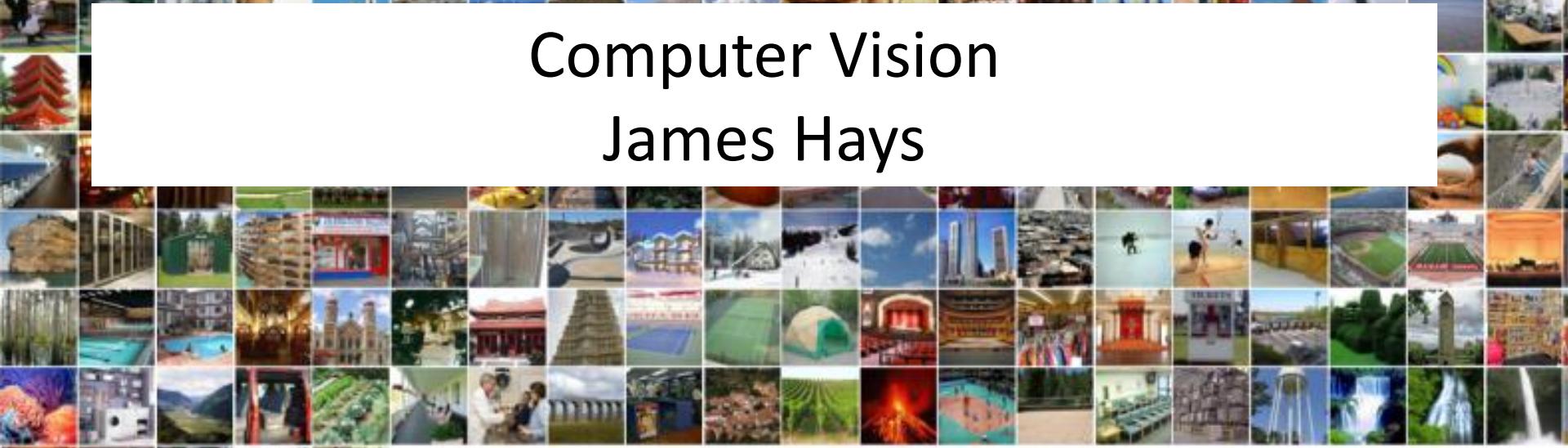




Large-scale category recognition and Advanced feature encoding



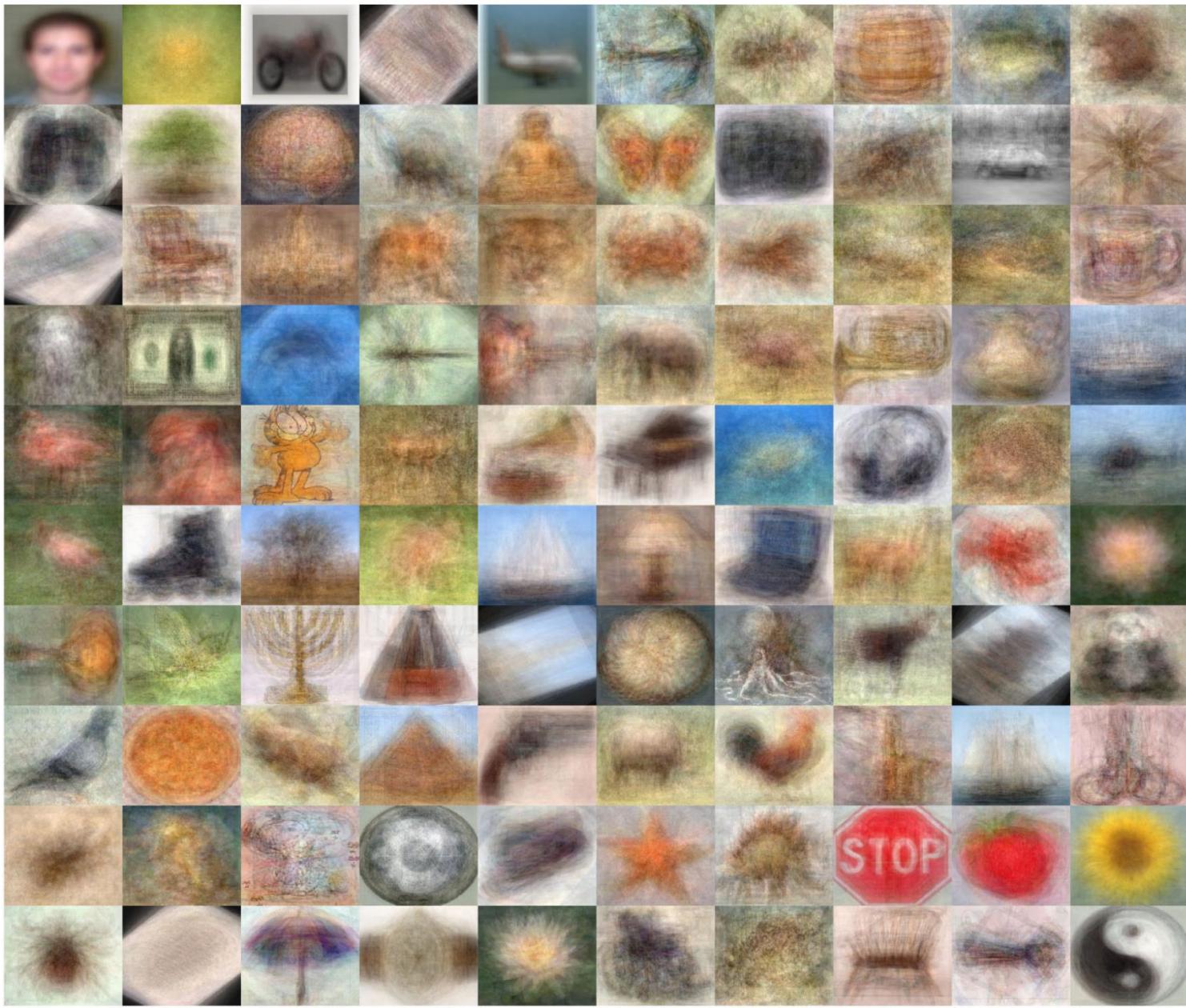
Computer Vision
James Hays

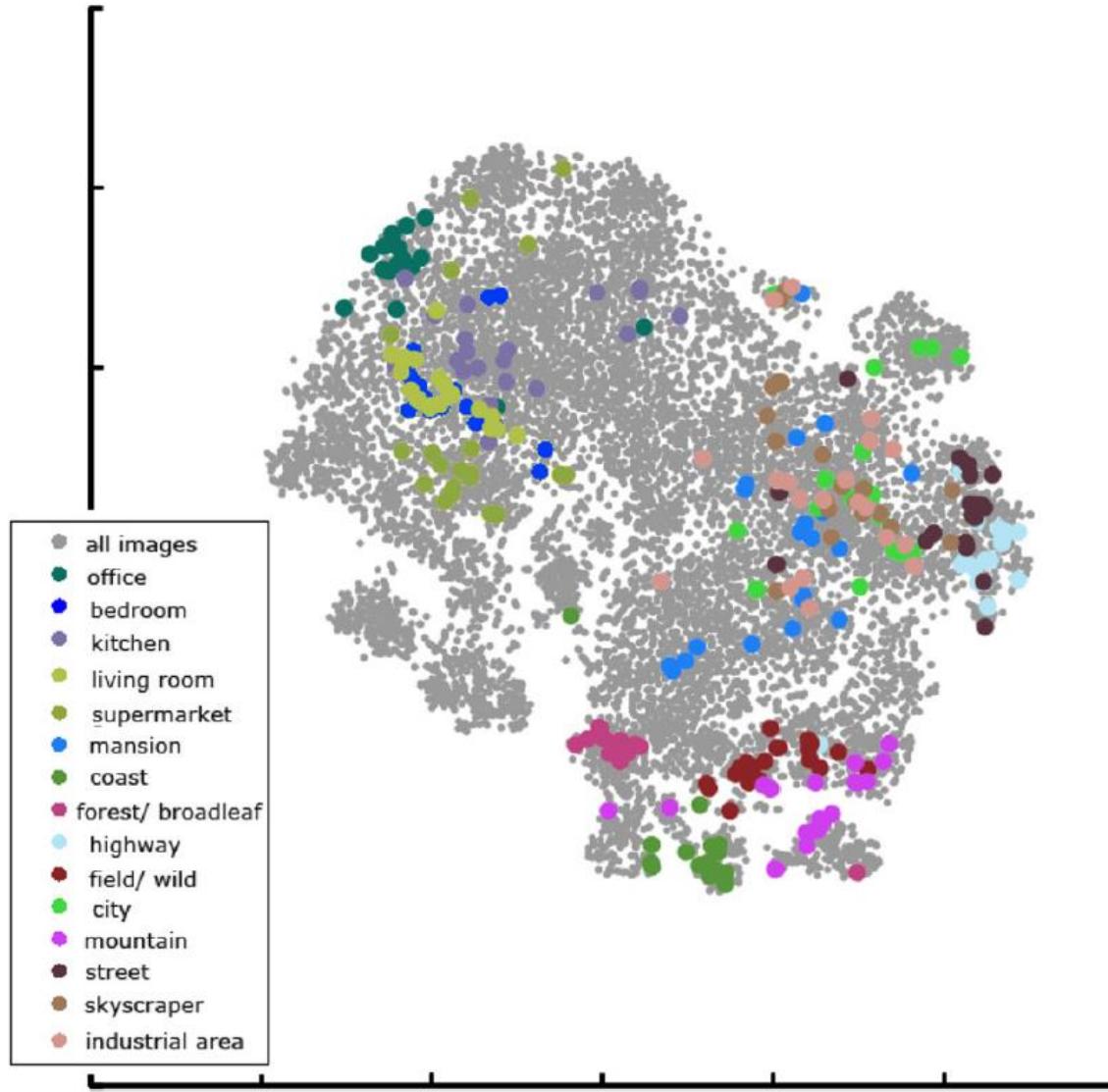


Why do good recognition systems go bad?

- E.g. Why isn't our Bag of Words classifier at 90% instead of 70%?
- Training Data
 - Huge issue, but not necessarily a variable you can manipulate.
- Representation
 - Are the local features themselves lossy?
 - What about feature quantization? That's VERY lossy.
- Learning method
 - Probably not such a big issue, unless you're learning the representation (e.g. deep learning).

CalTech 101 - 2004





The SUN Attribute Database: Beyond Categories for Deeper Scene Understanding.

Genevieve Patterson, Chen Xu, Hang Su, and James Hays.

International Journal of Computer Vision. vol. 108:1-2, 2014. Pp 59-81.



SUN Database: Large-scale Scene Categorization and Detection



Jianxiong Xiao, James Hays[†], Krista A. Ehinger,
Aude Oliva, Antonio Torralba

Massachusetts Institute of Technology

[†] Brown University



Scene Categorization

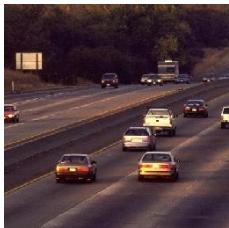
Oliva and Torralba, 2001



Coast



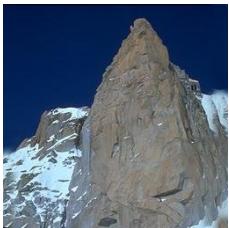
Forest



Highway



Inside
City



Mountain



Open
Country



Street



Tall
Building

Fei Fei and Perona, 2005



Bedroom



Kitchen



Living Room



Office



Suburb

Lazebnik, Schmid, and Ponce, 2006



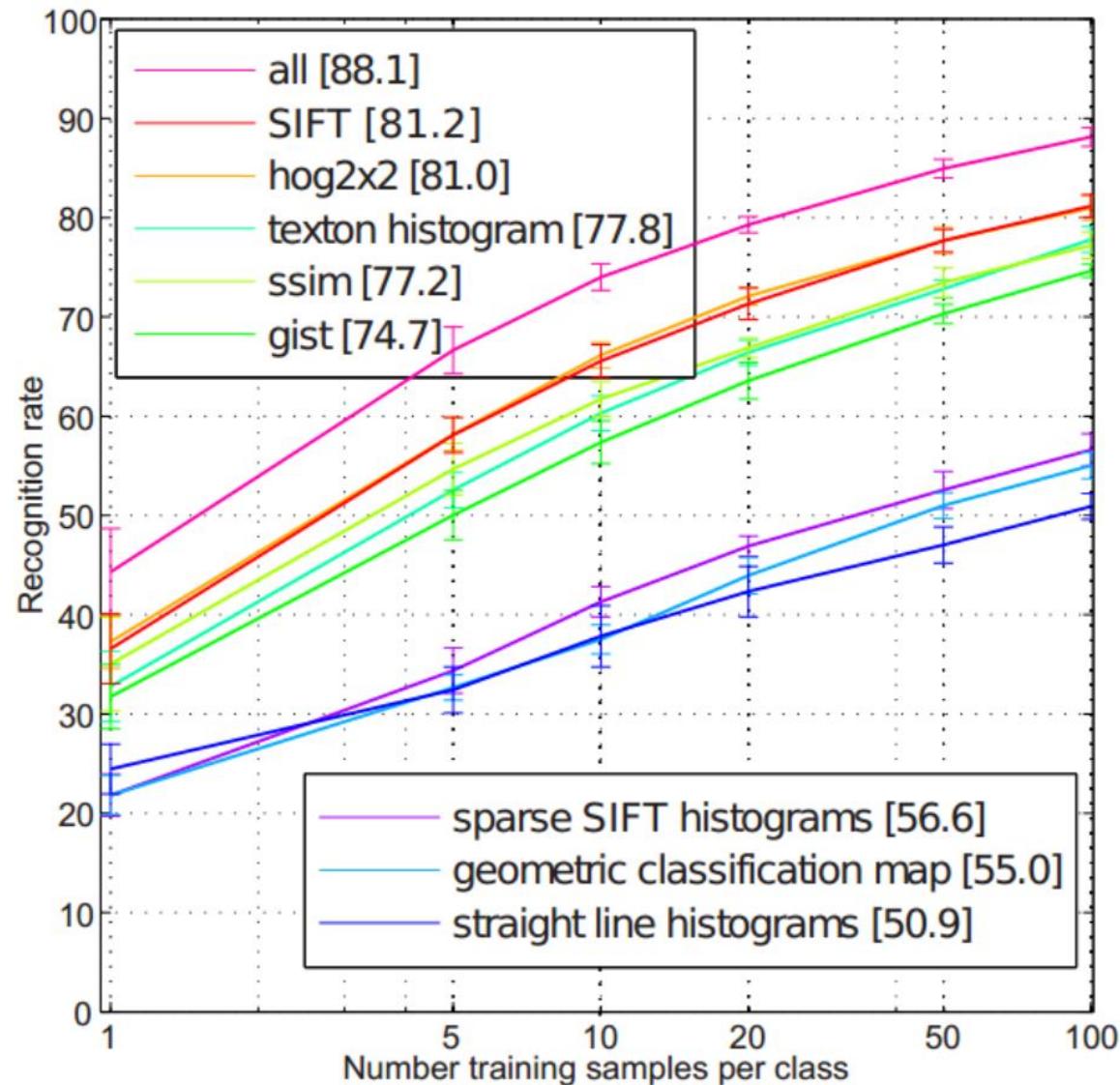
Industrial



Store

15 Scene
Database

15 Scene Recognition Rate



How many object categories are there?



abbey



airplane cabin



airport terminal





apple orchard



assembly hall



bakery





car factory



cockpit



construction site





food court



interior car



lounge





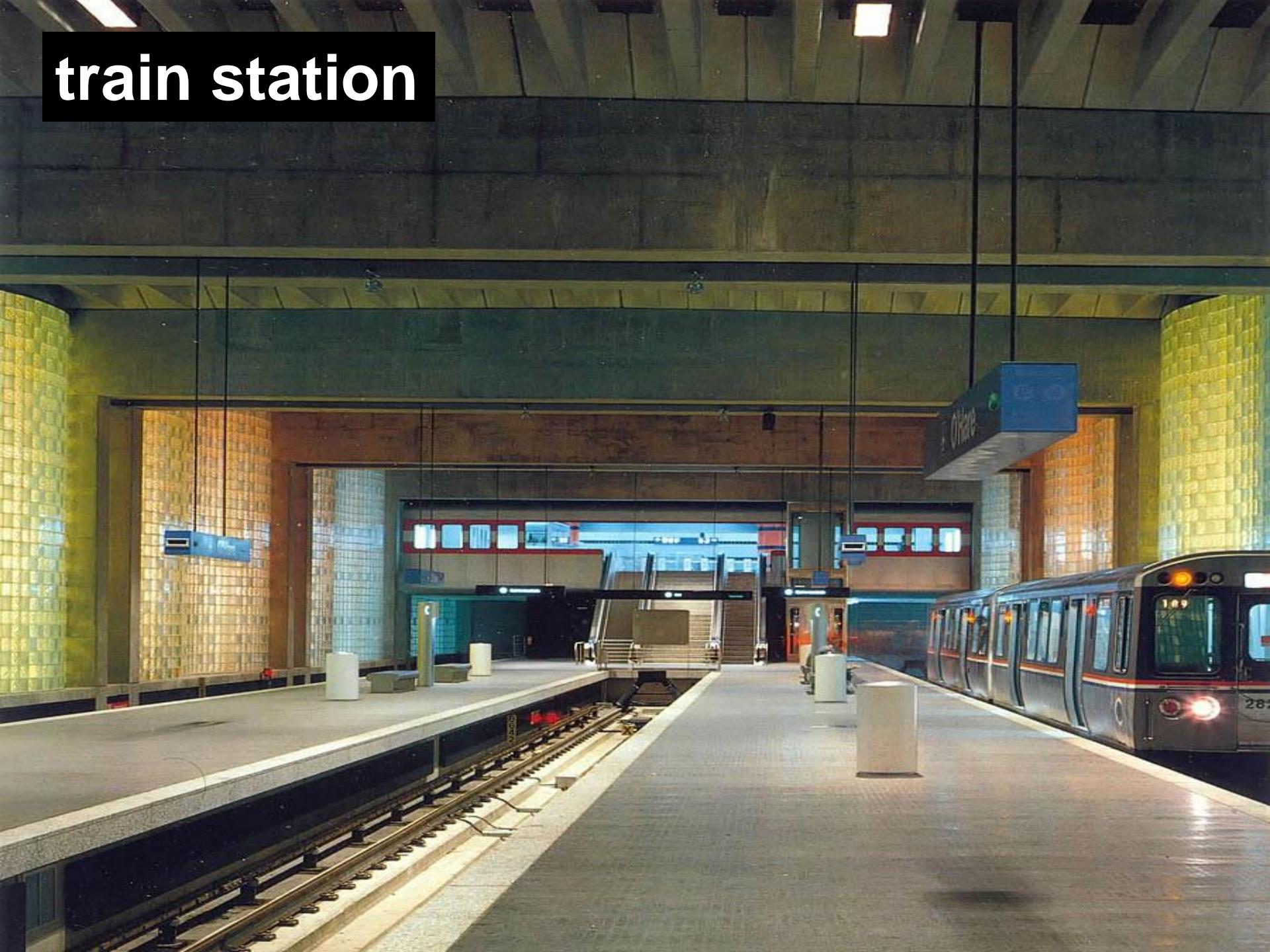
stadium



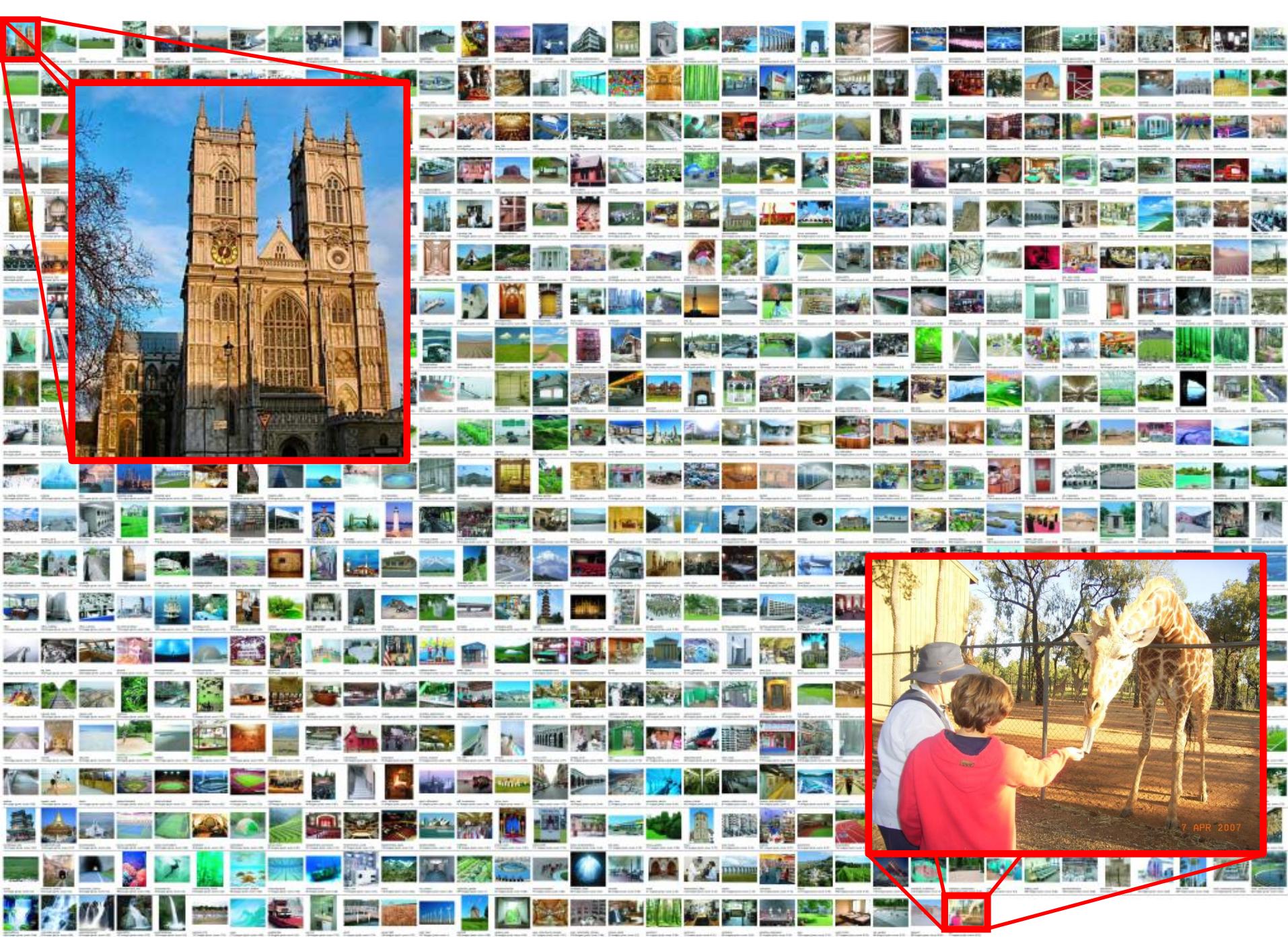
stream



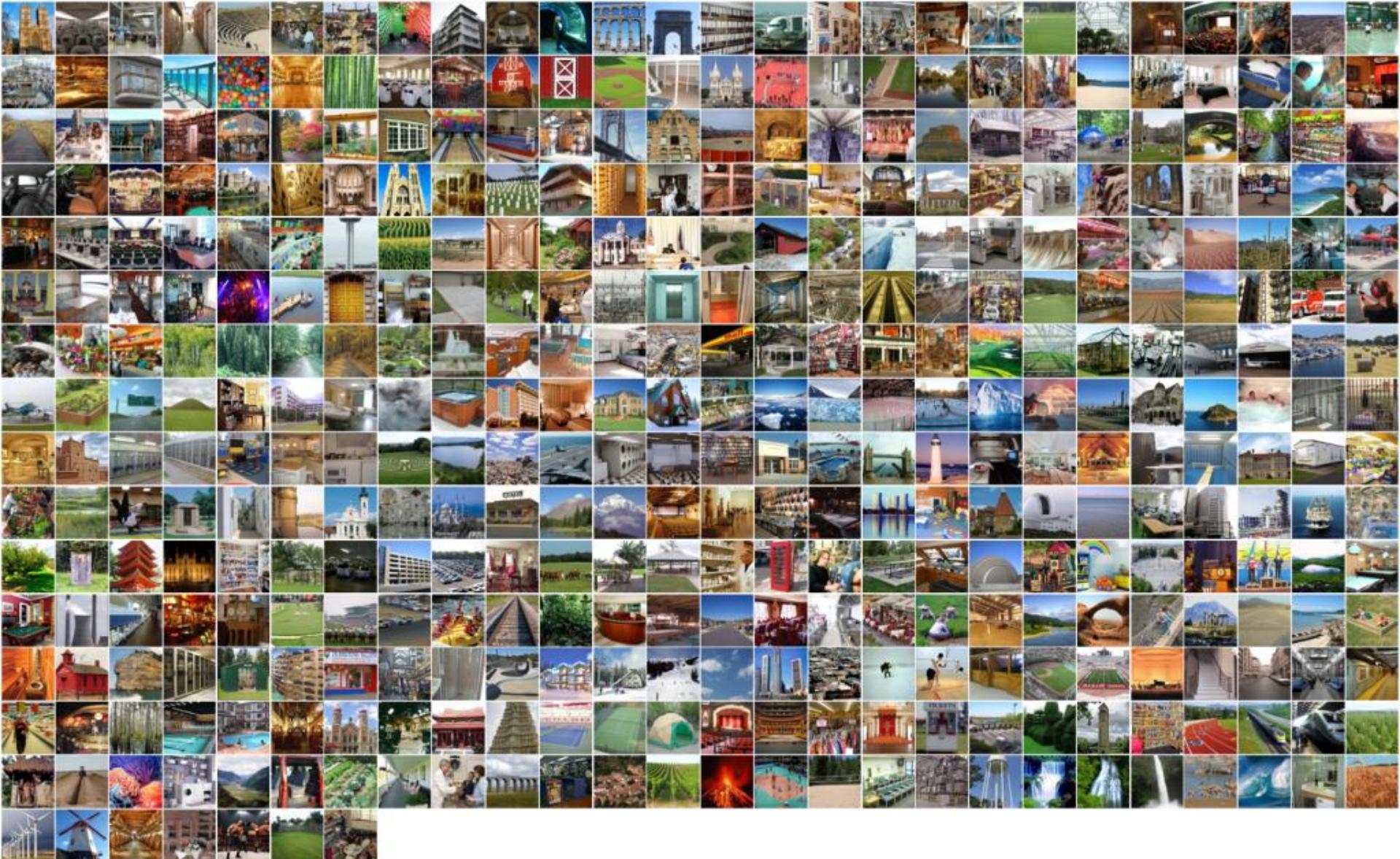
train station







397 Well-sampled Categories



Evaluating Human Scene Classification



?

“Good worker”

98%

90%

68%

Accuracy

bathroom(100%)



beauty salon(100%)



bedroom(100%)



bullring(100%)



playground(100%)



podium outdoor(100%)



greenhouse outdoor(100%)



wind farm(100%)



veterinarians office(100%)



riding arena(100%)



tennis court outdoor(100%)



Scene category

Inn (0%)



Bayou (0%)



Basilica (0%)



Most confusing categories

Restaurant patio (44%)



Chalet (19%)



River (67%)



Coast (8%)



Cathedral(29%)



Courthouse (21%)



Conclusion: humans can do it

- The SUN database is reasonably consistent and differentiable -- even with a huge number of very specific categories, humans get it right 2/3rds of the time *with no training*.
- We also have a good benchmark for computational methods.

How do we classify scenes?

How do we classify scenes?



Ceiling Light		Ceiling Lamp		
Door	Door	Painting		
Wall	Door	wall	mirror	wall
	Door		mirror	
	Wall			Lamp
	Door			phone
Floor		Fireplace	armchair	alarm
		armchair		Side-table
		Coffee table		carpet

Different objects, different spatial layout

Which are the important elements?



cabinets	ceiling	cabinets
window		
seat	window	seat
seat	seat	seat
seat	seat	seat

cabinets	ceiling	cabinets
window		
seat	seat	seat
seat	seat	seat
seat	seat	seat

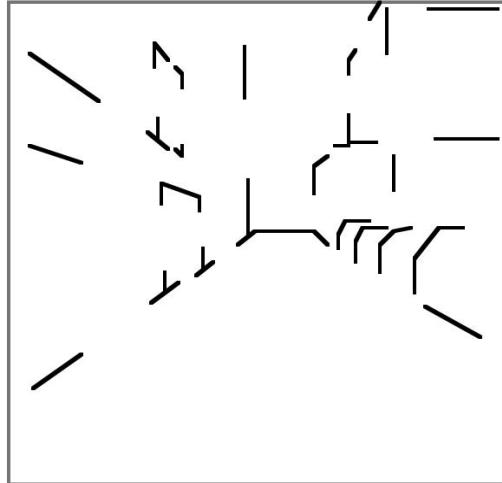
	ceiling	
wall	column	screen
seat	seat	seat

Similar objects, and similar spatial layout

Different lighting, different materials, different “stuff”

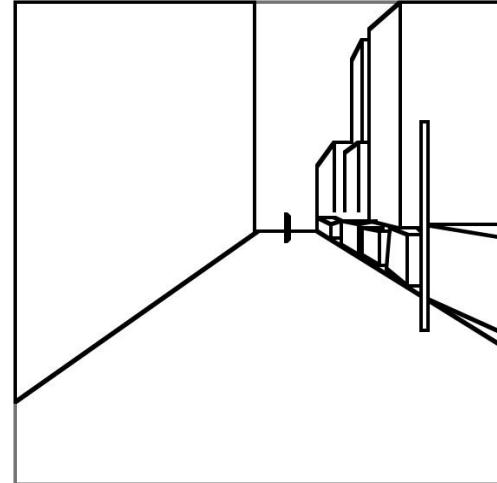
Scene emergent features

“Recognition via features that are not those of individual objects but “emerge” as objects are brought into relation to each other to form a scene.” – Biederman 81



Suggestive edges and junctions

Biederman, 1981



Simple geometric forms

Biederman, 1981



Blobs

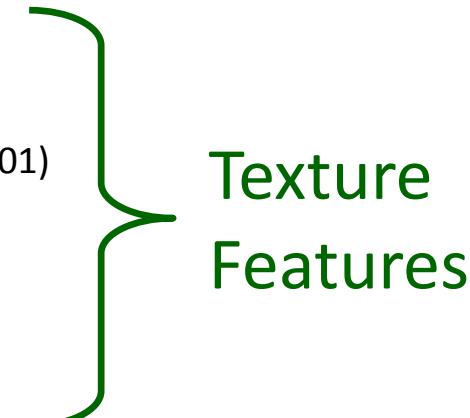
Bruner and Potter, 1969



Textures

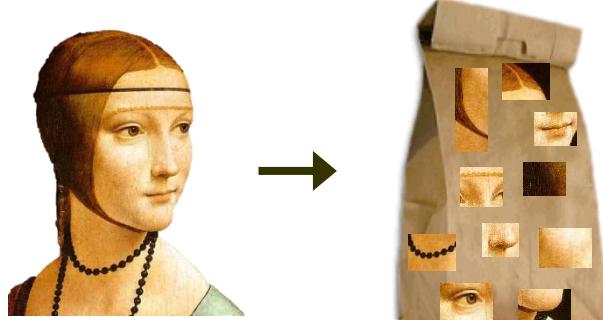
Oliva and Torralba, 2001

Global Image Descriptors

- Tiny images (Torralba et al, 2008)
 - Color histograms
 - Self-similarity (Shechtman and Irani, 2007)
 - Geometric class layout (Hoiem et al, 2005)
 - Geometry-specific histograms (Lalonde et al, 2007)
 - Dense and Sparse SIFT histograms
 - Berkeley texton histograms (Martin et al, 2001)
 - HoG 2x2 spatial pyramids
 - Gist scene descriptor (Oliva and Torralba, 2008)
- 
- Texture
Features

Global Texture Descriptors

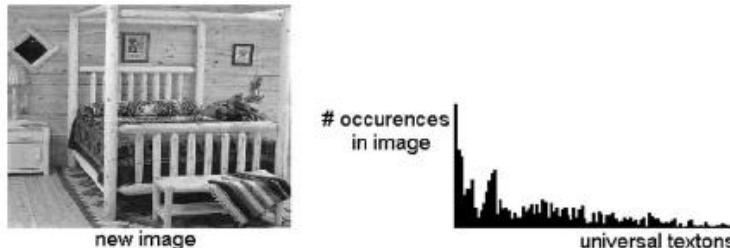
Bag of words



Sivic et. al., ICCV 2005

Fei-Fei and Perona, CVPR 2005

Non localized textons



Walker, Malik. Vision Research 2004

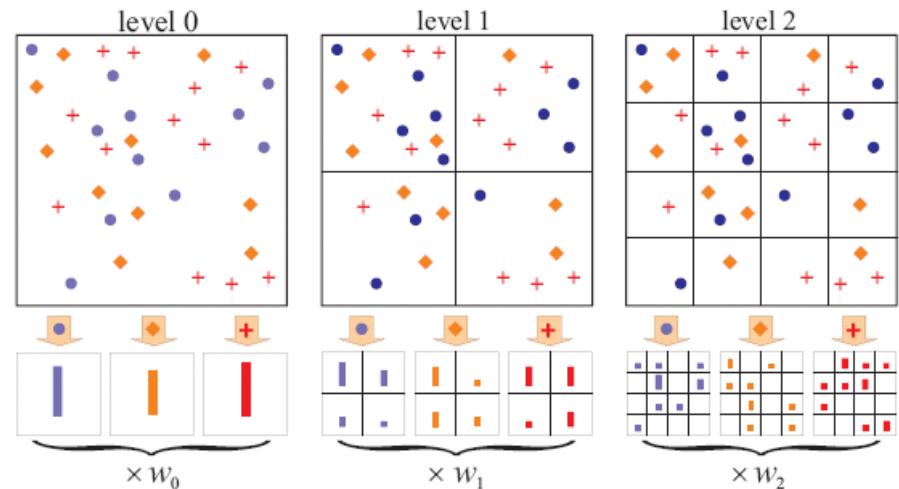
...

Spatially organized textures



M. Gorkani, R. Picard, ICPR 1994

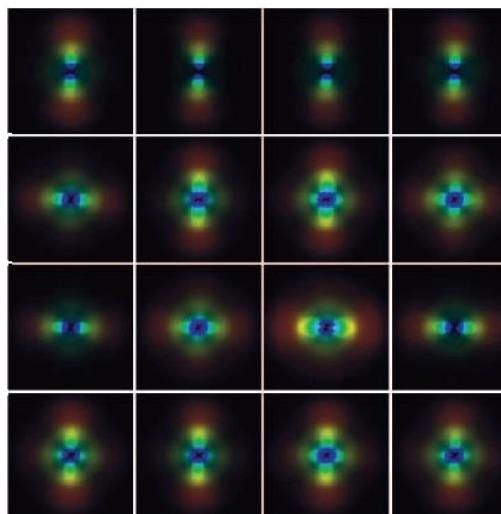
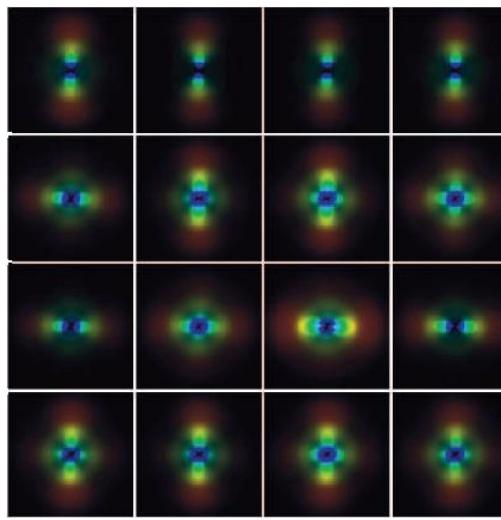
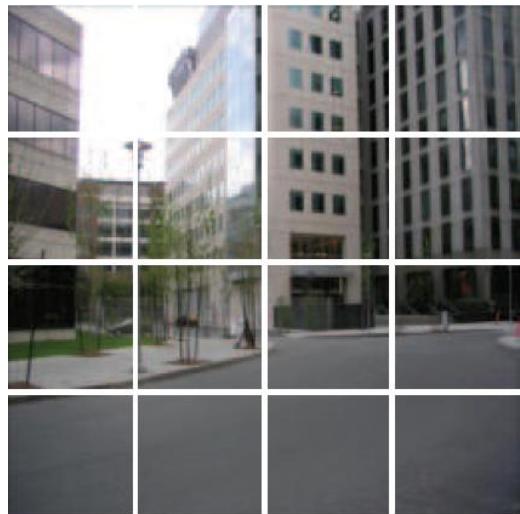
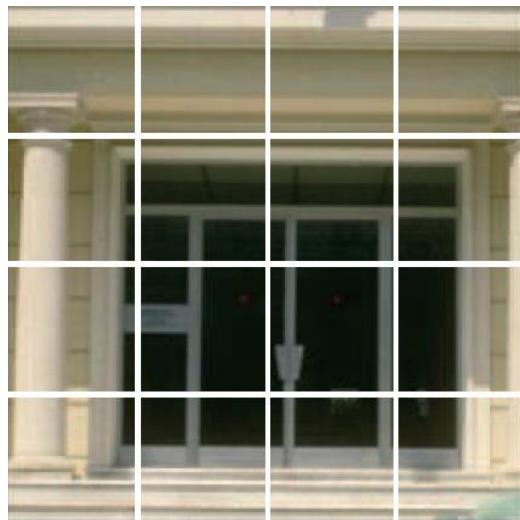
A. Oliva, A. Torralba, IJCV 2001



S. Lazebnik, et al, CVPR 2006

Gist descriptor

Oliva and Torralba, 2001



- Apply oriented Gabor filters over different scales
- Average filter energy in each bin

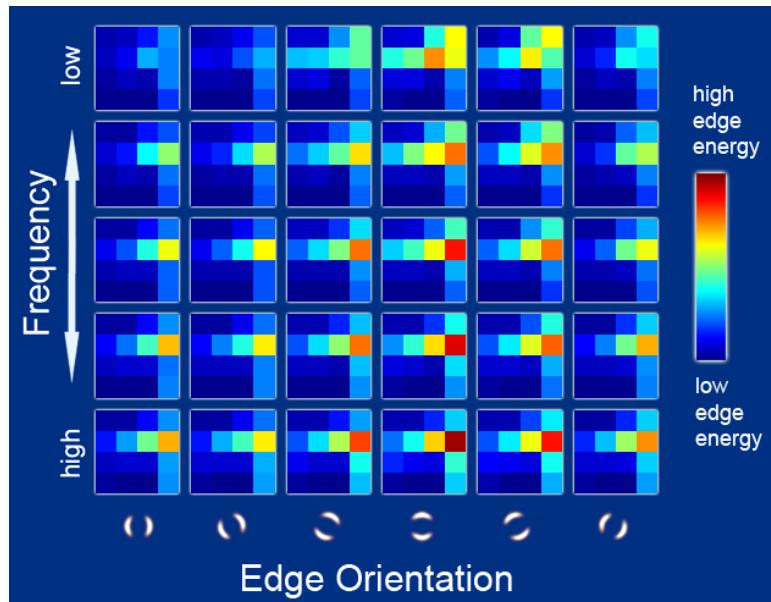
8 orientations
4 scales
x 16 bins
512 dimensions

Similar to SIFT (Lowe 1999) applied to the entire image

M. Gorkani, R. Picard, ICPR 1994; Walker, Malik. Vision Research 2004; Vogel et al. 2004;
Fei-Fei and Perona, CVPR 2005; S. Lazebnik, et al, CVPR 2006; ...

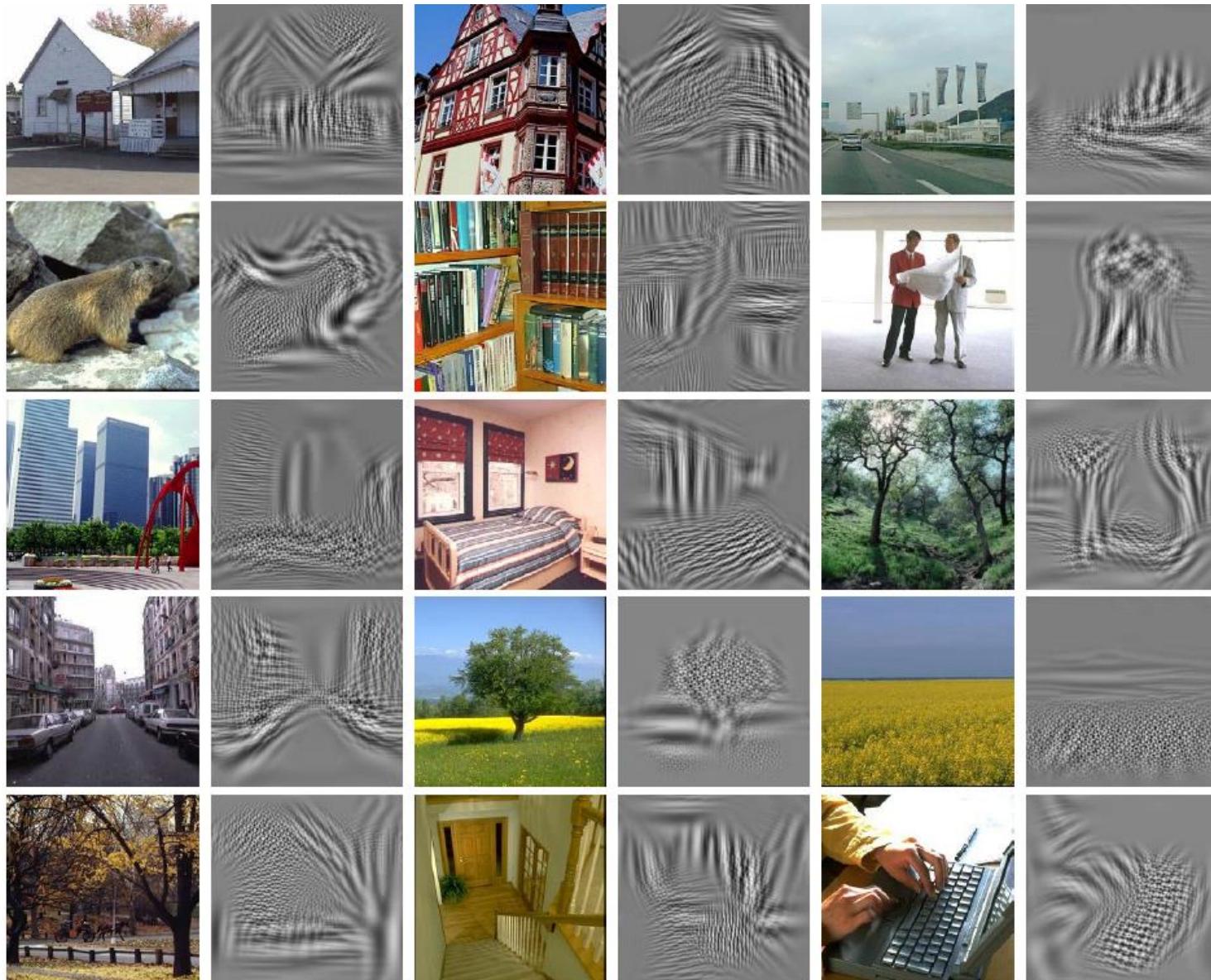
Global scene descriptors

- The “gist” of a scene: Oliva & Torralba (2001)



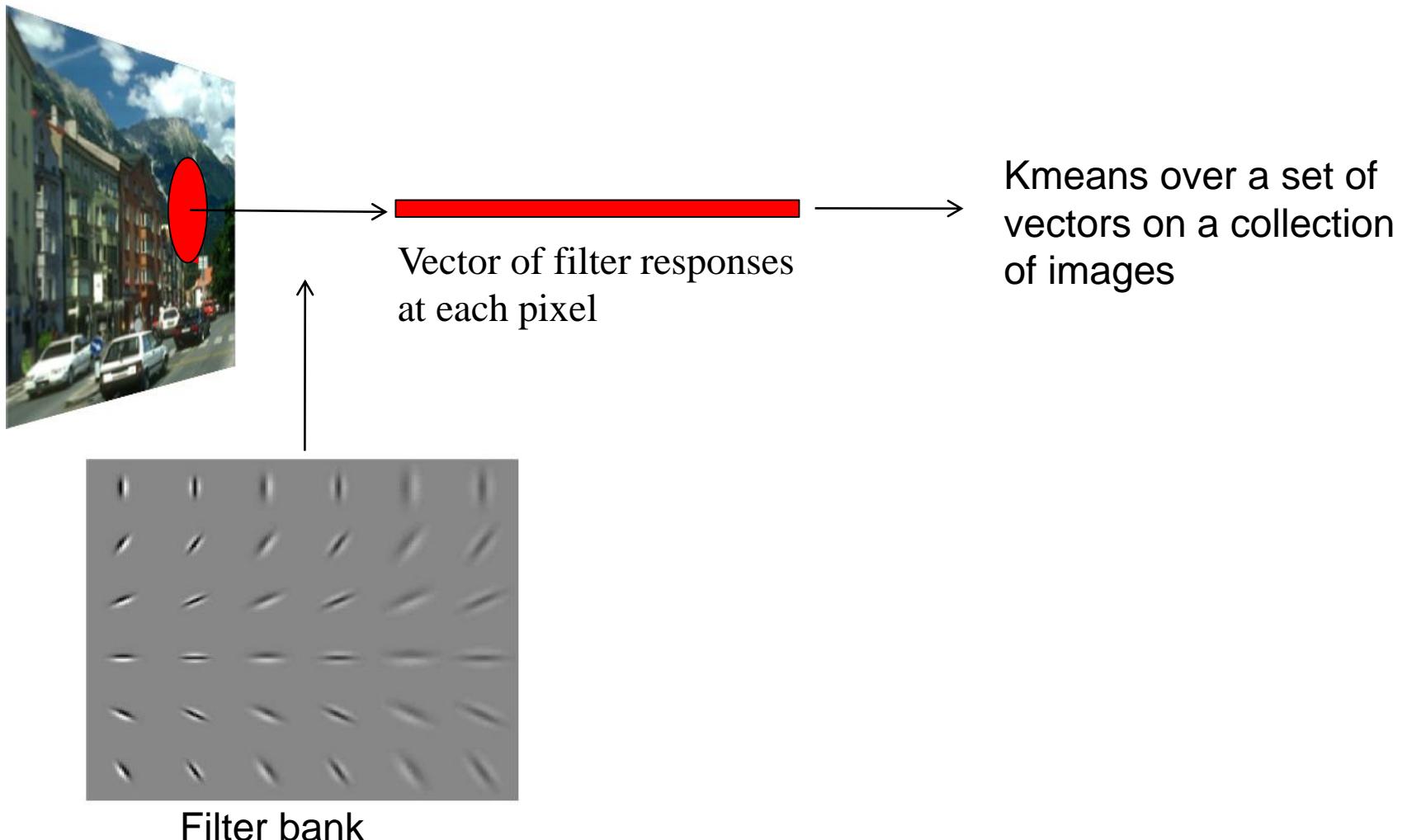
<http://people.csail.mit.edu/torralba/code/spatialevelope/>

Example visual gists



Global features (I) ~ global features (I')

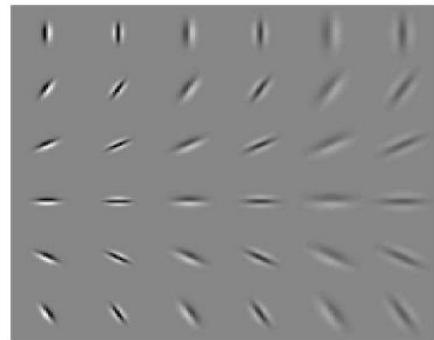
Textons



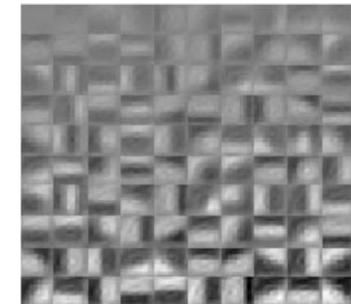
Textons



Filter bank



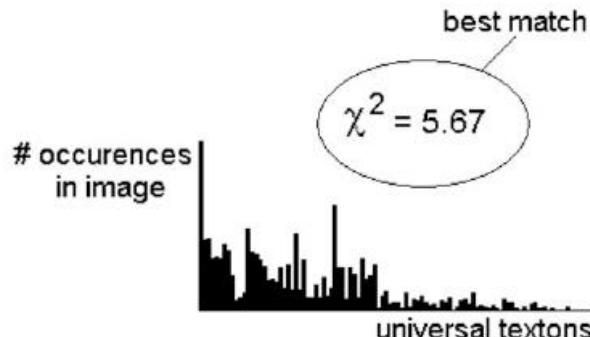
K-means (100 clusters)



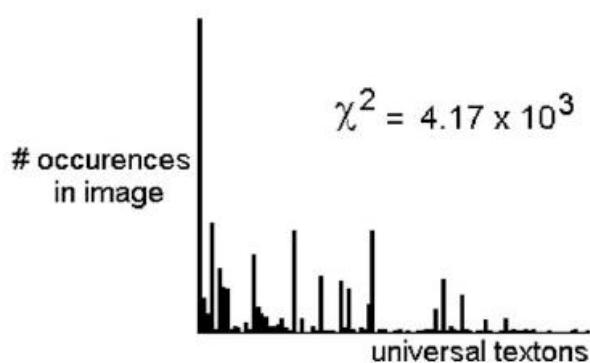
Malik, Belongie, Shi, Leung, 1999



label = bedroom



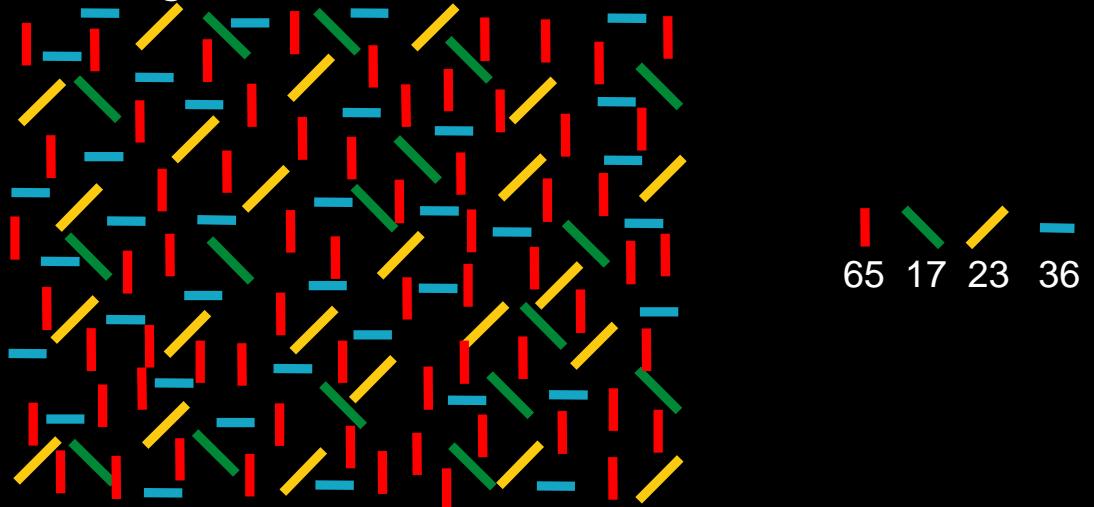
label = beach



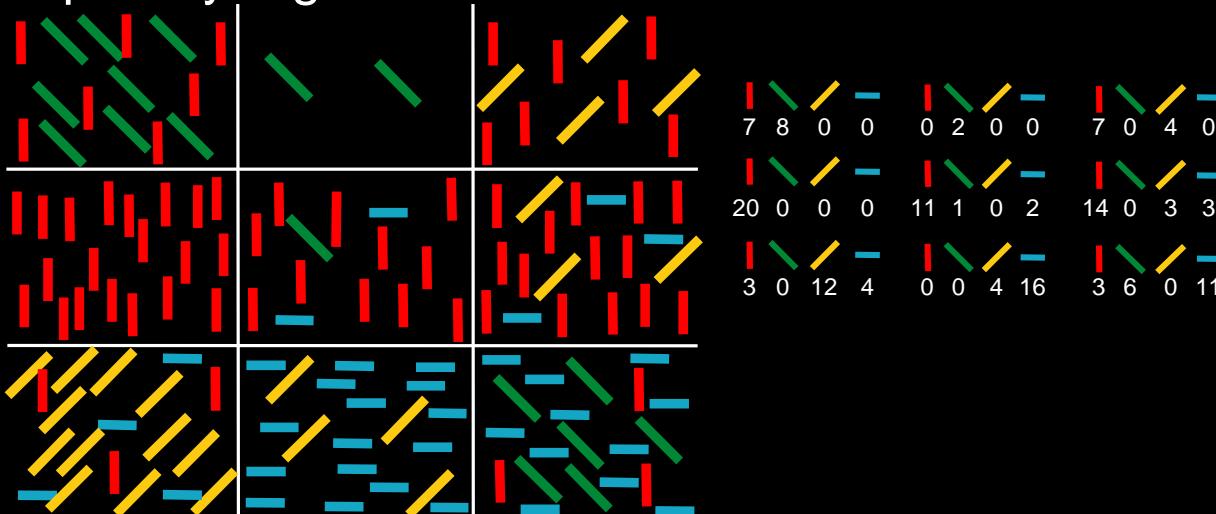
Walker, Malik, 2004

Bag of words

Bag of words model

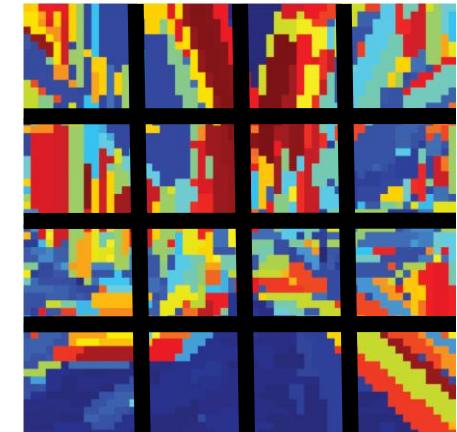
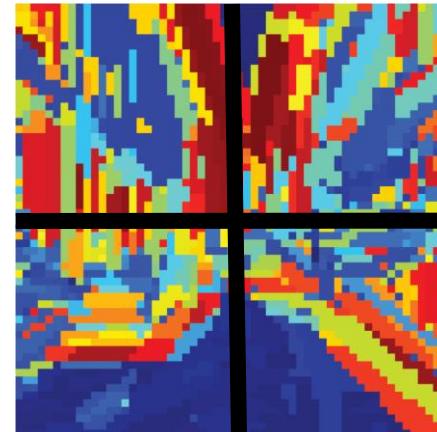
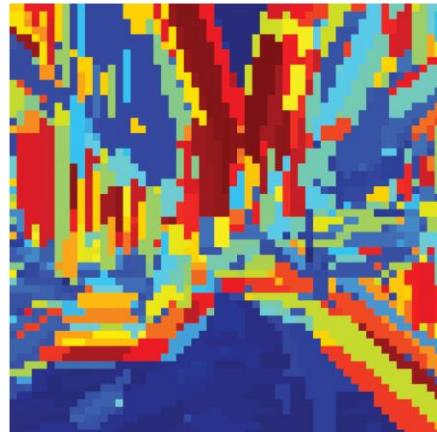


Spatially organized textures



Bag of words & spatial pyramid matching

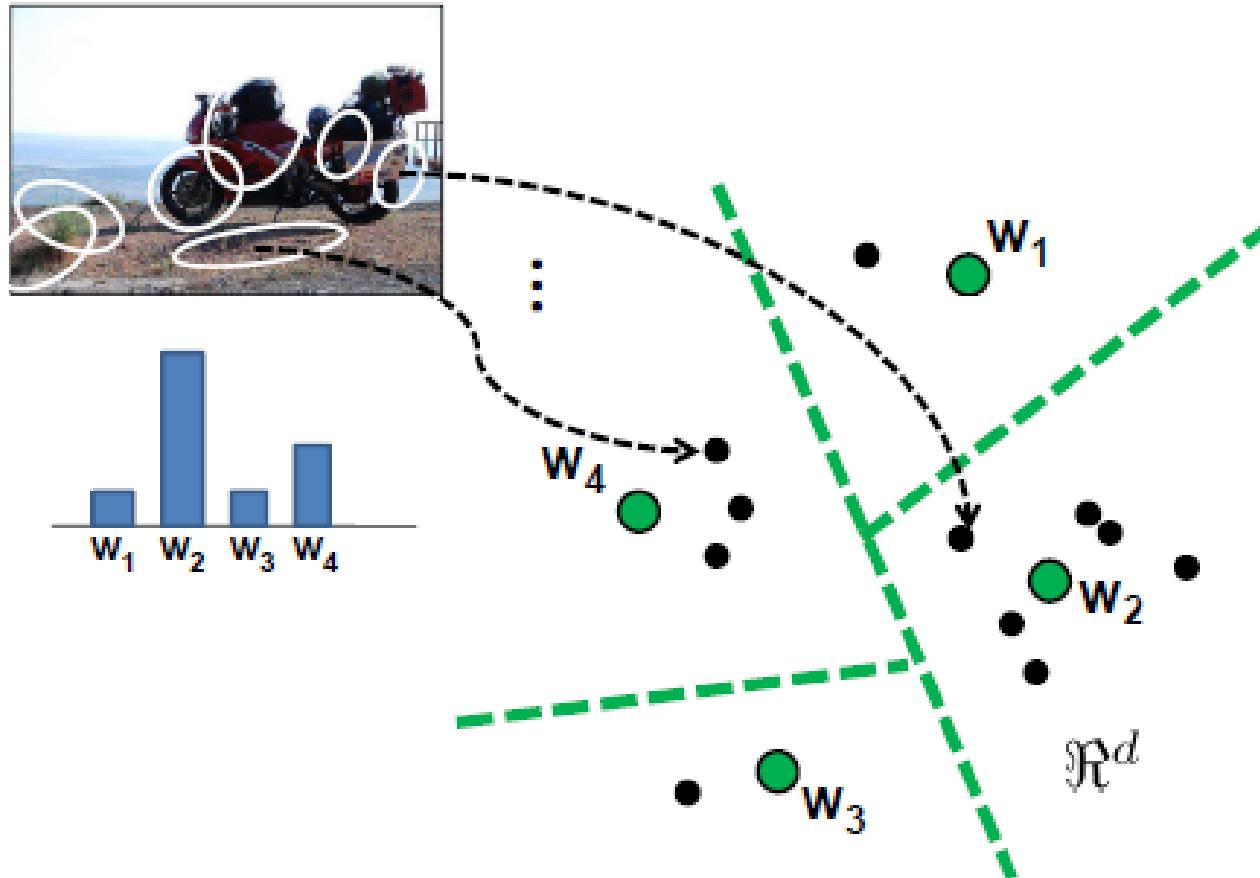
Sivic, Zisserman, 2003. Visual words = Kmeans of SIFT descriptors



Better Bags of Visual Features

- More advanced quantization / encoding methods that are near the state-of-the-art in image classification and image retrieval.
 - Soft assignment (a.k.a. Kernel Codebook)
 - VLAD
 - Fisher Vector
- Deep learning has taken attention away from these methods.

Standard Kmeans Bag of Words

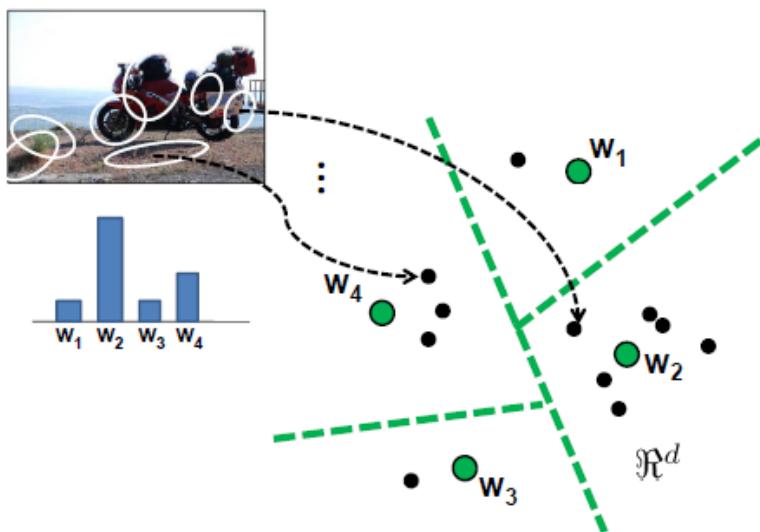


http://www.cs.utexas.edu/~grauman/courses/fall2009/papers/bag_of_visual_words.pdf

Motivation

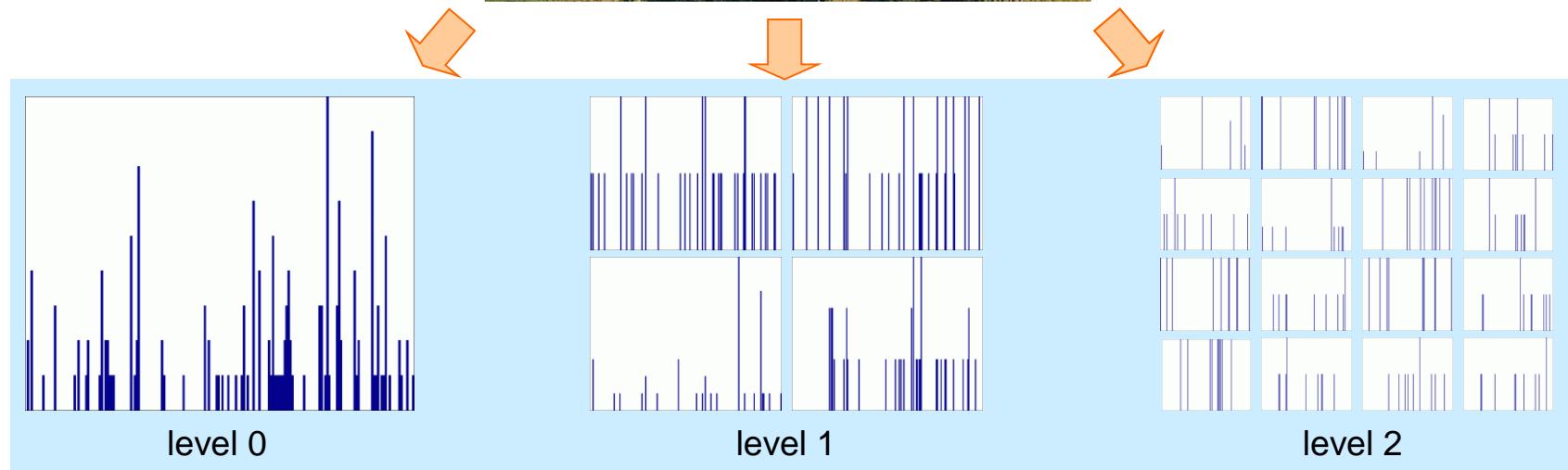
Bag of Visual Words is only about **counting** the number of local descriptors assigned to each Voronoi region

Why not including **other statistics**?



http://www.cs.utexas.edu/~grauman/courses/fall2009/papers/bag_of_visual_words.pdf

We already looked at the Spatial Pyramid



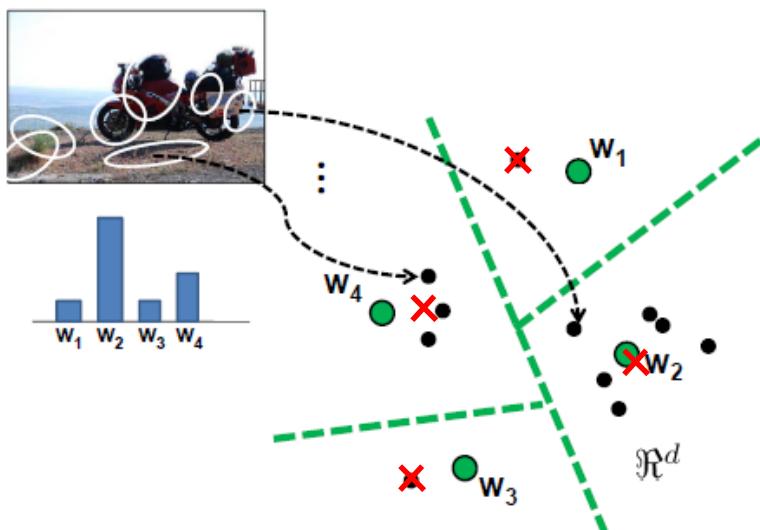
But today we're not talking about ways to preserve *spatial* information.

Motivation

Bag of Visual Words is only about **counting** the number of local descriptors assigned to each Voronoi region

Why not including **other statistics**? For instance:

- mean of local descriptors \times



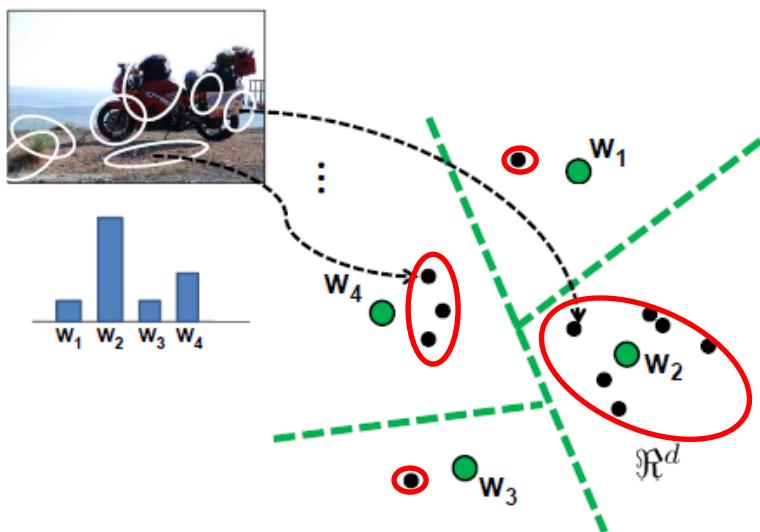
http://www.cs.utexas.edu/~grauman/courses/fall2009/papers/bag_of_visual_words.pdf

Motivation

Bag of Visual Words is only about **counting** the number of local descriptors assigned to each Voronoi region

Why not including **other statistics**? For instance:

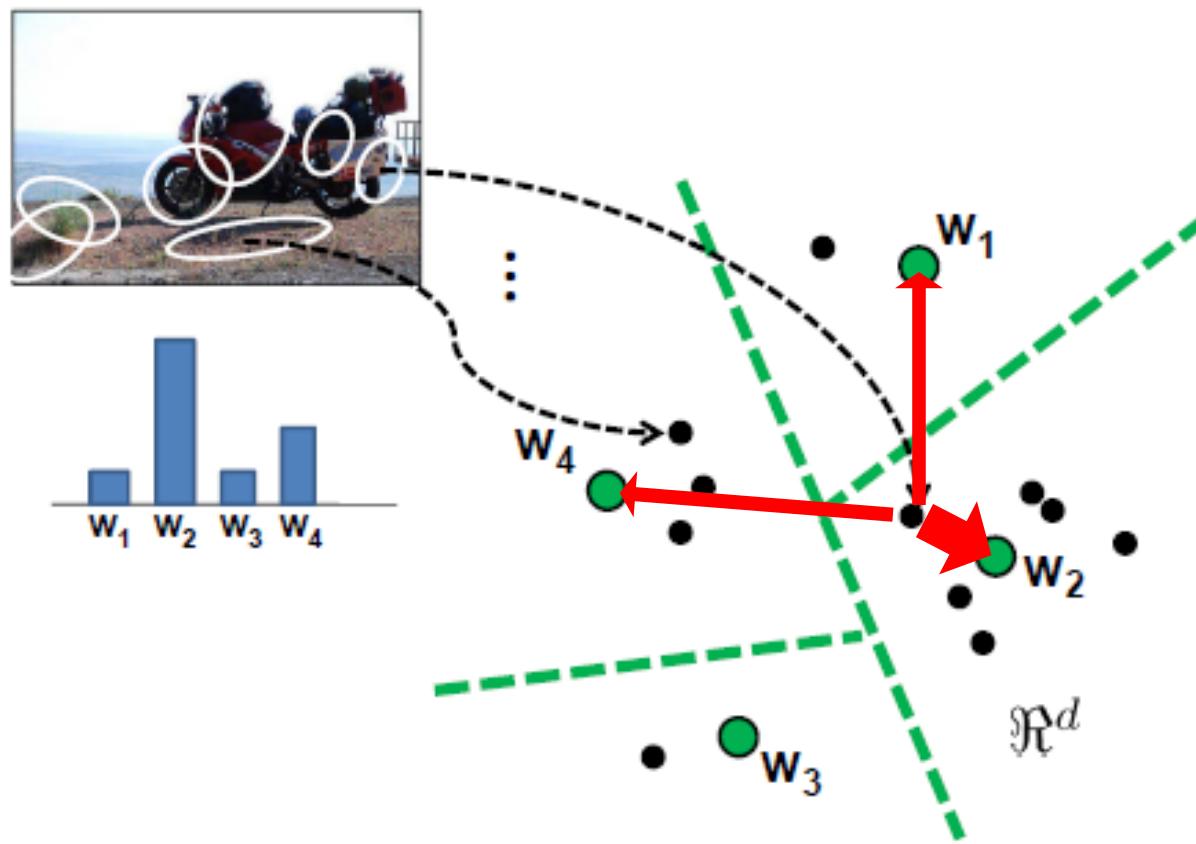
- mean of local descriptors
- (co)variance of local descriptors



http://www.cs.utexas.edu/~grauman/courses/fall2009/papers/bag_of_visual_words.pdf

Simple case: Soft Assignment

- Called “Kernel codebook encoding” by Chatfield et al. 2011. Cast a weighted vote into the most similar clusters.



Simple case: Soft Assignment

- Called “Kernel codebook encoding” by Chatfield et al. 2011. Cast a weighted vote into the most similar clusters.
- This is fast and easy to implement (try it for Project 4!) but it does have some downsides for image retrieval – the inverted file index becomes less sparse.



New query image

Word #	Image #
1	3
2	
7	1, 2
8	3
9	
10	
...	
91	2
...	

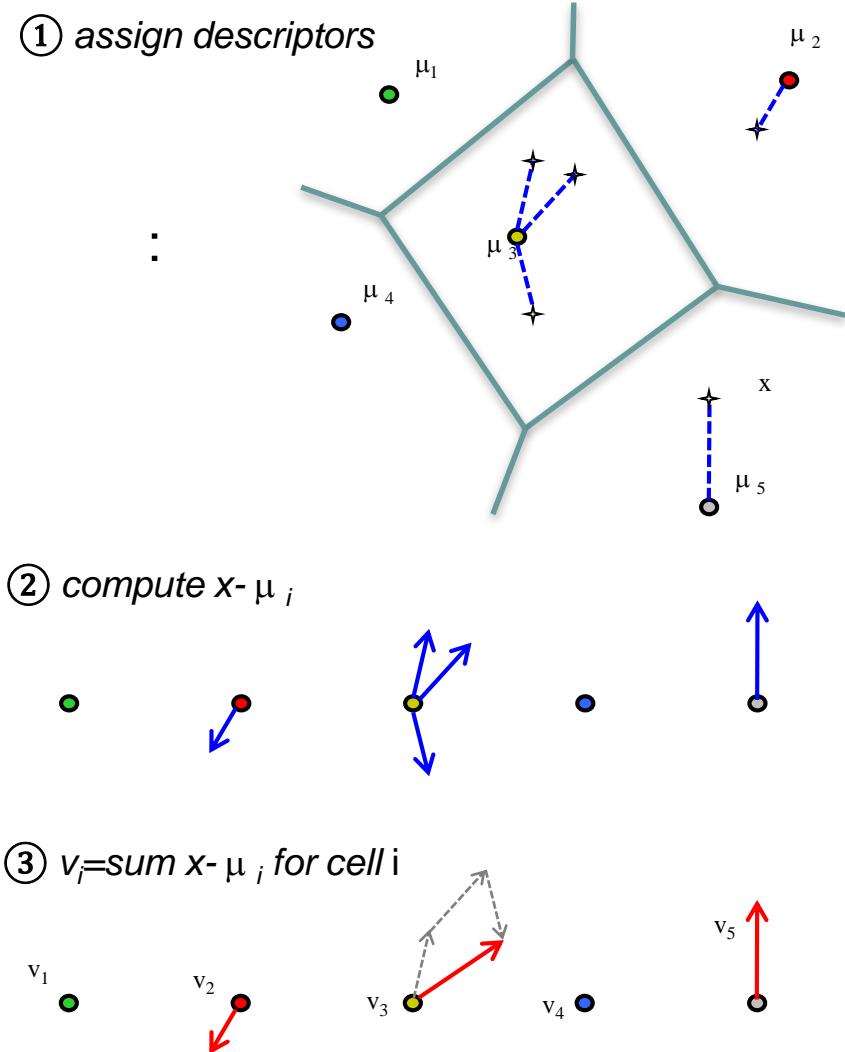
VLAD

Given a codebook $\{\mu_i, i = 1 \dots N\}$,
e.g. learned with K-means, and a set of
local descriptors $X = \{x_t, t = 1 \dots T\}$

- ① assign $\text{NN}(x_t) = \arg \min_{\mu_i} \|x_t - \mu_i\|$

- ②③ compute: $v_i = \sum_{x_t: \text{NN}(x_t) = \mu_i} x_t - \mu_i$

- concatenate v_i 's + ℓ_2 normalize



Jégou, Douze, Schmid and Pérez, "Aggregating local descriptors into a compact image representation", CVPR'10.

A first example: the VLAD

A graphical representation of $v_i = \sum_{x_t: \text{NN}(x_t) = \mu_i} x_t - \mu_i$



Jégou, Douze, Schmid and Pérez, "Aggregating local descriptors into a compact image representation", CVPR'10.

The Fisher vector

Score function

Given a likelihood function u_λ with parameters λ , the **score function** of a given sample X is given by:

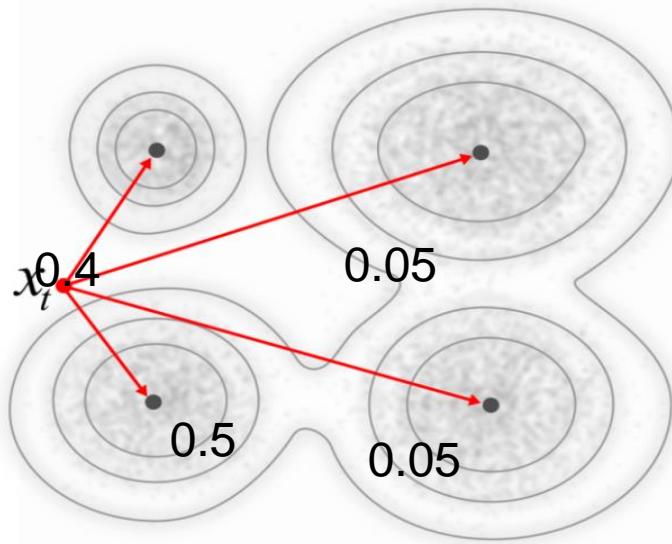
$$G_\lambda^X = \nabla_\lambda \log u_\lambda(X)$$

→ Fixed-length vector whose **dimensionality depends only on # parameters**.

Intuition: direction in which the parameters λ of the model should we modified to better fit the data.

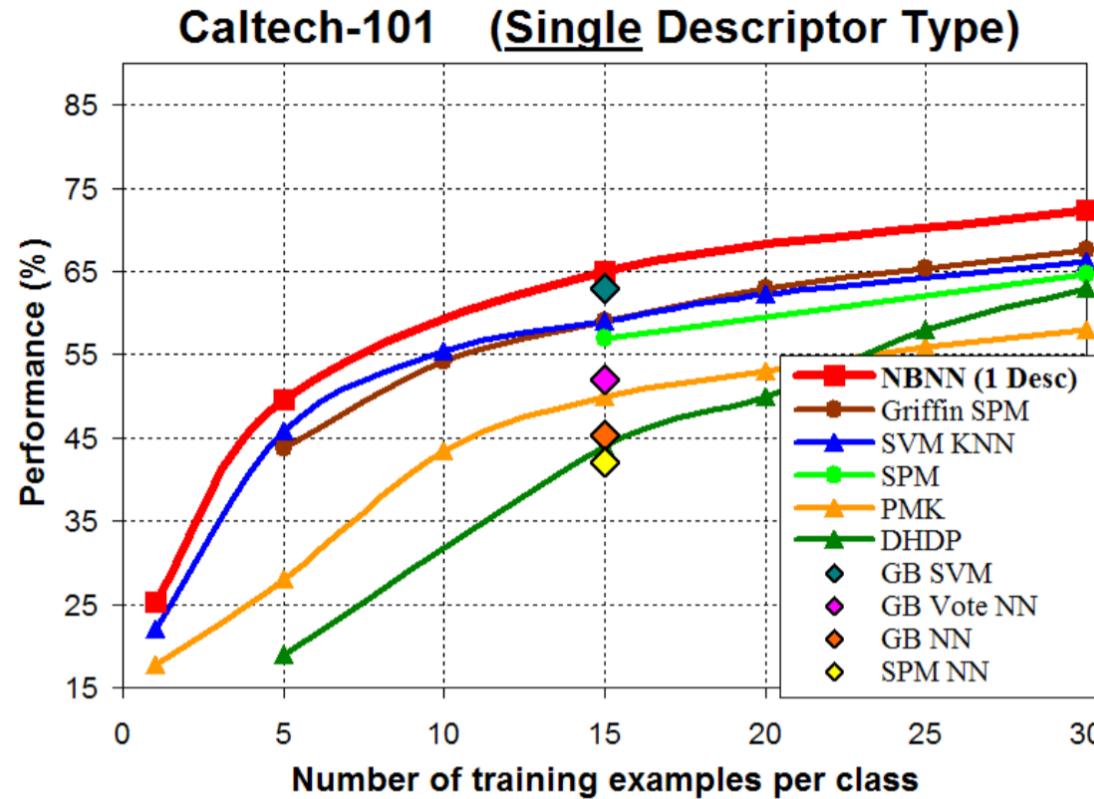
Aside: Mixture of Gaussians (GMM)

- For Fisher Vector image representations, u_λ is a GMM.
- GMM can be thought of as “soft” kmeans.



- Each component has a mean and a standard deviation along each direction (or full covariance)

What about skipping quantization / summarization completely?



In Defense of Nearest-Neighbor Based Image Classification
Boiman, Shechtman, Irani. CVPR 2008

Summary

- We've looked at methods to better characterize the distribution of visual words in an image:
 - Soft assignment (a.k.a. Kernel Codebook)
 - VLAD
 - Fisher Vector
 - No quantization

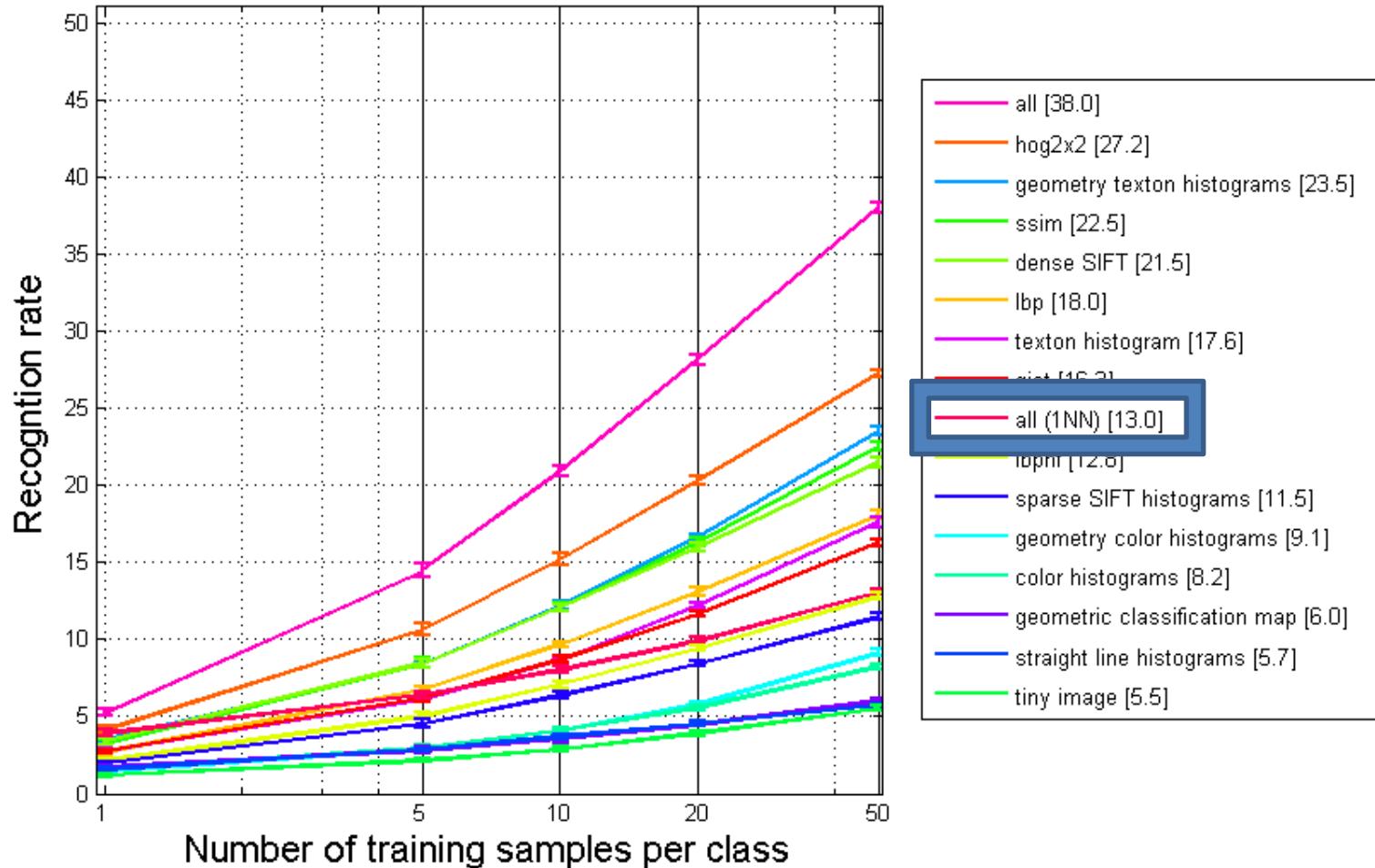
Learning Scene Categorization

Forest path
Vs.
all

Living - room
Vs.
all

Feature Accuracy

Humans [68.5]



Classifier: 1-vs-all SVM with histogram intersection, chi squared, or RBF kernel.

A look into the results

Airplane cabin (64%)



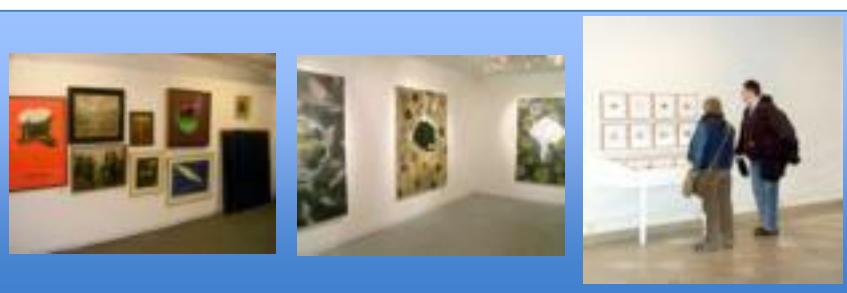
Van interior Discotheque



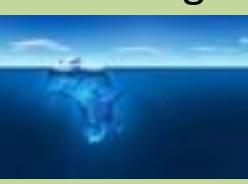
Toyshop



Art gallery (38%)



Iceberg



Hotel room



Kitchenette



All the results available on the web

limousine interior
(95% vs 80%)



riding arena
(100% vs 90%)



sauna
(96% vs 95%)



skatepark
(96% vs 90%)



subway interior
(96% vs 80%)



Humans good
Comp. good

Humans bad
Comp. bad

Human good
Comp. bad

Human bad
Comp. good



Database and source code available at
<http://groups.csail.mit.edu/vision/SUN/>

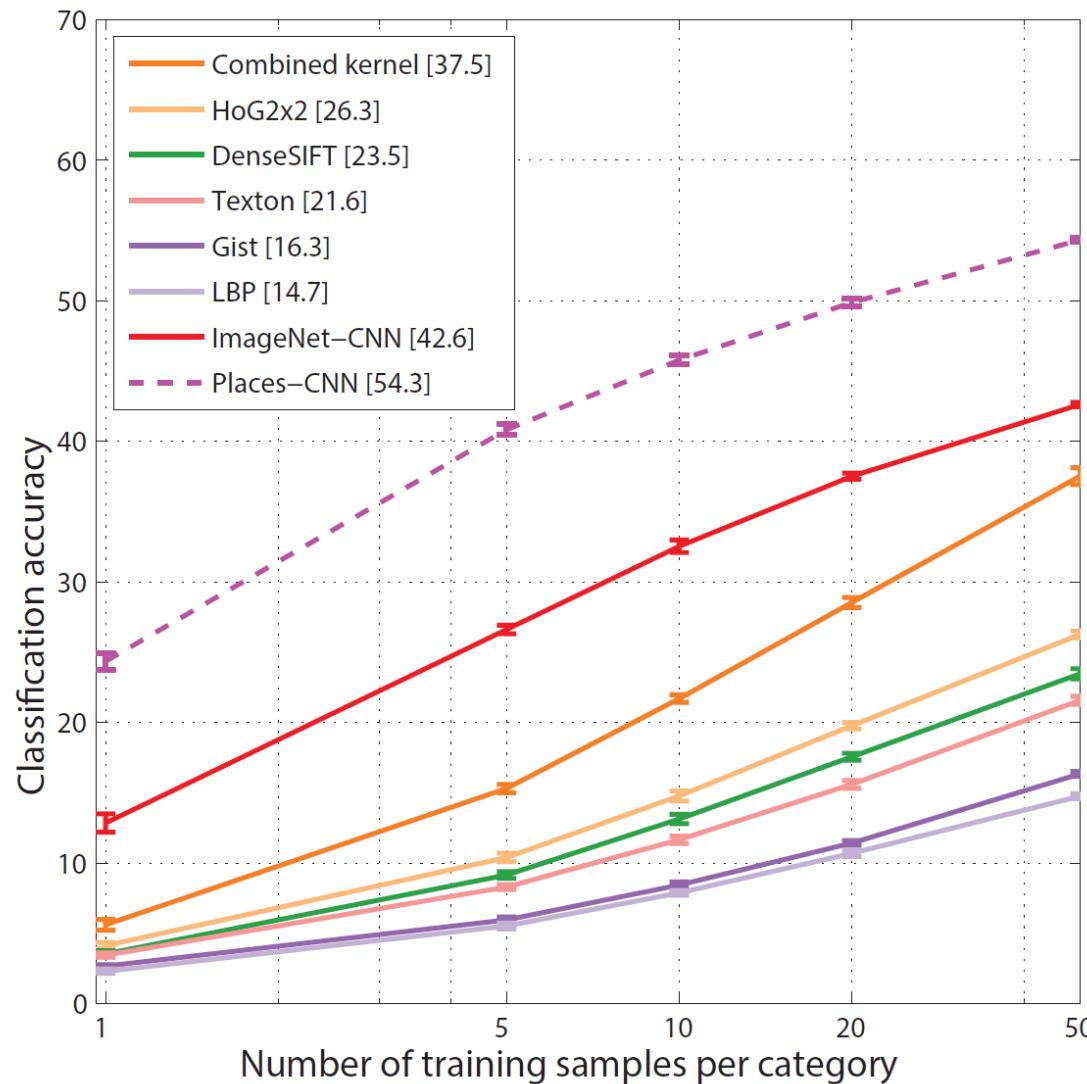
Additional details available:

SUN Database: Large-scale Scene Recognition from Abbey to Zoo. Jianxiong Xiao, James Hays, Krista A. Ehinger, Aude Oliva, Antonio Torralba.
CVPR 2010.

How do we do better than 40%?

- Features from deep learning on ImageNet get 42%
- Fisher vector encoding gets up to 47.2%

Benchmark on SUN397 Dataset



B. Zhou, A. Lapedriza, J. Xiao, A. Torralba, and A. Oliva. "Learning Deep Features for Scene Recognition using Places Database." Advances in Neural Information Processing Systems 27 (NIPS), 2014