

NING-HSU WANG

No.101, Section.2, Kuang-Fu Road, Hsinchu, Taiwan 30013, R.O.C
albert100121@gapp.nthu.edu.tw◇ <https://albert100121.github.io/>

ABOUT ME

A master/research student at NTHU, Vision Science Lab (VSLab) advised by Prof. Min Sun.

Research Interest: Computer Vision, Machine Learning, Deep Learning

Current Research Topics: Computer Vision, Stereo Matching, Depth Estimation, 3D Reconstruction

EDUCATION

National Tsing Hua University

January 2018 - Present

Master in Electrical Engineering

GPA: 4.3/4.3

National Chiao Tung University

Sep 2013 - June 2017

Bachelor in Mechanical Engineering

GPA: 3.41/4.0, Last 60: 3.67/4.0, Ranking: 13/49, 25/99

PUBLICATIONS

360SD-Net: 360° Stereo Depth Estimation with Learnable Cost Volume

- **Ning-Hsu Wang**, Bolivar Solarte, Yi-Hsuan Tsai, Wei-Chen Chiu, Min Sun

- International Conf. on Computer Vision 2019 (ICCV 2019) Workshop, **Spotlight**

EXPERIENCE

Vision Science Lab, National Tsing Hua University

January 2018 - Present

Research Student

- 360° Stereo Depth Estimation

Young Entrepreneurs of the Future, Epoch Foundation

January 2018 - July 2018

Participant

- YEF Garage Party (Second Place), YEF Elevator Pitch, YEF Workshop

Atos

August 2017

On-site Engineer

- Internet System Maintenance

Tokyo Electron Limited Robot Combat

2017

Participant

Programming Education Product Sales

2014 - 2016

Part Time Sales

- Taipei International Automation Exhibition Sales

- Department Store Clerk

NCKU Badminton Open

2015, 2017, 2018

CSL (College Sports League) Badminton Competition, Mechanical Engineering 2014-2016

CSL Badminton Competition, Mechanical Engineering, Northern Taiwan 2013-2016

Hsinchu District Badminton Competition 2015

Umpire and Service Judge

University System of Taiwan, Badminton Invitation Competition

2014

Website Management and Promotion

NCTU Department Badminton Team

2013-2017

NCTU Piano Club

2014-2017

NCTU Guitar Club

2013

PROJECTS

- 360° Stereo Depth Estimation and 3D Reconstruction** *January 2018 - Present*
- Python
- Deep Learning Application on Pytorch
- Design of Logistic UAV (Unmanned Aerial Vehicle)** *2017*
- UAV Surveillance
- Wireless Unloading Motor Control
- Unloading Mechanism Design
- Body Design
- Implementation of *The Lambda Method for Integer Ambiguity Estimation*** *2016*
- Matlab Simulation
- Object Searching Robot Design** *2016*
- Labview
- Ultrasonic Avoidance Design
- Image Processing
- Motor Control

ABILITIES AND CERTIFICATIONS

Programming	C/C++, Python, Assembly, HTML, CSS
DL Framework	Pytorch, TensorFlow
Software & Tools	Industrial Control & Simulation: Labview Mathematics Simulation: Matlab Electrical Circuit Simulation: LTSpice Computational Fluid Dynamics Simulation: ANSYS-Fluent Computer-aided Design Drafting Software: AutoCAD, Solidworks
Hardware	Arduino, 8051
Misc.	OpenCV, Github, Vim, Linux, L^AT_EX
Language	Fluent in Mandarin (Native) Proficient in English, TOEIC Golden Certification (Score: 900) Elementary Proficiency in Japanese (4 semester)

AWARDS

- International Conf. on Computer Vision 2019 (ICCV 2019) 360 PI Workshop *2019*
- ***Spotlight Paper***
- **360SD-Net: 360° Stereo Depth Estimation with Learnable Cost Volume**
- Young Entrepreneurs of the Future Garage Party, Epoch Foundation *2018*
- *Second Place*
- CSL Badminton Competition, Mechanical Engineering *2016*
- *Team Competition, Third Place*
- CSL Badminton Competition, Mechanical Engineering, Northern Taiwan *2015*
- *Team Competition, Third Place*
- NCTU Sports Competition, Shot put *2016*
- *Fourth Place*
- The Best High School Service Team of Taipei *2012*