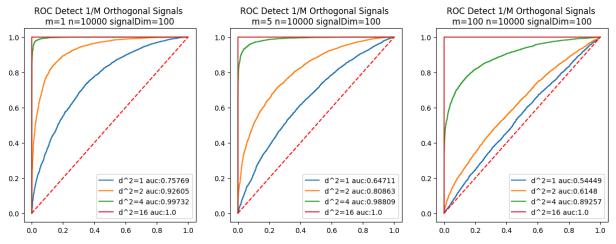
### 1a) 1/M orthogonal signals (any exists)

```
In [ ]: import numpy as np
        import matplotlib.pyplot as plt
        from sklearn import metrics
        # M = num signals to generate
        # N = dimension of signals
        def generate_orthogonal_signals(M, N):
            signals = np.random.normal(size=(M, N))
            orthogonal_signals = np.zeros((M, N))
            for i in range(M):
                 orthogonal_signals[i] = signals[i]
                 for j in range(i):
                    orthogonal_signals[i] -= np.dot(orthogonal_signals[j], signals[i]) / np
                 # Normalize the signal
                 orthogonal_signals[i] /= np.linalg.norm(orthogonal_signals[i])
            priors = np.random.dirichlet(np.ones(M), size=1)
            return orthogonal_signals, priors
        def calcPdPfa(data):
            h1s = data[data[:,1] == 1].shape[0]
            h0s = data[data[:,1] == 0].shape[0]
            currh1 = h1s
            currh0 = h0s
            pd = [1]
            pfa = [1]
            if h0s == 0:
                 pfa.append(0)
                 pd.append(1)
            if h1s == 0:
                pfa.append(1)
                 pd.append(0)
            for i in data:
                if i[1] == 1:
                    currh1 -= 1
                 elif i[1] == 0:
                    currh0 -= 1
                 pfa.append(0 if h0s == 0 else currh0/h0s)
                 pd.append(0 if h1s == 0 else currh1/h1s)
            pd.append(0)
            pfa.append(0)
            return pd,pfa
```

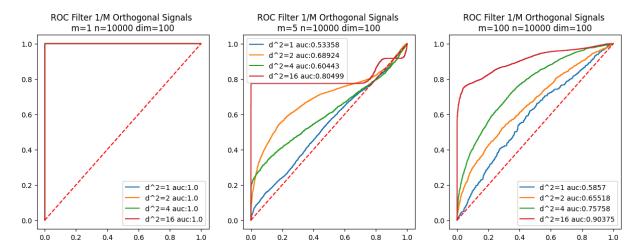
```
In [ ]: np.random.seed(seed=0)
M = [1,5,100]
```

```
d2 = [1,2,4,16]
E = 1
signalDim = 100
n = 10000
def detect_1_M(x, noise_variance, m_orthogonal_signals):
    prodSum = E/noise_variance * (x @ m_orthogonal_signals.T)
    # print("prodsum",prodSum)
    exp = np.exp(prodSum)
    # print("exp",exp)
    lambdaa = (1/m) * np.sum(exp, axis=1)
    # print("Lambda", Lambdaa)
    return lambdaa
fig, ax = plt.subplots(1,len(M), figsize=(15,5))
for i,m in enumerate(M):
    for d in d2:
        noise_variance = E/d
        m_orthogonal_signals, _ = generate_orthogonal_signals(m, signalDim)
        rand m = np.random.choice(m, n//2)
        h1 = m_orthogonal_signals[rand_m] + np.random.normal(0, noise_variance, siz
        h0 = np.random.normal(0, noise_variance, size=(n//2, signalDim))
        decisionStats = np.ndarray((n,2))
        decisionStats[n//2:,0] = detect_1_M(h0, noise_variance, m_orthogonal_signal
        decisionStats[n//2:,1] = 0
        decisionStats[:n//2,0] = detect_1_M(h1, noise_variance, m_orthogonal_signal
        decisionStats[:n//2,1] = 1
        decisionStats = decisionStats[decisionStats[:, 0].argsort()]
        pd,pfa = calcPdPfa(decisionStats)
        auc = metrics.auc(pfa,pd)
        ax[i].plot(pfa,pd, label=f"d^2={d} auc:{round(auc,5)}")
        ax[i].legend()
        ax[i].set_title(f"ROC Detect 1/M Orthogonal Signals \nm={m} n={n} signalDim
    ax[i].plot([0, 1], [0, 1], 'r--')
plt.show()
```



# 1b) 1/M orthogonal signals (which one exists)

```
In [ ]: # np.random.seed(seed=0)
        M = [1,5,100]
        d2 = [1,2,4,16]
        E = 1
        signalDim = 100
        n = 10000
        def filter_1_M(x, priors, m_orthogonal_signals):
            # print(x[0])
            # print("ortho",m_orthogonal_signals)
            dotprod = (x @ m_orthogonal_signals.T)
            # print("dotprod",dotprod[0])
            weighted dotprod = dotprod * priors
            # print(weighted_dotprod)
            result = np.argmax(weighted_dotprod, axis=1)
            # print("res", result)
            lambdaa = weighted_dotprod[np.arange(weighted_dotprod.shape[0]), result]
            # print("lambda", lambdaa)
            return lambdaa, result
        fig, ax = plt.subplots(1,len(M), figsize=(15,5))
        for i,m in enumerate(M):
            for d in d2:
                 noise variance = E/d
                m_orthogonal_signals, priors = generate_orthogonal_signals(m, signalDim)
                 rand_m = np.random.choice(m, n)
                 signals = m_orthogonal_signals[rand_m] + np.random.normal(0, noise_variance
                 decisionStats = np.ndarray((n,2))
                 lambdaa,result = filter_1_M(signals, priors, m_orthogonal_signals)
                 # print(rand m)
                 # print(np.where(rand_m==result,1,0))
                 decisionStats[:,0] = lambdaa
                 decisionStats[:,1] = np.where(rand_m==result,1,0)
                 decisionStats = decisionStats[decisionStats[:, 0].argsort()]
                 pd,pfa = calcPdPfa(decisionStats)
                 auc = metrics.auc(pfa,pd)
                 ax[i].plot(pfa,pd, label=f"d^2={d} auc:{round(auc,5)}")
                 ax[i].legend()
                 ax[i].set\_title(f"ROC Filter 1/M Orthogonal Signals \\nm={m} n={n} dim={sign}
            ax[i].plot([0, 1], [0, 1], 'r--')
        plt.show()
```



#### 2) SKEP

```
In [ ]: np.random.seed(seed=0)
        D2 = [1,2,4,16]
        E = 1
        FREQ = 10
        K=10
        N = 1000
        T = np.linspace(0, 2 * np.pi, K)
        def simulate(signal, ax, title, filter):
            ret = []
            for d in D2:
                 noise_variance = E/d
                 h1 = signal + np.random.normal(0, noise_variance, size=(N//2, K))
                 h0 = np.random.normal(0, noise_variance, size=(N//2, K))
                 decisionStats = filter(h1, h0)
                 decisionStats = decisionStats[decisionStats[:, 0].argsort()]
                 pd,pfa = calcPdPfa(decisionStats)
                 auc = metrics.auc(pfa,pd)
                 ax.plot(pfa,pd, label=f"d^2={d} auc:{round(auc,5)}")
                 ret.append(auc)
            ax.legend()
            ax.set_title(title)
            ax.plot([0, 1], [0, 1], 'r--')
            return ret
        def ske(signal, ax, title):
            def filter(h1, h0):
                 decisionStats = np.ndarray((N,2))
                 decisionStats[:N//2,0] = h1 @ signal.T
                 decisionStats[:N//2,1] = 1
                 decisionStats[N//2:,0] = h0 @ signal.T
```

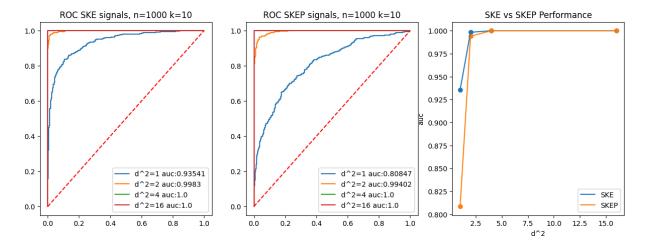
```
decisionStats[N//2:,1] = 0
        return decisionStats
    return simulate(signal,ax,title,filter)
def skep(signal, amp, ax, title):
   def filter(h1, h0):
        decisionStats = np.ndarray((N,2))
        decisionStats[:N//2,0] = np.power(np.sum(h1*amp*np.cos(FREQ * T), axis=1),2
        decisionStats[:N//2,1] = 1
        decisionStats[N//2:,0] = np.power(np.sum(h0*amp*np.cos(FREQ * T), axis=1),2
        decisionStats[N//2:,1] = 0
        return decisionStats
    return simulate(signal,ax,title,filter)
def skea(signal, phase, ax, title):
   def filter(h1, h0):
        decisionStats = np.ndarray((N,2))
        decisionStats[:N//2,0] = np.sum(h1*np.sin(FREQ * T + phase), axis=1)
        decisionStats[:N//2,1] = 1
        decisionStats[N//2:,0] = np.sum(h0*np.sin(FREQ * T + phase), axis=1)
        decisionStats[N//2:,1] = 0
        return decisionStats
   return simulate(signal,ax,title,filter)
def compareROC(data,ax, title):
   for label, d in data.items():
        ax.plot(D2, d, label=label)
        ax.scatter(D2, d)
   ax.set_xlabel("d^2")
   ax.set_ylabel("auc")
   ax.set_title(title)
   ax.legend()
```

```
In []: np.random.seed(seed=0)

unknownPhase = np.random.uniform(0, 2*np.pi)
amp = 1
signal = amp * np.sin(FREQ * T + unknownPhase)

fig, ax = plt.subplots(1,3,figsize=(15,5))
data = {}
data['SKE'] = ske(signal,ax[0], f"ROC SKE signals, n={N} k={K}")
data['SKEP'] = skep(signal, amp, ax[1], f"ROC SKEP signals, n={N} k={K}")

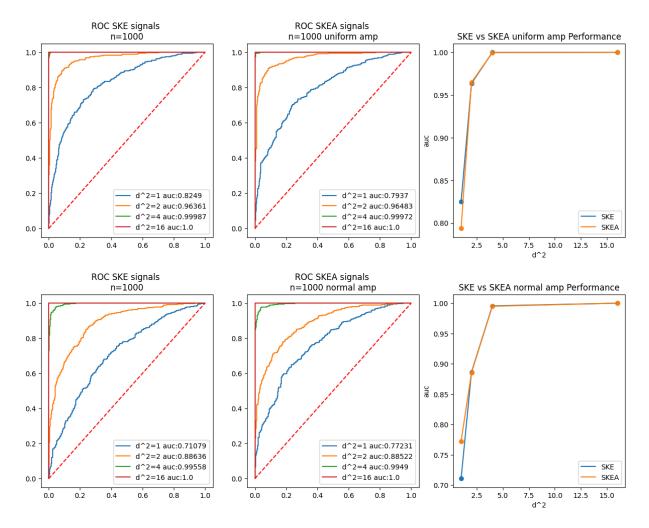
compareROC(data, ax[2], "SKE vs SKEP Performance")
plt.show()
```



The ROC for SKEP and SKE show that performance decreases when there are more unknowns, which is expected. As  $d^2$  decreases, noise variance increases, so the performance of SKE and SKEP decrease. However, SKEP performance gets worse faster than SKE.

#### 3) SKEA

```
In [ ]: np.random.seed(seed=0)
        # uniform amp
        unknownAmp = np.random.uniform(0,1)
        phase = np.random.uniform(0, 2*np.pi)
        signal = unknownAmp * np.sin(FREQ * T + phase)
        fig, ax = plt.subplots(1,3,figsize=(15,5))
        data = \{\}
        data['SKE'] = ske(signal, ax[0], f"ROC SKE signals \nn={n}")
        data['SKEA'] = skea(signal, phase, ax[1], f"ROC SKEA signals \nn={n} uniform amp")
        compareROC(data, ax[2],"SKE vs SKEA uniform amp Performance")
        plt.show()
        # normal amp
        unknownAmp = abs(np.random.normal(0,1))
        phase = np.random.uniform(0, 2*np.pi)
        signal = unknownAmp * np.sin(FREQ * T + phase)
        fig, ax = plt.subplots(1,3,figsize=(15,5))
        data = \{\}
        data['SKE'] = ske(signal, ax[0], f"ROC SKE signals \nn={n}")
        data['SKEA'] = skea(signal, phase, ax[1],f"ROC SKEA signals \nn={n} normal amp")
        compareROC(data, ax[2],"SKE vs SKEA normal amp Performance")
        plt.show()
```



Like SKEP, the ROC for SKEA and SKE show that performance decreases when there are more unknowns, which is expected. As  $d^2$  decreases, noise variance increases, so the performance of SKE and SKEA decrease. When we assume that the unknown amplitude is drawn from a uniform[0,1] distribution, performance is only worse than the SKE case when  $d^2=1$ . When we assume that the unknown amplitude is drawn from a Normal[0,1] distribution, performance only really differs from the SKE case when  $d^2=1$ , but this time the performance is better, with AUC for the SKE case being 0.71 compared to the AUC for the SKEA case being 0.77.

## All together

```
In []: np.random.seed(seed=0)

amp = np.random.uniform(0.0,1.0)
phase = np.random.uniform(0, 2*np.pi)
signal = amp * np.sin(FREQ * T + phase)

fig, ax = plt.subplots(1,3,figsize=(15,5))
data = {}
data['SKE'] = ske(signal, ax[0], f"ROC SKE signals \nn={N}, k={K}")
data['SKEA'] = skea(signal, phase, ax[1],f"ROC SKEA signals \nn={N}, k={K}")
```

```
data['SKEP'] = skep(signal, amp, ax[2],f"ROC SKEP signals \nn={N}, k={K}")
plt.show()

fig, ax = plt.subplots()
compareROC(data, ax,"SKE vs SKEP vs SKEA Performance")
plt.show()
```

