

#### **Header Files**

Up to now, all source code was placed into one file. For reasonable programs, this is not desirable, especially if functions are reused by different programs.

Unfortunately, C++ has no real module system like, e.g. Pascal or Java, to group similar functions or types. Instead, header files are used to make C++ objects known to different source files.

As you remember, functions can be used if they were previously declared or implemented. By separating declaration and implementation into header and source file:

```
// header file: f.hh
void f ( int n, double f );
```

```
// source file: f.cc
void f ( int n, double f )
{ ... }
```

the function can be reused by just including the header file.



#### **Header Files**

Including another file into the current source code is performed by the **include** directive:

```
#include "filename" or 
#include < filename>
```

The first version is usually used for files in the same project, whereas the second version is for files from other projects, e.g. the operating system or the C++ compiler.

```
#include "f.hh" // contains decl. of "f"
int main ()
{
   f( 42, 3.1415926 );
}
```



#### **Header Files**

#### Remark

By convention, the filename suffix of the header file should be either "h" (like in C), "H", "hh" or "hpp".



### C++ Library

The C++ compiler comes with a set of standard include files containing declarations of many functions:

cstdlib: standard C functions, e.g.

- exit: stop program,
- atoi and atof: string to int and double conversion,
- qsort: sort arrays,
- malloc and free: C-style dynamic memory management,

cmath: mathematical functions, e.g.

- sqrt: square root,
- abs: absolute value,
- sin and cos,
- log: natural logarithm



### C++ Library

cstdio: C-style IO functions, e.g.

- printf: print variables to standard output,
- fopen, fclose, fread and fwrite: file IO

cstring: string functions, e.g.

- strlen: string length,
- strcat: string concatenation,
- strcmp: string comparison,
- strcpy: string copy

cctype: character tests, e.g.

- isdigit: test for digit,
- islower: test for lower case,
- isspace: test for white-space

etc.: cassert, cerrno, cinttypes, climits, ctime.



### C++ Library

Specific C++ functionality usually comes in the form of the *standard template library*. It is implemented via classes (see later) and provided by the following header files:

iostream: file input/output functions and classes,

vector: dynamic containers similar to arrays,

valarray: similar to vector but better suited for numerics,

limits: functions for determining type limits, e.g. minimal or maximal values,

map: associative array, e.g. indices are arbitrary types,

list: provides standard list and iterators,

complex: provides complex datatype,

etc.

The specific classes and their usage will be discussed later.



### Libraries without Headers (LAPACK)

LAPACK is written in Fortran and no header files exist for C++. Therefore, we will have to write them ourselves. Consider

```
SUBROUTINE DGESVD( JOBU, JOBVT, M, N, A, LDA, S, U, LDU, VT, LDVT, WORK, LWORK, INFO )

CHARACTER
INTEGER
DOUBLE PRECISION
$

LDA, * ), S(*), U(LDU, *),
VT(LDVT, *), WORK(*)
```

To define a C++ function corresponding to the above Fortran function the datatypes have to be mapped to C++ types. In Fortran, every variable is provided as a pointer, hence:

```
CHARACTER \rightarrow char *,

INTEGER \rightarrow int * and

DOUBLE PRECISION \rightarrow double *.
```



#### Libraries without Headers (LAPACK)

Fortran function names are in lower case and end with and underscore '\_', when seen from C or C++. Hence, the name of the above Fortran function is dgesvd\_:

Furthermore, there is a difference between C and C++ functions. Fortran only provides C-style functions, whereas the above is a C++ function. To tell the compiler, that a C-style function should be declared, the **extern "C"** instruction is provided:



### Libraries without Headers (LAPACK)

Afterwards, the function dgesvd\_ can be used like any other C++ function. To compute the SVD  $M = U \cdot S \cdot V^T$  of a matrix M, the code looks like:



#### **Header File Recursion**

The **include** directive can be seen as simple text replacement: the directive is replaced by the content of the corresponding file.

```
#include "f.hh"
int main ()
{
    f( 42, 3.1415926 );
}
```

```
void f ( int n, double f );
int main ()
{
    f( 42, 3.1415926 );
}
```

This might lead to infinite loops, if you have recursive include directives in different files, e.g. "file1.hh" includes "file2.hh", which by itself includes "file1.hh".

```
// FILE: file1.hh
#include "file2.hh"
...
```

```
// FILE: file2.hh
#include "file1.hh"
...
```



### **Header File Encapsulation**

To prevent infinite loops, two other directives are provided:

```
#ifndef (NAME)

#endif
```

tests, if the symbol  $\langle NAME \rangle$  was previously defined by the directive #define  $\langle NAME \rangle$ 

If it was not defined, all source code between the **ifndef** directive and the corresponding **endif** will be included by the C++ compiler. Otherwise, the source code will be omitted.

#### Remark

It is recommended to name the symbol  $\langle NAME \rangle$  after the name of the header file.



#### **Header File Encapsulation**

Now, for the recursive example:

```
// FILE: file1.hh

#ifndef __FILE1_HH
#define __FILE1_HH

#include "file2.hh"

#endif
```

```
// FILE: file2.hh
#ifndef __FILE2_HH
#define __FILE2_HH
#include "file1.hh"
#endif
```

If "file1.hh" is included by a source file, the symbol "\_\_FILE1\_HH" will be defined and the content of the header file included. Similar, #include ''file2.hh'' will be replaced by the content of "file2.hh". If now again "file1.hh" should be included, "\_\_FILE1\_HH" is already defined and the content of "file1.hh" is omitted, stopping the recursion.



#### **Header File Encapsulation**

### **Coding Principle No. 19**

Always encapsulate your header files by an **ifndef-define-endif** construct.



#### **Inline Functions**

It is also possible to implement a function in a header file. In that case, it has to be declared **inline**, because otherwise, the function is defined in each source file, where the header is included. If you than compile all source files together, you would have multiple instances of the same function, which is not allowed.

```
#ifndef __SQUARE_HH
#define __SQUARE_HH

inline
double
square ( const double x )
{
    return x*x;
}
#endif
```



#### **Variables**

Beside functions, you can also declare variables in header files. For non-const data, the declaration and definition has to be separated to prevent multiple instances. In the header file, the variables have to be declared with the keyword **extern**:

```
// header file: real.hh
#ifndef __REAL_HH
#define __REAL_HH

typedef double real_t;

const real_t PI = 3.1415926; // const: "extern" not needed
extern real_t eps;
extern int stepwidth;
#endif
```



#### **Variables**

The definition than has to be made in a source file:

```
// source file: real.cc
#include "real.hh" // for real_t

real_t eps = 1e-8;
int stepwidth = 1024;
```

Afterwards, every module including the corresponding headerfile has access to the variables eps and stepwidth:

```
#include "real_t.hh"
int
main ()
{
    eps = 1e-4;
    cout << stepwidth << endl;
    return 0;
}</pre>
```



### Module Scope

If a function or variable is declared in a header file, it is globally visible by all other parts of the program. It is in global scope. For variables, that simplifies access, e.g. global variables do not need to be supplied as function parameters. But it has a major drawback: every function can change the variable, independent on possible side effects.

Better approach: define a function for changing the variable. That way, the access can be controlled:

```
// header
void
set_eps ( const real_t aeps );
real_t
get_eps ();
```



### Module Scope

Therefore:

### Coding Principle No. 20

Only if absolutely neccessary make non-const variables global.

#### Remark

The static declaration of a variable or function in a source file prevents other modules from using that variable or function, respectively.



#### **Namespaces**

Following situation: we have written datatypes and functions for dense matrices in a module, e.g.

```
struct matrix_t {
    size_t    nrows, ncolumns;
    real_t * coeffs;
};

matrix_t * init    ( ... );
void    mul_vec ( ... );
```

and you want to join that with another module for sparse matrices:

```
struct matrix_t {
    size_t    nrows, ncolumns, nnzero;
    size_t * rowptr, * colind;
    real_t * coeffs;
};

matrix_t * init    ( ... );
void    mul_vec ( ... );
```



#### **Namespaces**

Problem: although functions with the same name are allowed, two datatypes must not have the same name.

```
Solution 1: rename all occurences of matrix_t for sparse matrices, and change all functions, or
```

Solution 2: put each type and function set into a different namespace.

A namespace is a mechanism in C++ to group types, variables and functions, thereby defining the scope of these objects, similar to a block. Till now, all objects were in the global namespace. Namespace definition:



#### **Namespaces**

Applied to the two matrix modules from above:

```
namespace Dense {
struct matrix_t {
  unsigned nrows, ncolumns;
  real_t * coeffs;
};

matrix_t * init (...);
void mul_vec (...);
}

namespace Sparse {
struct matrix_t {
  unsigned nrows, ncolumns, nnzero;
  unsigned * rowptr, * colind;
  real_t * coeffs;
};

matrix_t * init (...);
void mul_vec (...);
}
```

This defines two namespaces Dense and Sparse, each with a definition of matrix\_t and corresponding functions.



#### Namespace Access

The access to functions or types in a namespace is performed with the namespace operator "::" :

```
Dense::matrix_t * D = Dense::init( 10, 10 );
Sparse::matrix_t * S = Sparse::init( 10, 10, 28 );
Dense::mul_vec( 1.0, D, x, y );
Sparse::mul_vec( 1.0, S, x, y );
```



#### **Namespace Access**

To make all objects in a namespace visible to the local namespace, the keyword **using** is provided:

```
using namespace Dense;
using namespace Sparse;

Dense::matrix_t * D = init( 10, 10 );  // call to Dense::init
Sparse::matrix_t * S = init( 10, 10, 28 );  // call to Sparse::init

mul_vec( 1.0, D, x, y );  // call to Dense::mul_vec
mul_vec( 1.0, S, x, y );  // call to Sparse::mul_vec
```

#### Remark

Remember, that types must have different names. Hence, the types for D and S have to be named with their namespaces.



#### **Namespace Access**

Restrict the usage of **using** to source files and avoid **using** directives in header files, because all modules including the header would also include the corresponding **using** instruction:

```
// header file: vector.hh
#include "dense.hh"
using namespace Dense;
... // vector definitions
```

```
// source file: module.cc
#include "vector.hh"
#include "sparse.hh"
using namespace Sparse;
void f ( matrix_t & M );
```

Here, matrix\_t is ambiguous, e.g. either Dense::matrix\_t or Sparse::matrix\_t.



#### Namespace Aliases

It is also possible to define an alias for a namespace, e.g. to abbreviate it:

```
namespace De = namespace Dense;
namespace Sp = namespace Sparse;

De::matrix_t * D = De::init( 10, 10 );
Sp::matrix_t * S = Sp::init( 10, 10, 28 );

De::mul_vec( 1.0, D, x, y );
Sp::mul_vec( 1.0, S, x, y );
```



#### **Nested Namespaces**

Namespaces can also be nested and different parts of a namespace can be defined in different modules:

```
namespace LinAlg {
    namespace Dense {
        ...
}
```

```
namespace LinAlg {
    namespace Sparse {
        ...
}
```

```
LinAlg::Dense::matrix_t * D = LinAlg::Dense::init( 10, 10 );
LinAlg::Sparse::matrix_t * S = LinAlg::Sparse::init( 10, 10, 28 );
LinAlg::Dense::mul_vec( 1.0, D, x, y );
LinAlg::Sparse::mul_vec( 1.0, S, x, y );
```



#### **Anonymous Namespaces**

Namespaces can also be defined without a name:

```
namespace {
    void f ()
    {
        ...
    }
}
```

The C++ compiler will then automatically assign a unique, hidden name for such a namespace. This name will be different in different modules.

Functions in an anonymous namespace can be used without specifying their namespace name:

```
namespace {
    void f () { ... }
}
void g () { f(); }
```



### **Anonymous Namespaces**

On the other hand, since the automatically assigned name is unique per module, only functions in the same module as the anonymous namespace can access the functions within:

```
// module 1
namespace {
    void f () { ... }
}

void g ()
{
    f(); // Ok: same module
}
```

Such functions are therefore hidden for other modules and purely local to the corresponding module.



### **Anonymous Namespaces**

#### Remark

If an anonymous namespace is defined in a header file, each module including the header would define a new, local namespace!

### Coding Principle No. 21

Put module local functions into an anonymous namespace.

This approach is different from the previous C-style version using **static** functions and variables and should be preferred.



#### The **std** Namespace

All functions (and classes) of the C++ standard library, e.g. sqrt or strcpy are part of the std namespace. Previous use always assumed a corresponding using command:

```
using namespace std;
const real_t PI = 3.14159265358979323846;
const real_t sqrtPI = sqrt( PI );
cout << sqrtPI << endl;</pre>
```

#### is equivalent to

```
const real_t PI = 3.14159265358979323846;
const real_t sqrtPI = std::sqrt( PI );
std::cout << sqrtPI << std::endl;</pre>
```