

Static Single Assignment (SSA) Objectives

- Given a CFG, the student will be able to compute the dominator relation for the CFG.
- Given a CFG, the student will be able to compute the dominance frontier and iterated dominance frontier for each node in the CFG.
- Given a CFG, the student will be able to compute the SSA-form for the CFG.
- Given SSA-form, the student will be able to convert it to normal form.

SSA Form

- An improvement to DU-UD chains.
- sparse representation
- each variable is defined once → each use has one reaching definition
- use ϕ -nodes to merge multiple definitions reaching a single point

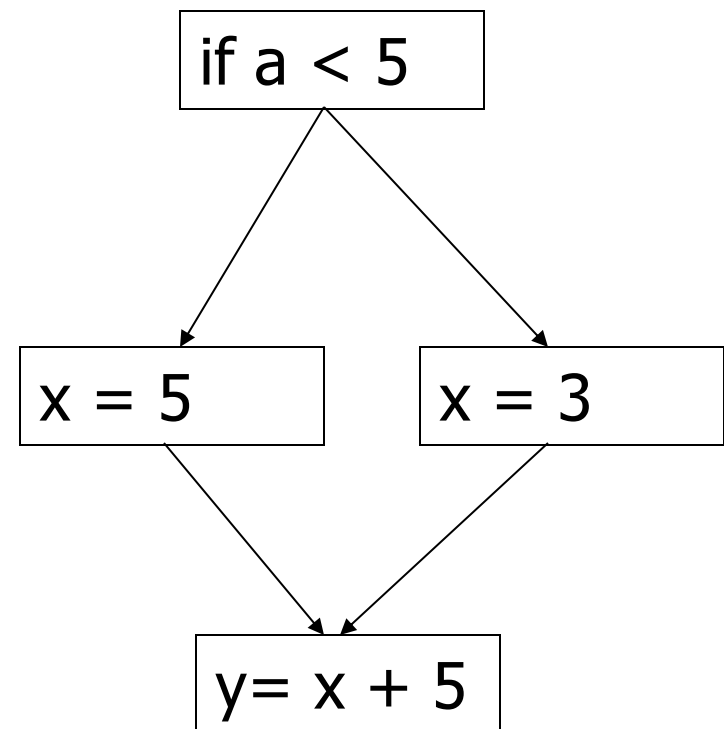
$v = 4$
 $x = v + 5$
 $v = 6$
 $y = v + 7$

becomes

$v_0 = 4$
 $x_0 = v_0 + 5$
 $v_1 = 6$
 $y_0 = v_1 + 7$

Control Flow

- What do we do when there are multiple definitions reaching a single point?
- In the example to the right, which definition of x is used at in the computation of y ?

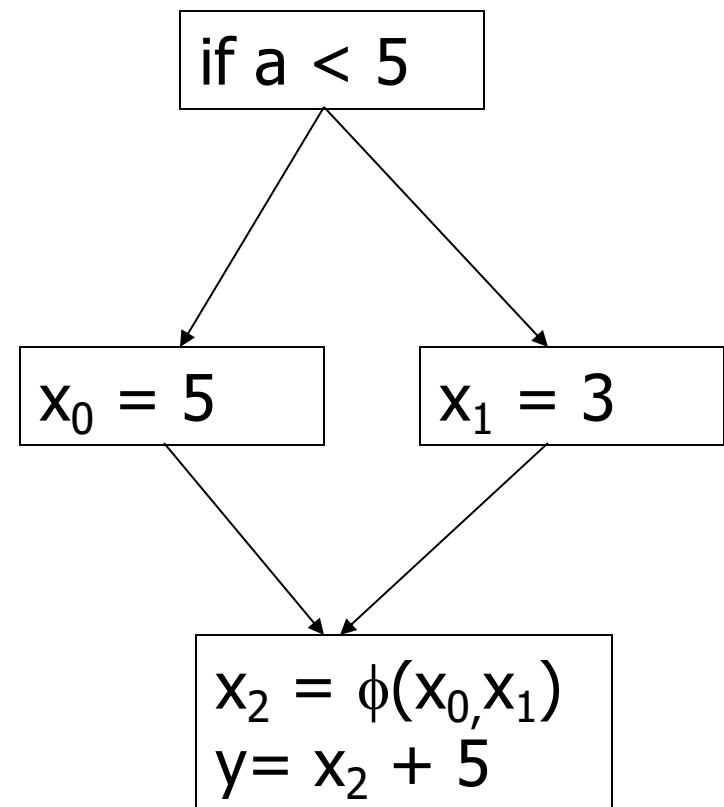


ϕ -nodes

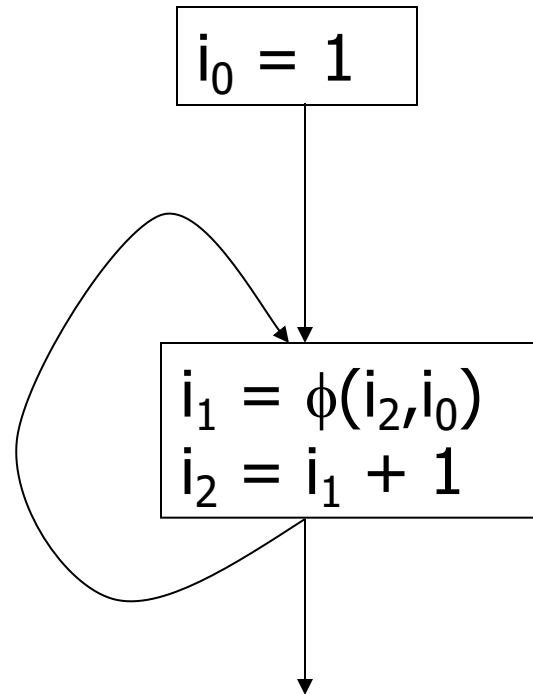
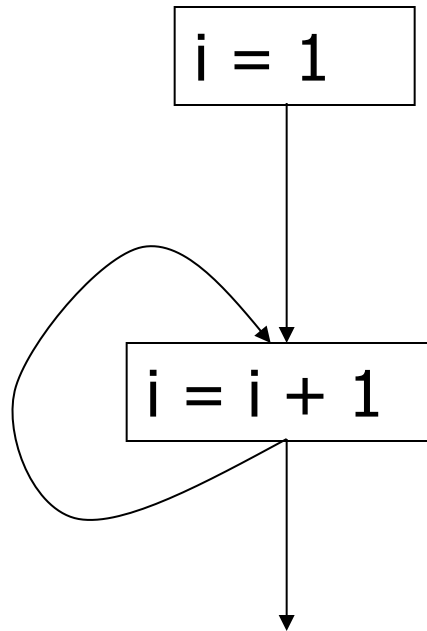
- Defⁿ: Consider a block b in the CFG with predecessors $\{p_1, p_2, \dots, p_n\}$ where $n > 1$. A ϕ -node

$$T_0 = \phi(T_1, T_2, \dots, T_n)$$

in b gives the value of T_i to T_0 on entry to b if the execution path leading to b has p_i as the predecessor to b .



Another Example



Placing ϕ -nodes

- Find the join points
 - top of basic blocks where different definitions reach on different paths
- Method
 - computing dominator relation for CFG
 - compute dominance frontiers for each basic block

Dominator Relation

- Defⁿ: A node n in a graph dominates a node m , denoted $n \underline{\gg} m$, if every path from the entry node to m contains n .

$$\begin{array}{ll} n \underline{\gg} n & \text{(reflexive)} \\ n \underline{\gg} m \wedge n \neq m \rightarrow !(m \underline{\gg} n) & \text{(antisymmetric)} \\ n \underline{\gg} m \wedge m \underline{\gg} r \rightarrow n \underline{\gg} r & \text{(transitive)} \end{array}$$

- $\underline{\gg}$ is a partial order on the CFG nodes

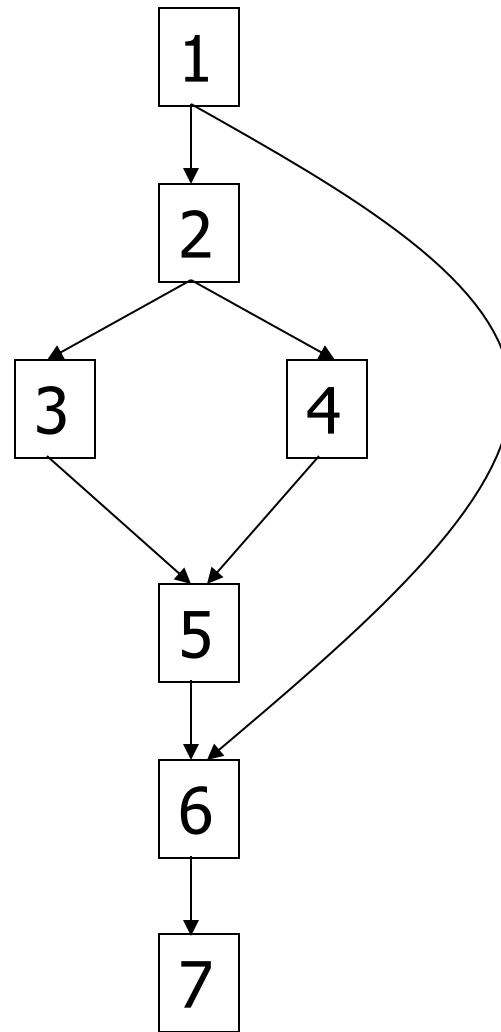
Computing Dominators

```
D(v0) = {v0}  
for each n ∈ V - {v0}  
  D(n) = V  
do {  
  for each n ∈ V - {v0}  
    D(n) = {n} ∪  
           ⋂p ∈ preds(n) D(p)  
} until no D(n) changes
```

$n \gg m \Leftrightarrow \forall p \in \text{pred}(m) \ n \gg p$

- ENTRY dominates all nodes
- Since \gg is a partial order, we can construct an ordering of all the nodes that each node dominates in order to construct a **dominator tree**.
- The immediate dominator of n , denoted **idom(n)**, is its parent in the dominator tree.
- The **idom(n)** is the member of $\text{dom}(n) - \{n\}$ with the largest dominator set since the **idom(n)** must be dominated by every dominator of n except n itself

Example



Dominance Frontiers

- Defⁿ: Node n is said to strictly dominate a node m , denoted $n \gg m$, if $n \neq m \wedge n \underline{\gg} m$.
- Defⁿ: The dominance frontier of a node n consists of the successors of all nodes dominated by n that are not strictly dominated by n .

$$DF(n) = \{m \mid \exists p \in \text{preds}(m) \text{ where } n \underline{\gg} p \wedge !(n \gg m)\}$$

- $DF(n)$ is the set of nodes where a join point for a definition of a variable in n can occur

Computing Dominance Frontiers

$$DF(n) = DF_{local}(n) \cup (\bigcup_{c \in \text{child}(n)} DF_{up}(c))$$

$$DF_{local}(n) = \{m \mid m \in \text{succ}(n) \wedge !(n \gg m)\}$$

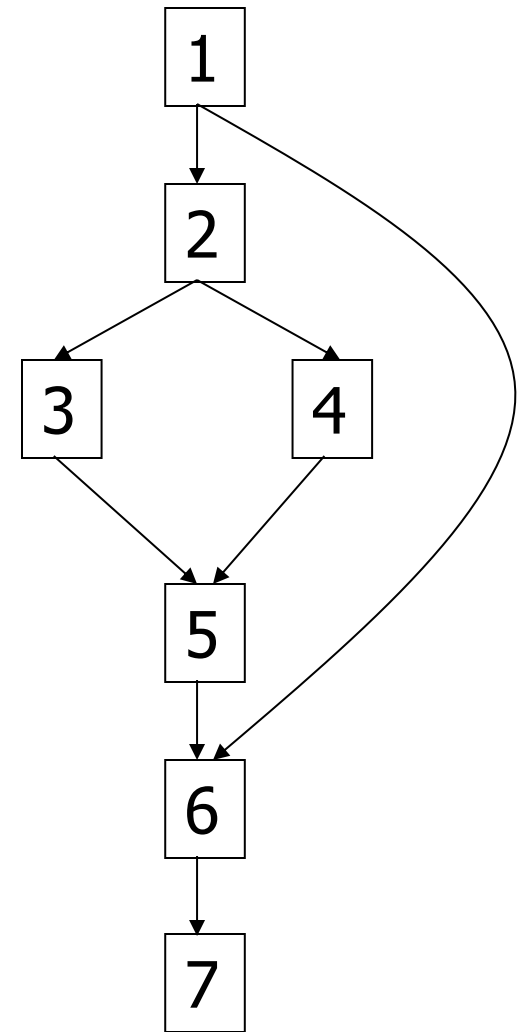
$$DF_{up}(c) = \{m \mid m \in DF(c) \wedge !(\text{idom}(c) \gg m)\}$$

- $DF_{local}(n)$ is the dominance frontier of n involving only the successors of n .
- $DF_{up}(c)$ propagates DF_{local} information up the dominator tree. Includes everything in the dominance frontier of the children of n that n does not dominate itself, excluding n .

Computing Dominance Frontiers

```
for each  $n \in DT$  in postorder {  
   $DF(n) = \emptyset$   
  for each  $c \in \text{child}(n)$   
    for each  $m \in DF(c)$   
      if  $!(n \gg m)$   
         $DF(n) \cup= \{m\}$   
  for each  $m \in \text{succ}(n)$   
    if  $!(n \gg m)$   
       $DF(n) \cup= \{m\}$   
}
```

- Compute the dominance frontier for the example



Placement of ϕ -nodes

- Let S_v be the set of all blocks with assignments to v plus the **ENTRY** node.

$$DF(S_v) = \bigcup_{n \in S_v} DF(n)$$

This is the set of all possible join points for assignments to v .

- If we place ϕ -nodes in each $b \in DF(S_v)$ will this be correct?
 - Does S_v contain all blocks in the dominance frontier of all blocks with definitions of v ?

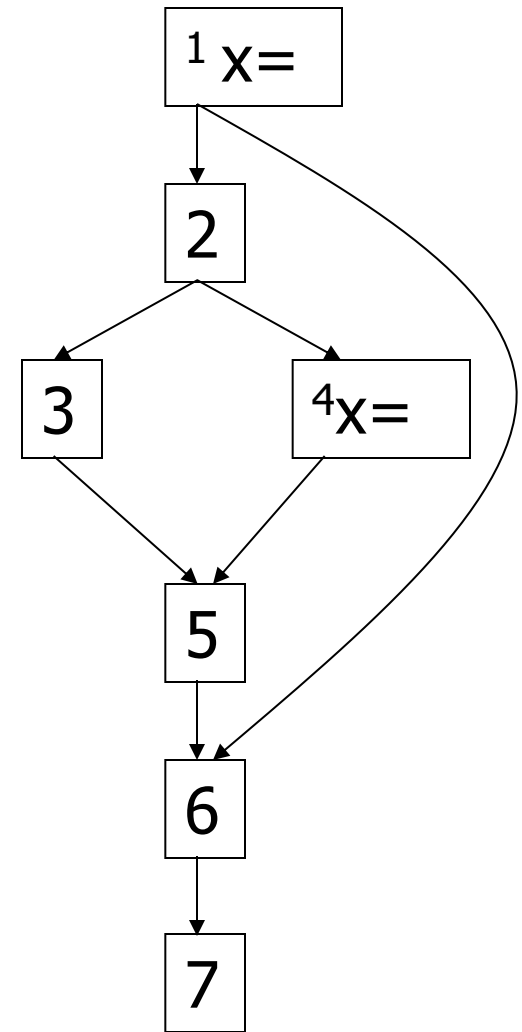
Iterated Dominance Frontier

- $DF^+(S_v)$ is the iterated dominance frontier for the set of definitions S_v
 - New blocks are potentially added for each ϕ -node insertion.
- Computing $DF^+(S_v)$
 - $DF_1(S_v) = DF(S_v)$
 - $DF_{i+1}(S_v) = DF(S_v \cup DF_i(S_v))$
 - $DF^+(S_v) = \bigcup_{i=1,\infty} DF_i(S_v)$

Iterated Dominance Frontier

```
Work =  $\emptyset$   
DF+(Sv) =  $\emptyset$   
for each b ∈ Sv {  
    Work ∪= {b}  
}  
while Work ≠  $\emptyset$  {  
    b = Work.Remove()  
    for each c ∈ DF(b) {  
        if c ∉ DF+(Sv) {  
            DF+(Sv) ∪= {c}  
            Work ∪= {c}  
        }  
    }  
}
```

- Compute the iterated dominance frontier for the example



Inserting ϕ -nodes

Perform live-variable analysis

```
for each  $T \in \text{Variables}$ 
  if  $T \in \text{Globals}$  {
     $S = \{b \mid b \text{ has a def of } T\}$ 
       $\cup \{\text{Entry}\}$ 
    Compute  $\text{DF}^+(S)$ 
    for each  $b \in \text{DF}^+(S)$ 
      if  $T \in b.\text{LiveIn}$  {
         $n = |\text{pred}(b)|$ 
        insert  $T = \phi(T_1, \dots, T_n)$  in  $b$ 
      }
  }
```

- Insert ϕ -nodes for previous example.
- leave parameters to ϕ -nodes named by path
 - renaming will get the correct names

Renaming Temporaries

- Need to replace uses with new names
 - walk the dominator tree
 - replace uses dominated by a definition

for each $T \in \text{Variables}$

$\text{NameStack}(T) = \emptyset$

$\text{Rename}(\text{ENTRY})$

Renaming Algorithm

```
Rename(b) {  
  for each  $I \in \Phi(b)$  of the form  $T_0 = \phi(T_1, \dots, T_n)$  {  
    push NewName() on NameStack( $T_0$ )  
    Definition(Top(NameStack( $T_0$ ))) =  $I$   
  }  
  for each  $I \in b$  in order {  
    for each  $T \in \text{Operand}(I)$  {  
      replace  $T$  by Top(NameStack( $T$ ))  
      add  $I$  to Uses(Top(NameStack( $T$ )))  
    }  
     $T = \text{Target}(I)$   
    push NewName() on NameStack( $T$ )  
    Definition(Top(NameStack( $T$ ))) =  $I$   
  }  
}
```

Renaming Algorithm Contd.

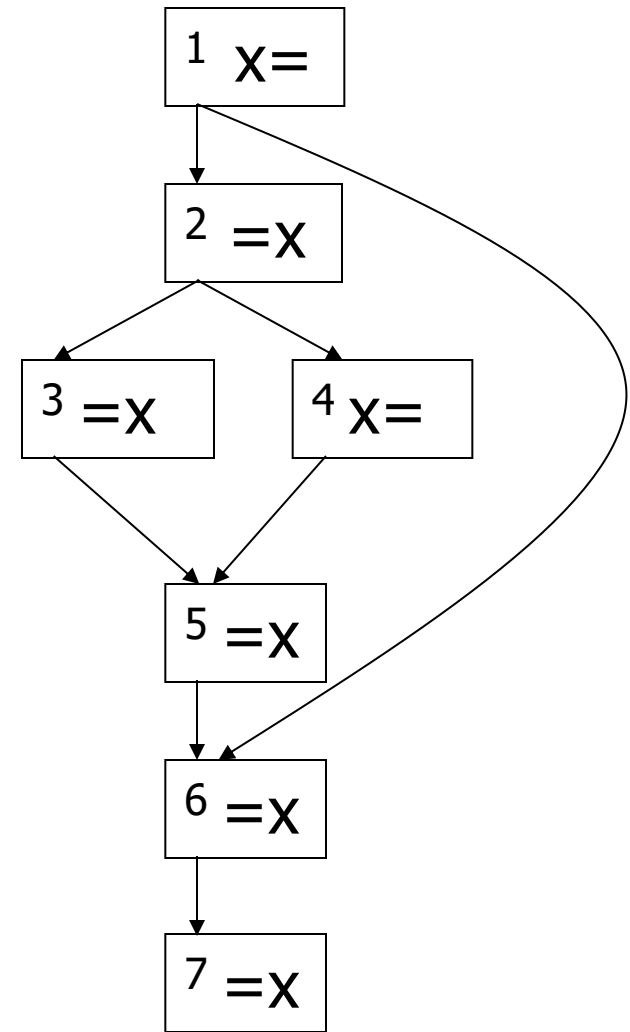
```
for each  $s \in \text{succ}(b)$  {  
   $j = \text{WhichPredecessor}(s, b)$   
  for each  $I \in \Phi(s)$  of the form  $T_0 = \phi(T_1, \dots, T_n)$  {  
    replace  $T_j$  by  $\text{Top}(\text{NameStack}(T_j))$   
    add  $I$  to  $\text{Uses}(\text{Top}(\text{NameStack}(T_j)))$   
  }  
}  
for each  $c \in \text{Children}(b)$   
   $\text{Rename}(c)$ 
```

Renaming Algorithm Contd.

```
for each  $I \in b$  in reverse order {  
     $T = \text{Target}(I)$   
    replace  $T$  by  $\text{Pop}(\text{NameStack}(T))$   
}  
for each  $I \in \Phi(b)$  of the form  $T_0 = \phi(T_1, \dots, T_n)$  {  
    replace  $T_0$  by  $\text{Pop}(\text{NameStack}(T_0))$   
}  
  
➤ Why are the l-values renamed on the way back up  
the dominator tree?
```

Example

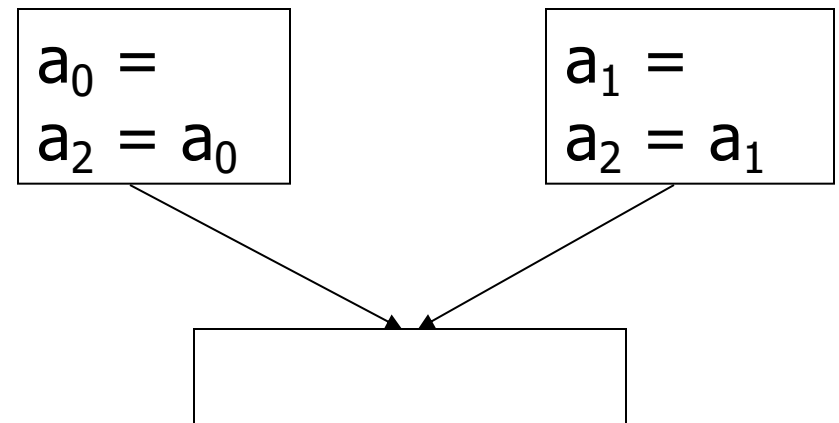
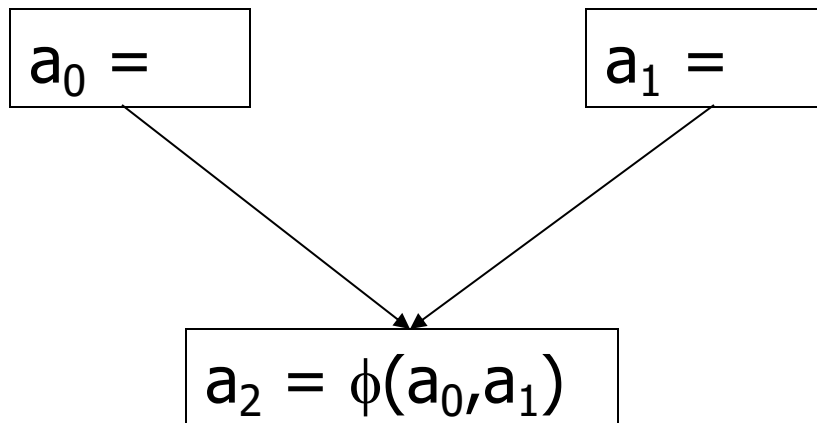
- Convert the code to the right to SSA



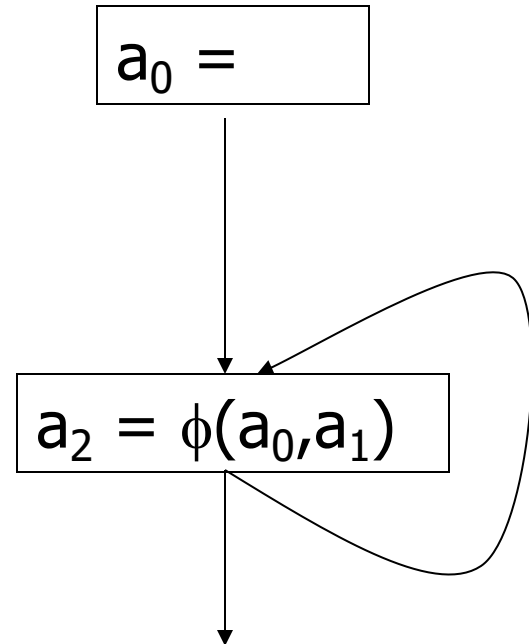
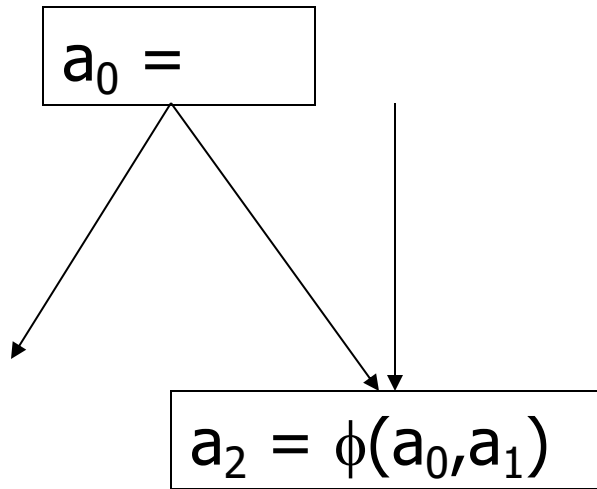
SSA to Normal Form

- ϕ -nodes require copies from operands to l-value for each operand

- Becomes



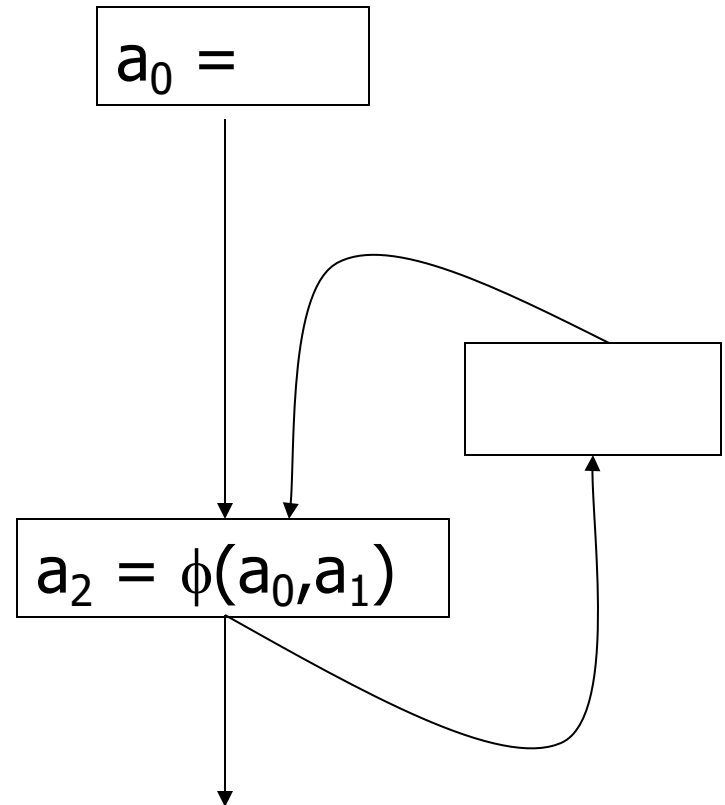
Problems with Direct Translation



- Cannot move a copy into predecessor
- Cannot put copy at beginning of block

Critical Edges

- Edges where the tail of the edge has more than one predecessor and the head of the edge has more than one successor are called **critical edges**.
- The solution is to insert a basic block on all critical edges so that the CFG has none.



Abnormal Edges

- Edges where the head is not definite (known branch target) are called **abnormal edges**.

```
switch(a) {  
  case 1:  
    // no break statement  
  case 2:  
}
```

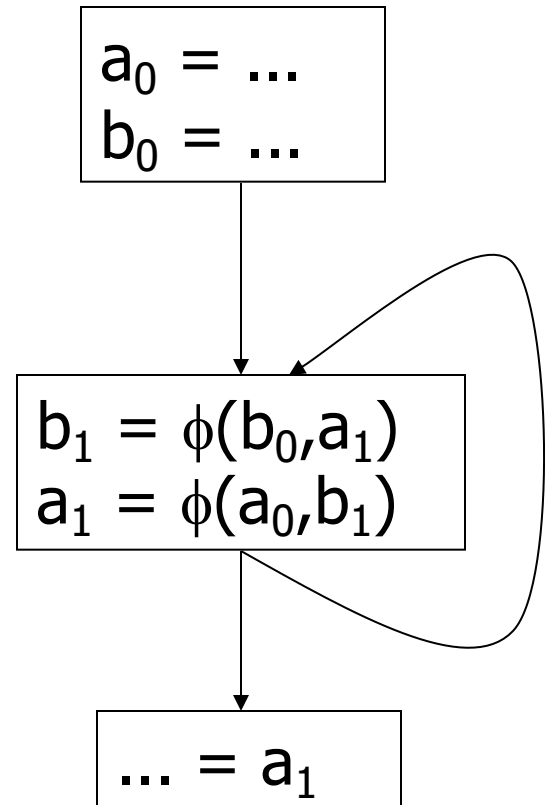
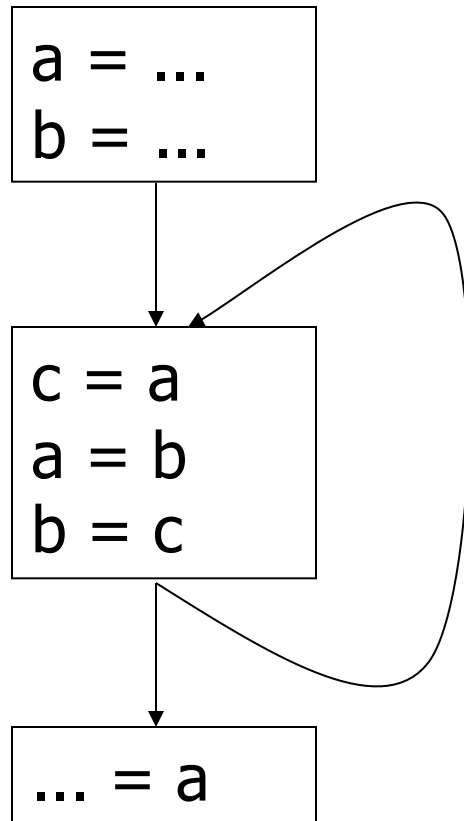
```
iLD      a, r1  
iMULI    8, r1, r2  
iLDA     br_table, r1  
BR       r2(r1)
```

```
...  
L1: nop
```

```
...  
L2: nop
```

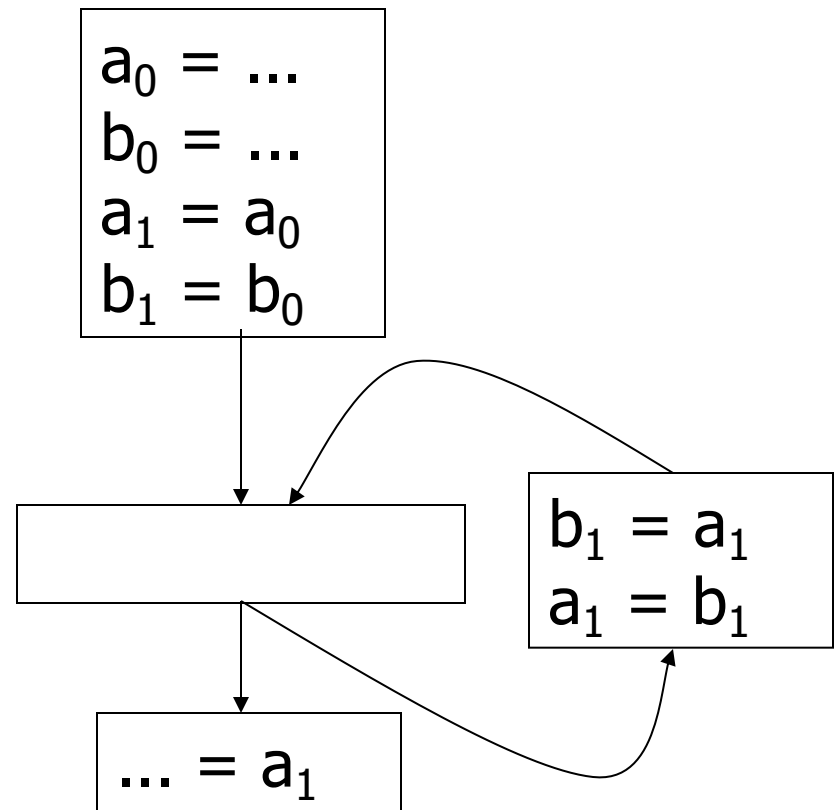
Must ensure that no blocks
will need to be inserted on
an abnormal critical edge

Optimized SSA Problems

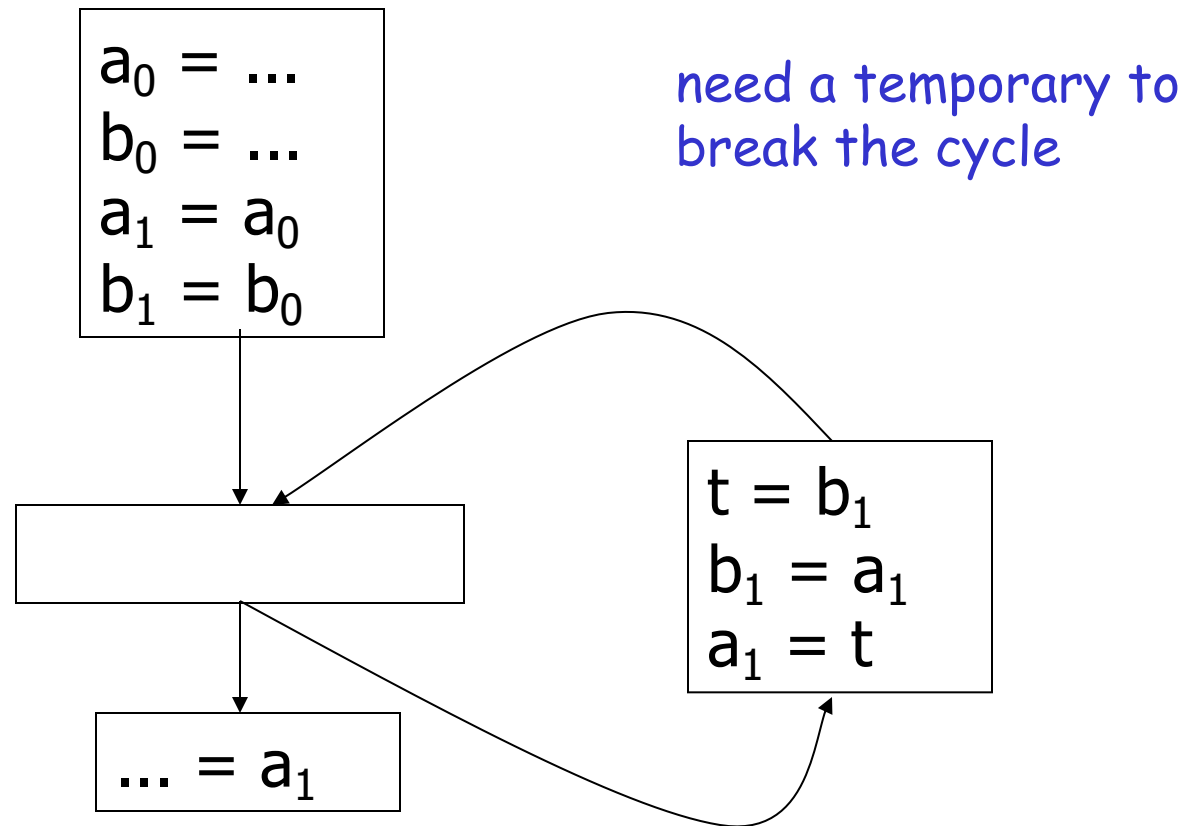


Optimized SSA Problems

- In a block b , all members of $\Phi(b)$ are executed simultaneously
- Direct translation of the previous code results in incorrect code.



Correct Translation



Translating to Normal Form

- Given a CFG in SSA form and a partition $P=\{P_1,\dots,P_n\}$ of the set of all variables, rewrite the CFG in normal form so that any two temporaries T_1 and T_2 in P_i are given the same temporary name and ϕ -nodes are replaced by equivalent copy operations. The partition must ensure that
 - In each block b , if two targets of ϕ -nodes are equivalent, then the corresponding arguments must be equivalent.
 - For each abnormal critical edge (c,b) if $T_0=\phi(T_1,\dots,T_i,\dots,T_n)$ is a ϕ -node in b and c is the i^{th} predecessor of b , then T_0 and T_i must be equivalent (no copies on abnormal critical edges).
- Each P_i has a single unique name
- Can use global value numbering to compute partition

Renaming ϕ -nodes

- Since all $i \in \Phi(b)$ are executed simultaneously, they need to be topologically sorted so that all uses of a variable T_i are generated before the definition.
- Since there may be cycles, these need to be handled separately
 - find cycles
 - break cycles with an additional temporary

Cycles within ϕ -nodes

- A graph $R(b)$ such that the nodes are the elements of P and there is an edge from $FIND(T_k)$ to $FIND(T_l)$ if there are temporaries T_k and T_l such that $T_k = \phi(\dots, T_l, \dots) \in \Phi(b)$.
- Use Tarjan's SCC algorithm to find cycles in $R(b)$.

Cycles within ϕ -nodes

- For each SCC do the following
 1. Enumerate the cycle in some topological order such that the first node is a successor of the last.
 2. Generate one extra temporary, T .
 3. Generate an instruction to copy the temporary representing the first node into T .
 4. Translate all of the other nodes except the last one normally.
 5. Generate an instruct to copy T into the temporary corresponding to the final node.

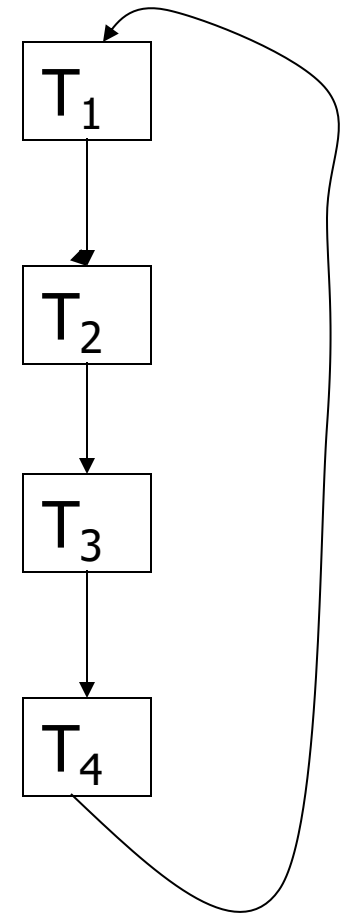
Example

$$T_1 = \phi(\dots, T_2, \dots)$$

$$T_2 = \phi(\dots, T_3, \dots)$$

$$T_3 = \phi(\dots, T_4, \dots)$$

$$T_4 = \phi(\dots, T_1, \dots)$$



Algorithm

```
foreach  $b \in G$  {  
  foreach  $i \in b$  {  
    foreach  $T \in \text{Operands}(i)$   
      replace  $T$  by  $\text{FIND}(T)$   
    foreach  $T \in \text{Targets}(i)$   
      replace  $T$  by  $\text{FIND}(T)$   
    if  $i = (T = T)$   
      delete  $i$  from  $b$   
  }  
  foreach  $c \in \text{pred}(b)$   
    call  $\text{eliminate-}\phi(c, b, \text{whichpred}(c, b))$   
}  
foreach  $b \in G$   
  remove  $\phi$ -nodes from  $b$ 
```

Algorithm

```
procedure eliminate- $\phi$ (c,b,i)
  call eliminateBuild(b,i)
  if nodeSet  $\neq \emptyset$  {
    Visited = Stack =  $\emptyset$ 
    foreach T  $\in$  nodeSet
      if T  $\notin$  Visited
        call elimForward(T)
    Visited =  $\emptyset$ 
    while Stack  $\neq \emptyset$  {
      pop T from Stack
      if T  $\notin$  Visited
        call elimCreate(T)
    }
  }
end eliminate- $\phi$ 
```

```
procedure elimForward(T)
  add T to Visited
  foreach S  $\in$  elimSucc(T)
    if S  $\notin$  Visited
      elimForward(S)
  push T onto Stack
end elimForward
```

Algorithm

```
procedure elimCreate(T)
  if elimUnvisitPred(T) {
    create new temp U
    append "U=T" to C
    foreach p ∈ elimPred(T)
      if p ∉ Visited {
        call elimBack(p)
        append "P=U" to C
      }
  }
  else if elimSucc(T) ≠ ∅ {
    add T to Visited
    take S from elimSucc(T)
    append "T=S" to C
  }
end elimCreate
```

```
function elimUnvisitPred(T)
  foreach p ∈ elimPred(T)
    if p ∉ Visited
      return true
  return false
end elimUnvisitPred
```

```
procedure elimBack(T)
  add T to Visited
  foreach p ∈ elimPred(T)
    if p ∉ Visited {
      call elimBack(p)
      append "P=T" to C
    }
  }
end elimBack
```

Algorithm

```
procedure eliminateBuild(b,i)
  nodeSet =  $\emptyset$ 
  foreach  $T_0 = \phi(\dots, T_i, \dots) \in \Phi(b)$ 
     $x_0 = \text{FIND}(T_0)$ 
     $x_1 = \text{FIND}(T_i)$ 
    if  $x_0 \neq x_1$  {
      call elimName( $x_0$ )
      call elimName( $x_1$ )
      add  $x_0$  to elimPred( $x_1$ )
      add  $x_1$  to elimSucc( $x_0$ )
    }
  }
end eliminateBuild
```

```
procedure elimName(T)
  if  $T \notin \text{nodeSet}$  {
    add T to nodeSet
    elimSucc(T) =  $\emptyset$ 
    elimPred(T) =  $\emptyset$ 
  }
end elimName
```

Example

$$F = \phi(\dots, B, \dots)$$

$$C = \phi(\dots, D, \dots)$$

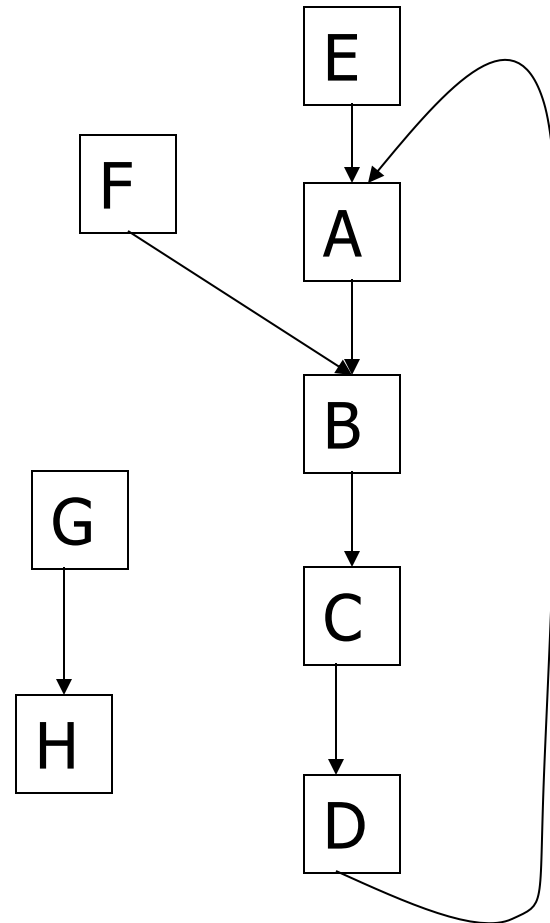
$$E = \phi(\dots, A, \dots)$$

$$G = \phi(\dots, H, \dots)$$

$$B = \phi(\dots, C, \dots)$$

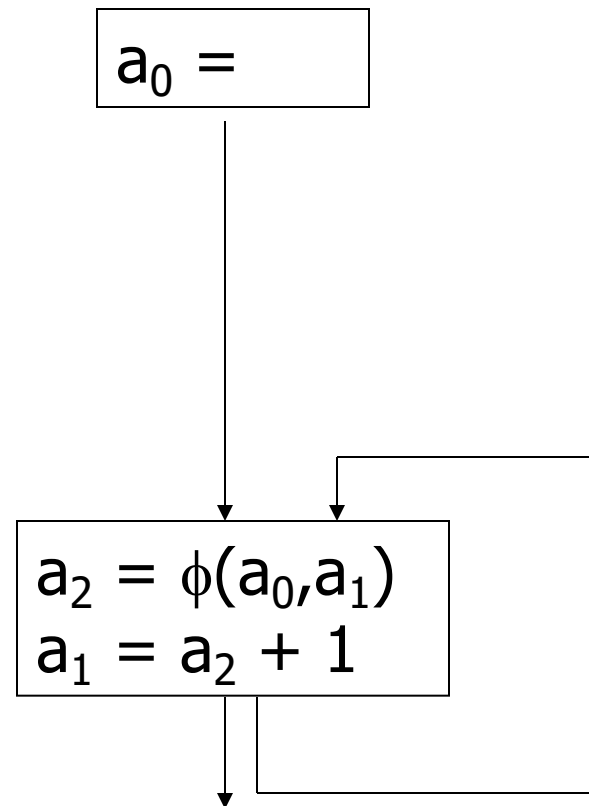
$$D = \phi(\dots, A, \dots)$$

$$A = \phi(\dots, B, \dots)$$



Critical Edges Re-visited

- In the CFG to the right, if a_2 is not used outside the block, the new basic block is unnecessary.
- Since inserting a block on a back edge puts a jump in loop, splitting the critical edge is not advisable.



Critical Edges Re-visited

- If a_2 is used outside the block, add a copy to a temporary \dagger and replace the uses of a_2 outside the block with \dagger

