## ASSIGNMENTS

TASKI

(a) From the table, we can see that in all the scenarios where KB is time, SI is time.

So,

 $kB = S_1$ 

(b) From the table, we can see that there is afterent one scenario where rot (ICB) is time [KB is False] but not (SI) is false [SI is Time]

So, NOT (KB) / NOT (Si) Took 2 The given scenlence med our aiteria not (An not Bn not cn D) 1 not (AOTAABACANOTD) Convey to CNF De rorges ( not A or not (not B) or not (not c) or ( not (not A) or not B or not E or not (not D)) DIN

(Not A or Bo or C or D) A

(A) or NOT B or NOT C or D)

Which is in CNF.

# Task 3

(i) Convert to How Form

B => A

ADC

DJE

CNE OF

B

Formand Charring

B DA, B

A>C, A

DDE, D

CAEDF, C, E

So KB F EX

(ii) Backwood Choig

Cosside CNE => F

ECF

Conside DDE, Distue

DE, DE

Conson A => C

Consider. 
$$B \Rightarrow A$$
,  $B$  is here
$$\begin{vmatrix} A & B \\ F \end{vmatrix} = \begin{vmatrix} A & A \\ C \end{vmatrix}$$

$$\begin{vmatrix} A & A \\ C \end{vmatrix}$$

Convey to CNF KB 7AVB 7 B V 19 JAVC. 7DVE 7C V 7E V F B RESOLUTION 7CVTE 7DVE TF 7CV7E VF 7CV7E 7CV7D 7C V 7D D 7C TAVC

7 A

7 C

7A 7BVA 73

So KB F X

TASK 4

CONSTANTS:

(a) Ray 1 2020 John - John the person Mary - Mary the person

PREDICATES:

Rains(x) - It raws on X Corce Chk(x,y)-X gre y a check for \$10x How (x) - x Mows lawn.

7B B

(BL)

Rains (May) => CoreChk (John, Mary)

Mon (Mary) (=) CoreChk (John, Mary)

(6)

7 Rains (May)

GreChk (JEhn, Mary)

Mon (Mary)

Symbols

Rans (rlay 1) - R\_1

Rains (38m) - R\_J

Rains (Mary) - R-M

Gate Chk (John Mary) - G. IM)

Crechk (Jan Joh) - a\_J\_J

Cove Chk (Joh, May 1) - G-J-1

auta

 $R_{-}M \Rightarrow G_{-}J_{-}M$   $M_{-}M \Leftrightarrow G_{-}J_{-}M$ 

Pat 5

TR\_1 a\_J\_M M\_M In all the Scenerios where the events

Southerst is forme (RI=F, C\_J\_M=T,
M\_M=T)

the conhect is also true.

So Events + Contract

So Conhact 13 Not Molated.

## Task 5

# PREDICATES

INPI(x) - X is Im PI INP2(x) - X is Im P2 Is Bive (x) - X is Blue Is Reo(x) - X is Red.

#### CONSTANTS

MI, M2, M3, M4, M5, M6 - Marbles.

# INITIAL STATE

ISRED (MI) N ISRED (M2) N ISRED (M3) N ISBLUE (M4) N ISBLUE (M3) N ISBLUE (M6) N INPI (M2) N INPI (M2) N INPI (M3) N INP2 (M6) N INP2 (M6) N INP2 (M6)

#### ACTIONS

# More 12 R(x, y)

PRE: INPI(x) ~ INPI(y) ~ IsRED (x) ~ IsRED(y)

EFF: 7/nP1(x) n 7/nP1(y) n /nP2(x) n /nP2(y)

### HorE 12B (x,4)

PRE: INPI(x) ~ INPI(y) ~ Is BLUE (x) ~ Is BLUE(0)

EFF: 7/NPI(x) A7/NPI(y) A /NP2(x) A/NP2(y)

# Move 21 (x, y)

PRE: INP2(x) n INP2(y) n IsRED(x) n IsBLUE(y)

EFF: 7/NP2(x) n 7/NP2(v) n /NP1(x) n /NP1(y)

GOAL INPI(MA) N INPI(M6) N INPI(M6) N INP2(MI) N INP2(M2) N INP2(M3) COMPLETE PLAN Move 12R(MI, M2) MOVEZI (MI M4) Move 21 (M2, M5) MOVE 12R(MI, M2) MOVE 21 (MIMG) MOVE 12R(M/M3) lask 6 Number of arguments per predicate: [14] Number of constants: 3 Namber of assymments per proliate: [3'34] For all predicates: [31x5 34x5]  $[15 \quad 405]$ Number of possible unique states (delfinal by number of true predicates): [25 2405]

1ASK 7	
EXEC. MONITORING	
No charge	are made to actions.
Davig planni-	my part we treat the though it is deterministic.
CONDITIONAL PLAN	sning
The follows changes	are mode:
More 12 R(x, y)	
	NPI(g) N ISRED(x) a ISRED(y)
EFF! (7/nPI(x) 171	wPi(y) n [NP2(x) n INP2(y))
V (7/NP1(	$NP(y) \wedge [NP2(x) \wedge [NP2(y))$ $\times) \wedge [NP2(x)) \vee (9[NP4(y) \wedge [NP2(y))]$

#### MOVE 12B(x,4)

PRE: INPI(x) N INPI(y) N ISBLUE(x) N ISBLUE(y)

EFT: (TIMPI(x) N TIMPI(W) N IMP2(x) N IMP2(y))

(TIMPI(x) N IMP2(x)) V (TIMPI(y) N IMP2(y))

MOVE 21 (x, y)

PRE: INPL(x) \( \text{INP2(4)} \) \( \text{ISRED(x)} \) \( \text{ISRED(x)} \) \( \text{INP2(4)} \) \( \text{INP2(4)} \) \( \text{INP1(x)} \) \( \text{INP1(y)} \) \( \text{INP2(4)} \) \( \text{INP1(y)} \)