

91258 / B0385 Natural Language Processing

Lesson 10. "One" Neuron

Alberto Barrón-Cedeño a.barron@unibo.it

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Previously

- From Words to Topics
- ML pipeline

Table of Contents

- 1. There Was Life Before Deep Learning
- 2. Some History
- 3. The Perceptron
- 4. More than One Neuron
- Chapter 5 of Lane et al. (2019)

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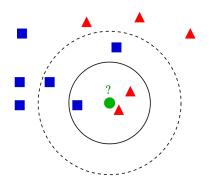
3 / 32

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(And Many Non-NN in-Production Models Prevail)

- Naïve Bayes
- k-nearest neighbors
- Random forests
- Support vector machines
- HMM
- Logistic Regression
- . . .

k-Nearest Neighbours



The class of \bullet is the same as the most frequent among its k neighbours

https://en.wikipedia.org/wiki/K-nearest_neighbors_algorithm

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Random Forests (showing only one decision tree here)

Playing Golf



Picture from https://medium.com/@MrBam44/decision-trees-91f61a42c724

Random Forests (showing only one decision tree here)

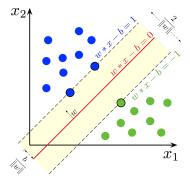
Playing Golf



Multiple decision trees are learned and the final class is the mode

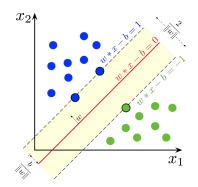
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Support Vector Machines



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Support Vector Machines



Kernels

Linear

RBF

Polynomial

Tree

https://en.wikipedia.org/wiki/Support-vector_machine

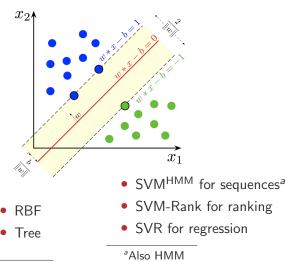
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Support Vector Machines

Kernels

Linear

Polynomial



https://en.wikipedia.org/wiki/Support-vector_machine

There are many, many others

9 / 32

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There are many, many others

• Often they are SotA (or close)

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- In general, they are *cheaper*

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- Some of them are *explainable*

- Often they are SotA (or close)
- In general, they are cheaper
- In general, they require less data
- Some of them are *explainable*
- Representations have to be engineered

Some History

Some History

Opening paragraph of Rosenblatt (1957)'s The Perceptron—a perceiving and recognizing automaton

Since the advent of electronic computers and modern servo systems, an increasing amount of attention has been focused on the feasibility of constructing a device possessing such human-like functions as perception, recognition, concept formation, and the ability to generalize from experience. In particular, interest has centered on the idea of a machine which would be capable of conceptualizing inputs impinging directly from the physical environment of light, sound, temperature, etc.—the "phenomenal world" with which we are all familiar — rather than requiring the intervention of a human agent to digest and code the necessary information.

11 / 32

Al Winters

1974–1980 First major winter 1987–1993 Second major winter

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¹https://en.wikipedia.org/wiki/Lighthill_report

²https://en.wikipedia.org/wiki/Fifth_generation_computer

Al Winters

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1974–1980 First major winter
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1987–1993 Second major winter

- 1966 Failure of MT
- 1970 Abandonment of connectionism (explain mental phenomena using artificial neural networks)
- 1971–75 DARPA's frustration wrt CMU's speech recognition research
 - 1973 Lighthill report decreases Al research in the UK¹
- 1973-74 DARPA's cutbacks to academic AI research

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¹https://en.wikipedia.org/wiki/Lighthill_report

²https://en.wikipedia.org/wiki/Fifth_generation_computer > 4 } > 2

Al Winters

	First major winter Second major winter
1970	Failure of MT Abandonment of connectionism (explain mental phenomena using artificial neural networks)
1973	DARPA's frustration wrt CMU's speech recognition research Lighthill report decreases AI research in the UK ¹ DARPA's cutbacks to academic AI research
	Collapse of the LISP machine market Cancellation of new spending on AI by the Strategic Computing Initiative
	Resistance to expert systems deployment and maintenance End of the Fifth Generation computer project's original goals ²
https://en.wikipedia.org/wiki/Lighthill_report	

13 / 32

• Intended to be a machine able of recognising images

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- Rough idea:

Input: features of an image (small subsections)

Parameters: weights for each feature (measure of importance)

Output: Fire once all potentiometers pass a certain threshold

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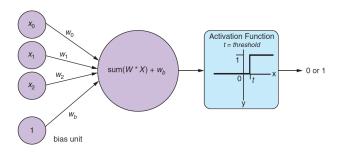
Parameters: weights for each feature (measure of importance)

Output: Fire once all potentiometers pass a certain threshold

Fired: positive match in the image

Did not fire: negative class

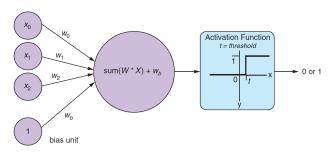
Numerical Perceptron³



(Lane et al., 2019, p. 158)

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Numerical Perceptron³



(Lane et al., 2019, p. 158)

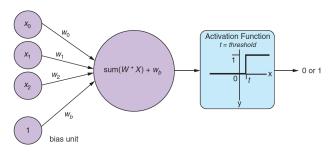
• Feature vector: $X = [x_0, x_1, \dots, x_i, \dots, x_n]$

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2024

15 / 32

Numerical Perceptron³

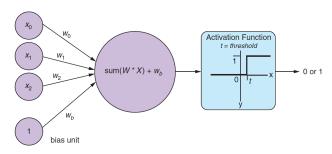


(Lane et al., 2019, p. 158)

- Feature vector: $X = [x_0, x_1, \dots, x_i, \dots, x_n]$
- Associated weight (per feature): $W = [w_0, w_1, \dots, w_i, \dots, w_n]$

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Numerical Perceptron³



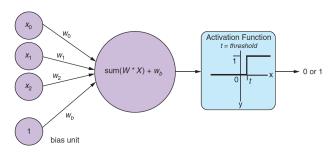
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- Associated weight (per feature): $W = [w_0, w_1, \dots, w_i, \dots, w_n]$
- Sum up: $(x_0 * w_0) + (x_1 * w_1) + \cdots + (x_i * w_i) + \ldots (x_n * w_n)$

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³I am intentionally dropping biological references

Numerical Perceptron³



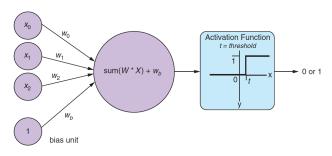
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- Bias: always-on input (resiliency to inputs of all zeros)

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Numerical Perceptron³

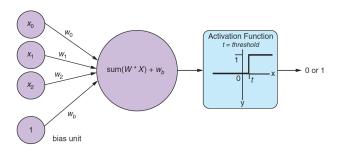


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- Activation (step) function

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Numerical Perceptron

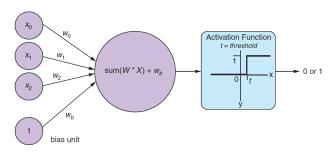


(Lane et al., 2019, p. 158)

$$\hat{y} = f(\vec{x}) = \begin{cases} 1 & \text{if } \sum_{i=0}^{n} x_i w_i > \text{threshold} \\ 0 & \text{otherwise} \end{cases}$$
 (1)

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Numerical Perceptron



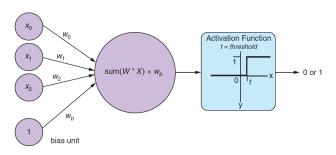
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This perceptron is a special case of a *neuron* —the base unit of a neural network

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Numerical Perceptron



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 (1)

This perceptron is a special case of a *neuron* —the base unit of a neural network

Let us see

16 / 32

Without Bias

"The output [of a perceptron] is a linear function of the input" (Goodfellow et al., 2016, p. 105)

$$\hat{y} = w^T x \tag{2}$$

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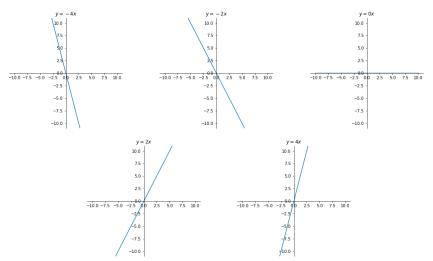
Without Bias

```
import matplotlib.pyplot as plt
import numpy as np
for i in range (-5, 5, 1):
    fig, ax = plt.subplots(figsize = (5,5))
    ax.spines['left'].set_position('center')
    ax.spines['bottom'].set_position('center')
    ax.spines['right'].set_color('none')
    ax.spines['top'].set_color('none')
    ax.set(title='$y=w^Tx$')
    x = np.arange(-5.0, 5.0, 0.01)
    plt.xlim((-5,+5))
    plt.ylim((-5,+5))
    ax.set(title='$y={}x$'.format(i))
    y = i*x #1 + np.sin(2 * np.pi * x)
    ax.plot(x, y)
    fig.savefig("linear_w{}.png".format(i))
    plt.show()
```

Not the nicest way to plot

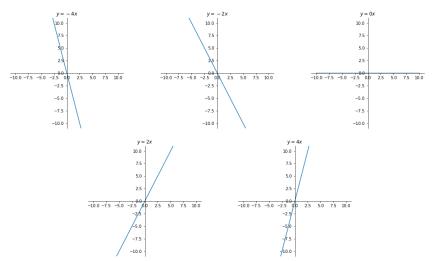
Without Bias

Plotting with different values of w



Without Bias

Plotting with different values of w; do you see an issue?



With Bias

$$\hat{y} = w^T x + b \tag{3}$$

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"[...] the mapping from parameters to predictions is still a linear function but the mapping from features to predictions is now an affine function" (Goodfellow et al., 2016, p. 107)

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20 / 32

With Bias

$$\hat{y} = w^T x + b \tag{3}$$

"[...] the mapping from parameters to predictions is still a linear function but the mapping from features to predictions is now an affine function" (Goodfellow et al., 2016, p. 107)

(does not need to pass by the origin)

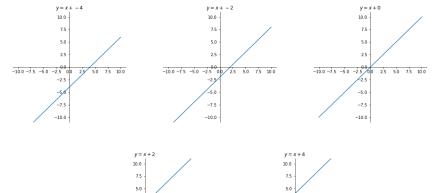
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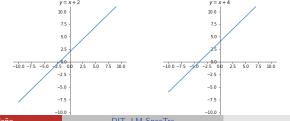
20 / 32

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Without Bias

Plotting with w = 1 and different values of b





Typical Learning Process (1/2)

Given an annotated dataset...

start with a random weight initialisation from a normal distribution

$$ec{w} \sim \mathcal{N}(\mu, \sigma^2)$$
 with $\mu \sim 0$ (but do not use $0!$)

Typical Learning Process (1/2)

Given an annotated dataset...

• start with a random weight initialisation from a normal distribution

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feed one instance and see if the predicted class is correct

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- feed one instance and see if the predicted class is correct
- 1: **if** the class is correct **then**
- 2: do nothing
- 3: **else**
- 4: adjust the weights (slightly; not until getting the class right!)

22 / 32

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Typical Learning Process (1/2)

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feed one instance and see if the predicted class is correct

- 1: if the class is correct then
- 2: do nothing
- 3: **else**
- 4: adjust the weights (slightly; not until getting the class right!)

Each weight is adjusted by how much it contributed to the resulting error

2024 22 / 22

Typical Learning Process (2/2)

- All instances in the training data are fed a number of times (iterations): epoch
- Typical stop criteria include
 - $error < \epsilon$ (convergence)
 - error stabilisation
 - max number of epochs reached

23 / 32

Example 1: Logical OR

input		output
0	0	0
0	1	1
1	0	1
1	1	1

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Mr. Perceptron can learn!

Example 1: Logical OR

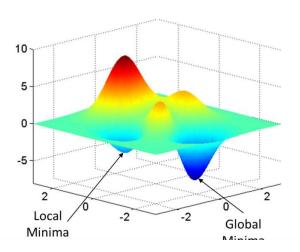
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0	1	1
1	0	1
1	1	1



Mr. Perceptron can learn!

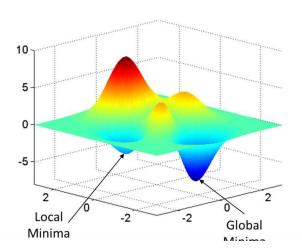
This learning model is called linear regression (another ML alternative)

Drawback: Local vs Global Minimum



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Drawback: Local vs Global Minimum



No guarantee that the model will reach the global optimal solution

Plot from M. Ryan's thesis (http://www.isni.org/isni/000000045916099%)

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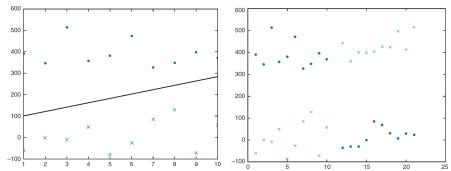
25 / 32

Drawback: Linearly separable

The perceptron can only deal with linearly separable data

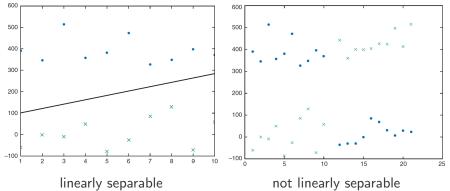
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Drawback: Linearly separable

The perceptron can only deal with linearly separable data



Example 2: Logical XOR

We have learned a logical OR function . . .

Can we learn a logical XOR?

2024

27 / 32

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Example 2: Logical XOR

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input		output	
() 0	0	
() 1	. 1	
1	0	1	
1	. 1	0	



Example 2: Logical XOR

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Can we learn a logical XOR?

input		output
0	0	0
0	1	1
1	0	1
1	1	0

$$\begin{array}{c|cccc} 1 & \bullet & \bullet \\ \hline 0 & \bullet & \bullet \\ \hline & 0 & 1 \end{array}$$

Let us see

Mr. Perceptron cannot learn!

. . . winter

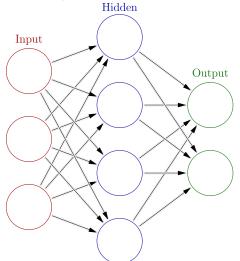
More than One Neuron

Neural Networks

A neural network is a combination of multiple perceptrons (and it can deal with more complex patterns)

Neural Networks

A neural network is a combination of multiple perceptrons (and it can deal with more complex patterns)



29 / 32

Some Formalisms

```
Input x = [x_1, x_2, x_3, ..., x_k]
Output f(x)^4
Answer y
```

 $^{^4}$ aka \hat{y}

⁵aka loss function

Some Formalisms

Input $x = [x_1, x_2, x_3, \dots, x_k]$ Output $f(x)^4$ Answer y

Cost Function⁵ Quantifier of the mismatch between actual and predicted output

$$err(x) = |y - f(x)| \tag{4}$$

⁴aka ŷ

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Some Formalisms

Input $x = [x_1, x_2, x_3, \dots, x_k]$ Output $f(x)^4$ Answer y

Cost Function⁵ Quantifier of the mismatch between actual and predicted output

$$err(x) = |y - f(x)| \tag{4}$$

Training goal Minimising the cost function across all input samples

$$J(x) = \min \sum_{i=1}^{n} err(x_i)$$
 (5)

 $^{^4}$ aka \hat{y}

⁵aka loss function

Next

- Backpropagation (briefly)
- Activation functions
- Keras



References

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2024

32 / 32