # how much of FOV is filled
fill = 1 if fill > 1 else fill # limit target solid angle to sensor FOV
# flame get spectral radiance in W/m^2.sr.cm-1
radianceFlame = ryplanck.planck(waven, flameTemperature, type='en')\
         .reshape(-1, 1)/numpy.pi
inbandirradianceFlame = radianceFlame * detR * tauA * emis * sfilter *\
         fill * opticsFOV
totalirradianceFlame = numpy.trapz(inbandirradianceFlame.reshape(-1, 1),
        waven, axis=0)[0]
signalFlame = totalirradianceFlame *transZ*responsivity *opticsArea
# now do path
inbandirradiancePath = Ipathwn * detR * sfilter * opticsFOV
totalirradiancePath = numpy.trapz(inbandirradiancePath.reshape(-1, 1), waven, axis=0)[0]
signalPath = totalirradiancePath * transZ*responsivity *opticsArea
```



Multi-spectral Calculations

$$v = Z_t \int_{A_0} \int_{A_1} \frac{1}{r_{01}^2} \int_0^\infty \epsilon_{\lambda} L_{\lambda}(T, A_0) \tau_{a\lambda} \tau_{s\lambda}(A_1) \mathcal{R}_{\lambda} \ d\lambda \ d(\cos \theta_0 A_0) \ d(\cos \theta_1 A_1).$$



- Spectral variables are vectors.
- Calculate irradiance at each wavelength 'bin' by vector element-wise multiplication.
- Add flux at all wavelengths.

radianceFlame = ryplanck.planck(waven, flameTemperature, type='en')\
.reshape(-1, 1)/numpy.pi

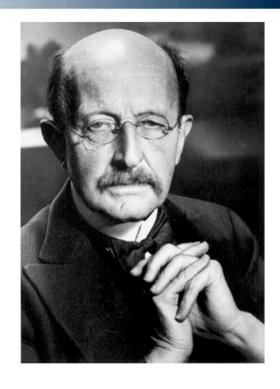
signalFlame = totalirradianceFlame *transZ*responsivity *opticsArea



Planck's Law

$$M_{e\lambda}(T) = \frac{2\pi hc^2}{\lambda^5 \left(e^{\frac{hc}{\lambda kT}} - 1\right)}$$

Pyradi provides functions for Planck Law emittance, as well as Planck Law temperature derivative in terms of: [W] or [q/s] and [μm, cm⁻¹, Hz].

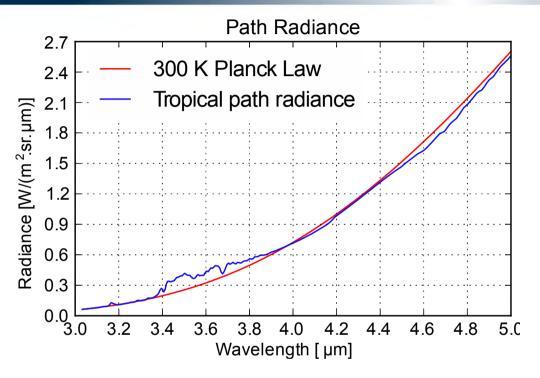


```
Mel = planck(wl, temperature[0], type='el') # [W/(m$^2$.$\mu$m)]
Mql = planck(wl, temperature[0], type='ql') # [q/(s.m$^2$.$\mu$m)]
Men = planck(n, temperature[0], type='en') # [W/(m$^2$.cm$^{-1}$)]

Mqn = dplanck(n, temperature[0], type='qn') # [q/(s.m$^2$.cm$^{-1}$.K)]
Mef = dplanck(f, temperature[0], type='ef') # [W/(m$^2$.Hz.K)]
Mqf = dplanck(f, temperature[0], type='qf') # [q/(s.m$^2$.Hz.K)]
```



Visualising Path Radiance



Flame sensor path:

- Horizontal path to space.
- Notice correspondence.
- Visualisation important!

#check path radiance against Planck's Law for atmo temperature

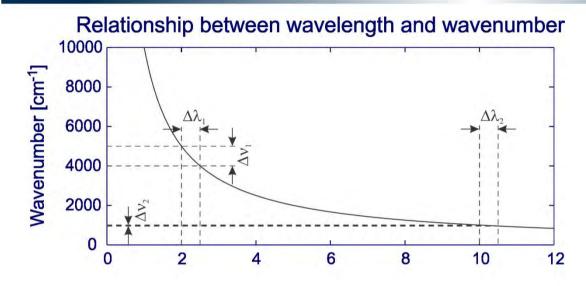
LbbTropical = ryplanck.planck(wavel, 273+27, type='el').reshape(-1, 1)/numpy.pi plot1.plot(2, wavel, LbbTropical, plotCol=['r'], label=['300 K Planck Law']) plot1.plot(2, wavel, lpathwl, plotCol=['b'], label=['Tropical path radiance']) currentP = plot1.getSubPlot(2) currentP.set_xlabel('Wavelength [\$\mu\$m]') currentP.set_ylabel('Radiance [W/(m\$^2\$.sr.\$\mu\$m)]')

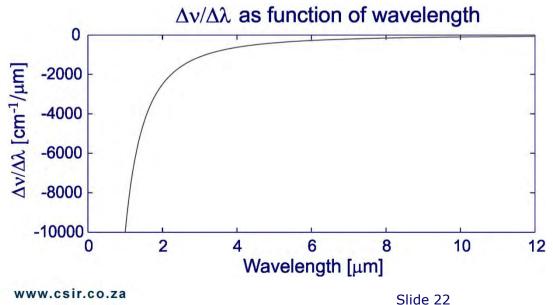
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currentP.set title('Path Radiance')



Wavelength and Wavenumber





Wavenumber is given by

$$\nu = 10^4/\lambda$$

where λ is in units of μ m.

The conversion of a spectral quantity requires the derivative, as follows:

$$d\nu = \frac{-10^4}{\lambda^2} d\lambda = \frac{\nu^2}{-10^4} d\lambda$$

$$dL_{\nu} = dL_{\lambda} \frac{\lambda^2}{10^4} = dL_{\lambda} \frac{10^4}{\nu^2}$$

Pyradi converts between spectral variables:

as well as spectral densities:

$$[W/(m^2 \cdot \mu m)],$$

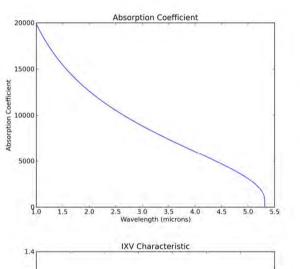
$$[W/(m^2 \cdot cm - 1)],$$

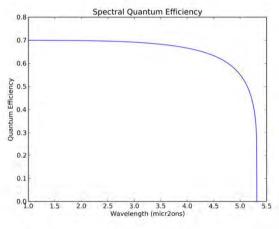
 $[W/(m^2 \cdot Hz)].$

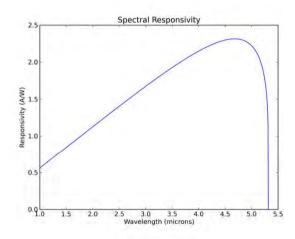


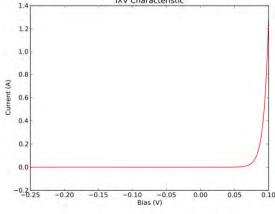
Detector Modelling

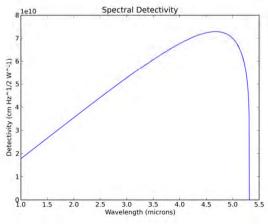
Detector model, based on first principles physics. Example shown is for InSb detector.











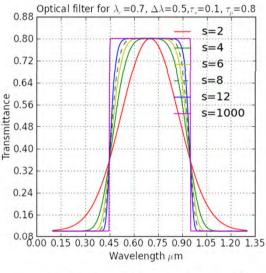


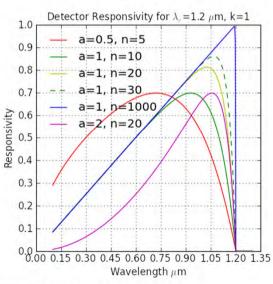
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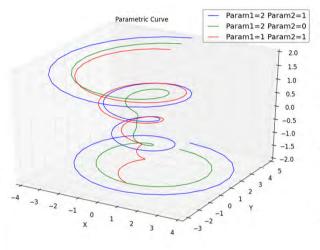
Slide 23

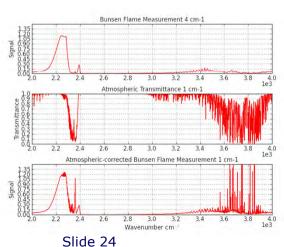


Utility Functions



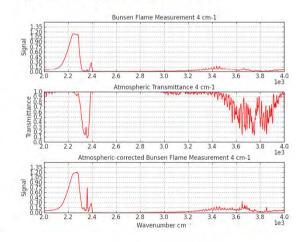






General purpose models:

- Spectral filter shapes.
- Photon detector shapes.
- Spectral convolution.
- Effective value normalisation.
- Various 2-D & 3-D plotting functions.

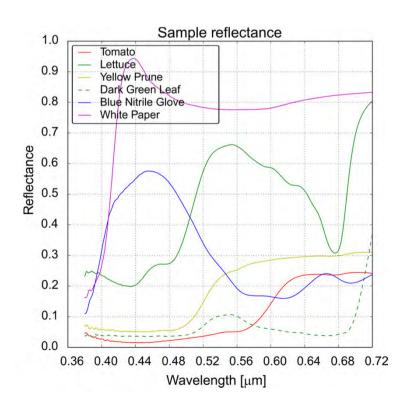


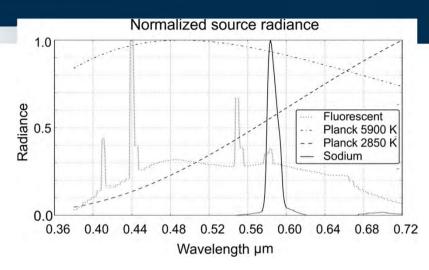
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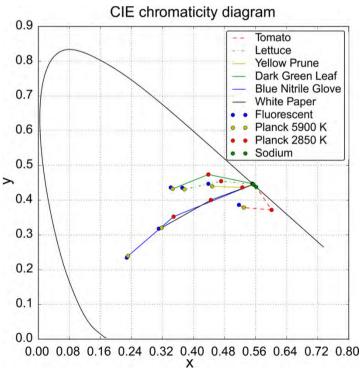


Chromaticity Coordinates

Basic functionality for CIE-1931 coordinate calculation for spectral source radiance and sample reflectance





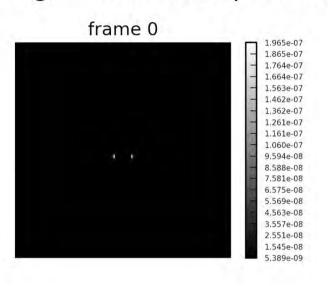


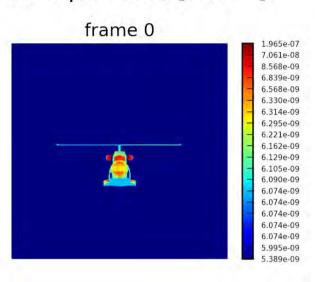
Slide 25

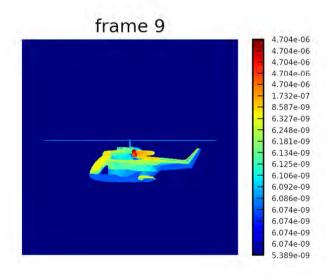


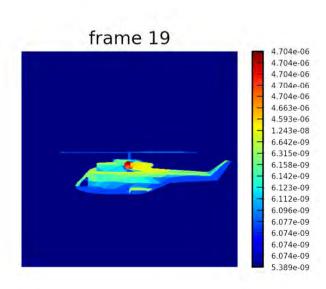
Histogram Equalisation

Image Irradiance (Square Root then Equalised) [W/m²]











Reading Data Files

Binary raw image files: select frames, size & data type.

```
imagefile = 'data/sample.ulong'
rows = 100
cols = 100
vartype = numpy.uint32
framesToLoad = [1, 3, 5, 7]
frames, img = readRawFrames(imagefile, rows, cols, vartype, framesToLoad)
```

FLIR Inc (CEDIP) *.ptw image files: select frames.

```
ptwfile = 'data/PyradiSampleMWIR.ptw'
header = readPTWHeader(ptwfile)
#loading sequence of frames
framesToLoad = [3,4,10]
data = getPTWFrames (header, framesToLoad)
```

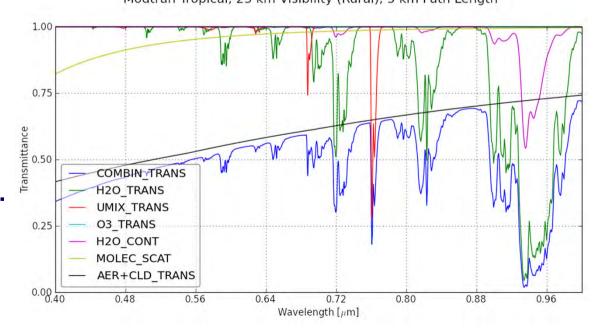
(Instrument calibration scaling still to follow).

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Read Modtran tape7 Files

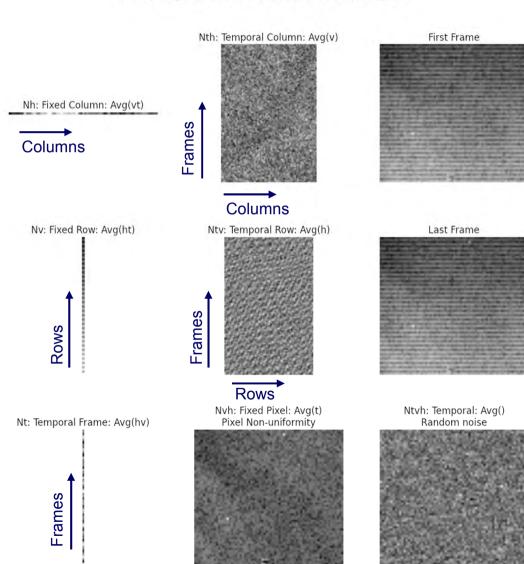
- Select columns by header title.
- Supports all four IEMSCT file variants.





3-D Noise Analysis

PTW Image Sequence 3-D Noise Components



3-D noise analysis of image sequences.

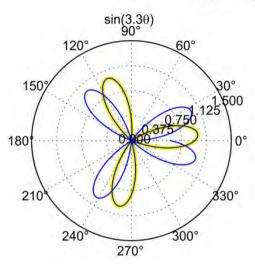
- Averages and filters along frames, rows and columns.
- Isolates individual noise causes.

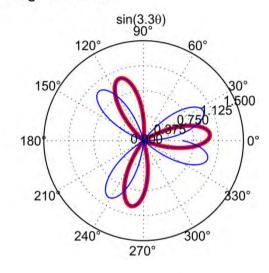


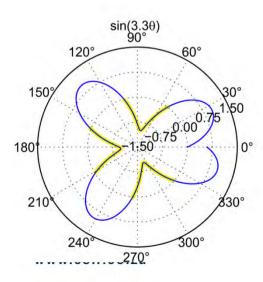


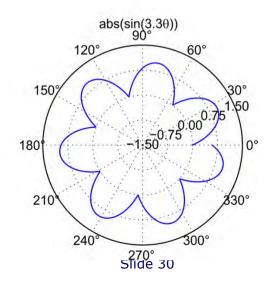
Polar Plots

Polar Plots of Negative Data









- -1 is a π phase shift: plot on 'other' side.
- Confuse direction with magnitude!
- Two options:
 - Highlight negative.
 - Zero not in centre.

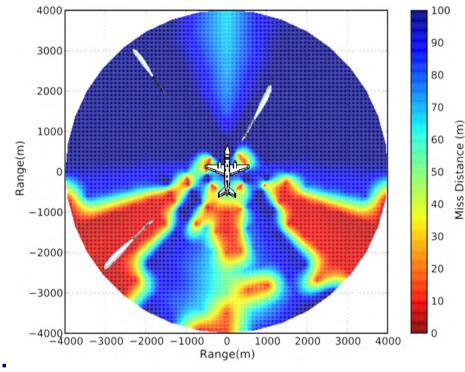




Aircraft Vulnerability

Missiles launched from red position are kills.

- Why are countermeasures not effective?
- Investigate Jam / Signal ratios.
- Investigate geometry: aircraft fuselage obscuration.
- Investigate angular 3-D signatures.

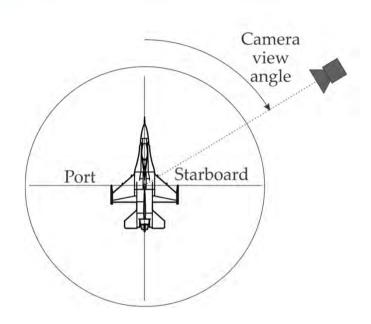


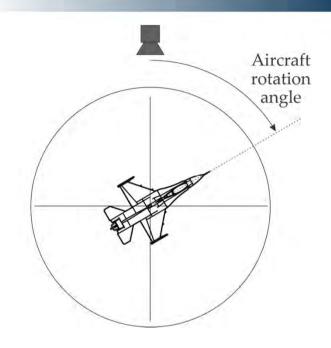
Welcome to the haunted house of 3-D signatures!





Two 3-D Scenarios



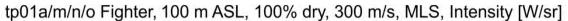


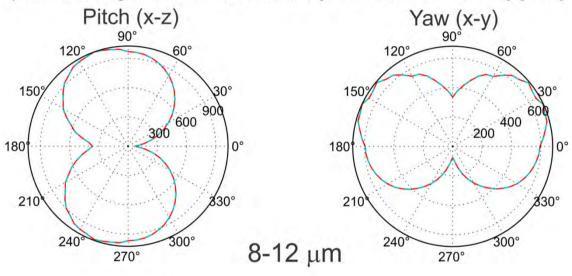
- Stationary target.
- Orbiting camera.
- Varying background.
- Stable sun position.

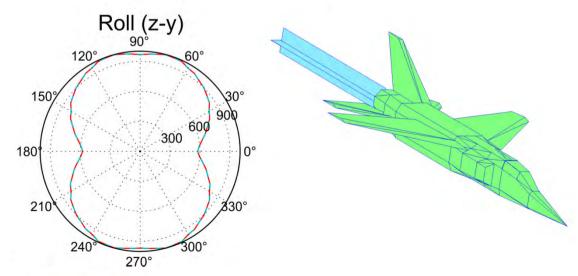
- Stationary camera.
- Rotating target.
- Varying sun position.
- Stable background.



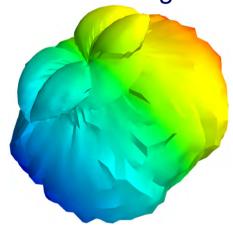
Intensity Polar Plots 8-12 μm



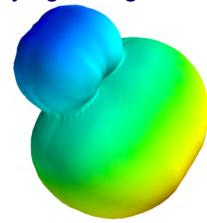




Rotating target: constant background

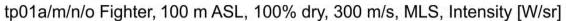


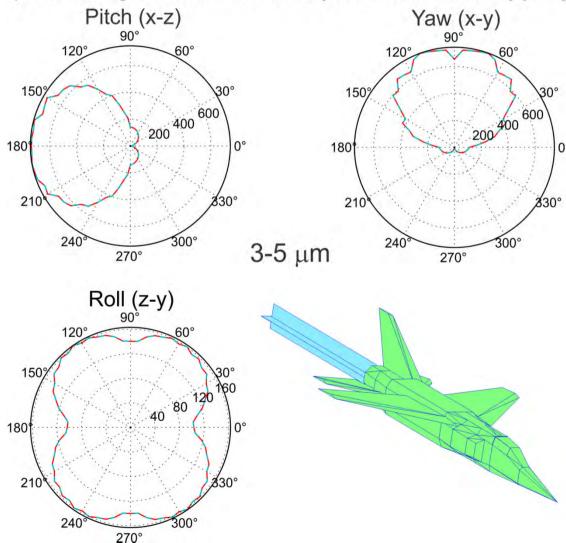
Orbiting sensor: varying background



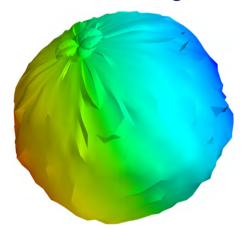


Intensity Polar Plots 3-5 μm

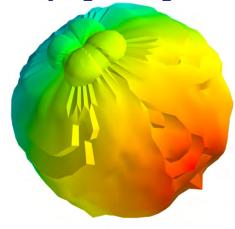




Rotating target: constant background

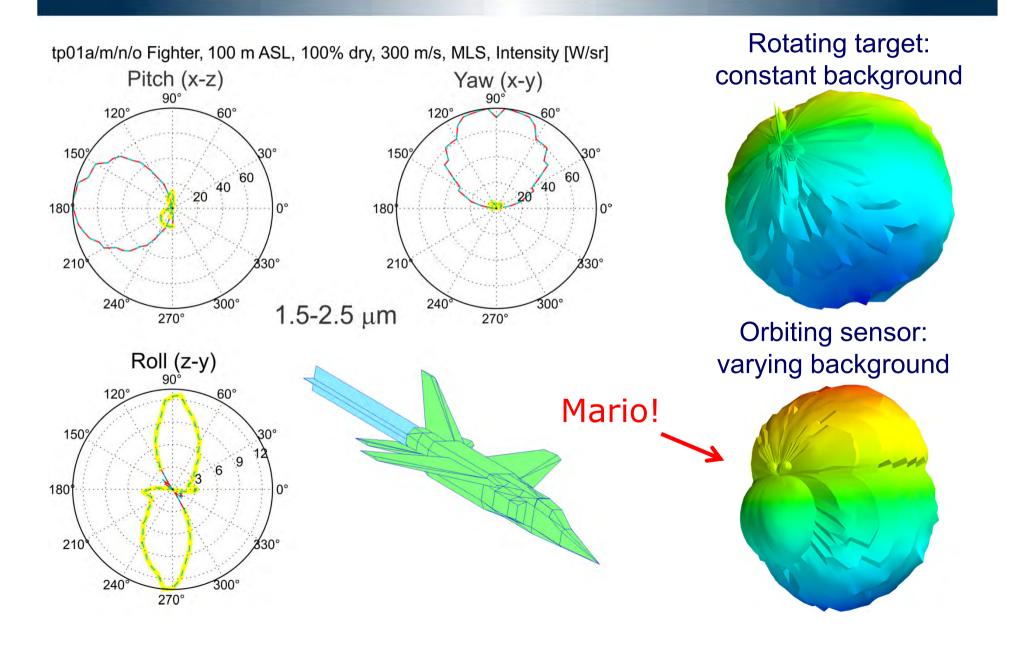


Orbiting sensor: varying background



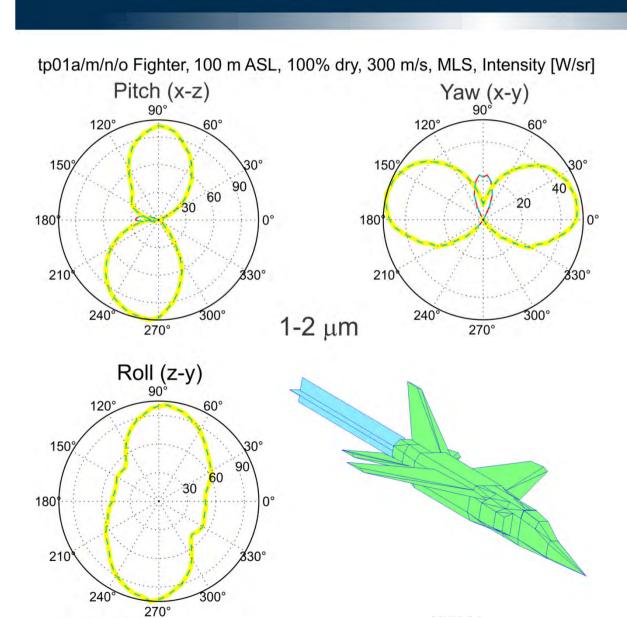


Intensity Polar Plots 1.5-2.5 μm

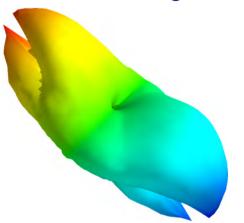




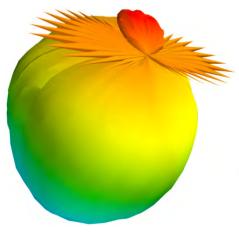
Intensity Polar Plots 1-2 μm



Rotating target: constant background

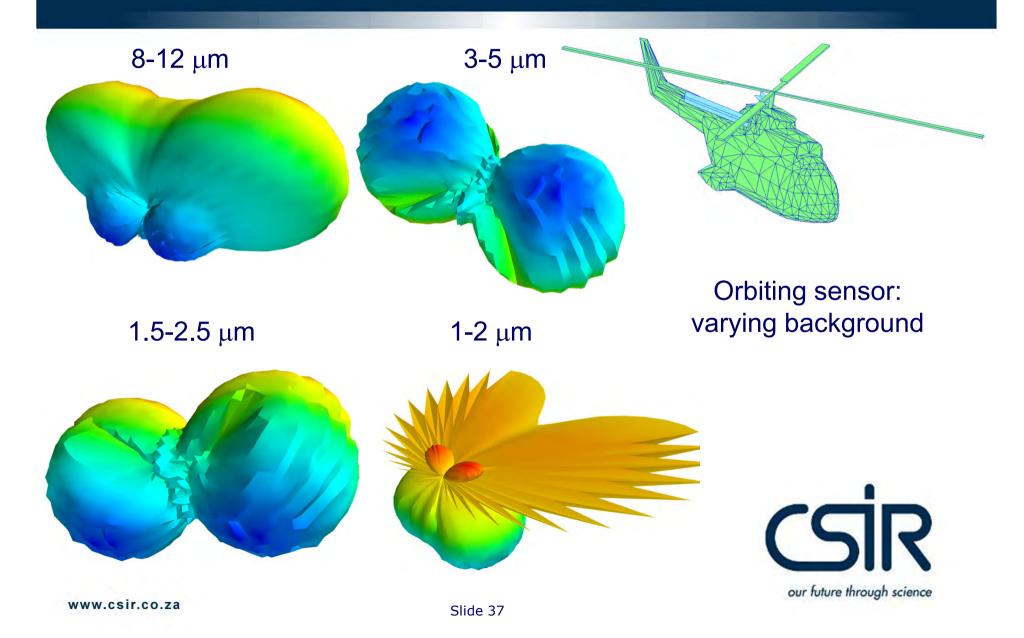


Orbiting sensor: varying background





Puma Helicopter Model





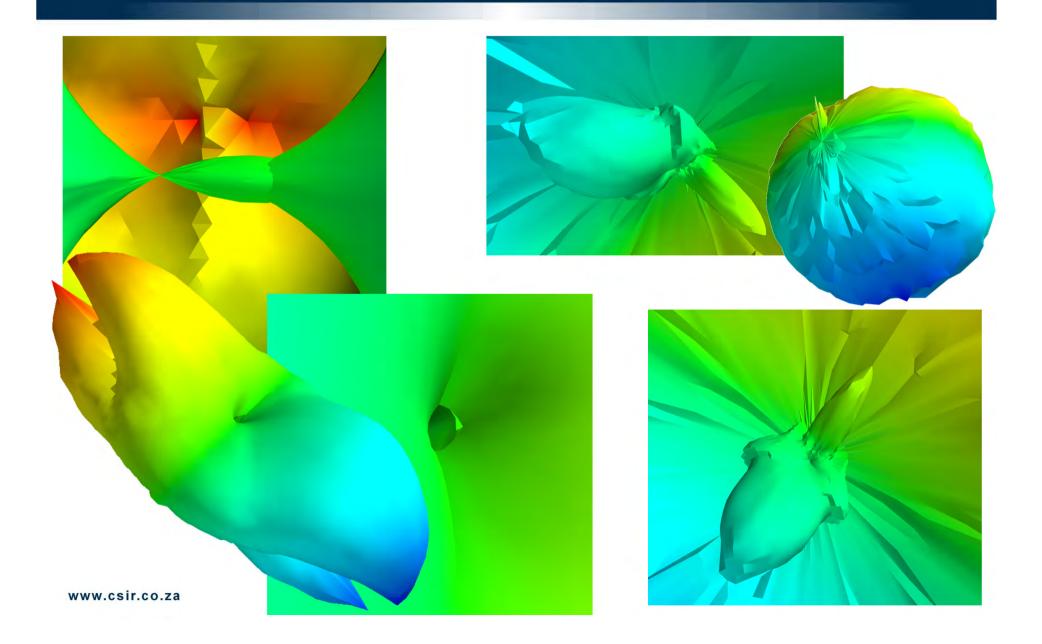
Going Inside!

You can actually go inside these shapes!





Going Inside!





Requirements

- Moderate hardware requirements.
- Supported on Linux & Windows.
- Software requirements (all are free):
 - Python 2.7.3.
 - Numpy 1.6.1.
 - Scipy 0.10.1.
 - Matplotlib 1.1.
 - Mayavi 4.1.





Authors, Sponsors & Users

- Collaborative effort between
 - CSIR, South Africa.
 - Denel Dynamics, South Africa.
 - Instituto Tecnologico de Aeronautica, Brazil.
- Used in CSIR and Denel for R&D, simulation model development and analysis.
- Targeting academic environment.
- Working towards the tool of choice in infrared laboratories.

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Open Source Considerations

Pyradi is available as open source software.

Mozilla Public License 1.1:

- Authors retain ownership of their respective contributions.
- Modifications by users must be released under compatible terms.

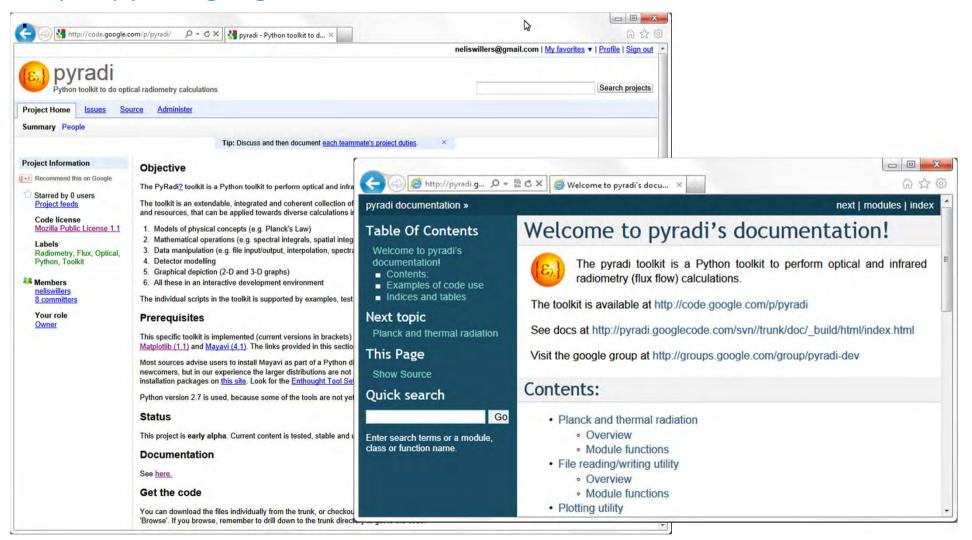
Potential users are encouraged to join in, and commit changes, updates and new contributions.





Hosted at Google Code: pyradi

http://code.google.com/p/pyradi
http://pyradi.googlecode.com/svn//trunk/doc/_build/html/index.html





Closing

- Pyradi only recently started already paying dividends.
- Visualisation proved to be most valuable.
- All are welcome to use and contribute.

