



# The Phoenix Board

Group 8

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CpE  
CpE  
EE

# Motivations

- We each wanted different ideas incorporated into a project
  - Solar energy/power management
  - Mobile communications (Wi-Fi or Bluetooth)
  - Computer vision
- We wanted something fun that would keep us all motivated throughout the duration of the project
- We wanted something that could be used regularly and reliably
- Quick travel within a college campus

# Goals and Objectives

## Core Features:

- A smooth and fast electric motor with easy speed control
- Rechargeable battery via solar and standard outlets
- PCB manages all onboard sensors
- Fast and consistent mobile communications
- Weight-sensitive safety mechanism
- Efficient and reliable

# Specifications

Total Board Weight	< 25 lbs
Maximum Board Speed	$\geq 15$ mph
Battery	36V, 10Ah, $\leq 10A$
Battery Charge Time	< 5 hours
Communication	< 0.5s response time between app and PCB
Motor Efficiency	> 70%
Battery Efficiency	> 80%
Cost	< \$1000

# Existing Projects

## Halo Board - 2nd Edition

- 14 lbs
- 286 lb weight limit
- 14 miles of ride time
- Max speed: 26 mph
- Recharge time: 3 hrs
- Cost: \$1,497.00 USD



## Evolve Boards - Bamboo GTX

- 19.4 lbs
- 220 lb weight limit
- 19 miles of ride time
- Max speed: 26 mph
- Recharge time: 4-5 hrs
- Cost: \$1,779.99 USD

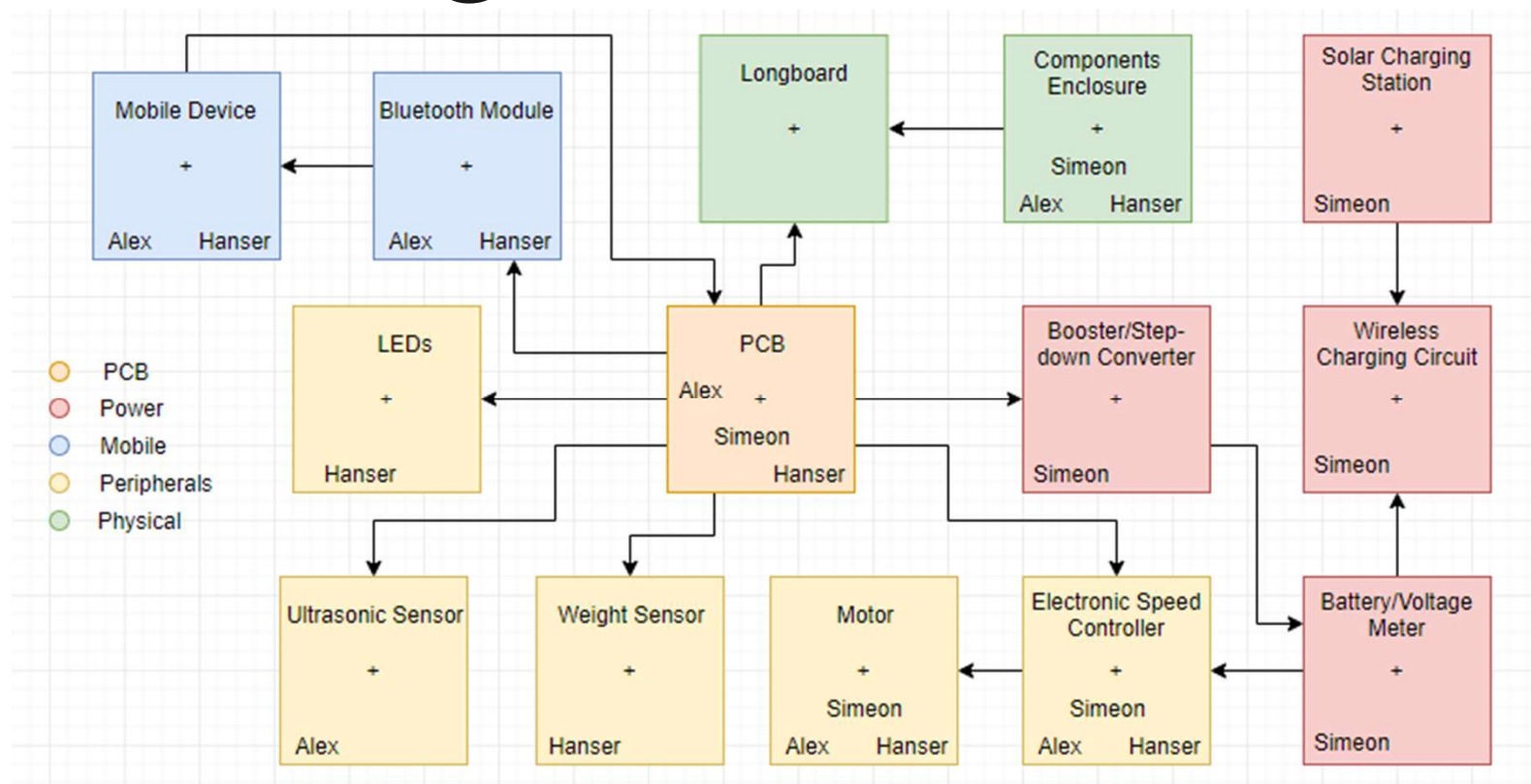


## Boosted Boards - Boosted Plus

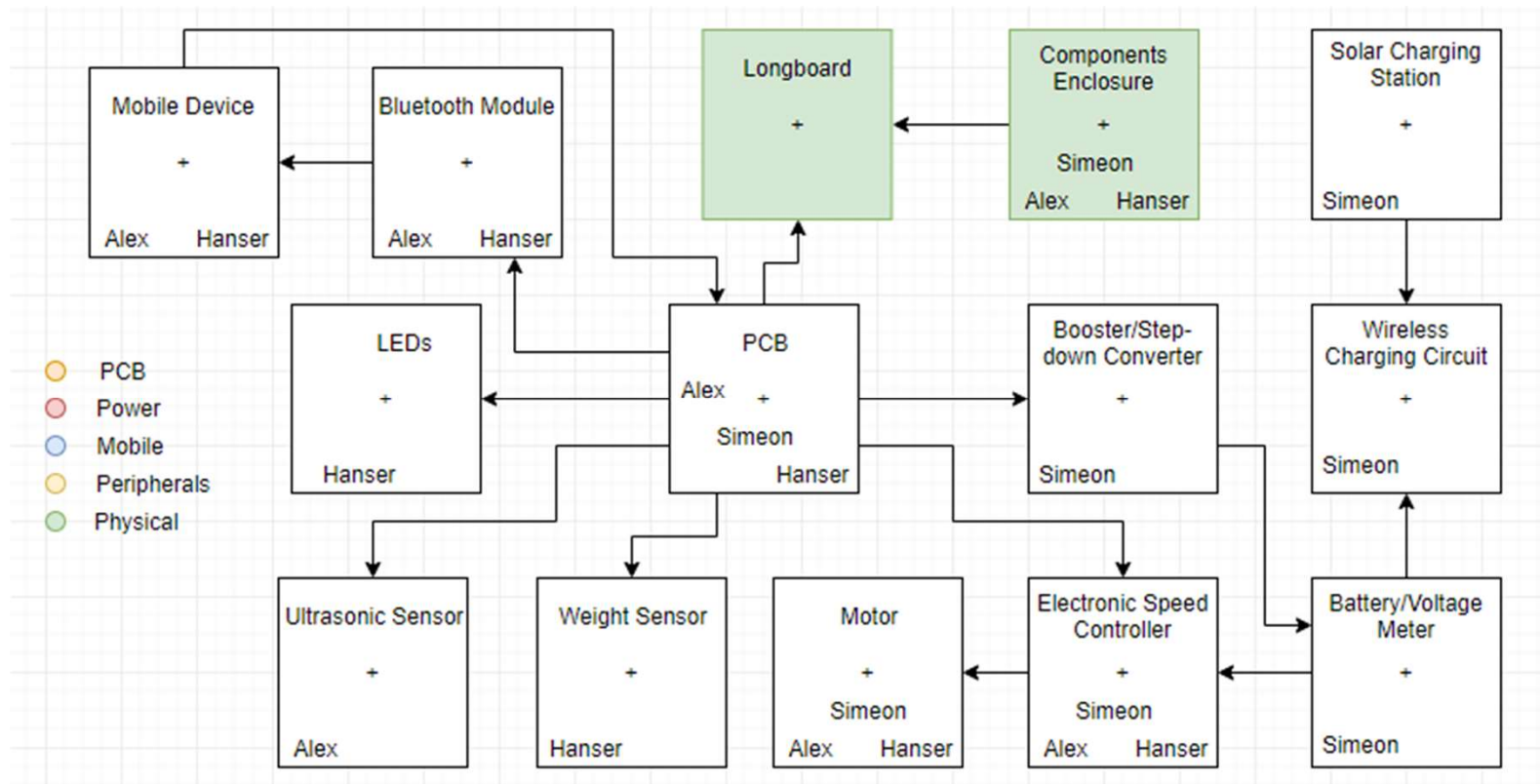
- 17 lbs
- 250 lb weight limit
- 14 miles of ride time
- Max speed: 22 mph
- Recharge time: 1.75 hrs
- Cost: \$1,399.00 USD



# Block Diagram



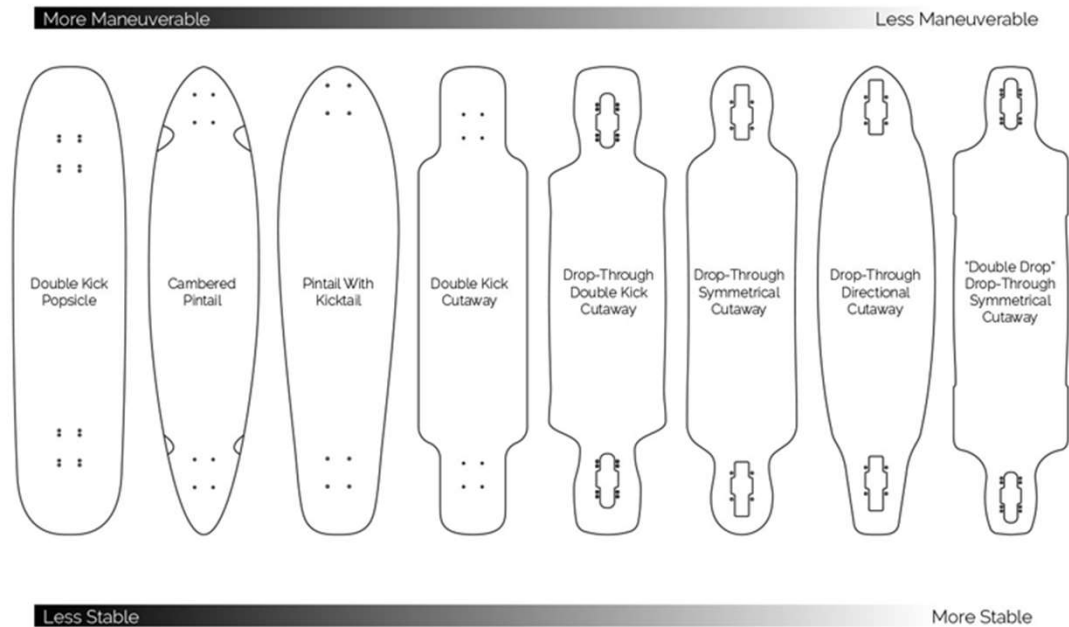
# Board and Enclosure



# Longboard Selection

## Stability/Maneuverability Factors:

- Length
- Width
- Weight
- Flex
- Style (Truck height)
- Shape

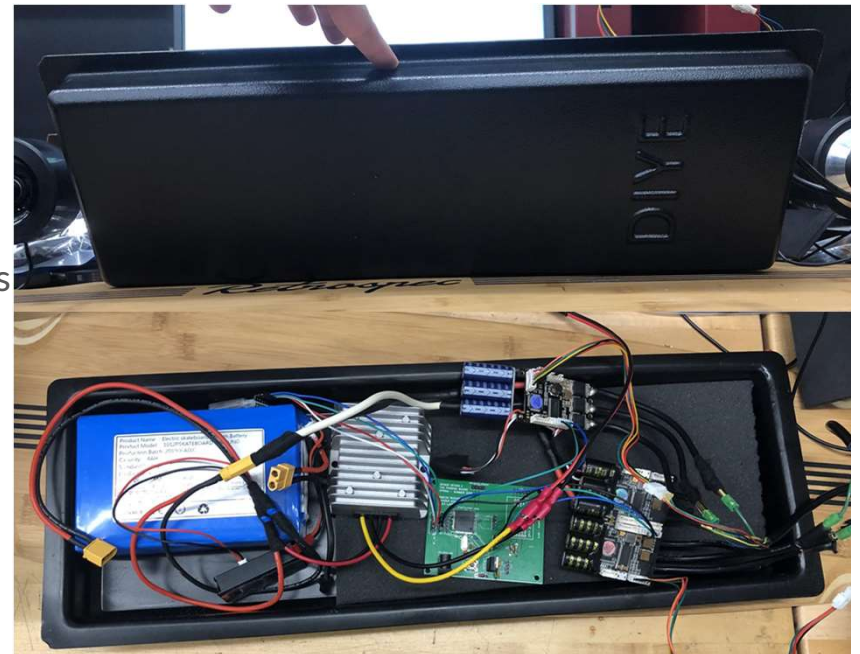




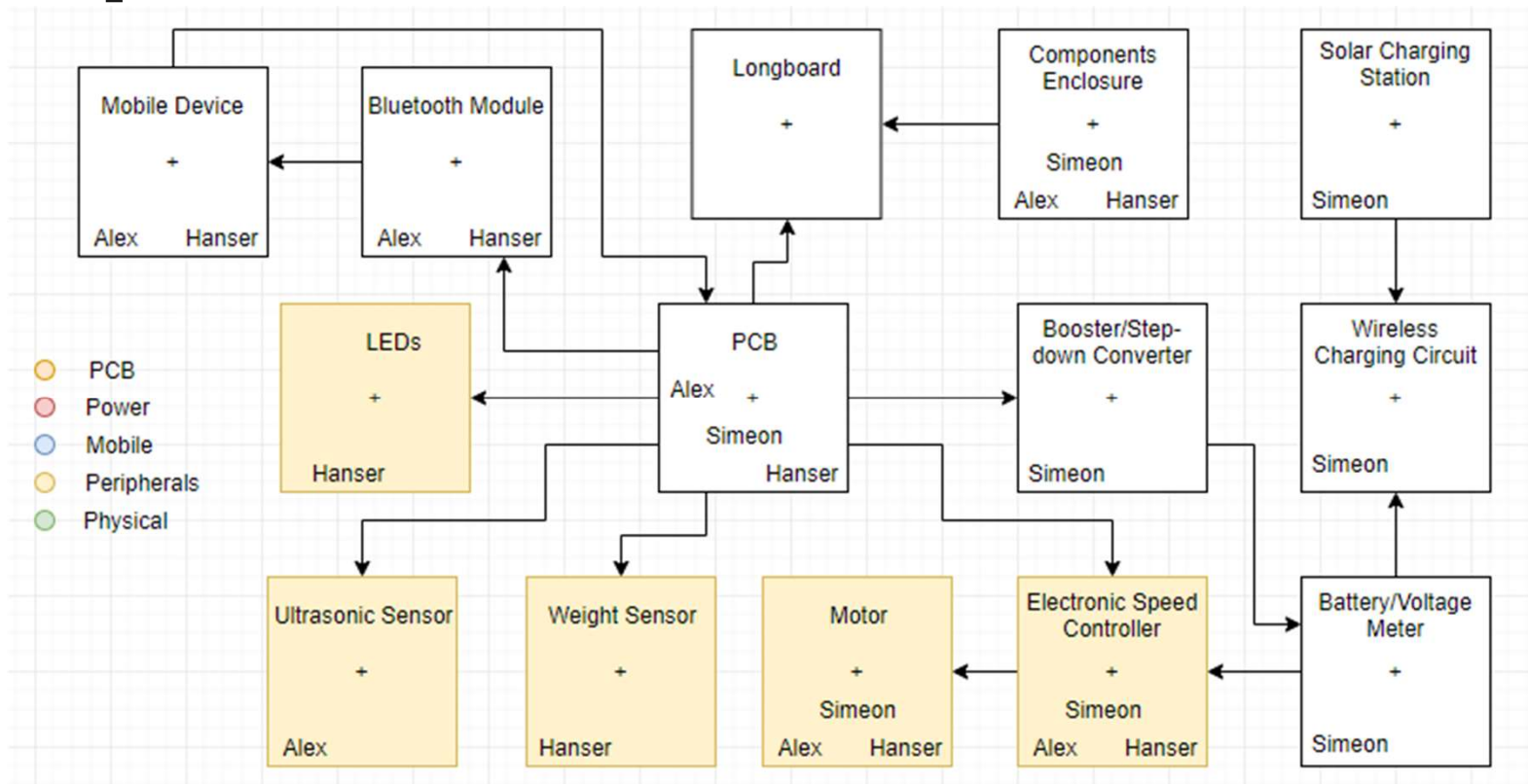
# Battery/Component Enclosure

DIYE Electric Skateboard Battery & Electronics Customizable & Scratch-Proof Battery Enclosure

- Outside: 21" x 7 1/40" x 1 3/4"
- Inside: 19 1/9" x 5 3/4" x 1 1/2"
- Heavy-Duty, Durable and Flexible
- Protection for ESC, Battery and Electronics
- Designed for custom built skateboards



# Peripherals



# Microcontroller

## ATMega2560

- Selected over MSP430F5529
  - Multiple UARTs which are needed for Bluetooth and motor control
  - Higher number of GPIO pins, needed for multiple sensors
  - Arduino libraries are widely available and easy to implement

	MSP430F5529	ATMega2560
Architecture	16-Bit	8-Bit
Speed	Up to 25 MHz	Up to 16 MHz
Flash	128 KB	256 KB
RAM	8 KB	8 KB
UART	1	4
I2C	1	1
SPI	1	5
GPIO Pins	64	86

# Embedded System IDE



## Embedded IDE: Arduino IDE

- Used for developing applications for Arduino based processors
- Supports C/C++
- Wide availability of documentation, tutorials, and ready-to-use libraries for peripherals

# Motors: Hub vs. Belt

## Hub Motors

- Motor is integrated into wheel reducing the amount of noise made
- Less drag which provides a longer battery life
- Reduced resistance allows users to free roll
- Thinner urethane sleeving around motor as opposed to full-sized wheel reduces shock absorption
- Typically weigh less

## Belt Motors

- Involve a belt/pulley system which can create significant amounts of noise
- Provide higher levels of torque
- Present a lot of resistance essentially barring free roll
- Can cause rider to feel a vibration when running
- Can use full-sized wheels for better shock absorption
- Typically weigh more

# Motor Selection

## Dual 90mm Hub Motor Kit

- Dual 6364 Hub Motors
- Weight: 9.57 lbs
- Motor size: 74.5 mm x 52 mm
- Wheel size: 90 mm
- Top Speed: 25 mph
- Operating voltage: 24V - 42V
- Simple integration
- Replaceable urethane sleeving



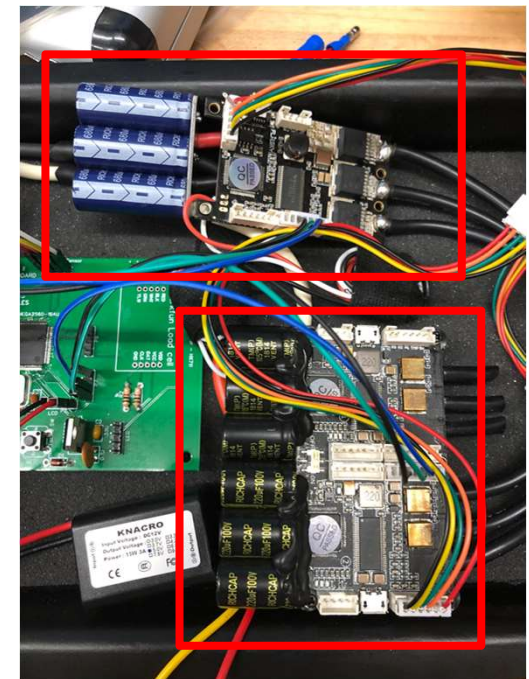
# Electronic Speed Control

Dual FSESC4.20 100A with Anodized Aluminum Heatsink (VESC Based)

- 50 A Continuous/single, 100A continuous/dual
- 8V - 60V (3-13S LiPo)
- DC, BLDC, FOC modes
- UART capable

FSESC 4.12 50A Based on VESC® 4.12

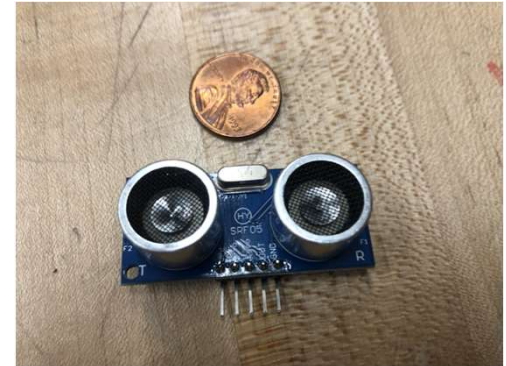
- 50 A Continuous/single
- 8V - 60V (3-13S LiPo)
- DC, BLDC, FOC modes
- UART capable



# Ultrasonic Sensor

## SMAKN Ultrasonic Module HY-SRF05 Distance Sensor

- Power Supply: +5V DC
- Idle Current: < 2mA
- Ranging Distance: 2 cm - 450 cm
- Resolution: 0.3 cm
- Full measuring angle: 30 degrees
- Effective angle: < 15 degrees
- Pins: VCC, GND, TRIG, ECHO, OUT
- Used for obstacle detection in front of the board and assist with engaging emergency slowdown to prevent/minimize rider injury





# Night Mode LEDs

CHINLY 16.4ft WS2812B Individually Addressable LED Strip

- Power Supply: +5V DC
- 5050 RGB LEDs
- 24-bit color (8-bit red, green, and blue data)
- LED strip can be cut to desired length without damaging LEDs.



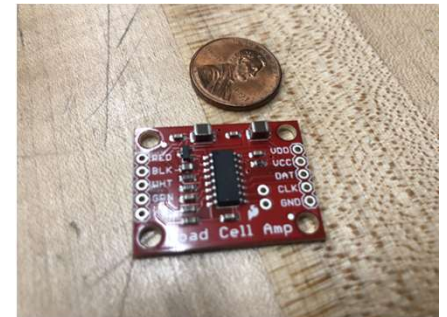
# Load Cell and Load Cell Amplifier

## Load Cell: TAS606 Load Cell - 200 kg

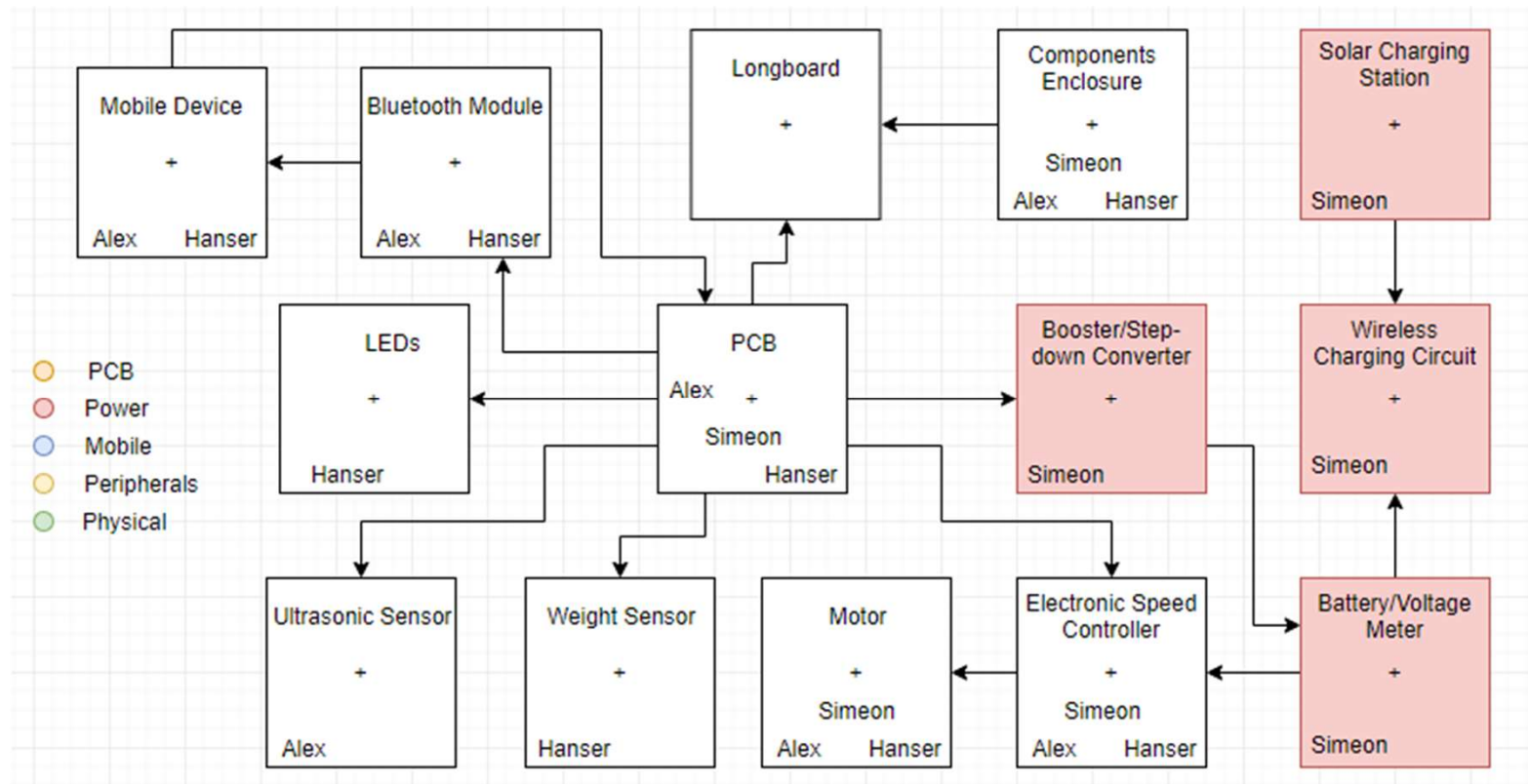
- 200 kg weight capacity
- Consists of 4 Strain gauges hooked up into a wheatstone bridge
- 20 mm x 11 mm, 2000 mm wire
- Operating Voltage: 5 - 15 V

## Load Cell Amplifier: SparkFun Load Cell Amplifier - HX711

- ADC to convert analog Load Cell signal into a Digital signal
- Operating Voltage: 2.7 V - 5 V
- Operating Current: < 1.5 mA



# Power Management System



# Solar Panel



## Solar Power

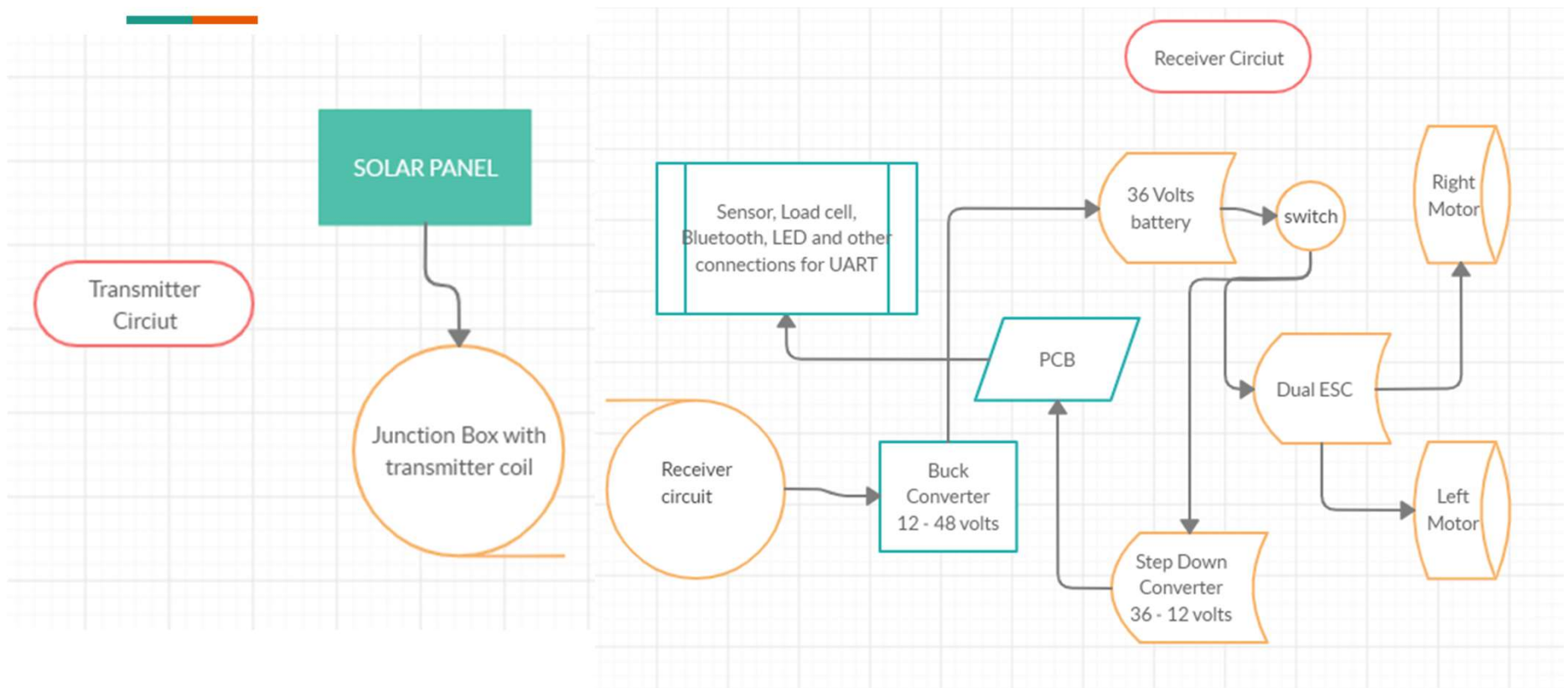
### Monocrystalline Panel - Pros

- First choice for highest efficiency
- Highest power output
- Requires least amount of space
- Longevity and long warranty from manufacturers

### Monocrystalline Panel - Cons

- More expensive
- Open circuit if covered by shade, dirt or snow (use of micro inverters required)
- More efficient in warmer weather

# Power Management Flowchart



# Battery

Battery - 36V Lithium-Ion

## Pros

- Greatest electrochemical potential
- Largest energy per weight
- High energy density
- Low internal resistance
- Low self discharge rate & low maintenance

## Cons

- Fragile
- Requires protection circuit for safe operation (most)
- Expensive to manufacture and requires frequent upgrade

# Battery Meter

- Voltage range of 12 - 84 volts
- Battery Meter with real time voltage reading
- Liquid Crystal Display for battery state
- Waterproof design
- No external switch needed
- Lead-acid and Lithium-ion compatible

# Wireless Charging

Magnetic Induction (Inductive)

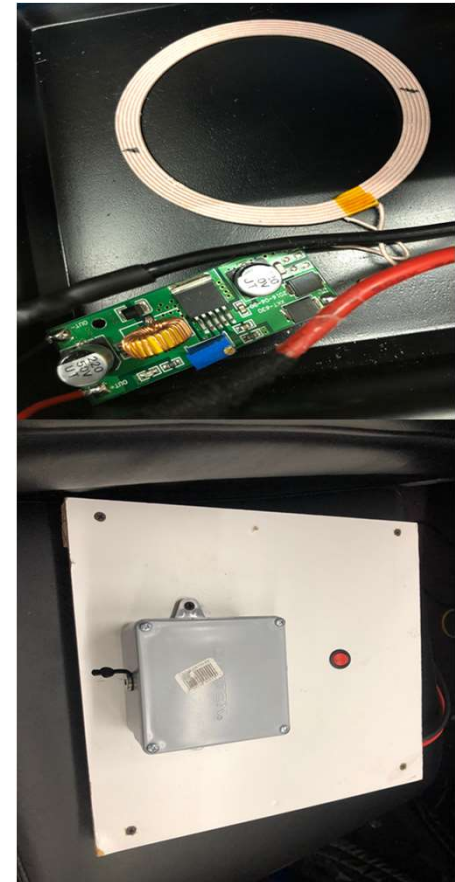
High resonant frequency wirelessly transfers energy using inductive coupling.

Pros

- Simple and efficient
- Safe
- Scalable
- Mature
- Good coupling

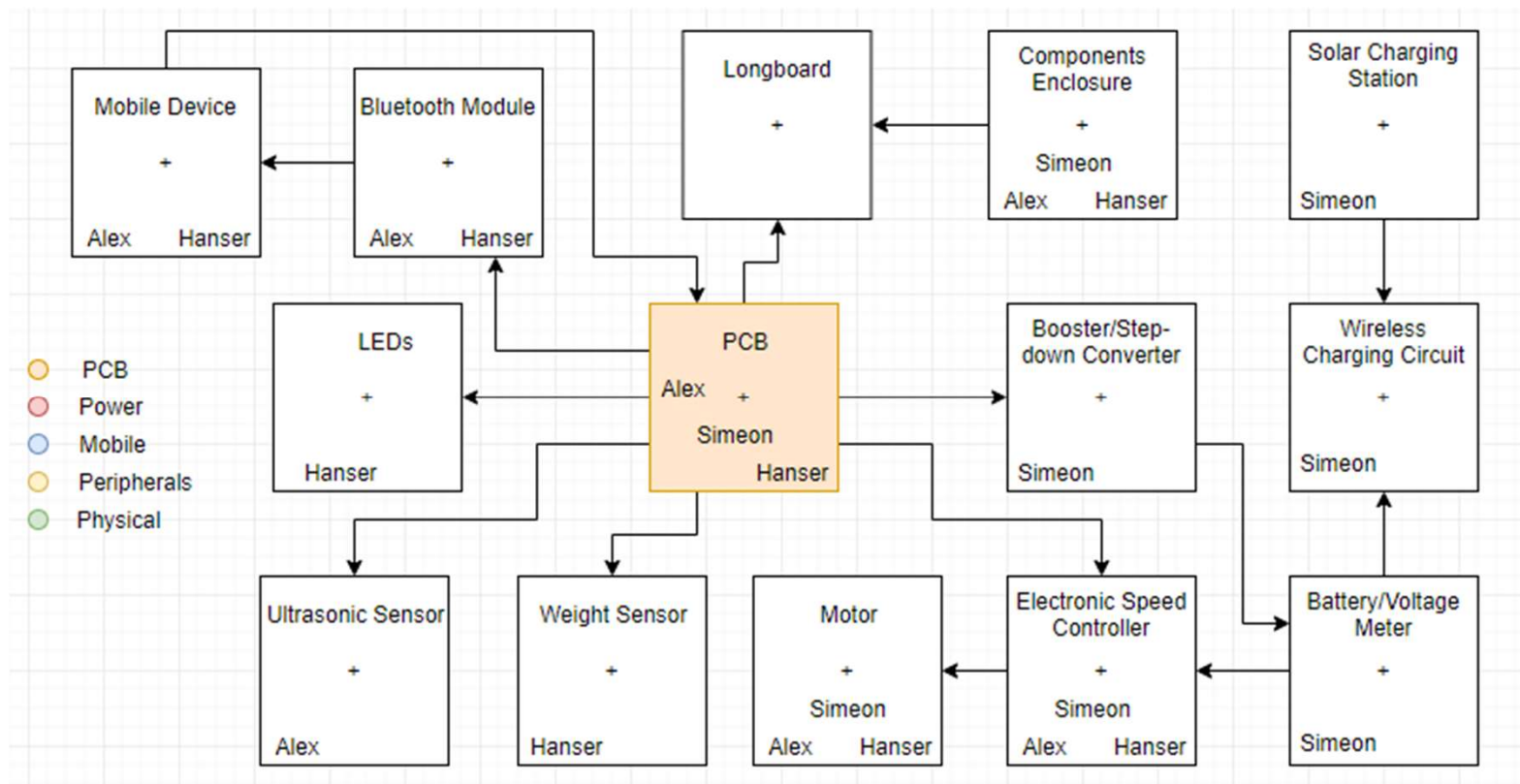
Cons

Has to be in close proximity

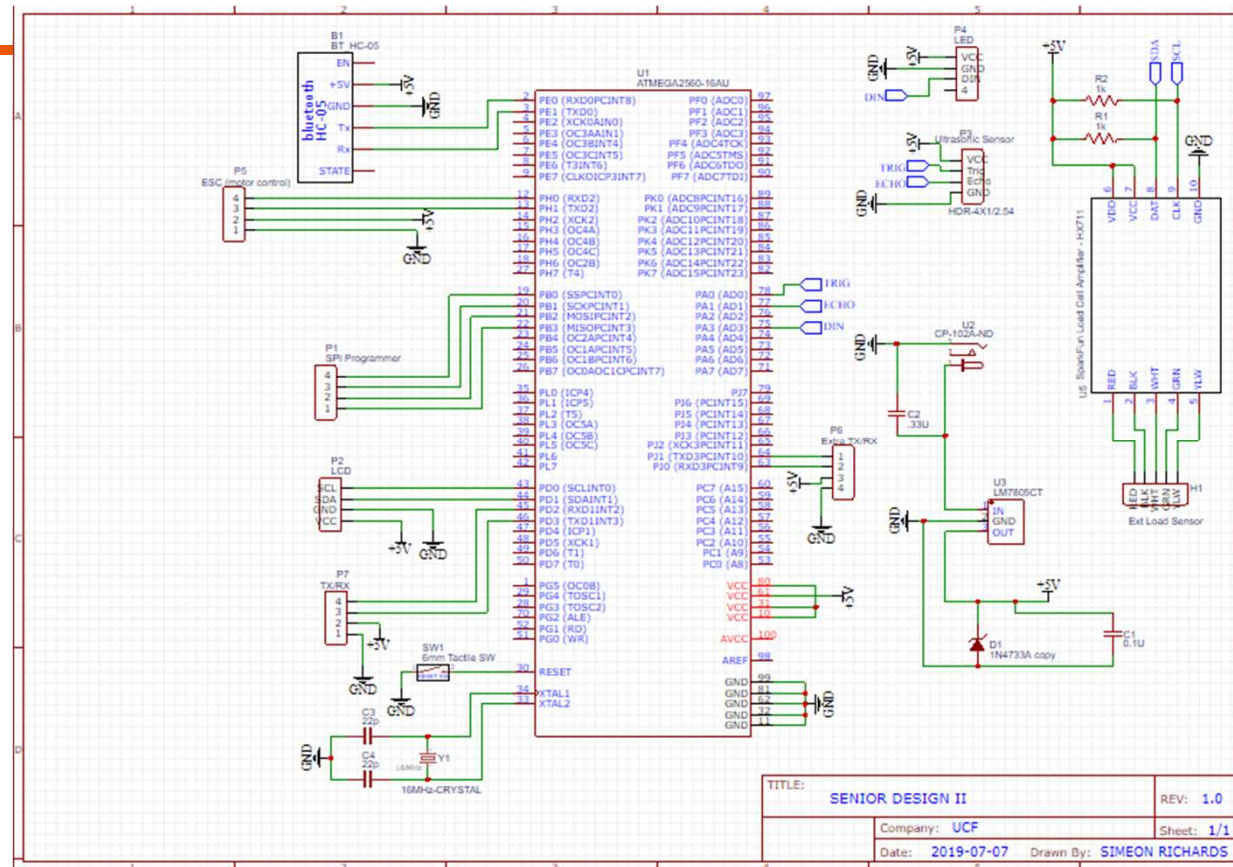




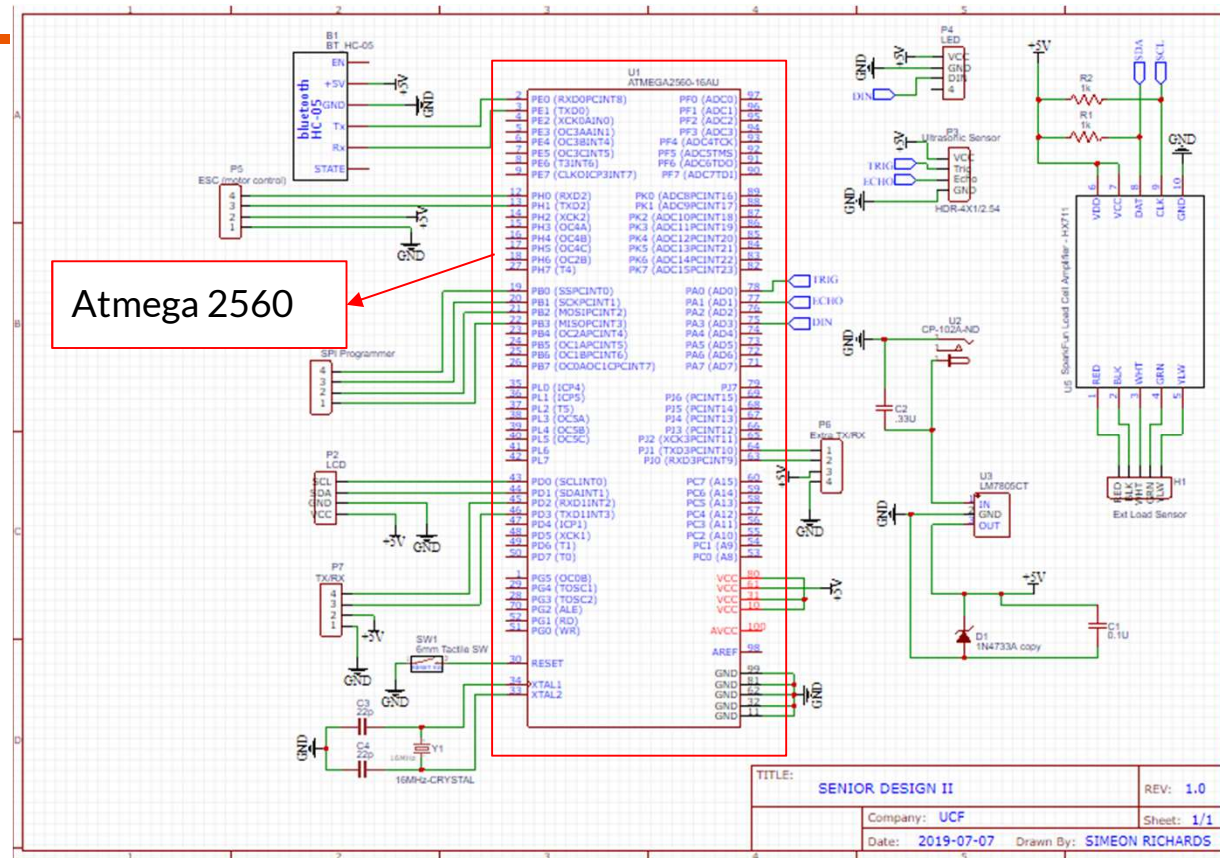
# PCB



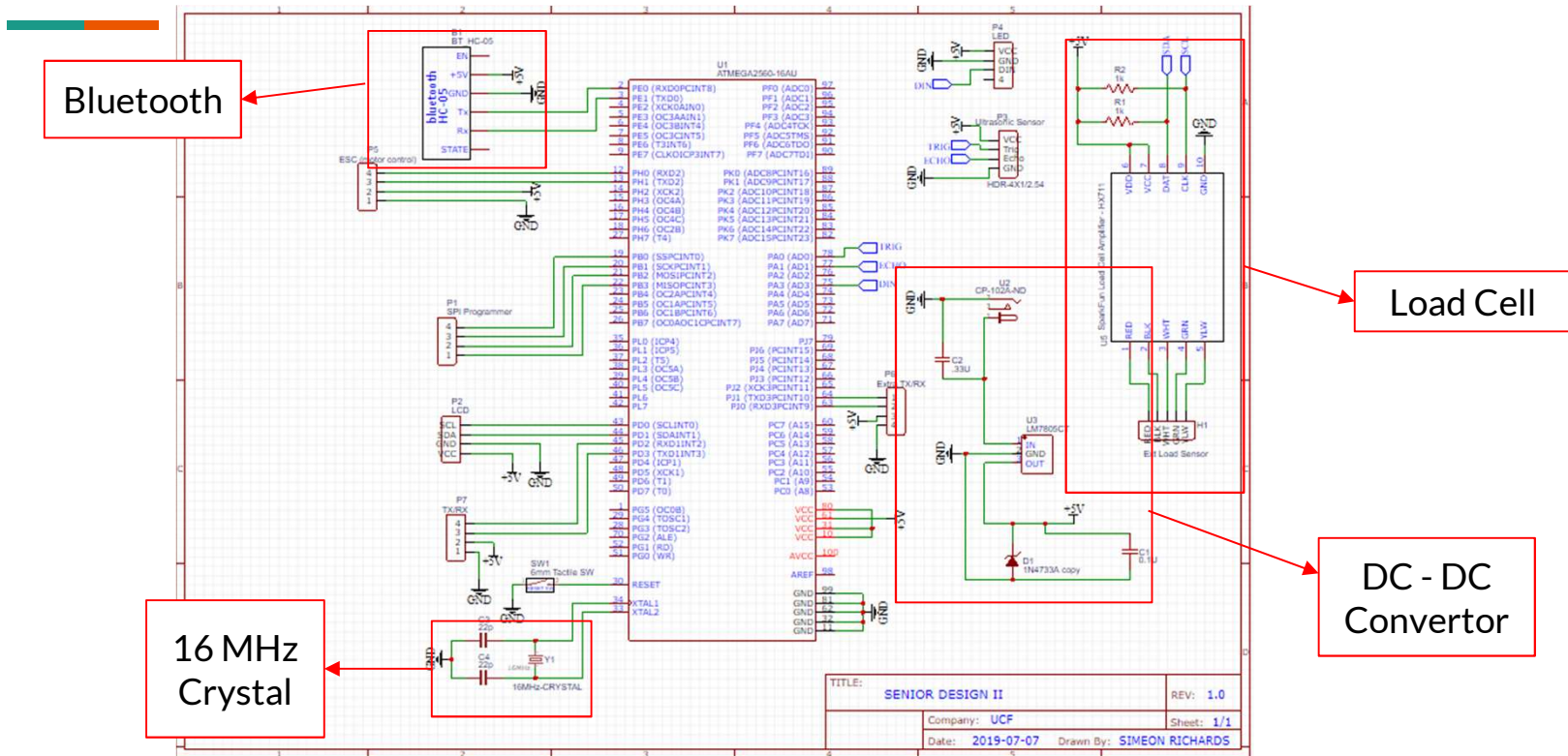
# PCB Schematic Design



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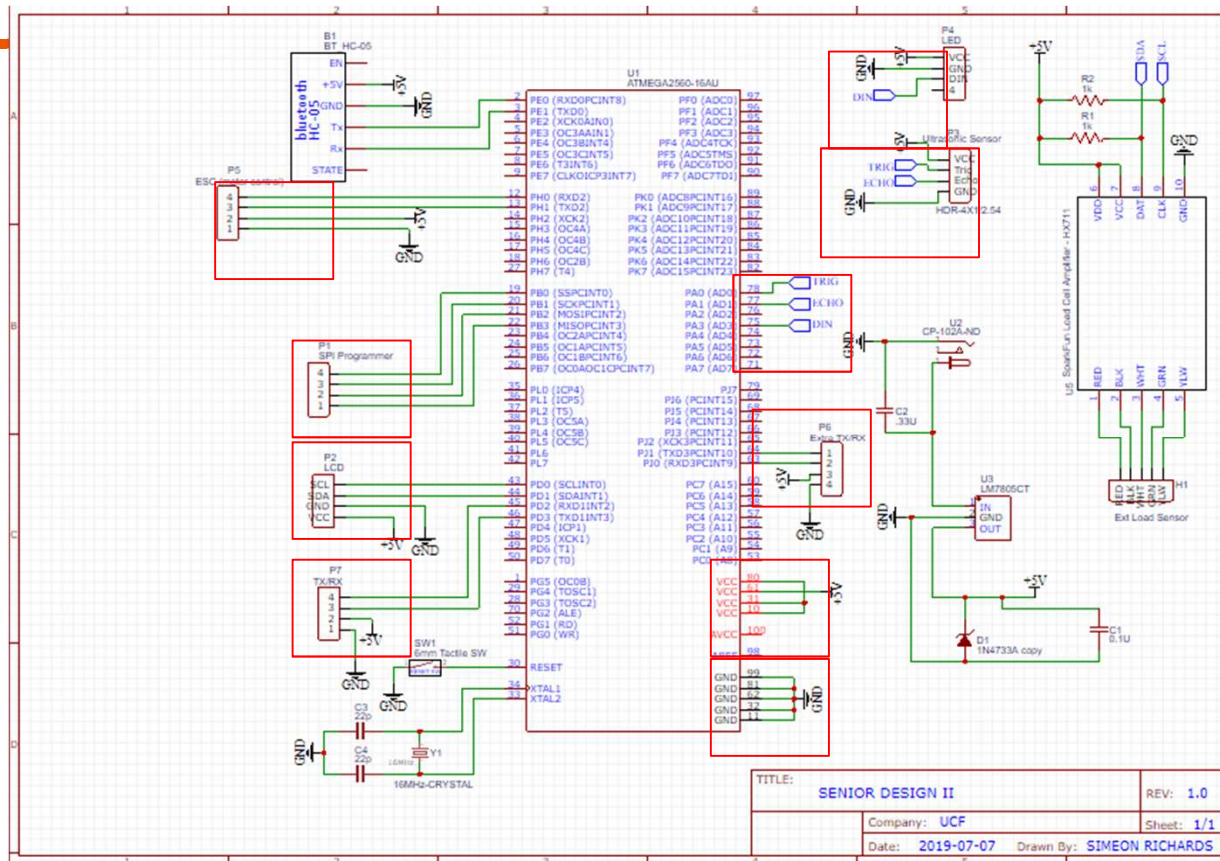


# PCB Schematic Design





# PCB Schematic Design

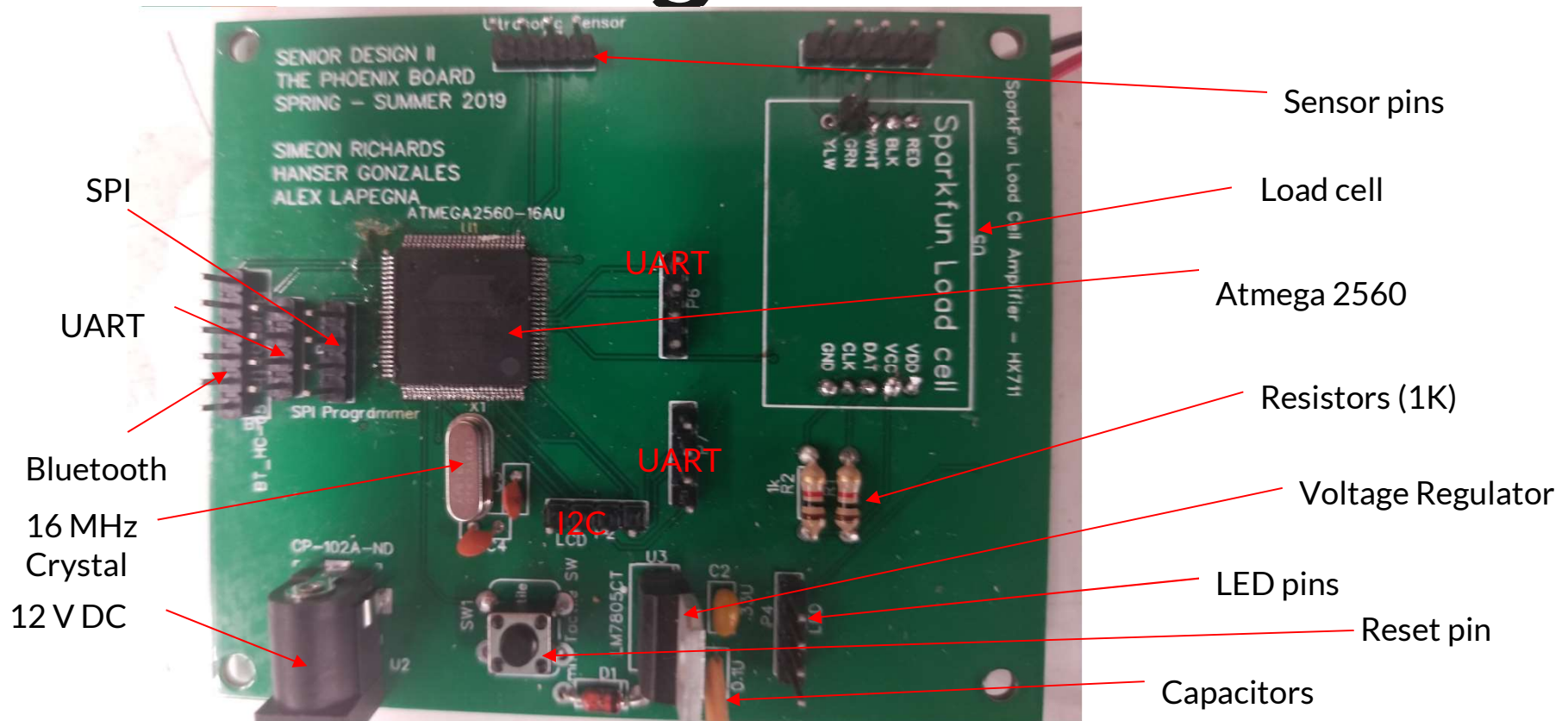


Pins and connectors for external devices

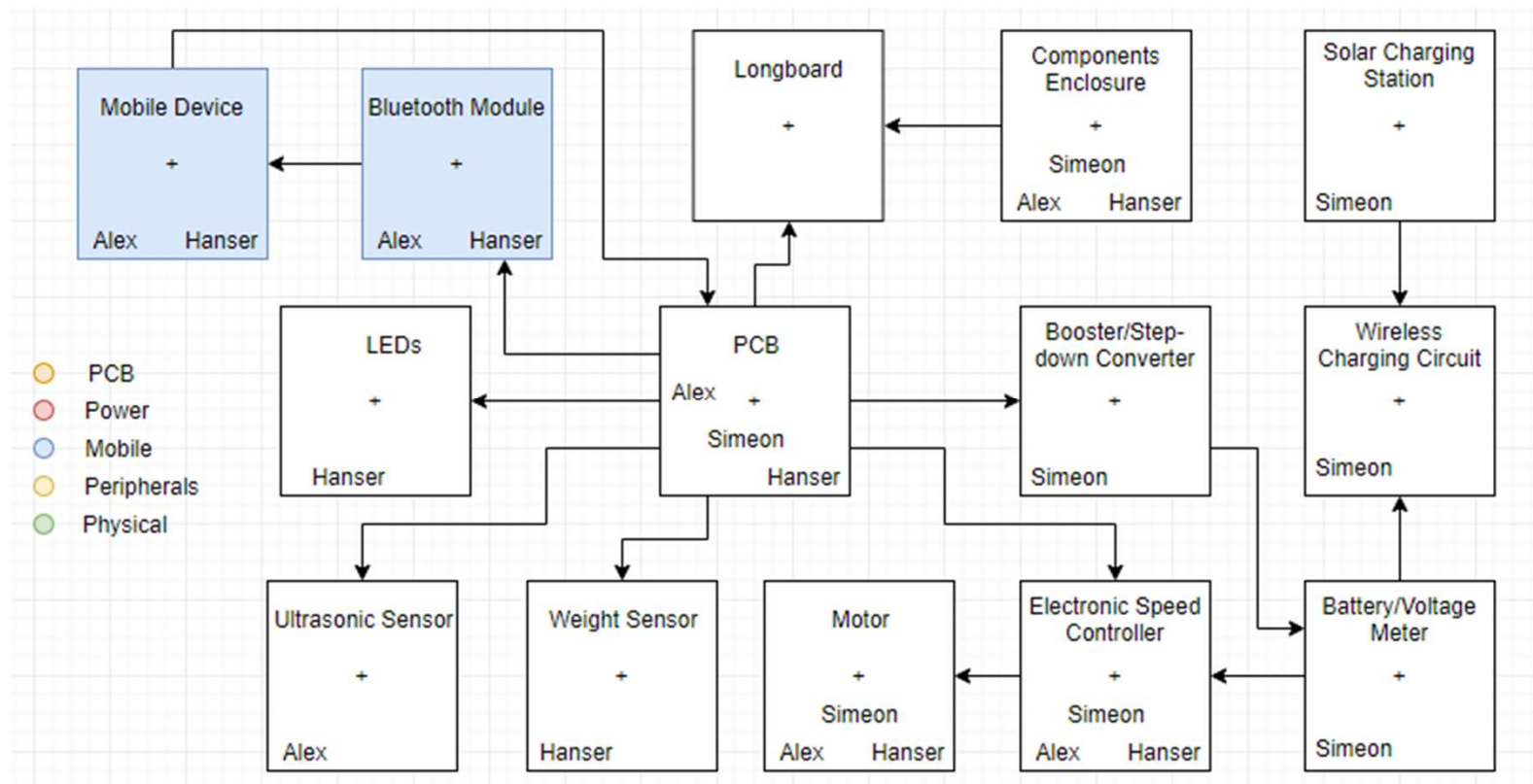
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Company: UCF		Sheet: 1/1
Date: 2019-07-07		Drawn By: SIMEON RICHARDS



# PCB Design



# Mobile App / Wireless Communication

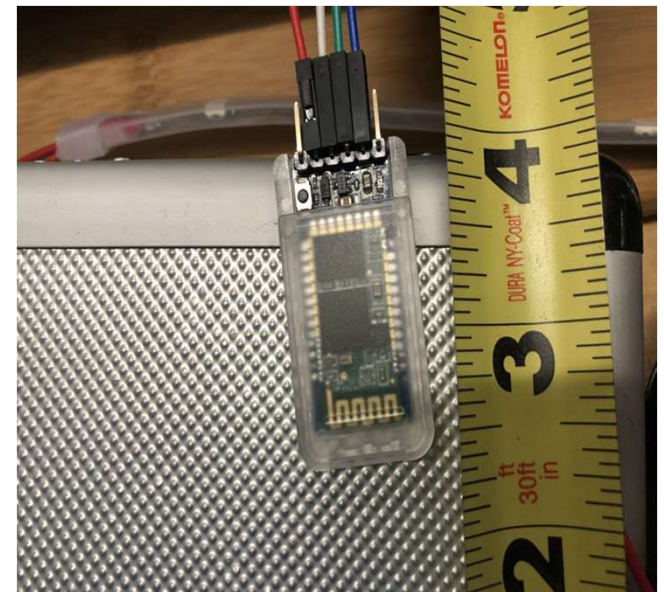




# Bluetooth Module

## DSD Tech HC-05 Bluetooth Serial Pass-Through module

- Bluetooth Classic 2.0 module
- +5 V
- Default baud rate of 9600
- Connected to PCB UART
- Used to received data from the mobile app

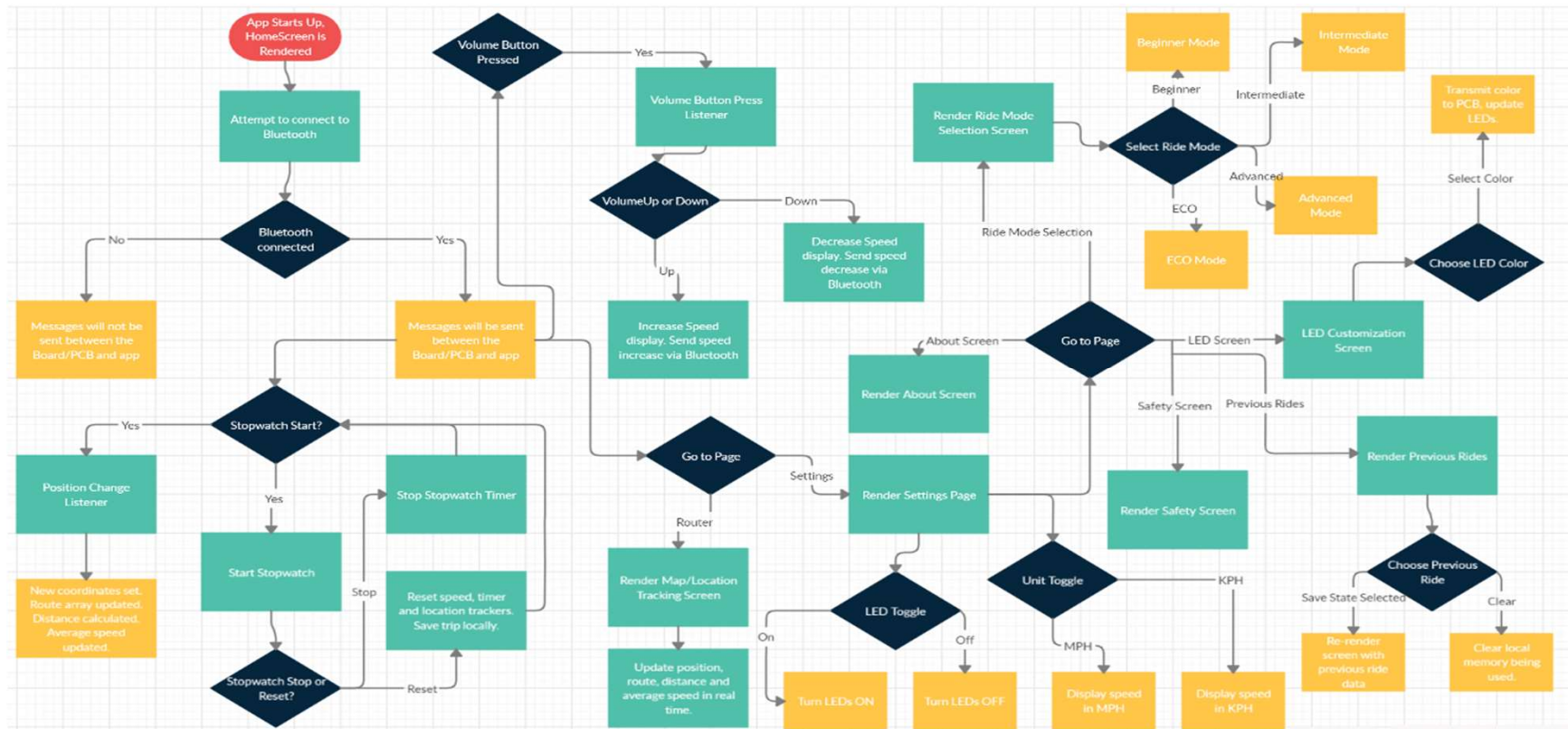


# Mobile Application IDE

## Mobile IDE: React Native

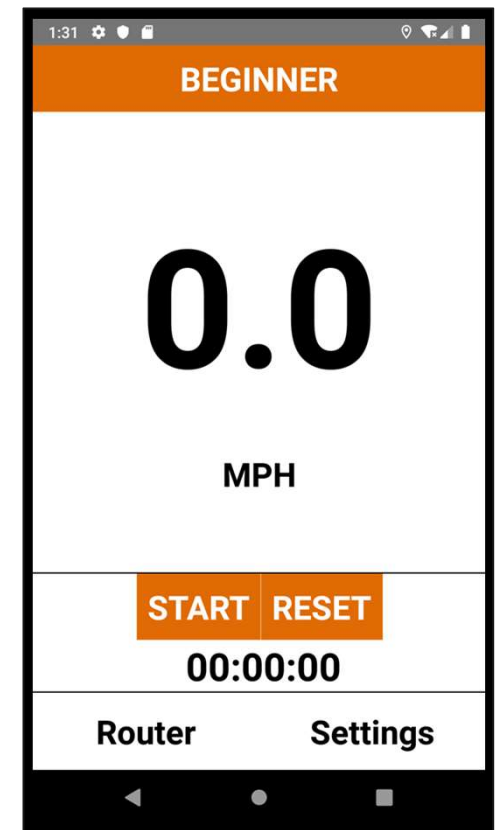
- React Native selected for ability to natively develop for both Android and iOS
- Utilizes Node.js, Python2, and Java SE Development Kit 8
- Development done in Android Studio
- Current goal is developing Android version only, future goal can expand to iOS version
- Testing done on Samsung Galaxy S5 and Android Virtual Device

# Flowchart



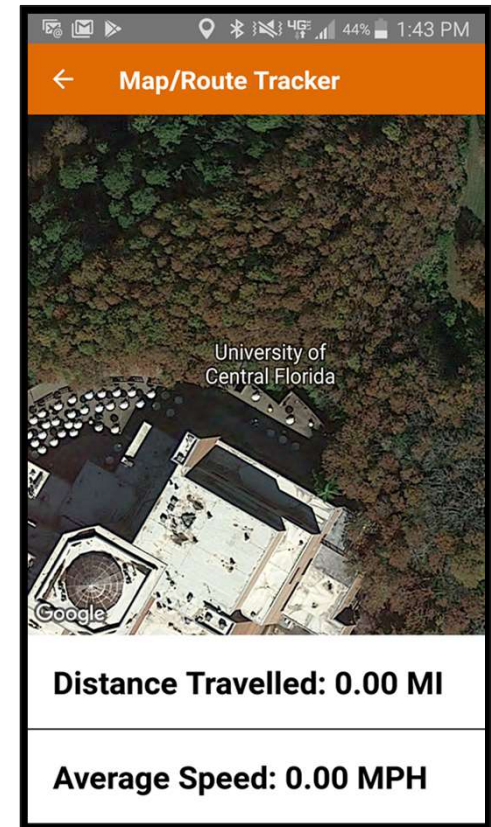
# Mobile App Design

- Bold header with current Ride Mode
- Speed, in MPH or KPH displayed prominently in center of screen
- Stopwatch used in tracking trip duration as well as average speed
- Reset button
  - Resets the stopwatch
  - Resets the board's speed
  - Logs trip into local memory
- Buttons to traverse to map screen and setting screen



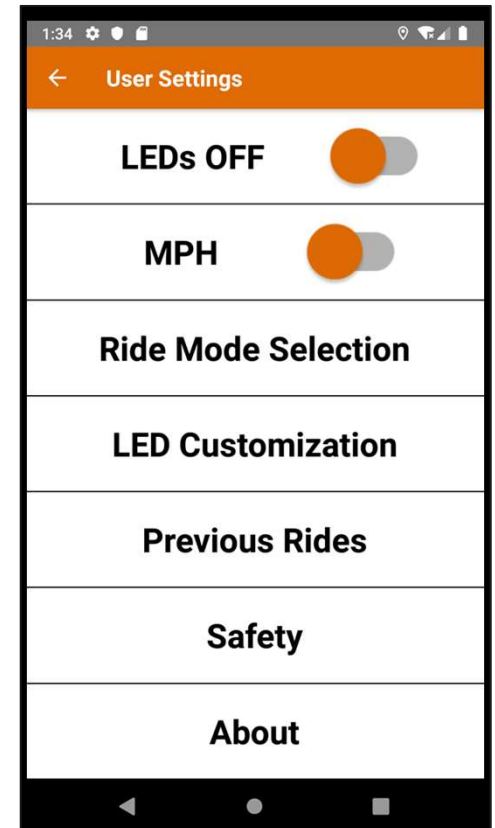
# Mobile App Design

- Integrated map
  - Using the phone's internal GPS in order to get this information
  - Tracks location in real time
- Tracking Ride Data
  - Can be used in various ways in order to maximize ride efficiency
  - Metrics can be used to compare different routes



# Mobile App Design

- Toggle switches, for the LEDs and for unit of measurement for speed/distance
- Access to multiple screens
  - Ride Mode Selection
  - LED Customization
  - Previous Rides
  - Safety
  - About



# Mobile App Design

- Ride Modes
  - Beginner
    - Includes ultrasonic sensor safety feature
  - Intermediate
  - Advanced
  - ECO
    - Disables safety features to extend battery life



# Embedded Design

- Board\_Main Setup
  - Initializes 3 UARTS: Bluetooth adapter and 2 VESC motor controls
  - Clears LED strip in case of any residual PWM signal on signal line
  - Initialize load cell for weight sensing
  - Initialize ultrasonic sensor for obstacle detection



# Embedded Design

- Board\_Main Loop
  - Check for load cell for rider, if non-zero input detected over threshold, transmit flag to app, signals app is safe to transmit data
  - Check for obstacles, if obstacle detected under threshold distance, begin emergency stop procedure, transmit flag to app

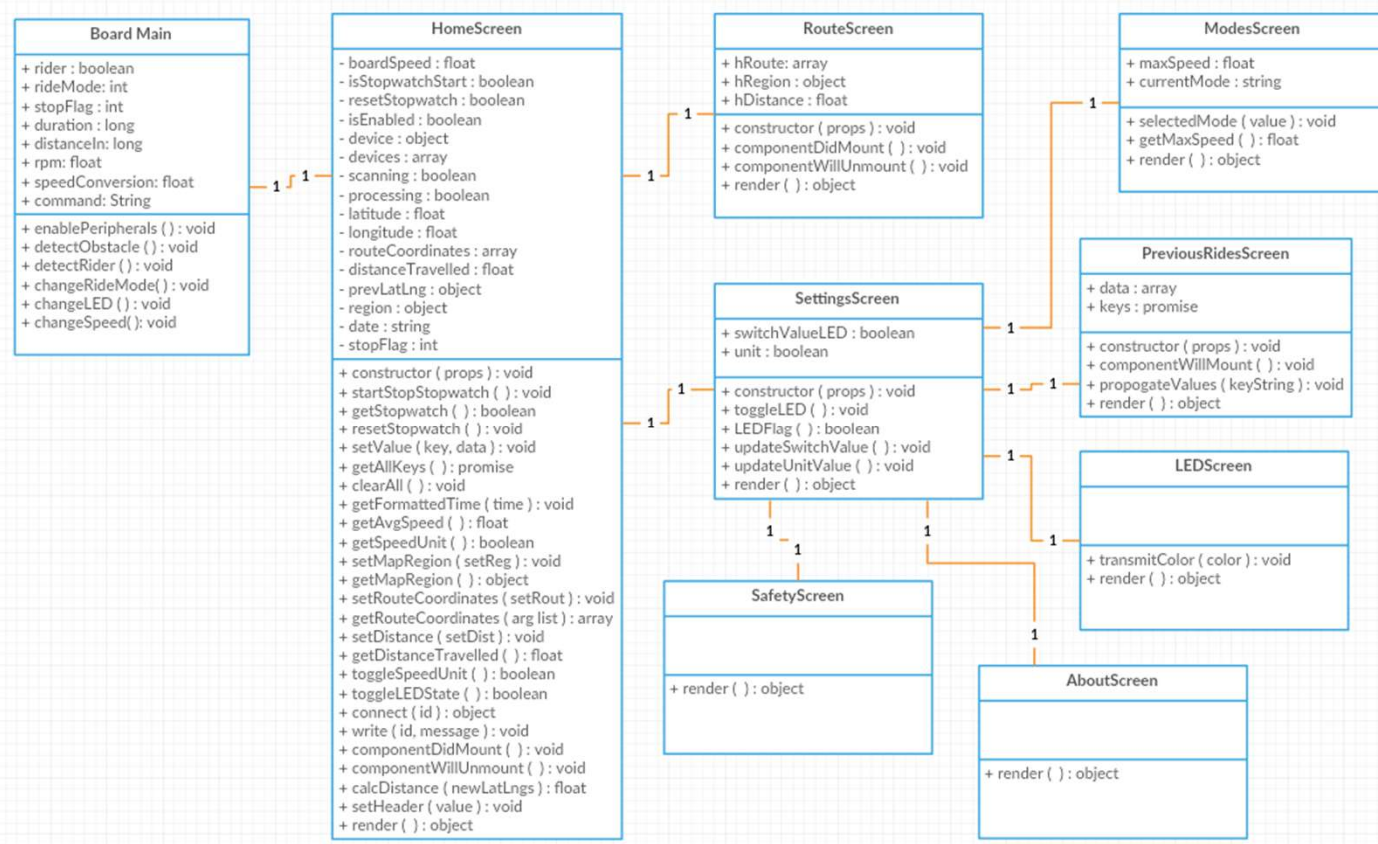
# Embedded Design

- Board\_Main Loop Cont'd
  - Check for incoming serial commands
    - LED Change
    - Speed Change
    - Ride Mode Change

# Complete Internals & Externals



# Class Diagram



# Constraints

- Economic
  - Exceeded project budget
- Size and weight
- User experience
  - Accessible for any level of rider
  - Customizable and easy-to-use app
- Ensuring safety of user without compromising experience

# Issues

- Having to switch from MSP430F5529 to ATmega2560 in last month of development
- Initial time lost designing MSP430 software and PCB
- Accidentally damaging part of our ESC
- Physically fitting all components into enclosure
- Communications between different mobile app components
- Finding best placement of wireless charging coils to maximize charging voltage
- Battery shorted the day before the presentation and damaged multiple components

# Distribution of Responsibilities

Name	Mobile App	PCB	Sensor Suite	Battery / Power Management	Motor / ESC	Components Enclosure
Alex	S	S	P		P	S
Hanser	P	S	S		S	P
Simeon		P		P	S	S

P = Primary

S = Secondary

# Initial Budget

Part	Price (USD)	Part	Price (USD)
Longboard	\$60	Ultrasonic Sensor	\$6
Load Cell	\$60	PCB Fabrication	\$50
Load Cell Amp	\$10	Voltage Regulator	\$7
Battery	\$146	RGB LED Strip	\$20
Battery Fuel Gauge	\$4	Launchpad	\$13
Hub Motor	\$220	MPPT Charge Cont.	\$47
Solar Panel	\$87	Boost Converter	\$34
Bluetooth Module	\$30		
Camera	\$40	Total	\$834.00



# Actual Expenses

Part	Price (USD)	Part	Price (USD)
Longboard	\$60	Ultrasonic Sensor	\$6
Load Cell	\$60	PCB Fabrication	\$150
Load Cell Amp	\$10	Voltage Regulator	\$7
Battery	\$146	RGB LED Strip	\$20
Battery meter	\$10	Arduino MEGA	\$30
Hub Motor	\$220	Boost Converter	\$60
Solar Panel	\$87	VESC	\$120
Bluetooth Module	\$30		
Miscellaneous	\$100	Total	\$1180.00

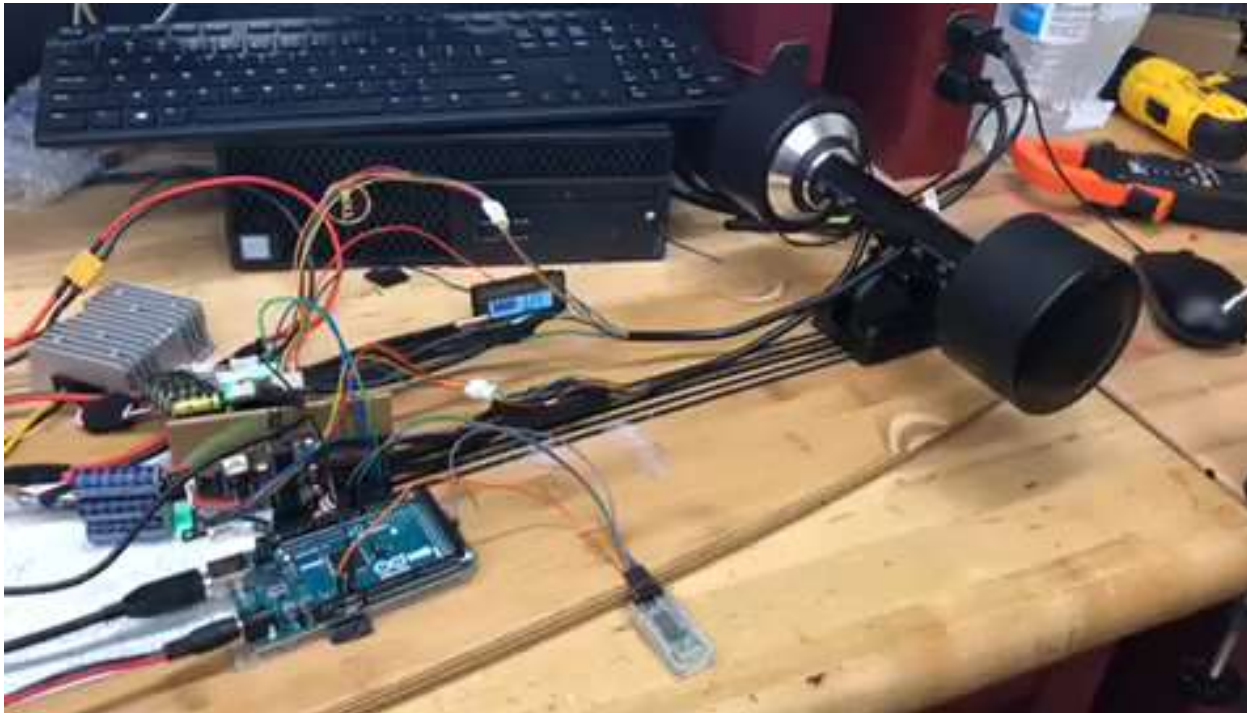


**Any  
Questions?**

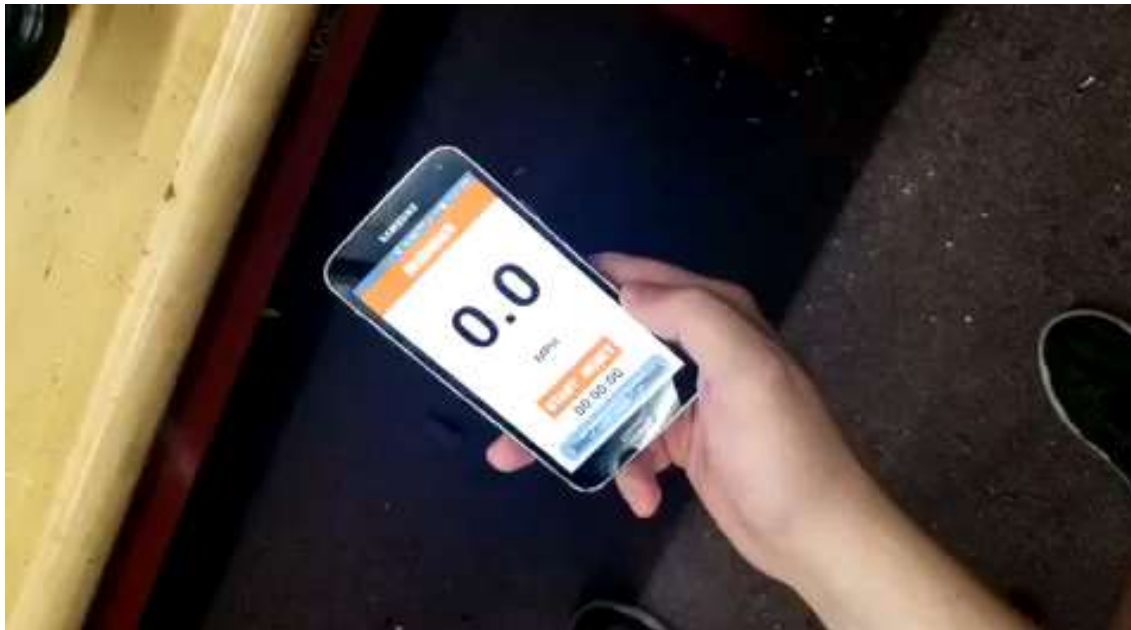
# Demo: Dual Motors



# Demo: Dual Motors, Max Speed



# Demo: LEDs (App and PCB)



# Demo: App, Motors, and PCB



## Demo: Wireless Charging (fast, DC power supply)



# Demo: Wireless Charging via Solar Panel

