
Correction Partiel - 24 octobre 2016

Exercice 1. Give a basis for null space and the column space of the following matrix

$$\mathbf{A} = \begin{pmatrix} 1 & 2 & 3 & -1 \\ -1 & 1 & 0 & -2 \\ 2 & -3 & -1 & 5 \end{pmatrix}.$$

Correction :

Let $\mathbf{X} = \begin{pmatrix} x \\ y \\ z \\ t \end{pmatrix} \in \text{Ker}(\mathbf{A})$, then one has

$$\begin{aligned} \mathbf{A}\mathbf{X} = 0 &\Leftrightarrow \begin{cases} x + 2y + 3z - t = 0 \\ -x + y - 2t = 0 \\ 2x - 3y - z + 5t = 0 \end{cases} \Leftrightarrow \begin{cases} x + 2y + 3z - t = 0 \\ 3y + 3z - 3t = 0 \\ -7y - 7z + 7t = 0 \end{cases} \Leftrightarrow \begin{cases} x + 2y + 3z - t = 0 \\ y + z - t = 0 \end{cases} \\ &\Leftrightarrow \begin{cases} x = -z - t \\ y = -z + t \end{cases} \end{aligned}$$

Thus the vectors $\begin{pmatrix} -1 \\ -1 \\ 1 \\ 0 \end{pmatrix}$ and $\begin{pmatrix} -1 \\ 1 \\ 0 \\ 1 \end{pmatrix}$ belong to $\text{Ker}(\mathbf{A})$. Moreover they are linearly independent and so they form a basis for $\text{Ker}(\mathbf{A})$.

Now, applying the rank nullity theorem we obtain

$$\dim(\text{Ker}(\mathbf{A})) + \dim(\text{Im}(\mathbf{A})) = 4 \Rightarrow \dim(\text{Im}(\mathbf{A})) = 2.$$

But, we have

$$\mathbf{A} \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} \quad \text{and} \quad \mathbf{A} \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 3 \\ 0 \\ -1 \end{pmatrix},$$

thus the vectors $\begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix}$ and $\begin{pmatrix} 3 \\ 0 \\ -1 \end{pmatrix}$ belong to $\text{Im}(\mathbf{A})$. Moreover they are linearly independent and so they form a basis for $\text{Im}(\mathbf{A})$.

Exercice 2. Find the eigenvalues of the following matrix

$$\mathbf{A} = \begin{pmatrix} 3 & -1 & 1 \\ 0 & 2 & 1 \\ 1 & -1 & 3 \end{pmatrix}.$$

Correction :

Let $\lambda \in \mathbb{R}$, we compute $\det(\mathbf{A} - \lambda \mathbf{I}_3)$, one has

$$\begin{aligned}\det(\mathbf{A} - \lambda \mathbf{I}_3) &= \begin{vmatrix} 3-\lambda & -1 & 1 \\ 0 & 2-\lambda & 1 \\ 1 & -1 & 3-\lambda \end{vmatrix} = (3-\lambda) \begin{vmatrix} 2-\lambda & 1 \\ -1 & 3-\lambda \end{vmatrix} + \begin{vmatrix} -1 & 1 \\ 2-\lambda & 1 \end{vmatrix} \\ &= (3-\lambda)((2-\lambda)(3-\lambda) + 1) + (-1 - (2-\lambda)) = (3-\lambda)(7 - 5\lambda + \lambda^2) + (\lambda - 3) \\ &= (3-\lambda)(6 - 5\lambda + \lambda^2) = -(\lambda - 3)^2(\lambda - 2).\end{aligned}$$

Thus the eigenvalues of \mathbf{A} are $\lambda = 2$ and $\lambda = 3$.

Exercise 3.

1. Project \mathbf{b} onto the column space of \mathbf{A} by solving the system $\mathbf{A}^T \mathbf{A} \hat{\mathbf{x}} = \mathbf{A}^T \mathbf{b}$ and then by computing $\mathbf{p} = \mathbf{A} \hat{\mathbf{x}}$ with

$$\mathbf{A} = \begin{pmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \end{pmatrix} \quad \text{and} \quad \mathbf{b} = \begin{pmatrix} 6 \\ 0 \\ 0 \end{pmatrix}.$$

Correction :

First we compute the matrix product $\mathbf{A}^T \mathbf{A}$, one has

$$\mathbf{A}^T \mathbf{A} = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \end{pmatrix} = \begin{pmatrix} 3 & 3 \\ 3 & 5 \end{pmatrix}$$

and

$$\mathbf{A}^T \mathbf{b} = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \end{pmatrix} \begin{pmatrix} 6 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 6 \\ 0 \end{pmatrix}.$$

Thus we search for $\hat{\mathbf{x}}$ such that

$$\begin{pmatrix} 3 & 3 \\ 3 & 5 \end{pmatrix} \begin{pmatrix} \hat{x}_1 \\ \hat{x}_2 \end{pmatrix} = \begin{pmatrix} 6 \\ 0 \end{pmatrix} \Leftrightarrow \begin{pmatrix} \hat{x}_1 \\ \hat{x}_2 \end{pmatrix} = \frac{1}{15-9} \begin{pmatrix} 5 & -3 \\ -3 & 3 \end{pmatrix} \begin{pmatrix} 6 \\ 0 \end{pmatrix} = \frac{1}{6} \begin{pmatrix} 30 \\ -18 \end{pmatrix} = \begin{pmatrix} 5 \\ -3 \end{pmatrix}.$$

We finally obtain

$$\mathbf{p} = \mathbf{A} \hat{\mathbf{x}} = \begin{pmatrix} 5 \\ 2 \\ -1 \end{pmatrix}.$$

2. Compute the corresponding projection matrix.

Correction :

The projection matrix \mathbf{P} satisfies

$$\begin{aligned}\mathbf{P} &= \mathbf{A}(\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T = \frac{1}{6} \begin{pmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 5 & -3 \\ -3 & 3 \end{pmatrix} \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \end{pmatrix} \\ &= \frac{1}{6} \begin{pmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 5 & 2 & -1 \\ -3 & 0 & 3 \end{pmatrix} = \frac{1}{6} \begin{pmatrix} 5 & 2 & -1 \\ 2 & 2 & 2 \\ -1 & 2 & 5 \end{pmatrix}.\end{aligned}$$

3. What conditions does this matrix have to check ?

Correction :

The matrix \mathbf{P} has to satisfy $\mathbf{P} = \mathbf{P}^T$, $\mathbf{P}^2 = \mathbf{P}$ and $\mathbf{P}\mathbf{b} = \mathbf{p}$.

Exercice 4. We consider the following matrix

$$\mathbf{A} = \begin{pmatrix} 2 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 2 \end{pmatrix}.$$

1. Using the Gram-Schmidt process, write the \mathbf{QR} factorization of the matrix \mathbf{A} .

Correction :

First one has $\mathbf{a}_1 = \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}$ thus $\mathbf{q}_1 = \frac{\mathbf{a}_1}{\|\mathbf{a}_1\|} = \frac{1}{\sqrt{6}}\mathbf{a}_1$.

Then we have $\mathbf{a}_2 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ and so

$$\tilde{\mathbf{q}}_2 = \mathbf{a}_2 - (\mathbf{q}_1^T \mathbf{a}_2) \mathbf{q}_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} - \frac{4}{6} \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} = \frac{1}{3} \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix}.$$

Thus we obtain

$$\mathbf{q}_2 = \frac{\tilde{\mathbf{q}}_2}{\|\tilde{\mathbf{q}}_2\|} = \frac{1}{\sqrt{3}} \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix}.$$

To finish $\mathbf{a}_3 = \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix}$. Then one has

$$\tilde{\mathbf{q}}_3 = \mathbf{a}_3 - (\mathbf{q}_1^T \mathbf{a}_3) \mathbf{q}_1 - (\mathbf{q}_2^T \mathbf{a}_3) \mathbf{q}_2 = \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix} - \frac{5}{6} \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} - \frac{2}{3} \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix}$$

and

$$\mathbf{q}_3 = \frac{\tilde{\mathbf{q}}_3}{\|\tilde{\mathbf{q}}_3\|} = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix}.$$

Thanks to the previous computations

$$\mathbf{Q} = (\mathbf{q}_1 | \mathbf{q}_2 | \mathbf{q}_3) = \begin{pmatrix} \frac{2}{\sqrt{6}} & -\frac{1}{\sqrt{3}} & 0 \\ \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} \end{pmatrix}$$

and

$$\mathbf{R} = \begin{pmatrix} \|\tilde{\mathbf{q}}_1\| & \langle \mathbf{q}_1, \mathbf{a}_2 \rangle & \langle \mathbf{q}_1, \mathbf{a}_3 \rangle \\ 0 & \|\tilde{\mathbf{q}}_2\| & \langle \mathbf{q}_2, \mathbf{a}_3 \rangle \\ 0 & 0 & \|\tilde{\mathbf{q}}_3\| \end{pmatrix} = \begin{pmatrix} \sqrt{6} & \frac{4}{\sqrt{6}} & \frac{5}{\sqrt{6}} \\ 0 & \frac{1}{\sqrt{3}} & \frac{\sqrt{3}}{2} \\ 0 & 0 & \frac{1}{\sqrt{2}} \end{pmatrix}.$$

2. Using this **QR** decomposition, find \mathbf{x} such that

$$\mathbf{Ax} = \begin{pmatrix} -5 \\ -1 \\ 1 \end{pmatrix}.$$

Correction :

We want to solve the linear system $\mathbf{Ax} = \mathbf{b}$ with $\mathbf{A} = \mathbf{QR}$, then

$$\begin{aligned} \mathbf{Ax} = \mathbf{b} &\Leftrightarrow \mathbf{QRx} = \mathbf{b} \Leftrightarrow \mathbf{Rx} = \mathbf{Q}^T \mathbf{b} \\ &\Leftrightarrow \begin{pmatrix} \sqrt{6} & \frac{4}{\sqrt{6}} & \frac{5}{\sqrt{6}} \\ 0 & \frac{1}{\sqrt{3}} & \frac{2}{\sqrt{3}} \\ 0 & 0 & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} \frac{2}{\sqrt{6}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{6}} \\ -\frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \\ 0 & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} -5 \\ -1 \\ 1 \end{pmatrix} \\ &\Leftrightarrow \begin{cases} \sqrt{6}x_1 + \frac{4}{\sqrt{6}}x_2 + \frac{5}{\sqrt{6}}x_3 = -\frac{10}{\sqrt{6}} \\ \frac{1}{\sqrt{3}}x_2 + \frac{2}{\sqrt{3}}x_3 = \frac{5}{\sqrt{3}} \\ \frac{1}{\sqrt{2}}x_3 = \frac{2}{\sqrt{2}} \end{cases} \Leftrightarrow \begin{cases} x_1 = -4 \\ x_2 = 1 \\ x_3 = 2 \end{cases} \end{aligned}$$