Reasoning with Many-Valued Interval Temporal Logic

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Introduction

Motivation

- Real-world scenarios involve uncertainty and temporal information
- Example:
 - Patient exhibits symptoms of "depressed mood" and "insomnia"
 - Symptoms:
 - Vary in intensity over time
 - Meet during certain intervals
 - Need to model:
 - Degrees of symptom severity
 - Temporal relationships between symptoms
- Traditional binary logic is insufficient for modeling such complexities

Limitations of Classical Logic

- Binary truth values (true or false)
- Cannot represent partial truths or degrees of certainty
- Difficult to model temporal relationships with uncertainty

Many-Valued Logics

- Handle partial truths and uncertainty
- Extend beyond the binary truth values of classical logic
- Examples:
 - Łukasiewicz logic
 - Gödel logic
 - Product logic
 - Intuitionistic logic

Interval Temporal Logic

- Focuses on reasoning over time intervals rather than time points
- Uses Allen's interval relations:
 - Before, During, Overlaps, Meets, etc.
- Useful for modeling temporal relationships between events

Many-Valued Interval Temporal Logic

- **Objective**: Model graded truths over time intervals
- Challenges:
 - Integrating many-valued truth with temporal relations
 - Developing reasoning systems to handle complexity

Our Contribution

- Developed a sound and complete tableau system for many-valued interval temporal logic
- ullet Based on $\mathrm{FL}_{\mathrm{ew}} ext{-algebras}$ to handle graded truth values
- Practical implementation for real-world applicability

Presentation Overview

Introduction

Preliminaries

Many-Valued Halpern and Shoham's Logic (MVHS)

Tableau System: Theory and Implementation

Experiments and Results

Conclusions and Future Work

Preliminaries

Halpern and Shoham's Interval Temporal Logic (HS)

- HS is a modal logic for reasoning about time intervals
- Uses modalities corresponding to Allen's interval relations
- Allows expression of **temporal relationships** between intervals
- Widely used in temporal reasoning, representation, and planning within Al



(a) Joseph Halpern.



(b) Yoav Shoham.

Allen's Interval Relations

relation	definition	example
		x y
after	$R_A([x,y],[w,z]) = (y,w)$	w z
later	$R_L([x,y],[w,z]) = \langle (y,w)$	W Z
begins	$R_B([x,y],[w,z]) = (x,w) \wedge < (z,y)$	w z ⊢⊢i
ends	$R_E([x,y],[w,z]) = \langle (x,w) \wedge = (y,z)$	w ż
during	$R_D([x,y],[w,z]) = \langle (x,w) \wedge \langle (z,y) \rangle$	w z ├────
overlaps	$R_O([x,y],[w,z]) = \langle (x,w) \wedge \langle (w,y) \rangle \langle (y,z)$	w z

Table 1: Allen's interval relations.

Limitations of Classical HS

- HS is based on classical (binary) logic
 - Propositions and temporal relations are either true or false
- Cannot handle:
 - Graded truths (partial truth values)
 - Uncertainty or imprecision
- Inadequate for modeling real-world scenarios with partial information

$\mathrm{FL}_{\mathrm{ew}} ext{-}\mathsf{Algebras}$

 \bullet FL_{ew}-algebras [6]

$$\textbf{\textit{A}} = \langle \textit{A}, \cap, \cup, \cdot, +, 0, 1 \rangle$$

are defined over **bounded integral commutative residuated lattices**

- A is the algebra's domain
- ⟨A, ∩, ∪, 0, 1⟩ represents a bounded complete lattice with upper bound 1 and lower bound 0
- $\langle A, \preceq \rangle$ corresponds to its lattice-ordered set $(\alpha \preceq \beta \text{ iff } \alpha = \alpha \cap \beta)$
- $\langle A,\cdot,1\rangle$ and $\langle A,+,0\rangle$ are **commutative monoids**, namely **t-norm** and **t-co-norm**, with both operations being monotone for \preceq (if $\gamma \preceq \alpha$ and $\delta \preceq \beta$, then $\gamma \cdot \delta \preceq \alpha \cdot \beta$ and $\gamma + \delta \preceq \alpha + \beta$)
- ullet We also define an **implication** operation \hookrightarrow

$$\alpha \hookrightarrow \beta = \sup\{\gamma \mid \alpha \cdot \gamma \preceq \beta\}.$$

A is a chain if ≤ is a total order; standard if A = [0,1] ⊂ R; finite
if A is finite. We will focus on finite FL_{ew}-algebras.

Example: Simple FL_{ew} -Algebra (G3)

- Set of truth values: $A = \{0, \alpha, 1\}$ with $0 < \alpha < 1$
- Operations defined as:
 - t-norm (·):

$$a \cdot b = \min(a, b)$$

• t-co-norm (+):

$$a + b = \max(a, b)$$

• implication (\hookrightarrow) :

$$a \hookrightarrow b = \begin{cases} 1 & \text{if } a \leq b \\ b & \text{otherwise} \end{cases}$$

- Calculation example:
 - $\alpha \cdot 1 = \min(\alpha, 1) = \alpha$
 - $\alpha + 1 = \max(\alpha, 1) = 1$
 - $\alpha \hookrightarrow 1 = 1$ since $\alpha \prec 1$



Figure 2: Lattice representing the order between the values in the designated ${\rm FL}_{\rm ew}$ -algebra.

Relation to Other Algebras

- $\bullet~FL_{ew}\mbox{-algebras}$ encompass several known algebras:
 - Gödel algebras
 - MV algebras
 - Product algebras
 - Heyting algebras
- Generalization allows for unified treatment
- Visual hierarchy:

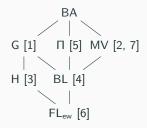


Figure 3: A partial taxonomy of well-known truth value algebras.

Many-Valued Halpern and

Shoham's Logic (MVHS)

Syntax of MVHS

- Propositional letters: p, q, r, ...
- Truth constants: $\alpha \in A$ (elements of the FL_{ew} -algebra)
- Logical binary connectives
 - Conjunction: ∧
 - Disjunction: V
 - Implication: →
- Unary modalities
 - $\langle X \rangle \varphi$ (there exists an interval related by X where φ holds)
 - $[X]\varphi$ (for all intervals related by X, φ holds)
- Formulas are built inductively using these elements

Many-Valued Linear Orderings and Strict Intervals

Many-valued linear orders

$$\widetilde{\mathbb{D}} = \langle D, \widetilde{<}, \widetilde{=} \rangle$$

- D is the domain
- $\widetilde{<}, \widetilde{=}: D \times D \to A$ are two functions mapping pairs of domain values to A of a $\mathrm{FL}_{\mathrm{ew}}$ -algebra A satisfying
 - 1. $\cong (x, y) = 1$ iff x = y
 - 2. $\cong (x, y) = \cong (y, x)$
 - 3. $\tilde{<}(x,x)=0$
 - 4. $\widetilde{<}(x,z) \succeq \widetilde{<}(x,y) \cdot \widetilde{<}(y,z)$
 - 5. if $\widetilde{<}(x,y) \succ 0$ and $\widetilde{<}(y,z) \succ 0$, then $\widetilde{<}(x,z) \succ 0$
 - 6. if $\widetilde{\leq}(x,y)=0$ and $\widetilde{\leq}(y,x)=0$, then $\widetilde{\equiv}(x,y)=1$
 - 7. if \cong (x, y) \succ 0, then \approx (x, y) \prec 1
- Many-valued strict intervals $\mathbb{I}(\widetilde{\mathbb{D}}) = \{[x,y] \mid \widetilde{<}(x,y) \succ 0\}$

Many-Valued Allen's Relations

relation	definition	example
		<i>x y y y z</i>
after	$R_A([x,y],[w,z]) = (y,w)$	w z
later	$R_L([x,y],[w,z]) = \langle (y,w)$	W Z
begins	$R_B([x,y],[w,z]) = (x,w) \wedge < (z,y)$	w z
ends	$R_E([x,y],[w,z]) = \langle (x,w) \wedge = (y,z)$	\vdash
during	$R_D([x,y],[w,z]) = \langle (x,w) \wedge \langle (z,y) \rangle$	W Z
overlaps	$R_O([x,y],[w,z]) = \langle (x,w) \wedge \langle (w,y) \wedge \langle (y,z) \rangle$	W Z

Table 2: Allen's interval relations.

Many-Valued Allen's Relations

relation	definition	example
		x y
after	$\widetilde{R}_A([x,y],[w,z]) = \widetilde{\Xi}(y,w)$	w z
later	$\widetilde{R}_L([x,y],[w,z]) = \widetilde{<}(y,w)$	W Z ⊢
begins	$\widetilde{R}_B([x,y],[w,z]) = \widetilde{\Xi}(x,w) \cdot \widetilde{\Xi}(z,y)$	W Z
ends	$\widetilde{R}_{E}([x,y],[w,z]) = \widetilde{<}(x,w) \cdot \widetilde{=}(y,z)$	w z
during	$\widetilde{R}_D([x,y],[w,z]) = \widetilde{<}(x,w) \cdot \widetilde{<}(z,y)$	w z
overlaps	$\widetilde{R}_O([x,y],[w,z]) = \widetilde{<}(x,w) \cdot \widetilde{<}(w,y) \cdot \widetilde{<}(y)$	v,z) w z

Table 2: Many-valued Allen's interval relations.

Semantics of MVHS

- Many-valued interval models $\widetilde{M} = \langle \mathbb{I}(\widetilde{\mathbb{D}}), \widetilde{V} \rangle$
 - Valuation function \widetilde{V} : Assigns truth values from A to formulas at intervals
- Atoms:
 - $\widetilde{V}(p,[x,y]) \in A$
 - $\widetilde{V}(\alpha,[x,y]) = \alpha \in A$
- Logical connectives:
 - $\widetilde{V}(\varphi \wedge \psi, [x, y]) = \widetilde{V}(\varphi, [x, y]) \cdot \widetilde{V}(\psi, [x, y])$
 - $\widetilde{V}(\varphi \lor \psi, [x, y]) = \widetilde{V}(\varphi, [x, y]) + \widetilde{V}(\psi, [x, y])$
 - $V(\varphi \to \psi, [x, y]) = V(\varphi, [x, y]) \hookrightarrow V(\psi, [x, y])$
- Modalities:
 - $\widetilde{V}(\langle X \rangle \varphi, [x, y]) = \bigcup_{[w,z] \in \mathbb{I}(\widetilde{\mathbb{D}})} (\widetilde{R}_X([x, y], [w, z]) \cdot \widetilde{V}(\varphi, [w, z]))$
 - $\widetilde{V}([X]\varphi,[x,y]) = \bigcap_{[w,z]\in\mathbb{I}(\widetilde{\mathbb{D}})} (\widetilde{R}_X([x,y],[w,z]) \hookrightarrow \widetilde{V}(\varphi,[w,z]))$

Satisfiability and Validity

• A formula φ is α -satisfied at [x,y] in \widetilde{M} if and only if

$$\widetilde{V}(\varphi,[x,y])\succeq\alpha$$

- A formula is α -satisfiable if and only if an interval exists in a multi-valued interval model where is α -satisfed
- A formula is α -valid if and only if it is α -satisfiable at every interval in every multi-valued interval model
- A formula is valid if and only if it is 1-valid

Application Example: Medical Diagnosis

- Scenario:
 - Patient exhibits symptoms:
 - "Depressed mood" (p)
 - "Insomnia" (q)
 - Symptoms vary in intensity over intervals
 - Algebra's domain $A = [0,1] \subset \mathbb{R}$
- Goal: Determine the degree to which an interval of "depressed mood" meets a period of "insomnia"
- Formula:

$$\varphi = p \wedge \langle A \rangle q$$

Evaluating the Example

Assign truth values:

- $\widetilde{V}(p, [x, y]) = 0.7$ • $\widetilde{V}(q, [w, z]) = 0.8$ • $\widetilde{R}_A([x, y], [w, z]) = \widetilde{=}(y, w) = 0.9$
- Then:

$$\widetilde{V}(\varphi,[x,y]) = \widetilde{V}(p \wedge \langle A \rangle q, [x,y])$$

$$= \widetilde{V}(p,[x,y]) \cdot \widetilde{V}(\langle A \rangle q, [x,y])$$

$$= 0.7 \cdot \widetilde{R}_{A}([x,y], [w,z]) \cdot \widetilde{V}(q, [w,z])$$

$$= 0.7 \cdot 0.9 \cdot 0.8$$

$$= 0.504$$

Interpretation and Benefits

• Result:

$$\widetilde{V}(\varphi,[x,y]) = 0.504$$

- Interpretation: It is not always the case that a period of "depressed mood" is followed by a period of "insomnia," but we can say that it happens in a non-negligible manner
- Benefits of MVHS:
 - Models graded truths over time intervals
 - Handles uncertainty and partial information
 - Provides quantitative insights into temporal relationships
 - Applicable to various real-world scenarios in AI

Tableau System: Theory and

Implementation

Need for a Tableau System

- Challenges in reasoning with MVHS
 - Many-valued truth values increase the complexity
 - Temporal modalities over intervals add to the intricacy
- Objective
 - Develop a systematic method for determining satisfiability and validity
 - Ensure soundness and completeness
- \bullet Solution: Fitting's style tableau system adapted for MVHS over finite $\mathrm{FL}_\mathrm{ew}\text{-}\mathsf{algebras}$

Overview of the Tableau Structure

Tree-like structure with nodes and branches



Figure 4: An example.

• Each node is associated with a decoration

$$Q(\beta \leq \psi, [x, y], \widetilde{\mathbb{D}})$$
 or $Q(\psi \leq \beta, [x, y], \widetilde{\mathbb{D}})$

- Q is a **truth judgment** either T (true) or F (false)
- $\beta \in A$ is a truth value from the FL_{ew} -algebra
- $\psi \in sub(\varphi)$ is a sub-formula of φ
- [x, y] is an interval
- $\widehat{\mathbb{D}}$ is a many-valued linear order
- Branches represent possible evaluations and are associated with a finite many-valued linear order

Overview of the Tableau Procedure

- **Purpose:** Systematically explore possible valuations to determine:
 - Satisfiability: If starting from $T(\alpha \leq \varphi)$ it finds an open branch (SAT-tableau), or
 - Validity: If starting from $F(\alpha \leq \varphi)$ it closes all branches (VAL-tableau)
- Expansion and branching: Systematically apply expansion rules to generate new nodes
- Closure: Close branches that contain contradictions using branch closing rules
- Termination
 - If all branches are closed, the formula is unsatisfiable
 - If at least one open branch remains, a satisfying model exists

Expansion Rules: Reverse

$$(T \succeq) \frac{T(\beta \preceq \psi, [x, y], \widetilde{\mathbb{D}})}{F(\psi \preceq \gamma, [x, y], c(B))}$$
 where $\beta \neq 0$ and γ is any maximal element not above β , i.e., $\gamma \not\succeq \beta$

$$(F \succeq) \frac{F(\beta \preceq \psi, [x,y], \widetilde{\mathbb{D}})}{T(\psi \preceq \gamma_i, [x,y], c(B)) \mid \ldots \mid T(\psi \preceq \gamma_n, [x,y], c(B))}$$
 where $\beta \neq 0$ and $\gamma_1, \ldots, \gamma_n$ are all maximal elements not above β , i.e., $\gamma_1, \ldots, \gamma_n \not\succeq \beta$

Figure 5: Reverse rules (1).

Expansion Rules: Reverse

$$(T \preceq) \frac{T(\psi \preceq \beta, [x, y], \widetilde{\mathbb{D}})}{F(\gamma \preceq \psi, [x, y], c(B))}$$
 where $\beta \neq 1$ and γ is any minimal element not below β , i.e., $\gamma \not\preceq \beta$

$$(F \preceq) \frac{F(\psi \preceq \beta, [x,y], \widetilde{\mathbb{D}})}{T(\gamma_i \preceq \psi, [x,y], c(B)) \mid \ldots \mid T(\gamma_i \preceq \psi, [x,y], c(B))}$$
 where $\beta \neq 1$ and $\gamma_1, \ldots, \gamma_n$ are all minimal elements not below β , i.e., $\gamma_1, \ldots, \gamma_n \not\preceq \beta$

Figure 6: Reverse rules (2).

Expansion Rules: Propositional

$$(T\wedge) \frac{T(\beta \preceq (\psi \wedge \xi), [x,y], \widetilde{\mathbb{D}})}{T(\beta_1 \preceq \psi, [x,y], c(B)) \mid \ldots \mid T(\beta_n \preceq \psi, [x,y], c(B))}$$

$$T(\gamma_1 \preceq \xi, [x,y], c(B)) \mid \ldots \mid T(\gamma_n \preceq \xi, [x,y], c(B))$$
where $\beta \neq 0$, $(\beta_i, \gamma_i) \in \mathbf{A} \times \mathbf{A}$ so that $\beta \preceq \beta_i \cdot \gamma_i$ and there is no other $(\beta_i', \gamma_i') \in \mathbf{A} \times \mathbf{A}$ such that $\beta \preceq \beta_i' \cdot \gamma_i', \beta_i' \preceq \beta_i$ and $\gamma_i' \preceq \gamma_i$.

$$(F\wedge) \frac{F(\beta \preceq (\psi \wedge \xi), [x,y], \widetilde{\mathbb{D}})}{T(\psi \preceq \beta_1, [x,y], c(B)) \mid \ldots \mid T(\psi \preceq \beta_n, [x,y], c(B))}$$

$$T(\xi \preceq \gamma_1, [x,y], c(B)) \mid \ldots \mid T(\xi \preceq \gamma_n, [x,y], c(B))$$
where $\beta \neq 0$, $(\beta_i, \gamma_i) \in \mathbf{A} \times \mathbf{A}$ so that $\beta \npreceq \beta_i \cdot \gamma_i$ and there is no other $(\beta_i', \gamma_i') \in \mathbf{A} \times \mathbf{A}$ such that $\beta \npreceq \beta_i' \cdot \gamma_i', \beta_i \preceq \beta_i'$ and $\gamma_i \preceq \gamma_i'.$

Figure 7: Propositional rules (1).

Expansion Rules: Propositional

$$(T\vee) \frac{T((\psi\vee\xi)\preceq\beta,[x,y],\widetilde{\mathbb{D}})}{T(\psi\preceq\beta_1,[x,y],c(B))\mid\ldots\mid T(\psi\preceq\beta_n,[x,y],c(B))}$$

$$T(\xi\preceq\gamma_1,[x,y],c(B))\mid\ldots\mid T(\xi\preceq\gamma_n,[x,y],c(B))$$
where $\beta\neq 1$, $(\beta_i,\gamma_i)\in \mathbf{A}\times\mathbf{A}$ so that $\beta_i+\gamma_i\preceq\beta$ and there is no other $(\beta_i',\gamma_i')\in \mathbf{A}\times\mathbf{A}$ such that $\beta_i'+\gamma_i'\preceq\beta,\beta_i\preceq\beta_i'$ and $\gamma_i\preceq\gamma_i'$.

$$(F\vee) \frac{F((\psi\vee\xi)\preceq\beta,[x,y],\widetilde{\mathbb{D}})}{T(\beta_1\preceq\psi,[x,y],c(B))\mid\ldots\mid T(\beta_n\preceq\psi,[x,y],c(B))} \\ T(\gamma_1\preceq\xi,[x,y],c(B))\mid\ldots\mid T(\gamma_n\preceq\xi,[x,y],c(B)) \\ \text{where } \beta\neq1,\ (\beta_i,\gamma_i)\in\textbf{\textit{A}}\times\textbf{\textit{A}} \text{ so that } \beta_i+\gamma_i\nleq\beta \text{ and there is no} \\ \text{other } (\beta_i',\gamma_i')\in\textbf{\textit{A}}\times\textbf{\textit{A}} \text{ such that } \beta_i'+\gamma_i'\nleq\beta,\beta_i'\preceq\beta_i \text{ and } \gamma_i'\preceq\gamma_i.$$

Figure 8: Propositional rules (2).

Expansion Rules: Propositional

$$(T \hookrightarrow) \frac{T(\beta \preceq (\psi \hookrightarrow \xi), [x, y], \widetilde{\mathbb{D}})}{T(\psi \preceq \beta_1, [x, y], c(B)) \mid \ldots \mid T(\psi \preceq \beta_n, [x, y], c(B))}$$

$$T(\gamma_1 \preceq \xi, [x, y], c(B)) \mid \ldots \mid T(\gamma_n \preceq \xi, [x, y], c(B))$$
where $\beta \neq 0$, $(\beta_i, \gamma_i) \in \mathbf{A} \times \mathbf{A}$ so that $\beta \preceq \beta_i \hookrightarrow \gamma_i$ and there is no other $(\beta_i', \gamma_i') \in \mathbf{A} \times \mathbf{A}$ such that $\beta \preceq \beta_i' \hookrightarrow \gamma_i', \beta_i \preceq \beta_i'$ and $\gamma_i' \preceq \gamma_i$.

$$(F \hookrightarrow) \frac{F(\beta \preceq (\psi \hookrightarrow \xi), [x,y], \widetilde{\mathbb{D}})}{T(\beta_1 \preceq \psi, [x,y], c(B)) \mid \ldots \mid T(\beta_n \preceq \psi, [x,y], c(B))}$$

$$T(\xi \preceq \gamma_1, [x,y], c(B)) \mid \ldots \mid T(\xi \preceq \gamma_n, [x,y], c(B))$$

$$\text{where } \beta \neq 0, \ (\beta_i, \gamma_i) \in \textbf{\textit{A}} \times \textbf{\textit{A}} \text{ so that } \beta \npreceq \beta_i \hookrightarrow \gamma_i \text{ and there is no}$$

$$\text{other } (\beta_i', \gamma_i') \in \textbf{\textit{A}} \times \textbf{\textit{A}} \text{ such that } \beta \npreceq \beta_i' \hookrightarrow \gamma_i', \beta_i' \preceq \beta_i \text{ and } \gamma_i \preceq \gamma_i'.$$

Figure 9: Propositional rules (3).

Expansion Rules: Modalities

$$(T\Box) \frac{T(\beta \preceq [X]\psi, [x, y], \widetilde{\mathbb{D}})}{T((\beta \cdot \gamma_1) \preceq \psi, [z_1, t_1], c(B))} \\ \cdots \\ T((\beta \cdot \gamma_n) \preceq \psi, [z_n, t_n], c(B)) \\ T(\beta \preceq [X]\psi, [x, y], c(B)) \\ \text{where } \gamma_i = \widetilde{R}_X([x, y], [z_i, t_i]), [z_i, t_i] \in o(c(B)), \\ \gamma_i \succ 0, \text{ and } \beta \cdot \gamma_i \neq 0 \\ (F\Box) \frac{F(\beta \preceq [X]\psi, [x, y], \widetilde{\mathbb{D}})}{F((\beta \cdot \gamma_1) \preceq \psi, [z_1, t_1], c(B)) \mid \dots \mid F((\beta \cdot \gamma_n) \preceq \psi, [z_n, t_n], c(B))} \\ \text{where } \gamma_i = \widetilde{R}_X([x, y], [z_i, t_i]), [z_i, t_i] \in o(c(B)) \cup n(c(B)), \\ \gamma_i \succ 0, \text{ and } \beta \cdot \gamma_i \neq 0$$

Figure 10: Temporal rules (1).

Expansion Rules: Modalities

$$(T\Diamond) \frac{T(\langle X \rangle \psi \preceq \beta, [x,y], \widetilde{\mathbb{D}})}{T((\psi \preceq (\gamma_1 \hookrightarrow \beta), [z_1, t_1], c(B))} \\ \dots \\ T(\psi \preceq (\gamma_n \hookrightarrow \beta), [z_n, t_n], c(B)) \\ T(\langle X \rangle \psi \preceq \beta, [x,y], c(B)) \\ \text{where } \gamma_i = \widetilde{R}_X([x,y], [z_i, t_i]), [z_i, t_i] \in o(c(B)), \\ \gamma_i \succ 0, \text{ and } \gamma_i \hookrightarrow \beta \neq 1 \\ (F\Diamond) \frac{F(\langle X \rangle \psi \preceq \beta, [x,y], \widetilde{\mathbb{D}})}{F(\psi \preceq (\gamma_1 \hookrightarrow \beta), [z_1, t_1], c(B)) \mid \dots \mid F(\psi \preceq (\gamma_n \hookrightarrow \beta), [z_n, t_n], c(B))} \\ \text{where } \gamma_i = \widetilde{R}_X([x,y], [z_i, t_i]), [z_i, t_i] \in o(c(B)) \cup n(c(B)), \\ \gamma_i \succ 0, \text{ and } \gamma_i \hookrightarrow \beta \neq 1 \\ \end{cases}$$

Figure 11: Temporal rules (2).

Branch Closing Rules

$$(X1) \frac{T(\beta \preceq \gamma, [x, y], \widetilde{\mathbb{D}})}{X} \qquad (X2) \frac{F(\beta \preceq \gamma, [x, y], \widetilde{\mathbb{D}})}{X}$$

$$\text{where } \beta \preceq \gamma \qquad \text{where } \beta \neq 0, \ \gamma \neq 1, \ \text{and } \beta \preceq \gamma$$

$$(X3) \frac{F(0 \preceq \psi, [x, y], \widetilde{\mathbb{D}})}{X} \qquad (X4) \frac{F(\psi \preceq 1, [x, y], \widetilde{\mathbb{D}})}{X}$$

$$(X5) \frac{T(\gamma \preceq \psi, [x, y], \widetilde{\mathbb{D}})}{X} \qquad (X6) \frac{Q(\cdot, \cdot, \widetilde{\mathbb{D}})}{X}$$

$$\text{where } \beta \preceq \gamma \qquad \text{where } \widetilde{\mathbb{D}} \text{ is inconsistent}$$

Figure 12: Branch closing rules.

Example: Tableau Construction

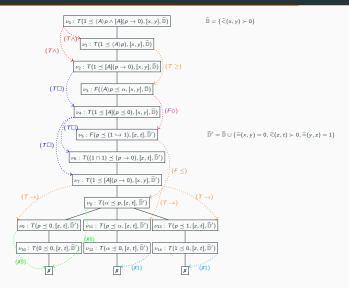


Figure 13: Some closed branches of the tableau for $\langle A \rangle p \wedge [A](p \to 0)$ and $1 \in G3$.

Soundness and Completeness over Finite $\mathrm{FL}_{\mathrm{ew}} ext{-Algebras}$

Soundness

- If a formula φ is α -satisfiable, then there exists an opened tableau for φ and α
- The rules preserve logical consequence

Completeness

- If a tableau is opened for φ and α , then φ is α -satisfiable.
- The method explores all necessary valuations

Implications

- \bullet The tableau system is a reliable decision procedure for MVHS over finite $\mathrm{FL}_\mathrm{ew}\text{-}\mathsf{algebras}$
- Provides a foundation for automated reasoning in MVHS

Implementation Overview

- Programming Language:
 - Julia, chosen for its performance in numerical computations
 - Benefits of Julia:
 - High-level syntax with efficient execution
 - Strong support for mathematical operations
- Open-source Advocacy:
 - Sole.jl (SymbOlic LEarning)¹, a framework for representing, reasoning, and learning from structured and unstructured data
 - SoleReasoners.jl, analytic tableau solvers for α -sat and α -val.
- Representation of Algebras:
 - \bullet Finite $\mathrm{FL}_\mathrm{ew}\text{--algebras}$ defined by specifying:
 - Domain (set of truth values A)
 - Truth tables for \cap , \cup , \cdot , + (\hookrightarrow is derived internally)
 - Validation:
 - $\bullet\,$ A one-time check ensures the algebra satisfies the ${\rm FL_{ew}}\mbox{-axioms}.$
 - Wrapped in the ManyValuedLogics submodule of SoleLogics.jl

¹https://github.com/aclai-lab/Sole.jl

Code Examples: Gödel Algebra (G3)

```
using SoleLogics
      using SoleLogics.ManyValuedLogics
      using SoleReasoners
      \alpha = FiniteTruth("\alpha")
     d3 = Vector{FiniteTruth}([\bot, \alpha, T])
     n = BinaryOperation(d3, Dict{Tuple{FiniteTruth, FiniteTruth}, FiniteTruth})
          (\alpha, \perp) \Rightarrow \perp, (\alpha, \alpha) \Rightarrow \alpha, (\alpha, \top) \Rightarrow \alpha,
(\bot, \bot) \Rightarrow \bot, (\bot, \alpha) \Rightarrow \alpha, (\bot, \top) \Rightarrow \top,
           (\alpha, \perp) \Rightarrow \alpha, (\alpha, \alpha) \Rightarrow \alpha, (\alpha, \top) \Rightarrow \top,
           (T, \bot) => T, (T, \alpha) => T, (T, T) => T
      G3 = FiniteFLewAlgebra(d3, n, u, ·, +, ⊥, T)
      diamondA = diamond(IA A)
24 boxA = box(IA A)
      p = Atom("p")
      \varphi = \Lambda(diamondA(p), boxA(\rightarrow(p, \bot))) # \varphi := \langle A \rangle p \wedge [A](p \rightarrow \bot)
      mvhsalphasat(T, \phi, G3)
```

Figure 14: Evaluation code example for $T(\top \leq \varphi)$ where $\varphi = \langle A \rangle \rho \wedge [A](\rho \to 0)$ and $\top \in \mathsf{G3}$.

Code Examples: Heyting Algebra (H4)

```
using SoleLogics
using SoleLogics.ManyValuedLogics
using SoleReasoners
\alpha = FiniteTruth("\alpha")
β = FiniteTruth("β")
d4 = Vector{FiniteTruth}([\bot, \alpha, \beta, T])
n = BinaryOperation(d4, Dict{Tuple{FiniteTruth, FiniteTruth}, FiniteTruth})
             (1, 1) \Rightarrow 1, (1, \alpha) \Rightarrow 1, (1, \beta) \Rightarrow 1, (1, T) \Rightarrow 1,
             (\alpha, \perp) \Rightarrow \perp, (\alpha, \alpha) \Rightarrow \alpha, (\alpha, \beta) \Rightarrow \perp, (\alpha, \top) \Rightarrow \alpha,
             (\beta, \perp) \Rightarrow \perp, (\beta, \alpha) \Rightarrow \perp, (\beta, \beta) \Rightarrow \beta, (\beta, \top) \Rightarrow \beta,
             (T, \perp) \Rightarrow \perp, (T, \alpha) \Rightarrow \alpha, (T, \beta) \Rightarrow \beta, (T, T) \Rightarrow T
u = BinaryOperation(d4, Dict{Tuple{FiniteTruth, FiniteTruth}, FiniteTruth})
             (\bot, \bot) \Rightarrow \bot, (\bot, \alpha) \Rightarrow \alpha, (\bot, \beta) \Rightarrow \beta, (\bot, \top) \Rightarrow \top,
             (\alpha, \perp) \Rightarrow \alpha, (\alpha, \alpha) \Rightarrow \alpha, (\alpha, \beta) \Rightarrow T, (\alpha, T) \Rightarrow T,
             (\beta, \perp) \Rightarrow \beta, (\beta, \alpha) \Rightarrow T, (\beta, \beta) \Rightarrow \beta, (\beta, T) \Rightarrow T.
             (T, \bot) \Rightarrow T, (T, \alpha) \Rightarrow T, (T, \beta) \Rightarrow T, (T, T) \Rightarrow T
H4 = FiniteFLewAlgebra(d4, n, u, \cdot, +, \bot, T)
diamondA = diamond(IA A)
boxA = box(IA A)
p = Atom("p")
\varphi = \Lambda(diamondA(p), boxA(\rightarrow(p, \perp))) # \varphi := \langle A \rangle p \wedge [A](p \rightarrow \perp)
mvhsalphasat(T. φ. H4)
```

Figure 15: Evaluation code example for $T(\top \leq \varphi)$ where $\varphi = \langle A \rangle p \wedge [A](p \to 0)$ and $\top \in H4$.

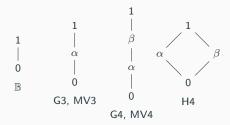
Key Challenges and Solutions

- Computational complexity increases with:
 - Size of the algebra: More truth values to consider
 - Complexity of the formula: More nodes and branches
- Optimization techniques:
 - Implemented priority queues to manage node expansion efficiently
 - Parallelization: Expanded independent branches using multi-core processors
- Pruning strategies: Periodically clean priority queues to remove expanded or closed nodes
- Efficient data structures:
 - Designed compact representations for nodes and branches
 - Minimized memory usage to handle large tableaux

Experiments and Results

Experiments and Results

 \bullet Six representative finite $\mathrm{FL}_\mathrm{ew}\text{-}\mathsf{algebras}$:



- G3 and MV3 (resp. G4 and MV4) differ because of the t-norm but share the same lattice structure
- Each algebra tested on the same 500 random formulas with heights up to 5 (i.e., 32 symbols)
- $\alpha \succ 0$ chosen randomly
- Branch priority policy kept random

Experiments and Results

- ullet Impact of using different $\mathrm{FL}_{\mathrm{ew}} ext{-Algebras}$
- All tests were conducted on a machine equipped with 2 Intel Xeon Gold 28-Core CPUs and 224GB of RAM
- Timeout of 30 seconds

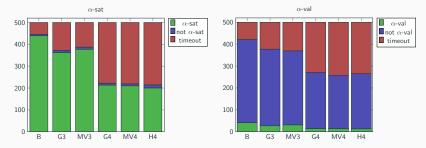


Figure 16: Results on common many-valued algebras for formulas of height up to 5 with a timeout of 30 seconds.

Conclusions and Future Work

Conclusions and Future Work

- Presented a customizable and flexible framework for many-valued interval temporal logic
- $\bullet~{\rm FL_{ew}}\mbox{-algebras}$ facilitate reasoning in systems with uncertainty and graded truths
- Developed a sound and complete tableau system for MVHS
- \bullet Ready-to-use open-source implementation with user-definable finite (${\rm FL_{ew}}\text{-}$)algebras 2
- Tested the tableau system over different finite algebras
- Future work:
 - Support for Interval Spatial Logic
 - Support for non-finite algebras
 - Real-world applications (Many-Expert Decision Tree Learning)

²https://github.com/aclai-lab/Sole.jl

Questions?

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