

# Intersection of Ellipsoidal Balls and Applications to Geometric Persistent Homology

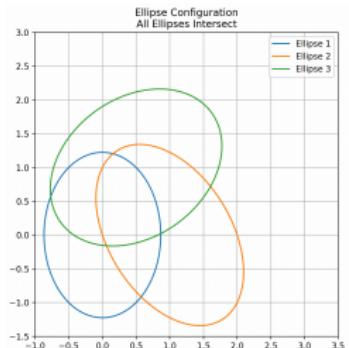
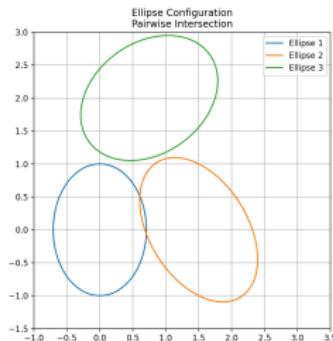
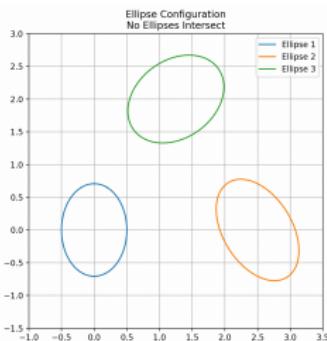
Sean Hill

Joint work with Barbara Giunti and Felix Ye

October 11, 2025

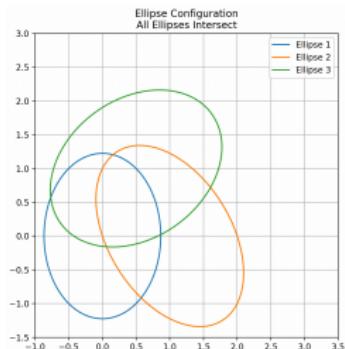
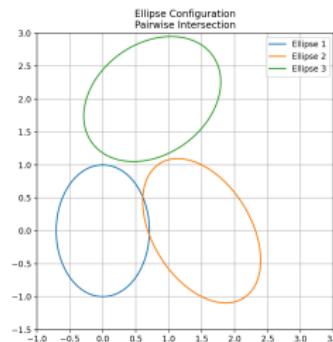
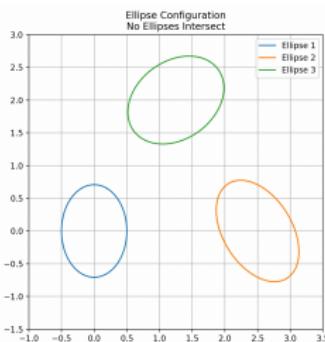
# Overview

- **Goal:** Characterize when a collection of ellipsoidal balls in  $\mathbb{R}^D$  intersect.



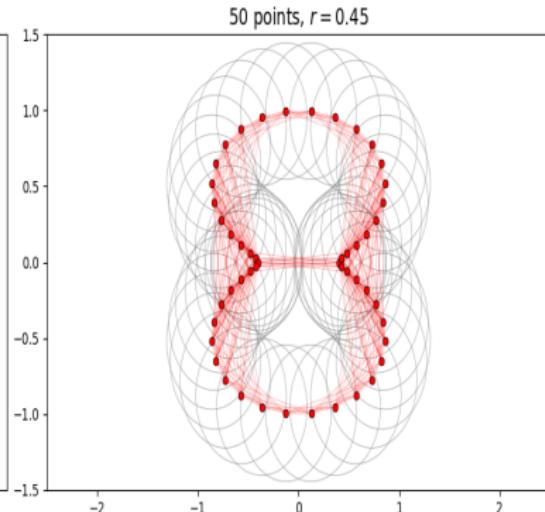
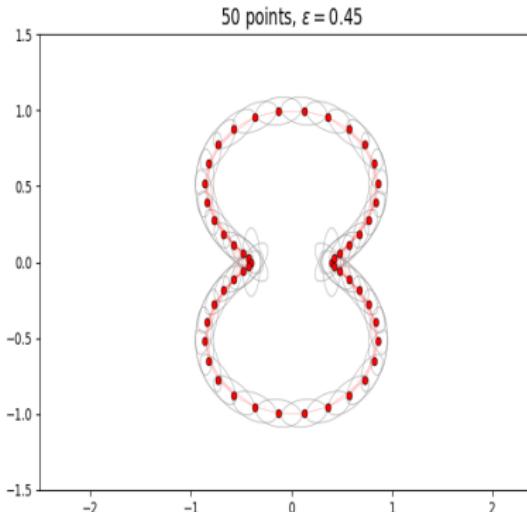
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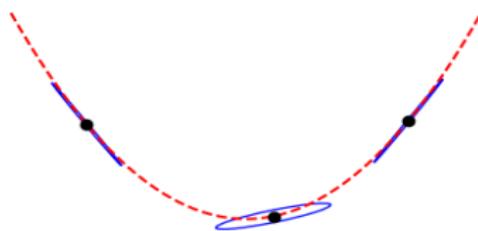
- ▶ **Motivation:** In manifold learning and persistent homology, replacing Euclidean balls with ellipsoidal ones provides a more sensitive description of local geometry.

# Tangent-Normal ellipsoids respect geometry

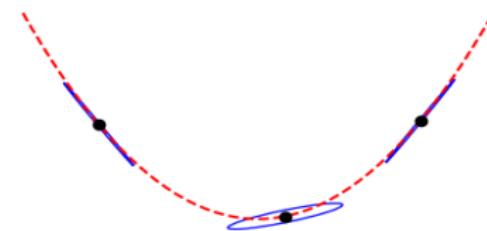


# Ellipsoidal-VR complex can create spurious features

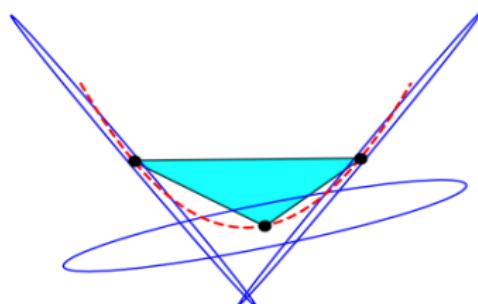
VR Complex ( $\varepsilon=0.1$ )



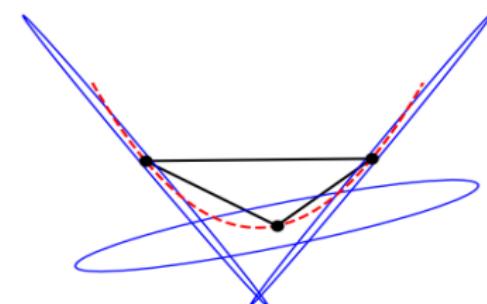
Čech Complex ( $\varepsilon=0.1$ )



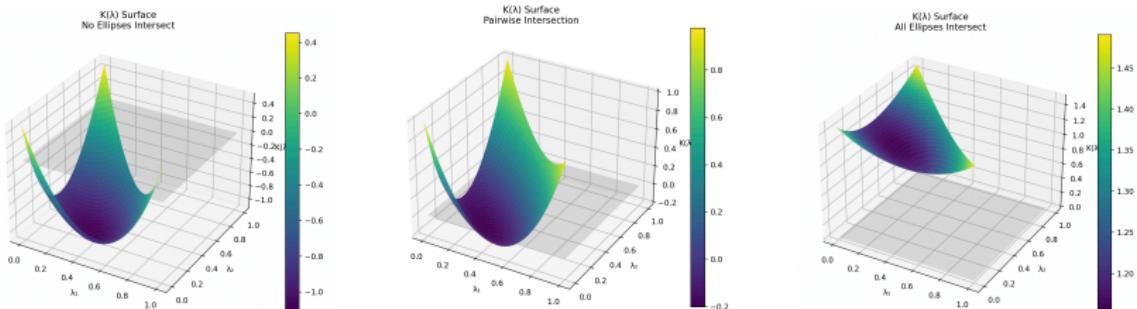
VR Complex ( $\varepsilon=0.5$ )



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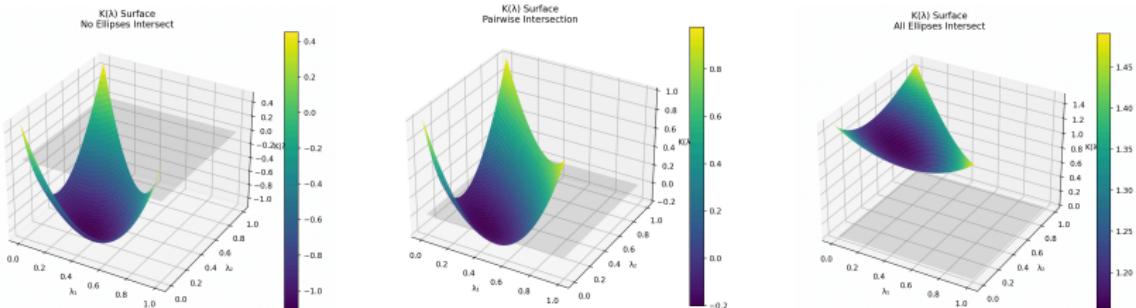


# Summary of result



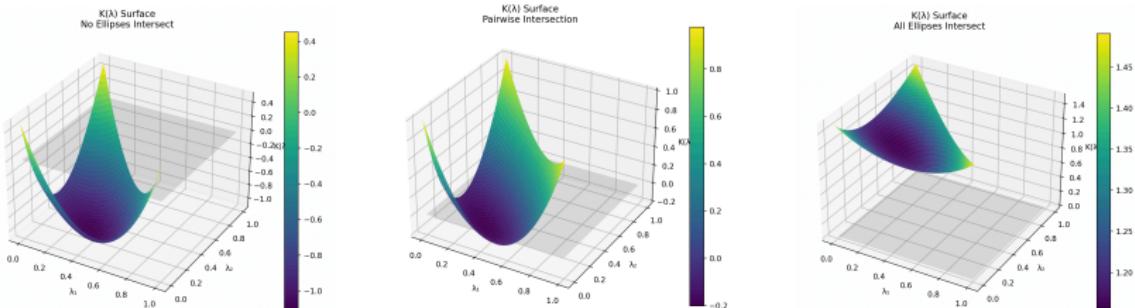
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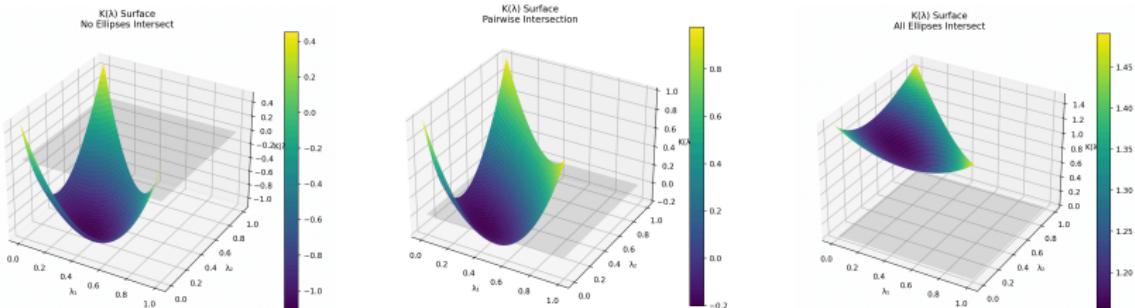
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- ▶ Results are known for  $k = 2$  ellipses. See Gilitschenski [1].
- ▶ We generalize this for  $k > 2$  and relate it to a LP-type problem for  $\epsilon^*$ .

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- ▶ Checking the intersection criterion once allows us to also compute the optimal radius  $\epsilon^* = f(S)$  (via KKT conditions).
- ▶ We show  $f(S)$  is a LP-type problem function.

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- ▶ Kališnik et al [3]: Ellipsoidal Rips filtrations better capture anisotropy and curvature, improving signal in bottlenecks.
- ▶ Challenge: Pairwise intersection checks can create spurious topological features (e.g., holes from pairwise intersecting ellipses).

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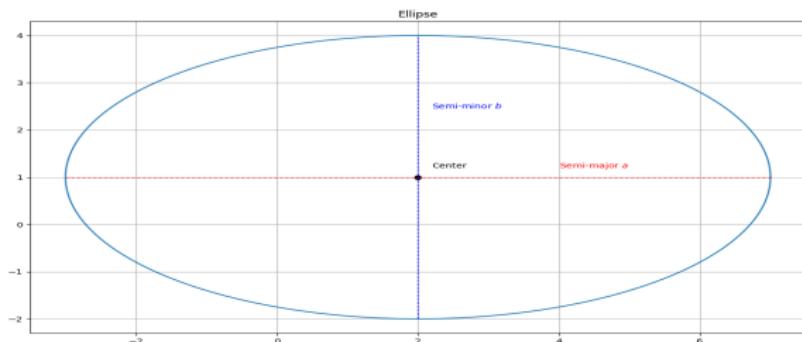
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### Counterexample (H., Giunti)

*Let  $S = \{x_1, x_2\}$  with any two distinct ellipsoidal balls centered at them that do not intersect. Then the affine hull of  $S$  is a line and the MVEEB is ill-posed: flatten an enclosing ellipsoidal ball in directions orthogonal to the line; its volume goes to zero.*

## Review: ellipses via high school geometry



Recall that an ellipse centered at the origin in the plane is the set of all points  $(x, y)$  such that

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1.$$

A point  $(x, y)$  lies in the interior of the ellipse if

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} < 1.$$

## Ellipses via linear algebra

The above equation can be written using linear algebra:

$$\begin{bmatrix} x \\ y \end{bmatrix} \begin{bmatrix} \frac{1}{a^2} & 0 \\ 0 & \frac{1}{b^2} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = x^2/a^2 + y^2/b^2.$$

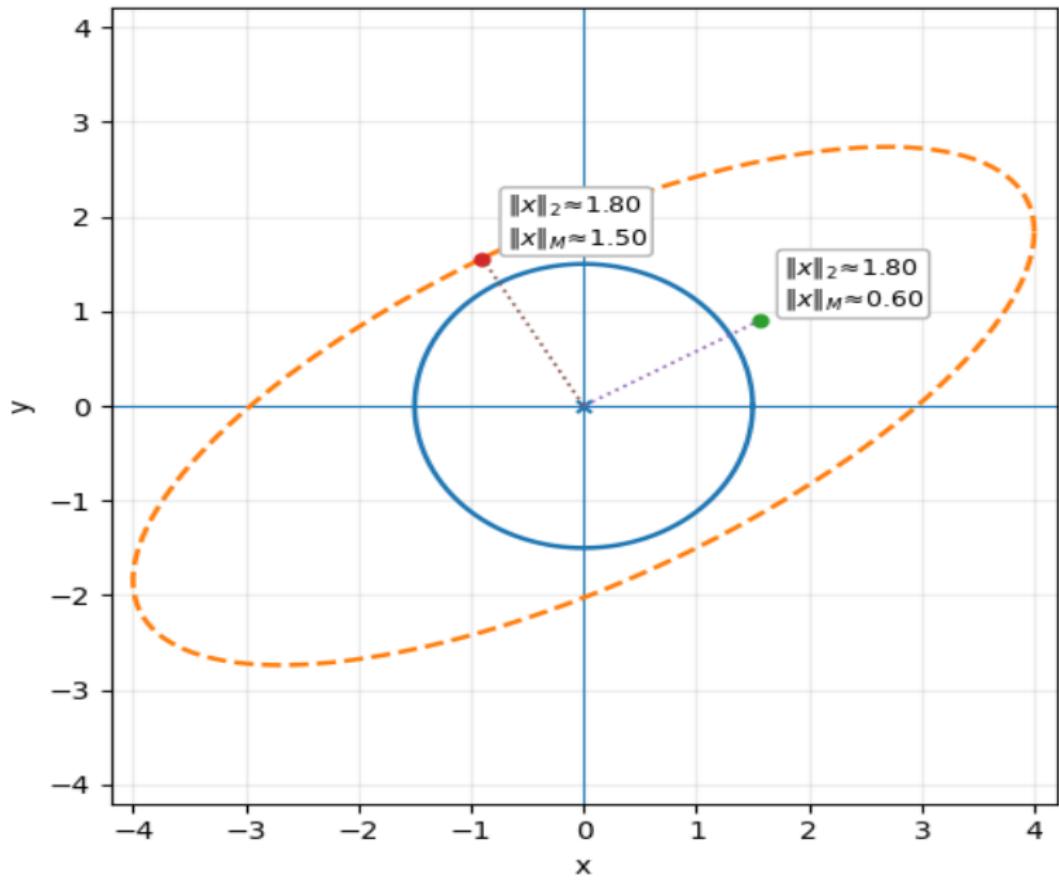
This generalizes ellipses to any dimension, axis and center  $\vec{x}$  using the Mahalanobis distance

$$\|\vec{y} - \vec{x}\|_{A(\vec{x})^{-1}}^2 := (\vec{y} - \vec{x})^T A(\vec{x})^{-1} (\vec{y} - \vec{x})$$

where  $A$  is a PD matrix, i.e. the above expression is always  $> 0$  for  $\vec{y} \neq \vec{x}$ .

# Mahalanobis distance

Euclidean distance (solid) vs Mahalanobis distance (dashed)



## Ellipsoidal balls

Let  $A_i$  be a real PD symmetric matrix and  $c_i \in \mathbb{R}^d$ . Define, for  $\epsilon \geq 0$ ,

$$E_i(\epsilon) := \{x \in \mathbb{R}^d : (x - c_i)^\top A_i^{-1} (x - c_i) \leq \epsilon^2\},$$

the ellipsoidal closed ball with orientation and scale determined by the matrix  $A_i$  centered at  $c_i$ . We emphasize that the ellipses are **not** homogeneous in orientation and scale.

## The optimal radius

Let  $I_k = \{1, 2, \dots, k\}$  and define, for any  $S \subset I_k$ ,

$$f(S) = \inf\{\epsilon \geq 0 : \cap_{i \in S} E_i(\epsilon) \neq \emptyset\}.$$

Thus,  $f(S)$  is the first radius at which the ellipsoidal balls at  $x_i$  intersect for the subset of indices  $i \in S$ .

## Criterion for intersection (generalization of Gilitschenski [1])

Theorem (H., Giunti)

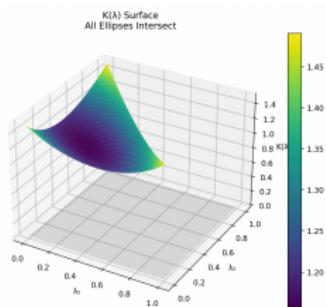
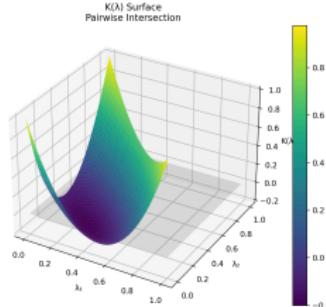
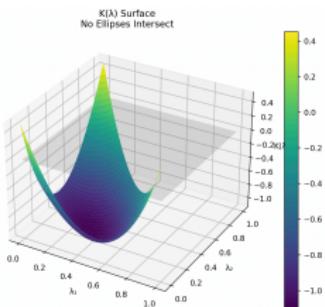
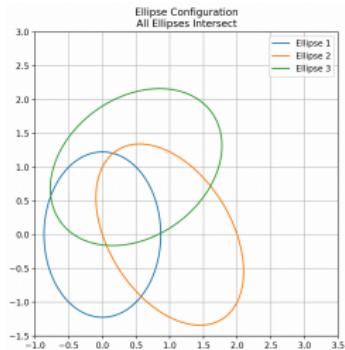
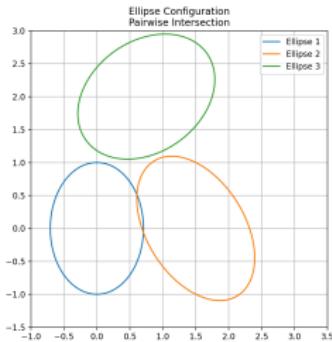
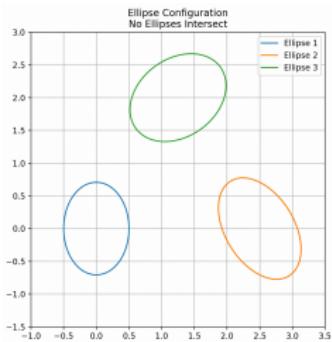
$$\cap_{i \in S} E_i(\epsilon) \neq \emptyset \iff \min_{\lambda \in \Delta^{|S|}} K(\lambda) > 0$$

where  $K(\lambda) = \epsilon^2 - C(\lambda)$ , with

$$C(\lambda) = \sum_{i \in S} \lambda_i (c_i - m(\lambda))^T A_i^{-1} (c_i - m(\lambda))$$

and  $m(\lambda)$  is a precision-weighted centroid of the  $x_i$ .

# Visualization of criterion



## Computing the optimal radius

Theorem (H., Giunti)

Let  $\lambda^*$  minimize  $K(\lambda)$  on the probability simplex. Then the optimal radius  $\epsilon^* = f(S)$  is given by

$$f(S) = \max_{1 \leq i \leq |S|} \|m(\lambda^*) - x_i\|_{A_i^{-1}}.$$

Further, the distance in the maximum is constant for  $i \in S$  such that  $\lambda_i^* > 0$ .

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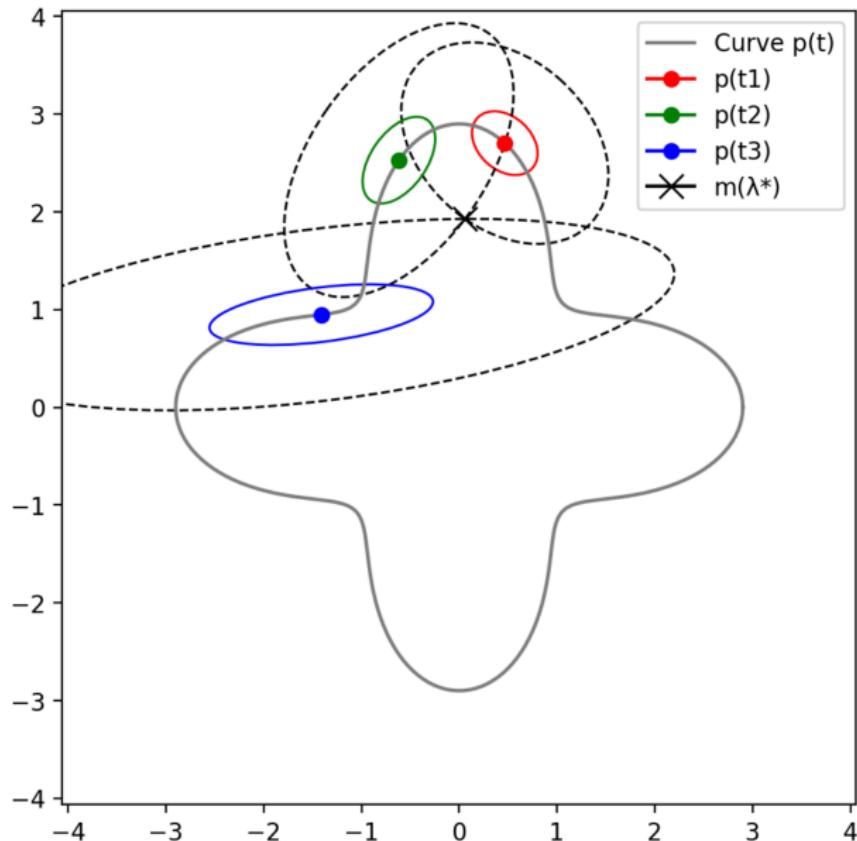
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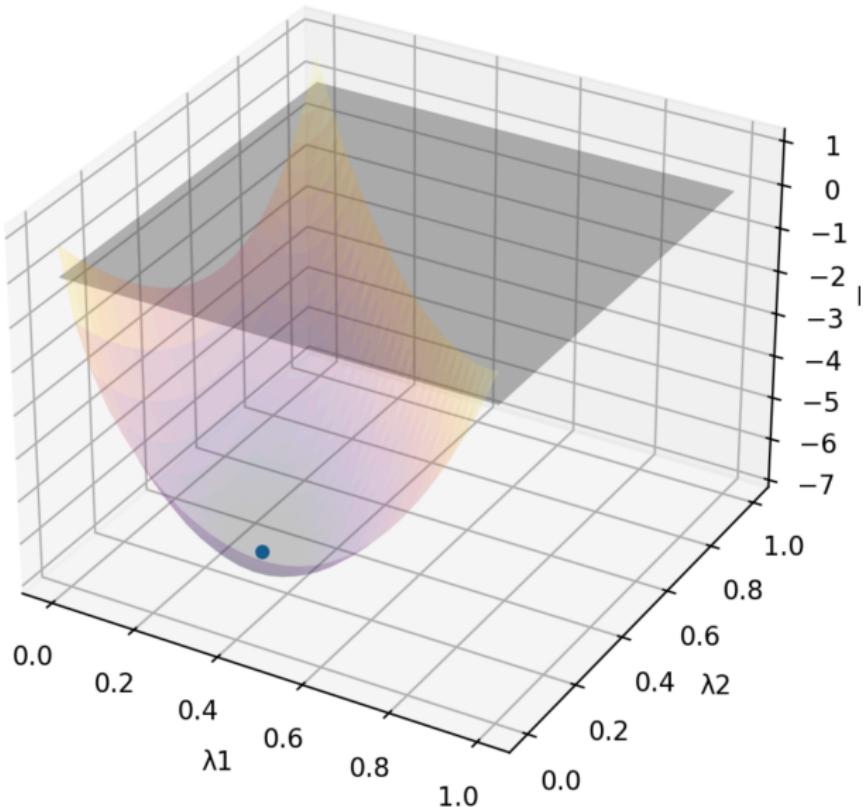
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- ▶ If  $\lambda_i^* = 0$  then  $m(\lambda^*)$  lies in the interior of  $E_i(\epsilon^*)$ .
- ▶ Otherwise if all  $\lambda_i^* > 0$  then  $\cap_i E_i(\epsilon^*) = \{m(\lambda^*)\}$ .

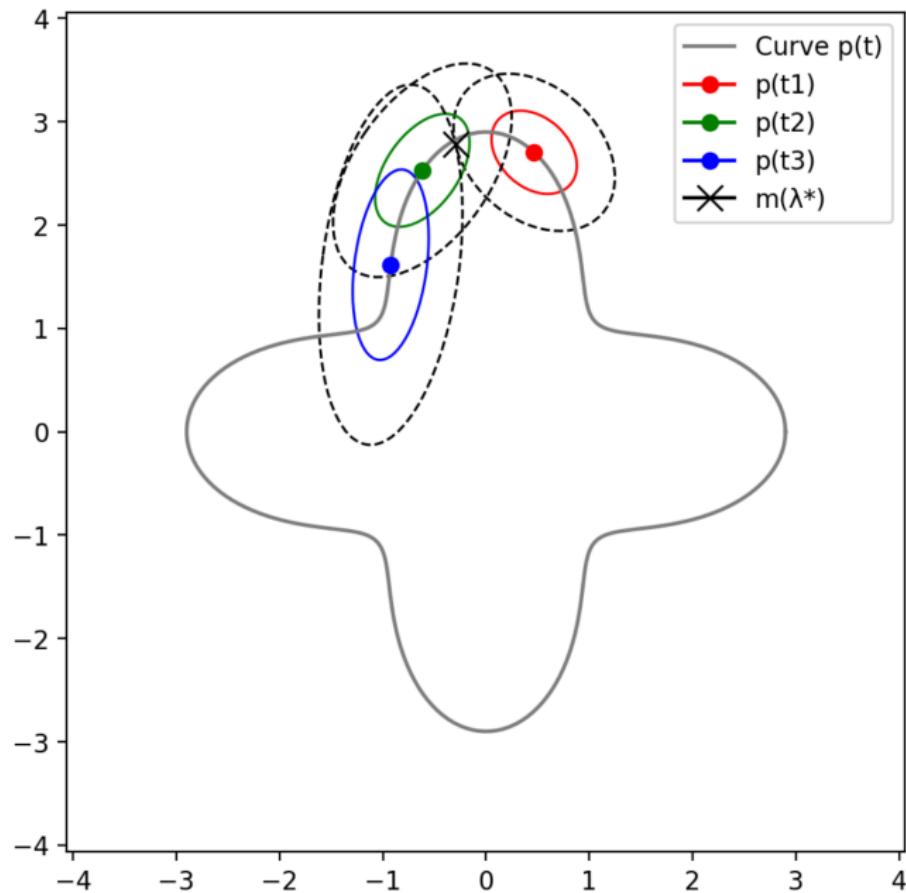
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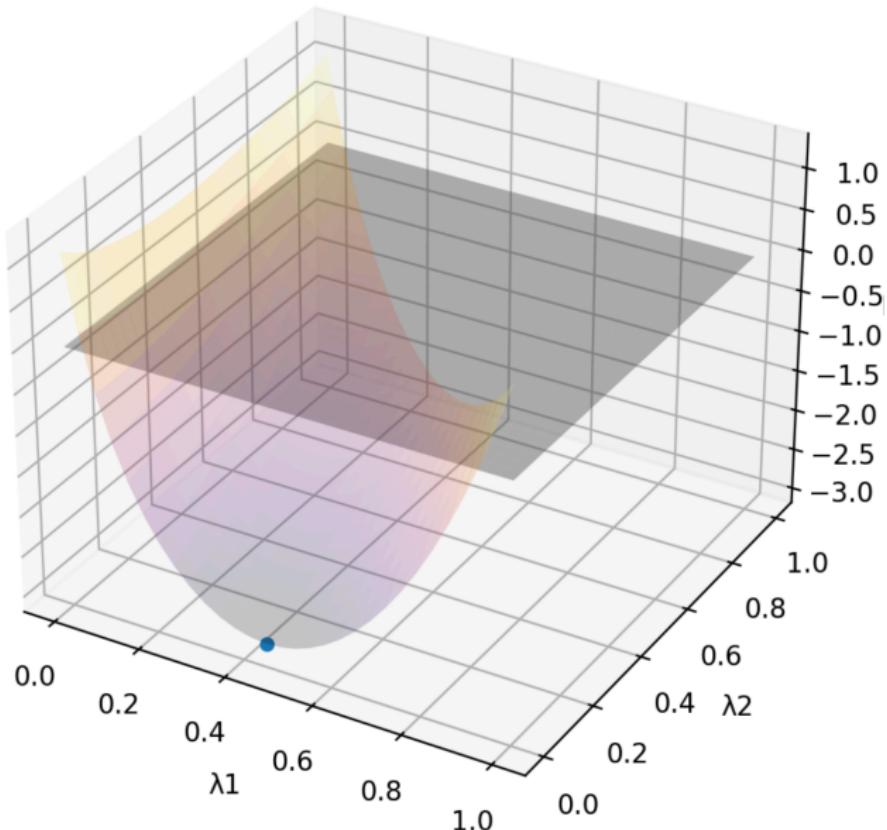
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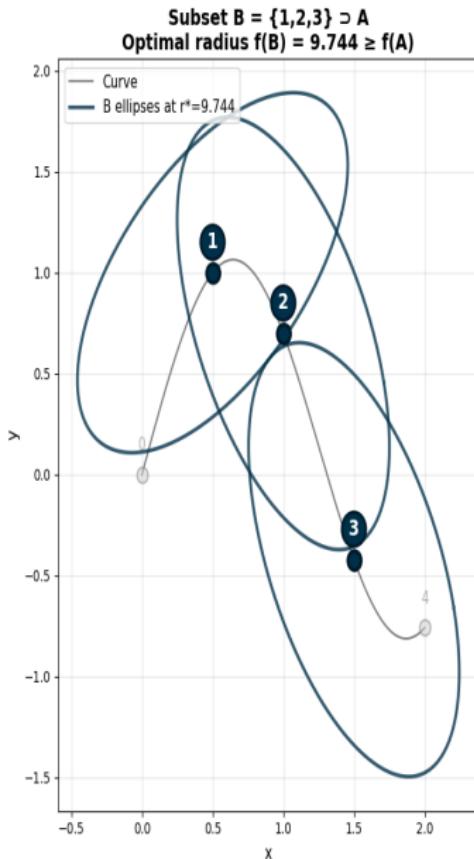
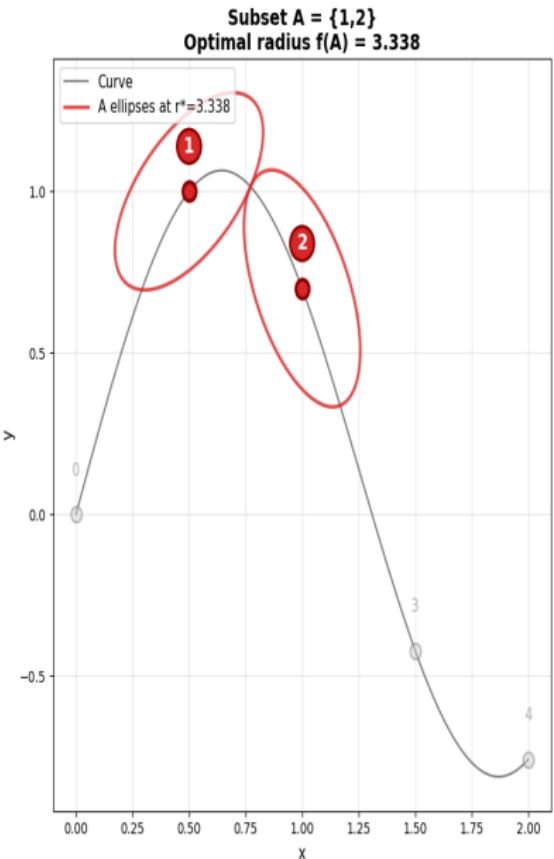
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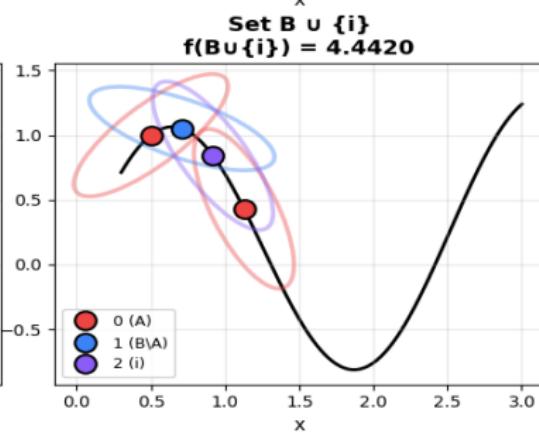
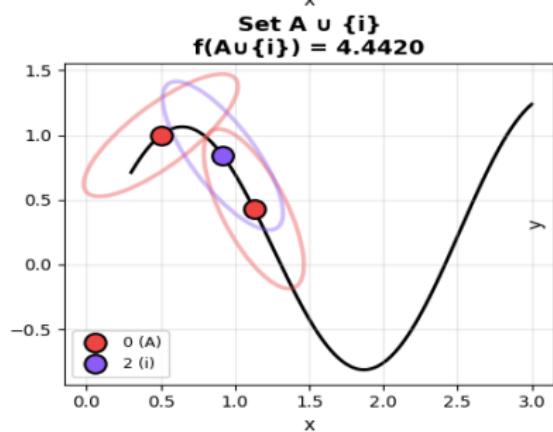
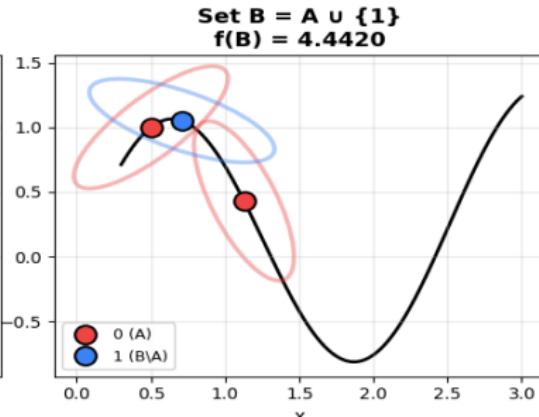
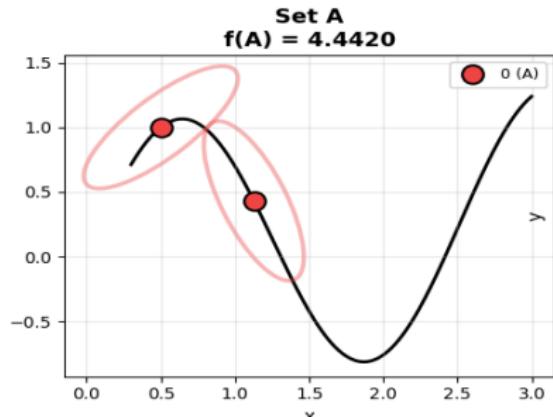
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2. *Locality: Suppose  $A \subset B \subset I_k$  and  $i \in I_k$ . If  $f(A) = f(B) = f(A \cup \{i\})$  then  $f(B) = f(B \cup \{i\})$ .*

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## Application of LP-type algorithms to our problem

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- ▶ LP-type algorithms help us compute  $f(S)$  from "basis" subsets  $B \subset S$  in a way that minimizes the number of evaluations of  $f(\cdot)$ .
- ▶ Plan for the future: study these algorithms and implement an efficient algorithm for building ellipsoidal Čech complexes.

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- ▶ For PH, ellipsoids respect tangent/normal anisotropy and curb spurious features that plague Euclidean-ball VR/Čech at comparable radii.

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## References I

- [1] Igor Gilitschenski and Uwe D. Hanebeck. “A robust computational test for overlap of two arbitrary-dimensional ellipsoids in fault-detection of Kalman filters”. In: *2012 15th International Conference on Information Fusion*. 2012, pp. 396–401.
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