

# 91258 Natural Language Processing

## Lesson 11. “More than One” Neuron

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## Previously

- ▶ The perceptron
- ▶ Intro to neural networks

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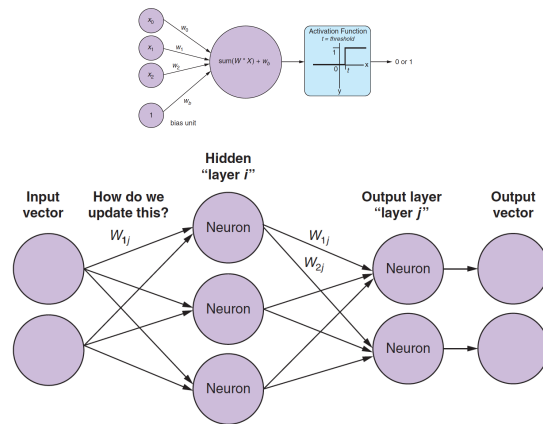
Some Guidelines

Chapter 5 of Lane et al. (2019)

**Backpropagation (brief)**

## Weight Updating

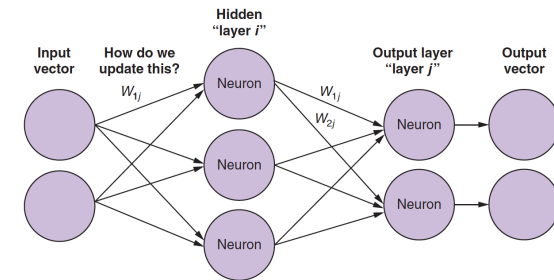
**Learning** in a “simple” perceptron<sup>1</sup> vs a fully-connected network



(Lane et al., 2019, p. 158, 168)

<sup>1</sup>Remember: aka linear regression

## Backpropagation (of the errors)



- The error is computed on the output vector
- How much error did  $W_{1i}$  “contribute”?<sup>2</sup>
- “Path”:  $W_{1i} \rightarrow [W_{1j}, W_{2j}] \rightarrow output$

<sup>2</sup>Notice that the first  $W_{1j}$  should be  $W_{1i}$

## Backpropagation (of the errors)

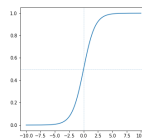
A better activation function

**Step function:**  $f(\vec{x}) = \begin{cases} 1 & \text{if } \sum_{i=0}^n x_i w_i > threshold \\ 0 & \text{otherwise} \end{cases}$

**Sigmoid function:** non-linear<sup>3</sup> and continuously differentiable

$$S(x) = \frac{1}{1 + e^{-x}} \quad (1)$$

Let us see



Non-linear  $\rightarrow$  model non-linear relationships

Continuously differentiable  $\rightarrow$  partial derivatives wrt various variables to update the weights

<sup>3</sup>The change of the output is not proportional to the change of the input.

## Backpropagation

Differentiating to adjust

**Squared error**<sup>4</sup>

$$SE = (y - f(x))^2 \quad (2)$$

**Mean squared error**

$$MSE = \frac{1}{n} \sum_{i=1}^n (y - f(x))^2 \quad (3)$$

**Calculus chain rule**

$$f(g(x))' = F'(x) = f'(g(x)) g'(x) \quad (4)$$

With (4) we can find the derivative of the actfunc  $\forall$  unit wrt its input.

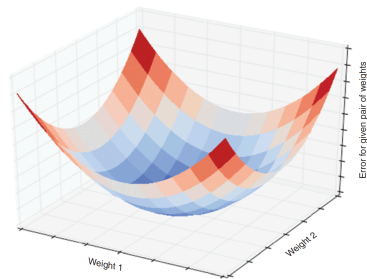
**Plain words:** find the contribution of a weight to the error and adjust it!

(no further math)

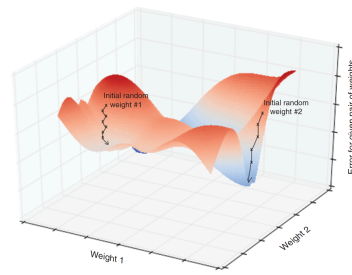
<sup>4</sup>In (Lane et al., 2019, p. 171) they say this is MSE; but there is no mean

## Backpropagation (of the errors)

~Gradient descent: minimising the error



Convex error curve



Non-convex error curve

(Lane et al., 2019, p. 173–174)

## Addressing Local minima

### Batch learning

- ▶ Aggregate the error for the batch
- ▶ Update the weight at the end
- ▶ → hard to find global minimum

### Stochastic gradient descent

- ▶ Look at the error for each single instance
- ▶ Update the weights right away
- ▶ → more likely to make it to the global minimum

### Mini-batch

- ▶ Much smaller batch, combining the best of the two worlds
- ▶ → Fast as batch, resilient as stochastic gradient descent

**Important parameter:** learning rate  $\alpha$

A parameter to define at what extent should we “correct” the error

**Keras**

## Some Popular Libraries

There are many high- and low-level libraries in multiple languages

- ▶ **PyTorch**  
Community-driven; <https://pytorch.org/>
- ▶ **Theano**
- ▶ **TensorFlow**  
Google Brain; <https://www.tensorflow.org/>
- ▶ **Others**

We will use **Keras**; <https://keras.io/>

## What is Keras

- ▶ High-level wrapper with an accessible API for Python
- ▶ Gives access to three alternative backends
  - ▶ TensorFlow
  - ▶ CNTK (MS)

## Keras

Logical exclusive OR (XOR) in Keras

input		output
0	0	0
0	1	1
1	0	1
1	1	0

1	●	●
0	●	●
	0	1

📖 Let us see

### First dense layer

- ▶ 2 inputs, 10 units
- ▶ 30 parameters
- ▶  $2 \times 10 \rightarrow 20$
- ▶ But we also have the bias! (10 more weights)

Now we can compile the model

📖 Let us see

### Second dense layer

- ▶ 10 inputs, 1 unit
- ▶ 11 parameters

## Some Guidelines

## Design Decisions

### Activation functions

Sigmoid

ReLU Rectified linear unit (and variations)

tanh Hyperbolic tangent

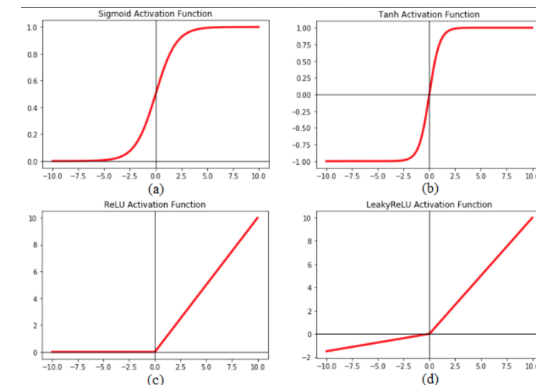


Figure source: (Kandel and Castelli, 2020)

## Design Decisions

### Activation functions

- ▶ Sigmoid
- ▶ ReLU (rectified linear unit)
- ▶ tanh (hyperbolic tangent)

### Learning rate

- ▶ Choosing one in advance
- ▶ Use **momentum** to perform dynamic adjustments

### Dropout

- ▶ Ignore randomly-chosen weights in a training pass to prevent overfitting

### Regularisation

- ▶ Dampen a weight from growing/shrinking too far from the rest to prevent overfitting

## Normalisation

### Example House classification.

Input number of bedrooms, last selling price

Output Likelihood of selling

Vector `input_vec` = [4, 12000]

### All input dimensions should have comparable values

Ideally, all features should be in the range  $[-1, 1]$  or  $[0, 1]$

**Typical normalisation:** mean normalisation, feature scaling, coefficient of variation

**NLP** typically uses TF-IDF, one-hot encoding, word2vec (already normalised)

## References

Kandel, I. and M. Castelli

2020. Transfer learning with convolutional neural networks for diabetic retinopathy image classification. a review. *Applied Sciences*, 10(6).

Lane, H., C. Howard, and H. Hapkem

2019. *Natural Language Processing in Action*. Shelter Island, NY: Manning Publication Co.