### BLAS AND LAPACK

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# Linear Algebra in Computational Chemistry

 $\mathbf{AV} = \mathbf{\Lambda V}$ 

\* Eigenvalue Problems

\* The Schrödinger equation

$$\hat{H}\Psi = E\Psi$$

- \* Configuration interaction (Hamiltonian matrix)
- \* Normal mode analysis (Hessian matrix)
- \* Moments of inertia (Inertia tensor)

# Linear Algebra in Computational Chemistry

Ax = b

- \* Linear Equation Systems
  - \* Orbital response equations (CPHF)
  - \* Hessian matrix inversion
  - \* Geometry step (potential-energy-surface scanning)

# Linear Algebra in Computational Chemistry

AB = C

- \* Matrix-Matrix Multiplication
  - \* Algebraic (basis-set) problems cast as matrix problems
  - \* Coupled cluster theory (many-body methods)
  - \* Self-consistent field theory (Roothaan's algorithm)

#### BLAS

- \* Basic Linear Algebra Subprograms
  - **\*** BLAS1:
    - \* vector norms
    - \* dot products
    - \* vector scaling
    - \* addition of a scalar multiple of one vector to another (AXPY):

$$\mathbf{y} = \alpha \mathbf{x} + \mathbf{y}$$

## BLAS

- \* Basic Linear Algebra Subprograms
  - **\*** BLAS2:
    - \* matrix-vector operations:

$$\mathbf{y} = \alpha \mathbf{A} \mathbf{x} + \beta \mathbf{y}$$

#### BLAS

- \* Basic Linear Algebra Subprograms
  - **\*** BLAS3:
    - \* matrix-matrix operations:

$$\mathbf{C} = \alpha \mathbf{A} \mathbf{B} + \beta \mathbf{C}$$

**\*** GEMM = GEneral Matrix Multiply:

#### LAPACK

- \* Linear Algebra PACKage for solving:
  - \* Systems of linear equations:

$$\mathbf{A}\mathbf{x} = \mathbf{b}$$

\* Singular value problems;

$$\mathbf{A} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}$$

\* Eigenvalue problems:

$$\mathbf{AV} = \mathbf{\Lambda V}$$

## **QR** Algorithm

#### $\mathbf{AV} = \mathbf{\Lambda V}$

QR Decomposition: A square matrix may be factored into a product of an orthogonal matrix and an upper-triangular matrix:

$$\mathbf{A} = \mathbf{Q}\mathbf{R}$$
 $\mathbf{Q}^T\mathbf{Q} = \mathbf{1}$ 

$$\mathbf{A}_0 \equiv \mathbf{A} = \mathbf{Q}_0 \mathbf{R}_0$$

$$\mathbf{A}_1 \equiv \mathbf{R}_0 \mathbf{Q}_0 = \mathbf{Q}_0^T \mathbf{Q}_0 \mathbf{R}_0 \mathbf{Q}_0 = \mathbf{Q}_0^T \mathbf{A}_0 \mathbf{Q}_0 = \mathbf{Q}_0^{-1} \mathbf{A} \mathbf{Q}_0$$

$$\mathbf{A}_{k+1} \equiv \mathbf{R}_k \mathbf{Q}_k = \mathbf{Q}_k^T \mathbf{Q}_k \mathbf{R}_k \mathbf{Q}_k = \mathbf{Q}_k^T \mathbf{A}_k \mathbf{Q}_k = \mathbf{Q}_k^{-1} \mathbf{A}_k \mathbf{Q}_k$$

## Naming Conventions

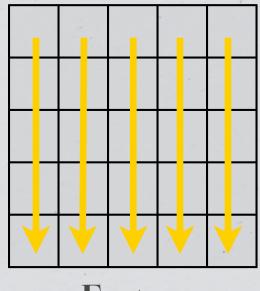
- \* Precision:
  - \* S = single precision real (float)
  - \* D = double-precision real (double)
  - \* C = single-precision complex
  - \* Z = double-precision complex
- \* Matrix type: GE = general; SY = symmetric
- \* Drivers: SV = solve; EV = eigenvalues; SVD = duh

## Library Interface: DGEMM

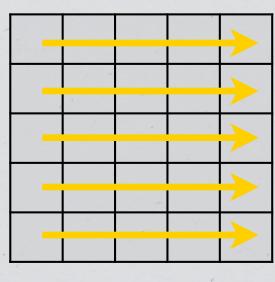
- \* C = alpha \* A \* B + beta \* C
  - \* TRANSA = 'n' (normal) or 't' (transpose)
  - \* TRANSA = 'n' (normal) or 't' (transpose)
  - \* M = rows of matrix C and of matrix A or A-transpose
  - \* N = columns of matrix C and of matrix B or B-transpose
  - \* K = columns of A/A-transpose and rows of B/B-transpose
  - \* ALPHA = (double) scalar
  - A = (double) array (or double \* in C/C++)
  - \* LDA = row-dim. (Fortran) or col.-dim. (C/C++) of matrix A
  - \* B = (double) array (or double \* in C/C++)
  - $\star$  LDB = row-dim. (Fortran) or col.-dim. (C/C++) of matrix B
  - \* BETA = (double) scalar
  - $\star$  C = (double) array (or double \* in C/C++)
  - $\star$  LDC = row-dim. (Fortran) or col.-dim. (C/C++) of matrix C.

#### Fortran vs. C/C++

- \* The ordering of the elements in memory of a matrix is different between Fortran and C/C++:
  - \* In Fortran: consecutive elements follow the columns
  - \* In C/C++: consecutive elements follow the rows



Fortran



C/C++

#### Fortran vs. C/C++

\* Given that the standard BLAS and LAPACK interfaces are defined to be Fortran77/90, some adjustments by C/C++ programs are necessary to call the functions correctly.

$$\mathbf{C} = \mathbf{A}\mathbf{B}$$

$$\mathbf{C}^T = (\mathbf{A}\mathbf{B})^T = \mathbf{B}^T \mathbf{A}^T$$

\* Thus, when calling DGEMM() from C/C++, we reverse the ordering of the matrices, but keep the same 'n' and 't' arguments.

## Library Interface: DSYEV

- $A \cdot V = W \cdot V$ 
  - \* JOBZ = 'n' (eigenvalues only) or 'v' (also eigenvectors)
  - \* UPLO = '1' (lower-triangle) or 'u' (upper-triangle) (not important for full matrix)
  - \* N = dimension of A
  - \* A = (double) array (or double \* in C/C++) containing the matrix. This is replaced by the eigenvectors on exit.
  - $\star$  LDA = row-dim. (Fortran) or col.-dim. (C/C++) of matrix A
  - \* W = (double) array (or double \* in C/C++) containing the eigenvalues in ascending order on exit.
  - \* WORK = (double) array (or double \* in C/C++) containing memory for temporary use by the function.
  - \* LWORK = (int) length of WORK.
  - \* INFO = 0 (if successful) on exit. (Other values indicate incorrect arguments or lack of convergence).

## Optimized BLAS/LAPACK

Maximum optimization of BLAS/LAPACK is vital for all computational chemistry software, and many implementations exist:

- \* Netlib: The original source of the code. Should never be used for production-level computations. (free)
- \* Intel Math Kernel Library (MKL): Hand optimized using evil and ancient magic for Intel processors. (\$\$)
- \* IBM Engineering and Scientific Subroutine Library (ESSL): Optimized for PowerPC architectures. (\$\$)
- \* Goto BLAS: Hand-optimized in assembler by Kazushige Goto. Astonishingly fast for Intel Nehalem and AMD Opteron. (BSD)
- \* Automatically Tuned Linear Algebra Subroutines (ATLAS): Self-tuning at compile time for a given architecture. (BSD)