```
dreven_pendul.py
                        Thu Mar 25 17:38:22 2021
import numpy as np
import matplotlib.pyplot as plt
import scipy.stats as ss
import scipy.optimize as scp
import os
import csv
exec(open('Kalibrering/kalibrering.py').read())
exec(open('../Scripts/Statistik.py').read())
exec(open('../Scripts/data_renser.py').read())
exec(open('../Scripts/chi_sq.py').read())
# fig, ax = plt.subplots(4, 3, figsize = (20, 12))
\# ax = ax.ravel()
fig, ax = plt.subplots(figsize = (16,8))
names = ['0_681', '0_755', '0_805', '0_863', '1_036', '1_091', '1_126', '1_162',
         '1_232', '1_270', '1_319', '1_452']
freks = np.array([0.681, 0.755, 0.805, 0.863, 1.036, 1.091, 1.126, 1.162,
                  1.232, 1.270, 1.319, 1.452])*2*np.pi
driv_freks = freks / (2*np.pi)
A = []
err_A = []
for i in range(len(names)):
    print(i)
    sol1 = Data('Kalibrering/frek' + names[i])
    sp\tilde{A}|nding = soll.points
    ts = sol1.t*1000
    vink = vinkel(sp\tilde{A}|nding, *kali)*(360/(2*np.pi))
    \# ax[i].plot(ts, vink, 'ro', alpha = 0.4, markersize = 4)
    error = propagation_function(spA|nding, vinkel, list(kali), pcov)
    def sinus(t, *p):
        A = p[0]
        w = p[1]
        k = p[2]
        d = p[3]
        return (A*np.cos(w*t+k)+d)
    guess = [(max(vink)-0.8)/2, freks[i], 0.4, 0.8]
   popt, pcov2 = scp.curve_fit(sinus, ts, vink, guess,
                                 sigma = error, absolute_sigma = True,
                                 bounds = ((0, -10, -10, -10), (3, 10, 10, 10))
    A.append(popt[0])
    err_A.append(np.sqrt(np.diag(pcov2))[0])
def dreven(omega, *p):
    F = p[0]
    omega_0 = p[1]
    b = p[2]
    return F/(np.sqrt(0.585**2*(omega**2 - omega_0**2)**2+b**2*omega**2))
guess = [25, 5, 2]
popt1, pcov1 = scp.curve_fit(dreven, freks, A, guess,
                              sigma = err_A, absolute_sigma = True)
```

```
# chi_sq, p_value = chi_sq(A,
print (popt1)
frekses = np.linspace(0.681, 1.451, 100)*2*np.pi
ax.plot(frekses, dreven(frekses, *popt1), color = 'black')
plot_propagation(frekses, dreven, popt1, pcov1, ax)
ax.errorbar(freks, A, err_A, fmt = 'o', color = 'red')
ax.plot(freks, A, 'k--')
# chisq, pval = chi_sq(np.array(freks),
                       np.array(A),
#
                       np.array(err_A),
#
                       dreven,
#
                       popt1,
                       len(A) - len(popt1))
om_0 = round(np.sqrt(np.diag(pcov1))[1],4)
ax.set_title('Dreven Oscillation'# + '$\chi$ = {}'.format(chisq)
             # + ' $p$ = '.format(pval),
                 $\omega_0$ = {} +- {}'.format(round(popt1[1],2), om_0),
             fontsize = 18)
ax.set_xlabel('frekvens', fontsize = 16)
ax.set_ylabel('Amplitude', fontsize = 16)
ax.legend()
fig.savefig('Plots/dreven')
fig, ax = plt.subplots(figsize = (16,8))
fors\tilde{A}, g = [1, 2, 3, 4]
ww = [5.32, 5.30, 5.28, 5.25]
ax.plot(forsÃ,g, ww, 'bo', label = 'mÃ¥lte $\omega_0$')
ax.plot(5, 6.03, 'ro', label = 'forudset $\omega_0$')
ax.set_title('Sammenligning af $\omega_0$', fontsize = 18)
ax.set_xlabel('forsÃ,g', fontsize = 16)
ax.set_ylabel('\omega_0', fontsize = 16)
ax.legend()
fig.savefig('Plots/dreven_res')
plt.show()
```