

AER525H1F Robotics

Syllabus and Course Information Fall 2015

Lecturer: Peter Szabo, PhD Candidate

Space Robotics Group

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TAs: GRADING: Allen Chee (allen.chee@mail.utoronto.ca)

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Lectures: Wednesday 9:00am-10:00am (WB130)

Friday 9:00am-11:00am (WB130)

Tutorials: Wednesday 10:00am-11:00am (WB130)

Office Hours: Wednesday 11:00am-12:00pm (SF4001)

Laboratories: (see Laboratory Schedule)

Primary Text: Introduction to Robotics - Mechanics and Control, Third Ed.

John J. Craig, Pearson Prentice Hall, 2005.

Supplementary: Robotics: 2008 AER525 Course Notes,

M. Reza Emami, University of Toronto. (provided)

Grading Breakdown: Assignments 15%

Laboratories15%Midterm Exam20%Final Exam50%

Syllabus:

Chapter	Description	Dates	
1	Introduction	Sep 11	
2	Spatial Descriptions & Transformations	Sep 16, Sep 18, Sep 23	
3	Manipulator Kinematics	Sep 25, Sep 30, Oct 2	
4	Inverse Manipulator Kinematics	Oct 7, Oct 9	
5	Jacobians: Velocities & Static Forces	Oct 14, Oct 16, Oct 21	
	Midterm	Oct 30	
6	Manipulator Dynamics	Oct 23, Oct 28, Nov 4, Nov 6	
7	Trajectory Generation	Nov 11, Nov 13, Nov 18	
8	Manipulator-Mechanism Design	Nov 20	
9	Linear Control of Manipulators	Nov 25, Nov 27, Dec 2	
10	Nonlinear Control of Manipulators	Dec 4, Dec 9	
	Exam Period	Dec 10-23	

Laboratory Schedule:

Section	Group	Room	Time	Lab 1	Lab 2	Lab 3	Lab 4
PRA0101	A	MB68	3pm-6pm	Sep 16	Sep 30	Nov 11	Nov 25
PRA0102	В	MB68	3 pm-6 pm	Sep 23	Oct 7	Nov 18	Dec 2
PRA0103	\mathbf{C}	MB68	$6 \mathrm{pm}$ - $9 \mathrm{pm}$	Sep 16	Sep 30	Nov 11	Nov 25
PRA0104	D	MB68	6 pm- $9 pm$	Sep 23	Oct 7	Nov 18	Dec 2

Assignment Schedule:

	Assign. 1	Assign. 2	Assign. 3	Assign. 4
Chapters Covered	2/3	4/5	6/7	8/9/10
Available	Sep 16	Sep 30	Oct 28	Nov 18
Due	Oct 7	Oct 21	Nov 18	Dec 9

Examination Details:

	Topics Covered	Type	Date
Midterm	Chapters 1-5	С	Oct 30
Final Exam	Chapters 1-10	X	TBA