

# 92586 Computational Linguistics

## Lesson 17. Recurrent Neural Networks

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## Previously

► CNNs for text

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Chapter 8 of Lane et al. (2019)

**Introduction**

## Introduction

### CNNs

- ▶ Good for analysing *full* texts (~sentences)
- ▶ Words tending to appear close to each other are spotted and play a joint role
- ▶ Longer relationships —farther than  $[3, 4]$  words are ignored

### What is missing?

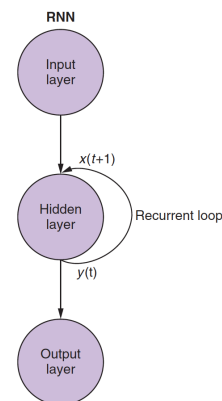
- ▶ Keeping track of what happened long ago
- ▶ Memory
- ▶ Language is **not an image** —no snapshots
- ▶ Language is a **sequence**; both text and speech

### Keeping the past in mind

## Remembering the Past

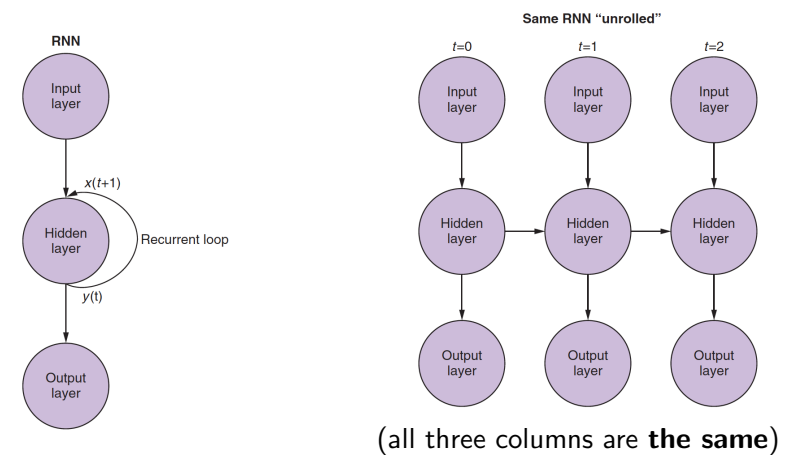
$w_0 w_1 w_2 w_3 \dots w_{t-1} w_t w_{t+1}$

- ▶ To understand a text at time  $t$ , we need to keep in mind what happened at time  $t - k$
- ▶ Recurrent neural nets (RRN) come into play
- ▶ RNNs combine what happened **before** and what is happening **now**



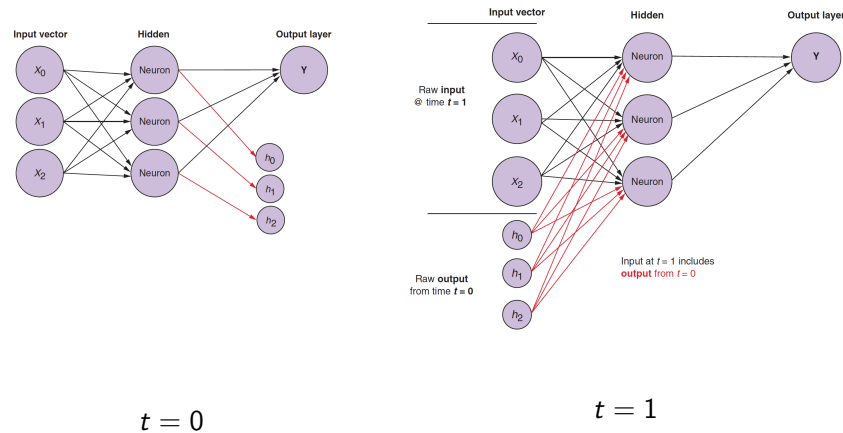
(Lane et al., 2019, p. 250)

## Full feed-forward networks that consider their own output



(Lane et al., 2019, p. 252)

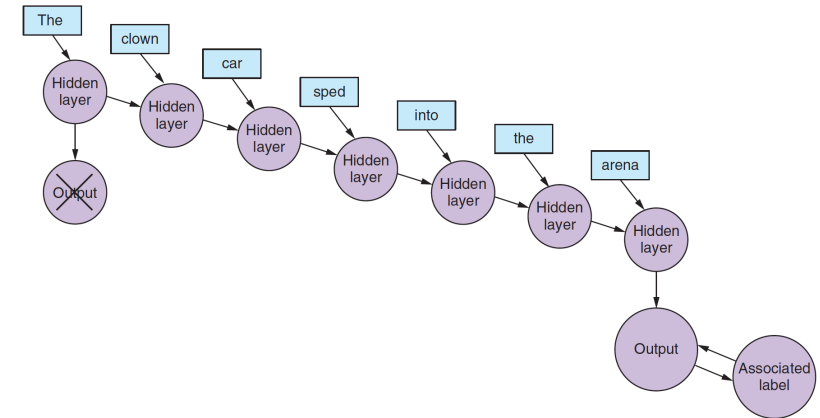
## Zooming into the unrolled RNN: $t$ and $t + 1$



- The red arrows are just *standard* connections, with weights
- Now we can feed the text, **one word at a time**

(Lane et al., 2019, p. 252–253)

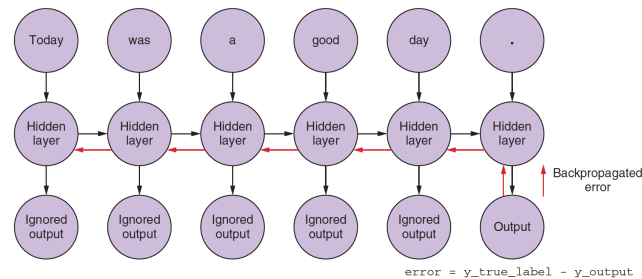
## “Multiple inputs, one output”



- No more length constraints (although we have to be reasonable)
- No more a bunch of snapshots; there is a sense of time

(Lane et al., 2019, p. 254)

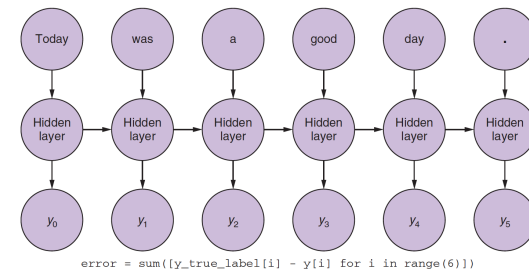
## Backpropagation through Time: the “Vanilla” Way



- All intermediate outputs are ignored; the loss is computed at the end
- The same chain rule is applied to do backpropagation; but this time it heads to “the past”
- The weight corrections are calculated for each  $t$
- The combined updates are applied **only** until reaching  $t = 0$

(Lane et al., 2019, p. 256)

## Backpropagation through Time: the Better Way



- We compute the loss combining all intermediate outputs
- The weight corrections are still additive: the update is applied until
  1. computing all errors and
  2. reaching back to the weight adjustments in  $t = 0$

Let us see

(Lane et al., 2019, p. 258)

## RNNs in Keras

## RNN in Keras: what we have so far

We have setup a simple recurrent neural network

- ▶ The input sequences have fixed length: 400 tokens (each 300D)
- ▶ Our recurrent layer contains 50 neurons
- ▶ The output will be  $400 \times 50$ :
  - ▶ 400 elements
  - ▶ one 50D vector each

`return_sequences=True`

True return the network value at each  $t$ : 400 50D vectors

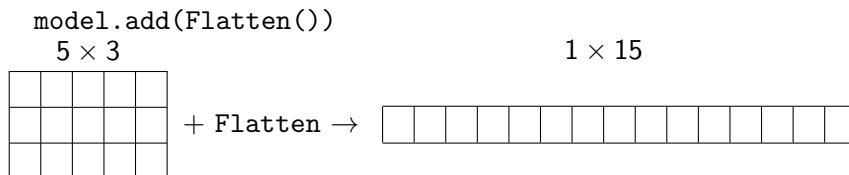
False return a single 50D vector (default)

**True** → **this is why we are padding**


 Let us see

## RNN in Keras: further details

- ▶ A Dense layer expects a *flat* vector



- ▶ In our case:  $400 \times 50 \rightarrow 1 \times 20,000$

 Let us see

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Example derived from <https://stackoverflow.com/questions/43237124/role-of-flatten-in-keras>

## Some parameters are “free”

`embedding_dims` comes from the embedding space; hard to change, but possible: other embeddings, 1-hot

`num_neurons` kind of arbitrary; can be changed

`maxlen` kind of arbitrary; can be changed (or neglected)

`batch_size` bigger → faster (higher local minimum risk)


`epochs` trivial to increase (don't start from scratch each time)

 Let us see

**Important:** unless you have access to HPC, don't go *bananas* when exploring parameters (and perhaps even in that case)

Try some sensitive configurations and keep track of all the settings and outputs<sup>1</sup>

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<sup>1</sup>See, for instance, Fericola et al. (2020) .

## References

Fernicola, F., S. Zhang, F. Garcea, P. Bonora, and  
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